

USEFUL GENERAL FORMULAS AND DEFINITIONS

Name	Formula	Units	Defination
Kilowatt loss	$= \frac{HP (.746) \times (1.0 - \text{efficiency})}{\text{efficiency}}$		
Power Output	$1HP = 745W = 0.746Kw$		HP : hosepower
Current	$I = \frac{E}{R}$	I in Amp	E : Volt R : Ohm
Input power	$P_{in} = E . I . \text{Cos}\phi \quad - (1 \phi)$ $P_{in} = \sqrt{3} . E . I . \text{Cos}\phi \quad - (3 \phi)$	P_{in} in W	E : Volt I : ampere
Output power	$P_{out} = E . I . \eta . \text{Cos}\phi \quad - (1 \phi)$ $P_{out} = \sqrt{3} . E . I . \eta . \text{Cos}\phi \quad - (3 \phi)$	P_{out} in W	
Efficiency	$\eta = \frac{P_{out}}{P_{in}} \times 100\%$		
Power factor	$\text{Cos}\phi = \frac{P_{in}}{\sqrt{3} . E . I} \quad \% \quad - (3 \phi)$		
Synchronous speed	$N_s = \frac{120 f}{P}$	N_s in min^{-1}	f : frequency of the power supply P : poles
Slip	$S = \frac{N_s - N}{N_s} \times 100\%$		N : motor speed
Torque	$T = \frac{974 Kw}{N}$	T in kgf-m	1 kgf-m = 9.8 N-m
Power	$P = 1.027 NT$	P in W	
Reative power absorbed by the motor	$Q = \sqrt{3} . E . I . \text{SIN } \phi \quad - (3 \phi)$	Q in VAR	

- The **Locked-Rotor Torque** of a motor is the minimum torque which it will develop at rest for all angular position of the rotor, with rated voltage applied at rated frequency
- The **Pull-in torque** is the maximum constant torque under which the motor will pull its connected inertial load into synchronous speed at rated voltage and frequency, when its field excitation is applied.
- The **Pull-out Torque** is the maximum sustained torque under which the motor will develop at synchronous-speed with rated voltage applied at rated frequency and with normal excitation
- The **Full-Load Torque** is the torque necessary to produce its rated horsepower at full-load speed.
In Kg at a 1 meter radius, it is equal to the KW times 974 divided by the full-load speed
- The **Accelerating Torque** is the difference between the motor torque and the load torque from 0 to pull-in speed.
A 10% or higher margin is desired to avoid a possible stalled or locked rotor position.
- The **Power Factor** or and alternating- current motor or generator is the ratio of the KVA input (or output) to the Kilowatt input