

New style compact hydraulic cylinders for 16 MPa with absolute position sensor.

- Provided with a small position sensor not affecting the compact design of the cylinder.
- Same dimensions as those of 160S-1 except the sensor on the cap side.
- Usable in a strong magnetic field where magnetic proximity sensors cannot be used.
- Applicable to cylinder with bores of 32 to 125 mm and strokes of 5 to 50 mm. (For strokes more than 60 mm, consult us.)
- The standard cylinders have male threaded rod ends.
- Mounting style: SD, FA and LA (foot type).



Standard Specifications

Type	General purpose type
Nominal pressure	16 MPa
Maximum allowable pressure	16 MPa
Proof test pressure	24 MPa
Minimum operating pressure	0.3 MPa
Working speed range	8 to 100mm/s
Working temperature range (Note 1) (ambient temperature)	-10 to +100°C (No freezing)
Structure of cushioning	None
Adaptable fluid	Petroleum-based fluid (When using another fluid, refer to the table of fluid adaptability.)
Tolerance for thread	JIS 6g(/6H)
Tolerance of stroke	0 to 0.8mm
Mounting style	SD, FA, LA
Rod end thread	Male thread (Note 2)

Notes) 1. At a temperature exceeding 60°C, the sensor is not damaged, but its accuracy is deteriorated.
 2. Since the piston rod has a built-in sensor, a female threaded rod is inapplicable. However, it may be applicable depending on the bore and stroke. Contact us.

Adaptability of Fluid to Seal Material

Seal material	Adaptable fluid				
	Petroleum-based fluid	Water-glycol fluid	Phosphate ester fluid	Water in oil fluid	Oil in water fluid
3] Fluorocarbon	○	×	○	○	○
6] HNBR	◎	◎	×	◎	◎

Notes) 1. ◎○: Applicable ×: Inapplicable
 2. The ◎-marked items are recommended seal materials in case of giving the first priority to abrasion resistance.

Terminologies

Nominal pressure
 Pressure given to a cylinder for convenience of naming. It is not always the same as the working pressure (rated pressure) that guarantees performance under the specified conditions.

Maximum allowable pressure
 Maximum allowable pressure generated in a cylinder (surge pressure, etc.).

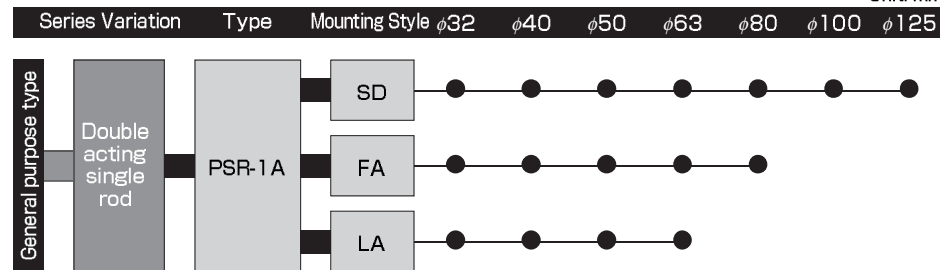
Proof test pressure
 Test pressure against which a cylinder can withstand without unreliable performance at the return to nominal pressure.

Minimum operating pressure
 Minimum pressure at which cylinder installed horizontally operates under no load.

Note) ● This series of cylinders does not have air vents.

Product Lineup

Unit: mm



Detector Specifications

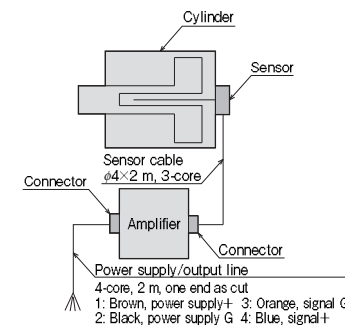
Power supply	12 to 24 V DC ±10% Ripple 10% or less	
Consumption current	30 mA or less	
Accuracy	Repeatability (Note 1)	±0.1%FS or less
	Linearity	±1%FS or less (at room temperature)
	Temperature characteristics (temperature drift)	±1%FS or less (at 0 to +60): Amplifier block ±2%FS or less (at 0 to +60): Sensor block ±10%FS or less (at -0 to +100): Sensor block
Output (Note 2)	1 to 5 V (1 V at piston retracting end)	
Response	4kHz(-3dB)	
Working temperature range	-10 to +100°C: Sensor block -10 to +60°C: Amplifier block (No freezing)	
Impact resistance	500 m/s ² , three times in each of X, Y and Z directions	
Water resistance (Note 3)	Sensor: Equivalent to IP66 Amplifier: Without protection	
Connection	Between sensor and amplifier: 3-core, φ4×2 m	
	From amplifier: 4-core, 2 m, one end as cut	

Notes) 1. Dispersion of output at the same position under the same conditions (temperature, power supply voltage, etc.).
 2. The sensor output at the rod advancing end varies depending on the cylinder stroke. Refer to the sensor output drawing contained in the outline drawings.
 3. The water resistance is deteriorated at high temperatures. Take care when cleaning. Install the amplifier in a place away from dust and drops of water.

Product Configuration

PSR-1A includes the following:

- Cylinder body with sensor (with cable between sensor and amplifier)
- Amplifier
- Cable with connector at one end and other end as cut for power supply/output (4-core, 2 m)



Standard Stroke Range

Bore (mm)	Cylinder stroke (mm)									
	5	10	15	20	25	30	35	40	45	50
φ32	○	○	○	○	○	○	○	○	○	○
φ40	○	○	○	○	○	○	○	○	○	○
φ50	○	○	○	○	○	○	○	○	○	○
φ63	○	○	○	○	○	○	○	○	○	○
φ80	○	○	○	○	○	○	○	○	○	○
φ100	○	○	○	○	○	○	○	○	○	○
φ125	○	○	○	○	○	○	○	○	○	○

Note) For strokes of more than 60 mm, contact us.

How to order

General Purpose Type

The item enclosed by broken line needs not to be entered, if unnecessary. ■ Semi-standard

● Standard type PSR-1A

① Type ② Seal material ③ Mounting style ④ Cylinder bore ⑤ Cushioning ⑥ Stroke ⑦ Thread type ⑧ Port type ⑨ Lock nut ⑩ Air vent type

③ Fluorocarbon
⑥ HNBR

⑤ SD Basic style
⑤ FA Rod flange
⑤ LA Foot type

Note) When ordering the FA style cylinder body, it is necessary to change dimension W/F of the SD style cylinder. For details, contact us.

SD : φ32 to φ125
FA : φ32 to φ80
LA : φ32 to φ63

⑨ None Without lock nut
⑨ L With one lock nut

Note) If two or more lock nuts are required, make an order for the additional lock nut(s).

⑩ None Rc thread
⑩ G G thread

Note) G thread is applicable only to the SD style.

No cushion

Male thread type

Cylinder stroke (mm)
5, 10, 15, 20, 25, 30, 35, 40, 45, 50 mm
Note) For strokes other than the above standard strokes, contact us.

⑩ None Without air vent (standard)
⑩ V With air vents
(order made: φ32 to φ125)

★ Port G thread type (only for SD style)

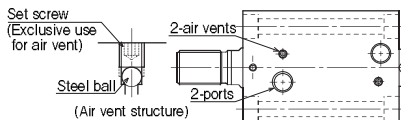
- For a port G thread type cylinder, specify the code as following.

(Example)
PSR-1A 6SD40N50TG
Port G thread type

Note) The port G thread has dimensions different from the standard dimensions depending on the bore. Refer to the dimensional drawing.

★ Air vent specifications (order made)

The air vents are laid on the port surface and located symmetrical positions to the ports.

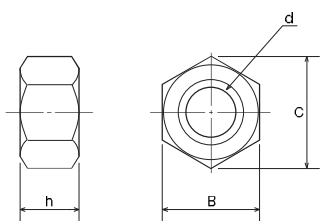


Dimensional Table

Unit: mm

Symbol	Part number	d	B	C	h
Bore					
φ32	LNH-16F-H	M16×1.5	22	25.4	10
φ40	LNH-20F-H	M20×1.5	27	31.2	12
φ50	LNH-24F-H	M24×1.5	32	37.0	14
φ63	LNH-30F-H	M30×1.5	41	47.3	17
φ80	LNH-39F-H	M39×1.5	55	63.5	20
φ100	LNH-48F-H	M48×1.5	70	80.8	26
φ125	LNH-64F-H	M64×2	90	104	35

Note) When making an order only for the lock nut, indicate the part number.



Weight Table

Unit: kg

Bore (mm)	Basic style (SD)		Flange type (FA)		Foot type (LA)		Amplifier weight
	Basic weight	Additional weight per mm of stroke	Basic weight	Additional weight per mm of stroke	Basic weight	Additional weight per mm of stroke	
φ32	1.5	0.025	2.1	0.025	1.5	0.027	0.05
φ40	1.9	0.030	3.1	0.030	1.9	0.034	
φ50	2.7	0.037	4.3	0.037	2.8	0.044	
φ63	4.2	0.047	6.3	0.047	4.5	0.062	
φ80	7.4	0.067	11.2	0.067	—	—	
φ100	14.0	0.102	—	—	—	—	
φ125	24.7	0.152	—	—	—	—	

Calculation formula) Cylinder weight (kg)=basic weight+(cylinder stroke (mm)×additional weight per mm of stroke)

Calculation example) PSR-1A, SD style, bore φ50, cylinder stroke 50 mm
2.7+(50×0.037)=4.55kg

Piston Pressure Receiving Area Table

Unit: mm²

Bore (mm)	Rod dia. (mm)	Double acting single rod	
		Extension side	Retraction side
φ32	φ18	804	550
φ40	φ22	1257	876
φ50	φ28	1963	1348
φ63	φ36	3117	2100
φ80	φ45	5027	3436
φ100	φ56	7854	5391
φ125	φ70	12272	8424

Calculation formula) F=A×P×β(N)

F: cylinder force (N)
A: piston pressure receiving area (mm²)
P: working pressure (MPa) β: load rate

Calculation example

Double acting single rod, bore φ40, working pressure: 16 MPa, load rate: 0.8
Cylinder force on extension side (N)
=1257×16×0.8=16090(N)
Cylinder force on retraction side (N)
=876×16×0.8=11213(N)

Standard Stroke Range

Bore (mm)	Cylinder stroke (mm)									
	5	10	15	20	25	30	35	40	45	50
φ32	○	○	○	○	○	○	○	○	○	○
φ40	○	○	○	○	○	○	○	○	○	○
φ50	○	○	○	○	○	○	○	○	○	○
φ63	○	○	○	○	○	○	○	○	○	○
φ80	○	○	○	○	○	○	○	○	○	○
φ100	○	○	○	○	○	○	○	○	○	○
φ125	○	○	○	○	○	○	○	○	○	○

Note) For strokes of more than 60 mm, contact us.

Discontinued

PQCPA Series dedicated to analog/pulse output from position sensing cylinders

- Environmentally-friendly lead-free indicator.
- Analog input and pulse input types are available.
- Provided with multi-point output function (5 points) as a standard function to enable to individually set the upper and lower limits. (Note 1)
- A 16-bit AD converter is provided to realize high resolution. (Analog input type)
- Provided with a counter with a response frequency of 200 kHz (Pulse input type)
- Provided with a pulse position correcting function. (Note 2)

Note 1) Setting the bank switching enables to use the multi-output function of up to 15 points.
 Note 2) Position correction can be made by mounting a cylinder sensor. Positional error caused by slippage of the encoder is eliminated.



Standard Specifications

Type	Analog	Pulse
Model number	PQCPA-CU-A	PQCPA-CU-P
Applicable input signals	Analog voltage/analog current	Phase AB
Display range	±999999	
Resolution	Stroke×1/10000	—
Reply frequency	1 kHz	200 kHz
Linearity	±0.02%FS	—
Signals	Voltage input 0 to 10 V Voltage input 1 to 5 V Current input 4 to 20 mA	Open collector input Differential input (line driver input) 12 V voltage input 24 V voltage input
Monitor output	Voltage output (Note)	Line driver output
Sampling speed	1000 times/sec	
Display speed	10 times/sec	
Display method	Display by fluorescent display tube	
Control input	No-voltage input (reed sensor/solid state sensor)	
Control output	Open collector Max. rating: 50 V DC, 50 mA (Provided with multi-point output function (5 points) to enable to individually set the upper and lower limits and pulse position correcting function)	
Power supply voltage	24 V DC ±10%	
Ambient temperature	0 to 50°C (No freezing)	
Ambient humidity	35 to 80%RH (No condensing)	

Note) The monitor output at current input (4 to 20 mA) is voltage output of 1 to 5 V.

Function Table

Type	Analog input	Pulse input
Model number	PQCPA-CU-A-A	PQCPA-CU-P-12
	PQCPA-CU-A-V	PQCPA-CU-P-24
Functions	—	PQCPA-CU-P-00
	Display of position	Display of position
	Bank switching	Bank switching
	Multi-point output	Multi-point output
	Positional data hold	Positional data hold
	—	0 setting signal
—	Correcting function	

List of Applicable Actuators

Series	Detection method	Signal type
PTN-1B	Absolute method	Analog type (4 to 20 mA, 0 to 10 V)
PTH-1B		
PTT-1B		
PSR-1A		
35P-3	Linear pulse encoder	Encoder type
70P-8		
140P-8		

Note) For the details of each cylinder, see the section of each series.

Position Sensing Cylinders

PSR-1A

Position Sensing Cylinders

PSR-1A

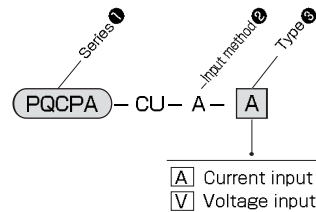
PSR-1A

PSR-1A

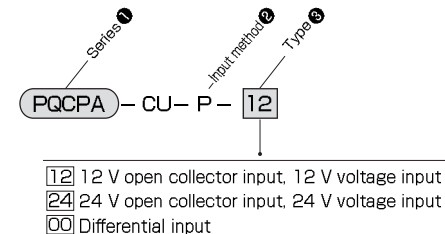
How to order **Discontinued**

Position Indicator

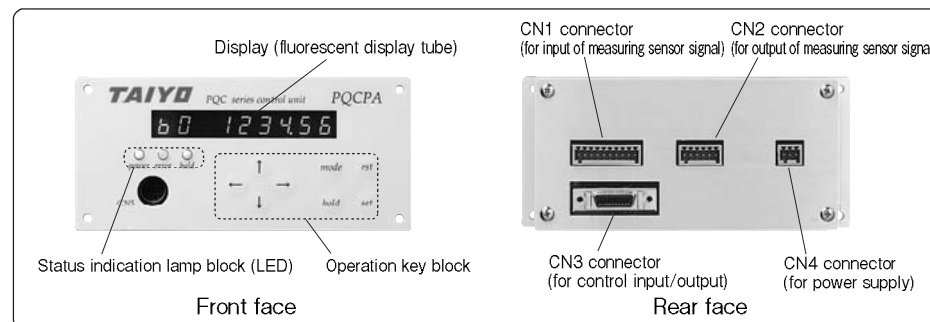
● Analog input



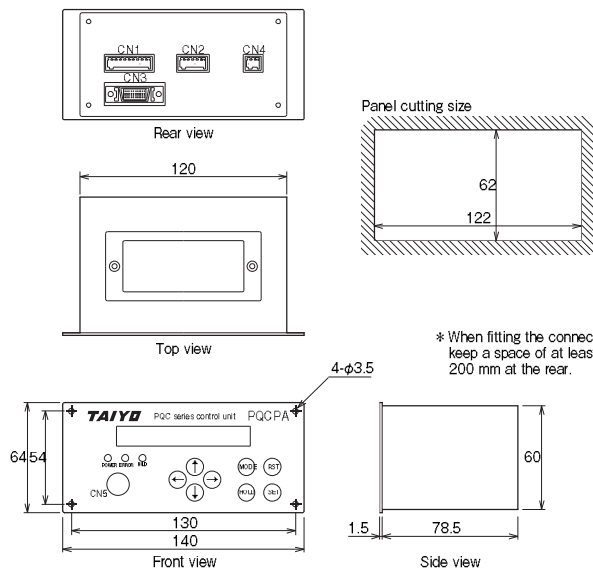
● Pulse input



Note) Cylinders do not come with indicators of differential input type [00].
(Specification to use the indicator in stand-alone state)

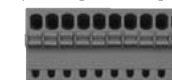


Dimensional Drawings

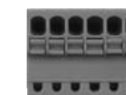


Supplied Connector

● CN1 connector (for input of length measuring sensor signal)



● CN2 connector (for output of length measuring sensor signal)



● CN3 connector (for control input/output)



● CN4 connector (for power supply)



Position Sensing Cylinders

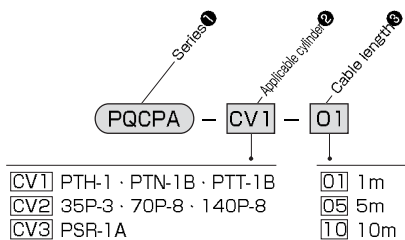
PSR-1A

PSR-1A

PSR-1A

Discontinued

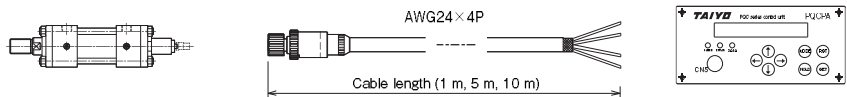
How to order cable between sensor and indicator



- * When ordering a cable, confirm the series name of the actuator on the sensor side. Some models cannot be connected.
- * After wiring, connect the indicator side connector to the CN1 connector on the indicator.

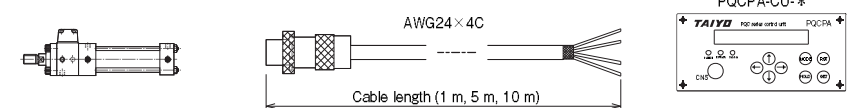
PQCPA-CV1 - Cable length

Applicable actuators: PTH-1B/PTN-1B/PTT-1B



PQCPA-CV2 - Cable length

Applicable actuators: 35P-3/70P-8/140P-8



PQCPA-CV3 - Cable length

Applicable actuators: PSR-1A

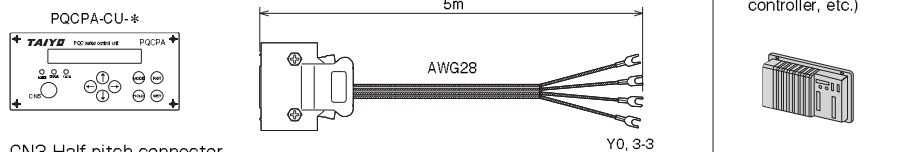


Note) PSR-1A comes with a 2m cable as a standard accessory. If another cable is required, select this cable. (In this case, disconnect the standard cable (2 m) of PSR-1A, and connect the selected cable directly to the amplifier.)

How to order I/O cable

PQCPA - IO

* The I/O cable is 5 m long.



CN3 Half-pitch connector
Note) Only the CN3 half-pitch connector is supplied as a standard accessory. If you need the connector with a cable, place an order for the connector.

Discontinued

External input/output

CN1

Pin No.	Description	Signals
1	Voltage/current input	Analog input
2	NC	-
3	Voltage/current GND	Analog input
4	Phase A	Pulse input
5	Phase -A	Pulse input
6	Phase B	Pulse input
7	Phase -B	Pulse input
8	+24V	Power supply output
9	+12V	Power supply output
10	GND	Power supply output:Phase AB GND

CN2

Pin No.	Description	Signals
1	Pout	Analog output
2	Vss	Analog output
3	A pulse	Pulse output
4	A pulse GND	Pulse output
5	B pulse	Pulse output
6	B pulse GND	Pulse output

CN4

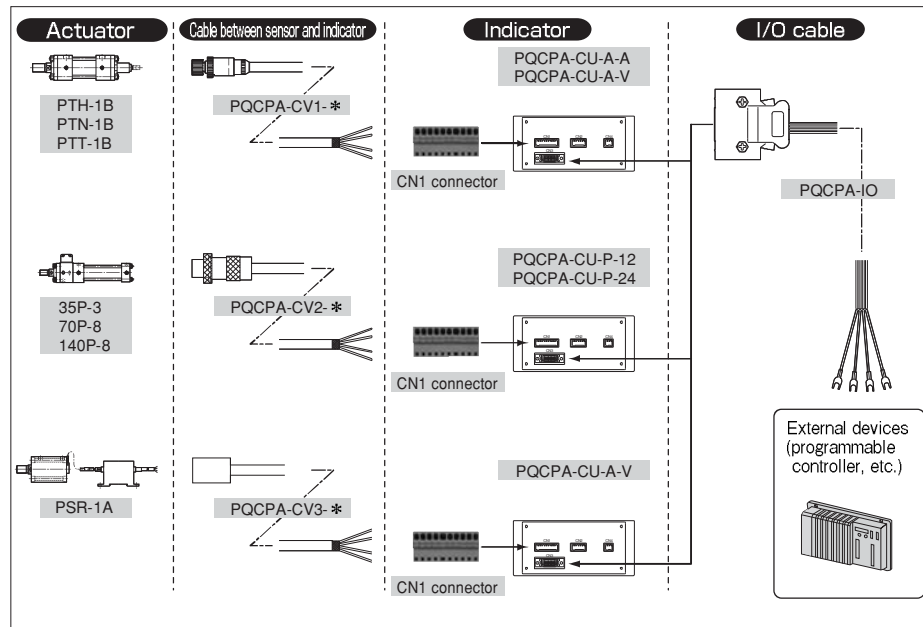
Pin No.	Description	Signals
1	P24	Power supply
2	N24	Power supply
3	PE	Power supply

CN3

Pin No.	Description	Signals
1	0 setting signal	Input
2	Positional data hold	Input
3	Correcting function	Input
4	Bank switching 0	Input
5	Bank switching 1	Input
6	Bank switching 2	Input
7	Reserved input	Input
8	Reserved input	Input
9	Input common	Input
10	Input common	Input
11	Multi-point output signal 0	Output
12	Multi-point output signal 1	Output
13	Multi-point output signal 2	Output
14	Multi-point output signal 3	Output
15	Multi-point output signal 4	Output
16	Reserved output	Output
17	Reserved output	Output
18	Reserved output	Output
19	Output common	Output
20	Output common	Output

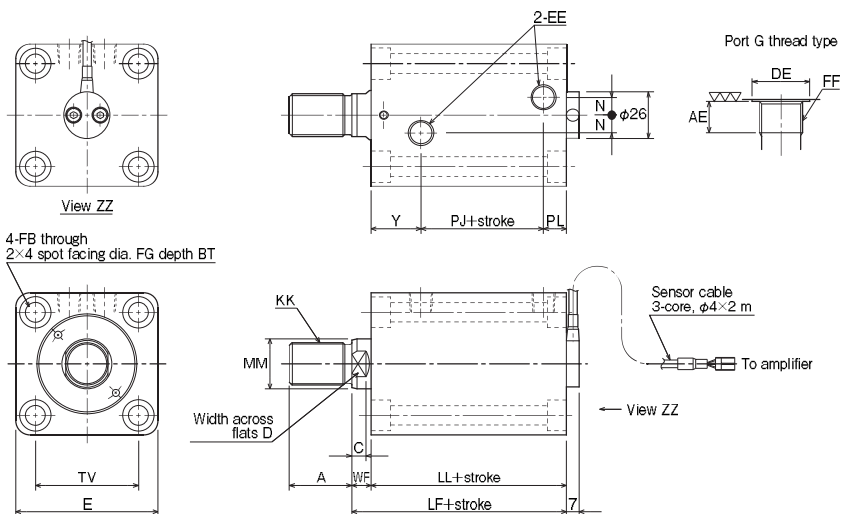
* For details, see the instruction manual.

Example of product configuration



PSR_1A/TPSR1A [Bore] CAD/DATA
is available. 

SD [General purpose type] PSR-1A [6] SD [Bore] N [Stroke] T

● Bore $\phi 32$ to $\phi 125$ 

Dimensional Table

Symbol Bore	A	AE	BT	C	D	DE	E	EE	FB	FF	FG	KK
$\phi 32$	25(40)	8	6.5	7	14	$\phi 17.2$	$\square 62$	Rc1/4	$\phi 6.6$	G1/8	$\phi 11$	M16×1.5
$\phi 40$	30(45)	8	8.6	7	19	$\phi 17.2$	$\square 70$	Rc1/4	$\phi 9$	G1/8	$\phi 14$	M20×1.5
$\phi 50$	35(50)	12	10.8	8	24	$\phi 21.5$	$\square 80$	Rc1/4	$\phi 11$	G1/4	$\phi 17.5$	M24×1.5
$\phi 63$	45(60)	12	13	9	30	$\phi 21.5$	$\square 94$	Rc1/4	$\phi 14$	G1/4	$\phi 20$	M30×1.5
$\phi 80$	60(80)	12	15.2	14	41	$\phi 21.5$	$\square 114$	Rc3/8	$\phi 16$	G1/4	$\phi 23$	M39×1.5
$\phi 100$	75(95)	12	19.5	22	50	$\phi 25.5$	$\square 140$	Rc3/8	$\phi 20$	G3/8	$\phi 29$	M48×1.5
$\phi 125$	95(125)	14	23.5	25	65	$\phi 30$	$\square 172$	Rc1/2	$\phi 24$	G1/2	$\phi 35$	M64×2

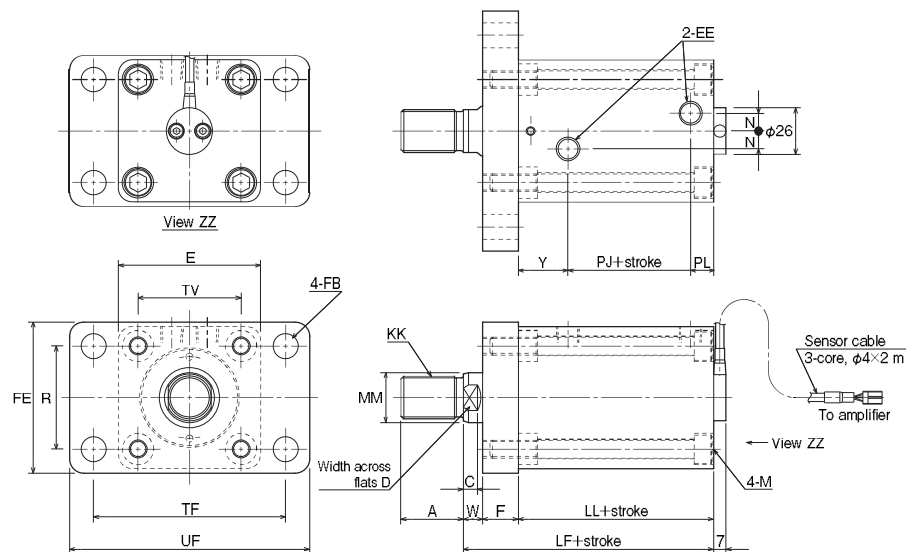
Symbol Bore	LF	LL	MM	N		PJ		PL		TV	WF	Y	
				Rc thread	G thread	Rc thread	G thread	Rc thread	G thread			Rc thread	G thread
$\phi 32$	64	54	$\phi 18$	10	10	14	14	12	12	$\square 47$	10	28	28
$\phi 40$	65	55	$\phi 22$	10	10	16	16	12	12	$\square 52$	10	27	27
$\phi 50$	71	60	$\phi 28$	10	14	19	13.5	13	18.5	$\square 58$	11	28	28
$\phi 63$	80	67	$\phi 36$	10	16	24	20	13	17	$\square 69$	13	30	30
$\phi 80$	95	78	$\phi 45$	15	19	25	24	18	18	$\square 86$	17	35	36
$\phi 100$	122	96	$\phi 56$	15	18	26	26	28	28	$\square 106$	26	42	42
$\phi 125$	135	105	$\phi 70$	25	25	29	29	30	30	$\square 132$	30	46	46

- Notes) 1. When the lock nut is used, the parenthesized dimension A is recommended.
 2. The tolerance of MM is f8.
 3. Since the piston rod has a built-in sensor, a female threaded rod is inapplicable as a rule. However, it may be applicable depending on the bore, stroke and dimension W. Contact us.

PSR_1A/TPSR1A [Bore] CAD/DATA is available.

FA [General purpose type] PSR-1A [6] FA [Bore] N [Stroke] T

●Bore $\phi 32$ to $\phi 80$



Dimensional Table

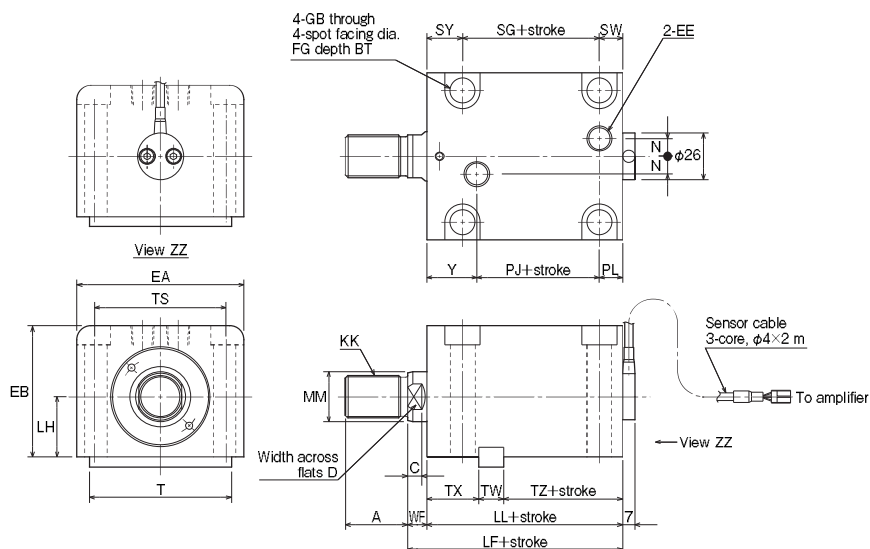
Symbol	A	C	D	E	EE	F	FB	FE	KK	LF
Bore										
$\phi 32$	25 (40)	7	14	$\square 62$	Rc1/4	15	$\phi 6.6$	62	M16X1.5	79
$\phi 40$	30 (45)	7	19	$\square 70$	Rc1/4	20	$\phi 11$	70	M20X1.5	85
$\phi 50$	35 (50)	8	24	$\square 80$	Rc1/4	20	$\phi 14$	85	M24X1.5	91
$\phi 63$	45 (60)	9	30	$\square 94$	Rc1/4	20	$\phi 14$	98	M30X1.5	100
$\phi 80$	60 (80)	14	41	$\square 114$	Rc3/8	25	$\phi 18$	118	M39X1.5	120

Symbol	LL	M	MM	N	PJ	PL	R	TF	TV	UF	W	Y
Bore												
$\phi 32$	54	M6X1	$\phi 18$	10	14	12	40	80	$\square 47$	95	10	28
$\phi 40$	55	M8X1.25	$\phi 22$	10	16	12	46	96	$\square 52$	118	10	27
$\phi 50$	60	M10X1.5	$\phi 28$	10	19	13	58	108	$\square 58$	135	11	28
$\phi 63$	67	M12X1.75	$\phi 36$	10	24	13	65	124	$\square 69$	150	13	30
$\phi 80$	78	M14X2	$\phi 45$	15	25	18	87	154	$\square 86$	185	17	35

- Notes) 1. When the lock nut is used, the parenthesized dimension A is recommended.
 2. The tolerance of MM is f8.
 3. Since the piston rod has a built-in sensor, a female threaded rod is inapplicable as a rule. However, it may be applicable depending on the bore, stroke and dimension W. Contact us.

PSR_1A/TPSR1A [Bore] CAD/DATA is available. 

LA [General purpose type] PSR-1A [6] LA [Bore] N [Stroke] T

●Bore $\phi 32$ to $\phi 63$ 

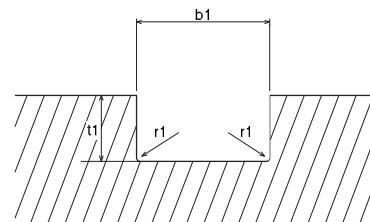
Dimensional Table

Symbol	A	BT	C	D	EA	EB	EE	FG	GB	KK	LF	LH
$\phi 32$	25 (40)	8.6	7	14	70	56	Rc1/4	$\phi 14$	$\phi 9$	M16 \times 1.5	64	25 \pm 0.06
$\phi 40$	30 (45)	10.8	7	19	80	64	Rc1/4	$\phi 17.5$	$\phi 11$	M20 \times 1.5	65	29 \pm 0.06
$\phi 50$	35 (50)	13	8	24	94	74	Rc1/4	$\phi 20$	$\phi 14$	M24 \times 1.5	71	34 \pm 0.06
$\phi 63$	45 (60)	15.2	9	30	114	89	Rc1/4	$\phi 23$	$\phi 16$	M30 \times 1.5	80	42 \pm 0.06

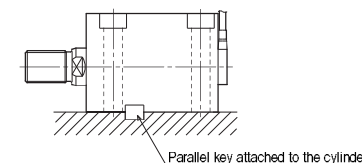
Symbol	LL	MM	N	PJ	PL	SG	SW	SY	T	TS	TW	TX	TZ	WF	Y
$\phi 32$	54	$\phi 18$	10	14	12	24	10	20	63	56	12	28	14	10	28
$\phi 40$	55	$\phi 22$	10	16	12	23	12	20	70	62	12	28	15	10	27
$\phi 50$	60	$\phi 28$	10	19	13	27	13	20	80	74	14	29	17	11	28
$\phi 63$	67	$\phi 36$	10	24	13	32	15	20	100	90	16	31	20	13	30

Notes) 1. When the lock nut is used, the parenthesized dimension A is recommended.
 2. The tolerance of MM is f8.
 3. Since the piston rod has a built-in sensor, a female threaded rod is inapplicable as a rule. However, it may be applicable depending on the bore, stroke and dimension W. Contact us.

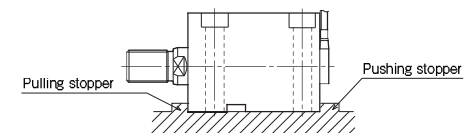
Recommended key groove dimensions



When using a parallel key



When not using a parallel key



The stopper size must be the same as the attached parallel key size.

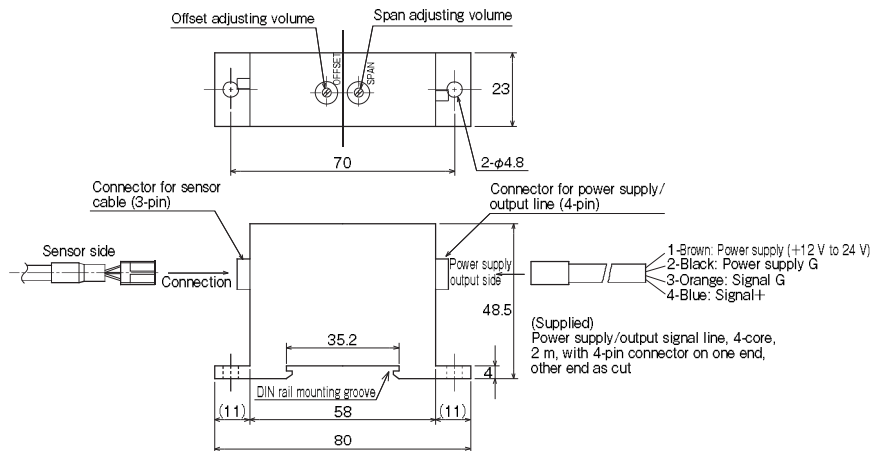
Dimensional Table

Bore	Nominal dimensions of key b \times h \times l	Key groove dimensions		
		b1	t1	r1
$\phi 32$	12 \times 8 \times 63(both rounded)	12 $^{0}_{-0.043}$	5 $^{+0.2}_{0}$	0.25 to 0.40
$\phi 40$	12 \times 8 \times 70(both rounded)	12 $^{0}_{-0.043}$	5 $^{+0.2}_{0}$	
$\phi 50$	14 \times 9 \times 80(both rounded)	14 $^{0}_{-0.043}$	5.5 $^{+0.2}_{0}$	
$\phi 63$	16 \times 10 \times 100(both rounded)	16 $^{0}_{-0.043}$	6 $^{+0.2}_{0}$	

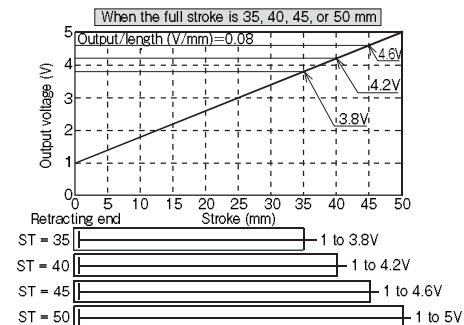
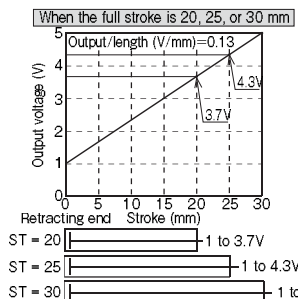
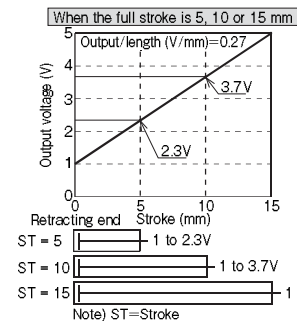
- When using the foot type, use the attached parallel key to install the cylinder, referring to the recommended key groove dimensions.
- When not using the parallel key, attach the stoppers at the front and rear with respect to the cylinder stroke direction. If the cylinder is used without a key or stoppers, excessive force is applied to the cylinder mounting bolts, and the bolts may be damaged.

PSR_1A/TPSR1A [Bore] CAD/DATA is available.

Amplifier



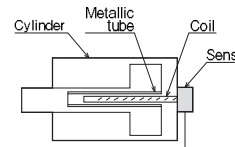
■ Sensor output (3 patterns according to cylinder full stroke range)



- Notes) 1. The values shown above are for reference. The actual output may be slightly different.
2. The amplifier block has an offset adjusting screw and a span adjusting screw, so that an adjustment of about 5% can be made.
3. The output voltage at the same stroke may vary depending on the full stroke range.
- (Example) The output voltage at a stroke of 5 mm on a cylinder with a full stroke of 15 mm differs from that at a stroke of 5 mm on a cylinder with a full stroke of 30 mm.

Principle of sensor

When a pulse signal is given to the coil, the pulse waveform shows not a regular form, but a form like a mound due to the inductance. If there is a metallic tube on the outside of the coil, the waveform changes further (the gradient becomes larger) under the influence of eddy current. This change to the waveform depends on the ratio of the area covered with the metallic tube. This sensor converts the ratio of the area covered with the metallic tube to a positionally correlated voltage.

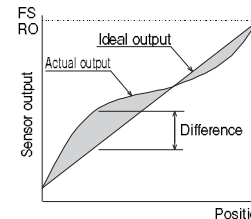


Linearity

The sensor accuracy under given conditions at a constant temperature is indicated. It is ideal that the sensor output is completely proportional to the position, but, actually, the sensor output shows a slight deviation.

The linearity (nonlinearity) refers to the difference between ideal output and sensor output and is normally indicated by the ratio (%FS or %RO) of the maximum value of deviation at the overall measurement length to the full stroke (FS) or rated stroke (RO).

For example, if the ratio is $\pm 1\%$ FS on a sensor with a stroke of 50 mm, an error of ± 0.5 mm may occur. Since this sensor (amplifier block) has span and offset adjusting volumes, the output can be adjusted at the 0 point and FS (full stroke) position.



Influence of rotation of piston rod

Although the metallic tube is fixed in the piston rod, the output is changed by the change of the distance in the circumferential direction (run-out) between the metallic tube and the sensor rod with a built-in coil. Therefore, the output may change approx. 0.2%FS when the piston rod is rotated. To obtain stable output, the cylinder should be connected in such a way that the rod is not rotated.

Influence of cable

If the cable length between the sensor and the amplifier is changed, the sensor output changes. Use the supplied cable without cutting or extending. The output obtained when the cable is in a coiled state may slightly differ from that when it is in a straight state. Lay the cable in such a way that it will not considerably change in state during use.

Combination of sensor and amplifier

Since the amplifier has been adjusted according to the sensor, if the amplifier is combined with other sensor, normal output cannot be obtained. When using several sensors, make sure that each amplifier has the same serial number as that of the corresponding sensor.

Power supply voltage

This sensor is hardly affected by fluctuation in supply voltage. However, it is slightly affected. When the power supply voltage changes from 12 V to 24 V, the change in output is less than 1%FS.

Influence of deformation of cylinder body and piston rod

- The elastic deformation of the cylinder body and piston rod is approx. 0.025 to 0.05 mm (equivalent to 0.05 to 0.1%FS) at a nominal pressure of 16 MPa.
- The expansion and contraction of the cylinder caused by temperature change is less than 0.1 mm (approx. 0.15%FS) at 0 to 100°C in the case of a stroke of 50 mm.
- If the work connecting part is loose, a difference in output by the looseness occurs on the work position basis at the advancing and retracting ends.

Temperature drift

The electric resistance values of the coil and metallic tube change with temperature, and the sensor output is affected by the temperature. The standard sensor is designed so that the temperature drift is reduced in a temperature range from 0 to 60°C. When the temperature exceeds 60°C, the error will become large. Carefully check the temperature. An example of influence of temperature on output of a sensor mounted on a cylinder is shown below.

