

ENGINEERING TOMORROW

Selection Guide 0.25 kW - 2 MW

VLT[®] AQUA Drive FC 202 series delivers the ultimate cost efficiency







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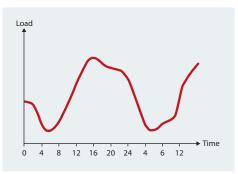
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In modern plants, energy savings are just part of the cost equation



Here in Aarhus, Denmark, this wastewater treatment plant has changed the energy picture, based on advanced process control and extensive use of the VLT® AQUA Drive. It is no longer a question of 60% energy savings, but rather of net production of energy from the whole plant.



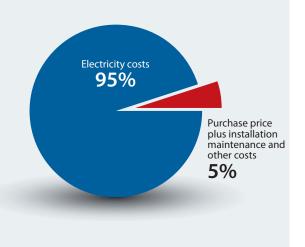
The considerable daily load variation in water or wastewater treatment plants makes it economically attractive to install control handles on more or less all rotating equipment such as pumps and blowers. The new generation of the VLT® AQUA Drive is the ideal choice for the water industry, giving you precise control and a perfect match for all your applications. The benefits are obvious:

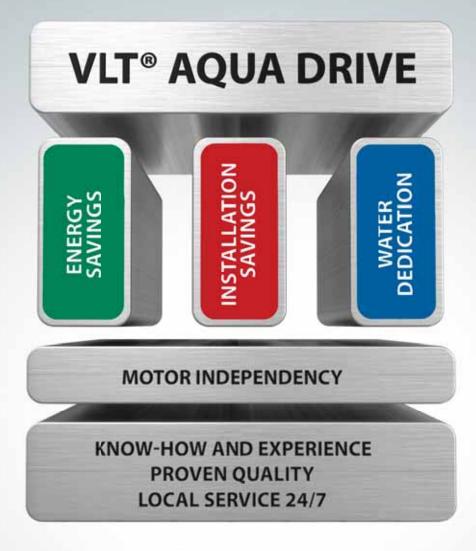
- Better water quality
- Better asset protection
- Less maintenance costs
- Reduced energy cost
- Higher plant reliability/ performance

Small investment – big returns Look at the lifetime savings

Over the last decades, the relative cost of Variable Speed Drives (VSDs) has dropped and energy prices have increased. This makes it more attractive to use VSDs on more or less all rotating equipment. Over the lifetime of the VSD, energy cost is the dominating economical factor. The energy efficiency of the VSD must therefore be a key selection parameter.

The new generation VLT[®] AQUA Drive's 0.5 to 2 % better installed energy efficiency compared with traditional drives is on same level as savings gained by moving from an IE2 to an IE3 motor.





Nothing beats know how and experience The new generation VLT® AQUA Drive built from the bottom up To deliver the ultimate cost efficiency

The new generation VLT® AQUA Drive is built on a solid foundation of knowhow and experience – combine this with Danfoss quality and our global network of local 24/7 service and you get rock solid reliability.

Fits all motors

Danfoss is the world's largest dedicated and motor independent VSD supplier. By keeping at the forefront of control algorithms for new motor technologies, we can always offer you a free choice between motor suppliers.

A powerful combination

Three pillars raise the performance of the VLT® AQUA Drive to new heights: It's our unique combination of energy savings, reduced installation costs and a solid dedication to all your water applications that sets the new generation VLT® AQUA Drive above the competition when it comes to overall lifetime savings.

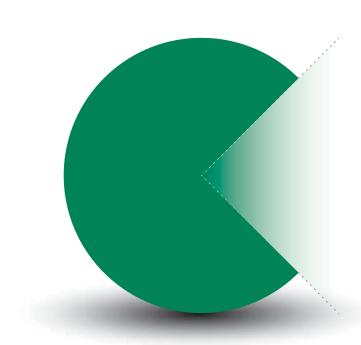
Up to 30% first-year cost savings

With a combination of powerful new features and functions, the new generation VLT® AQUA Drive can realistically offer first-year cost savings between 10 – 30%, relative to the investment made in the drives, compared to traditional drive solutions.



Market leading energy efficiency Save up to 25% of investment first year

Our tight focus on energy efficiency at every stage of development including the net efficiency when the new generation VLT® AQUA Drive is installed means that you get a drive that delivers cost savings of up to 25 % of investment in the drive in its first year, when compared to traditional VSD solutions. That's the equivalent to the savings gained by choosing an IE 3 motor instead of an IE 2.



Efficiency

5 reasons to choose new VLT® AQUA Drive

- 1. Energy efficient VSD design
- 2. Intelligent heat management
- 3. Automatic adaption to application
- 4. Energy efficient harmonic mitigation
- 5. Optimal control of all motors

Energy efficient design The new generation VLT® AQUA Drive's control algorithm and design focuses on reducing heat loss, to maximise energy efficiency.

2. Intelligent heat management

An unique back channel cooling concept transfers up to 90% of heat away from the room. This results in large energy savings on unnecessary air conditioning.

Go to www.danfoss.com for video.

3. Automatic adaption to application

Around 90% of all motors are oversized by more than 10%. AEO functionality can deliver energy savings of around 2% at the 90% load, with typical savings up to 5% over the whole range.

4. Energy efficient harmonic mitigation

Our unique VLT[®] Low Harmonic Drive with integrated AAF filter delivers an energy efficiency that is 2-3 % better than traditional VSD with Active Front End technology. Sleep function at low load secures further energy savings.

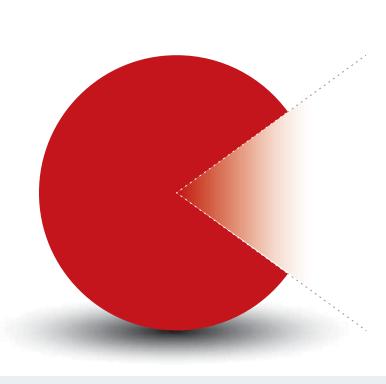
5. Optimal control of all motors

The VLT® AQUA Drive's capability to efficiently operate the diff erent motor types in the market, secures you a free choice between motor suppliers. One of the latest developments is for high speed PM motors.

The unique Danfoss VVC+ control technology is ideal for high speed turbo blowers using PM motors, offering from 0.5 to 3 % additional installed energy savings compared with using traditional VSDs.

Installation savings and user friendliness Save up to 20%

Based on our lengthy experience with the first ever dedicated water and wastewater drive on the market, the new generation VLT® AQUA Drive offers very efficient installation and commissioning solutions which, compared to traditional VSDs, off er cost saving of between 10-20%.



Simplicity

Reasons to choose new VLT[®] AQUA Drive

1. Less panel space

- 2. Direct outdoor installation
- 3. Long cable capability as standard
- 4. Reduce air conditioning investment
- 5. Integrated harmonic mitigation
- 6. Printed circuit board protection as standard
- 7. Easy commissioning
- 8. Minimum 10 years' lifetime

1. Less panel space

The unique combination of Danfoss VLT® Low Harmonic Drive with integrated AAF filters, the ability to install the new generation VLT® AQUA Drive side by side and its compact design offer a very space-friendly package when the complete solution is installed.

2. Direct outdoor installation

As standard, Danfoss offers VSD in IP66/NEMA4X. In addition to the convenience of having the VSD close to the pump, for example, this typically reduces cable costs, removes the need for air condition capacity and lowers control room costs.

3. Long cable capability as standard

Without the need for additional components, the VLT® AQUA Drive provides trouble free operation with cable lengths up to 150 m screened and 300 m unscreened.

4. Air conditioning investment reduced by 90%

Unique Danfoss back channel cooling system offers up to 90% reduction in investment for air cooling systems to remove heat from the VSDs.

5. Integrated harmonic mitigation

The VLT® AQUA Drive is delivered with integrated harmonic mitigation solutions to a THDi level of 40% as standard. This saves space and costs while making installation easier.

6. Printed circuit boards protection as standard

From 90 kW the VLT® AQUA Drive comes as standard with 3C3 PCB coating to ensure long lifetime even in harsh wastewater environments.

7. Easy commissioning

Whether it's a 0.25 kW or 2 MW drive you get the same control panel with local language, the new SmartStart function and many other time saving features.

8. Designed for a minimum 10 years' lifetime

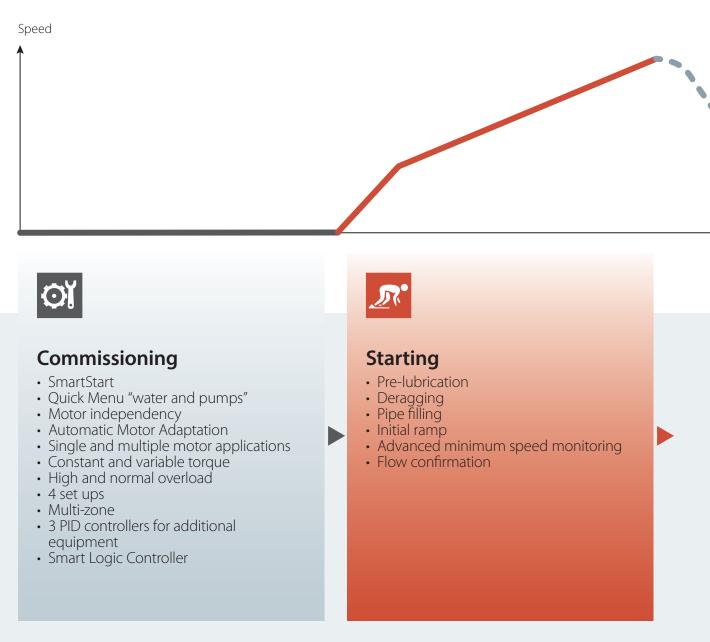
With the VLT® AQUA Drive's high quality components, maximum 80% load on components and intelligent heat management reducing dust on PCB's, the need for routine scheduled parts replacements, such as electrolytic capacitors and fans has been removed.



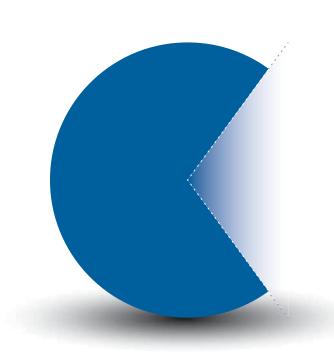
An unsurpassed fit for all your water applications

The new generation VLT® AQUA Drive is the perfect match for all water and wastewater applications. Specially designed software features help protect your assets in many ways such as by avoiding water hammer, reducing maintenance on pumps and blowers and by saving additional energy compared with traditional VSD controls. The new generation VLT® AQUA Drive gives your rotating equipment the best possible lifetime, with the lowest energy consumption and maintenance costs. All while protecting your assets.

The new generation VLT[®] AQUA Drive has features for all operation conditions, from commissioning to stopping



Lifetime benefits





- 1. User friendliness
- 2. Flexibility
- 3. Reliability
- 4. Energy saving
- 5. Pipe and plant asset protection
- 6. Reduced maintenance

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Operation

- Automatic energy optimisation
- Lubrication
- End of curve detection
- Dry run detection
- Low flow detection and sleep mode
- Flying start and kinetic backup
- Timed actions
- Preventative maintenance
- Deragging
- Flexible and intelligent handling of user infos, warnings and alarms
- Flow compensation

Stopping

- Check valve ramp
- Final ramp
- Post lubrication
- Deragging

Time



Benefits of using VLT® AQUA Drive in water supply

Pumping water out to the customer from the water work can seem to be a simple process. The fact is, that energy for these pumps typically represent 60-80% of total energy consumption for the whole water supply system. Besides the major energy savings of around 40% obtained by regulating the pressure in the network with VLT® AQUA Drives, the regulation will typically also:

- Limit the risk of bacteria and contamination of tap water
- Lower the risk of road breaks and costly pipe repair
- Extend your network's service life
- Reduce water consumption
- Postpone investment in plant
 upgrades
- Reduce risk of water hammer



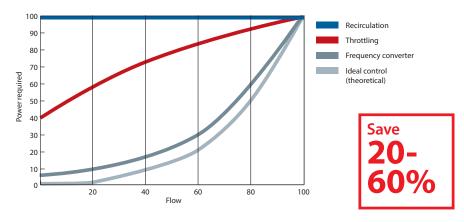
Try it yourself

By using the VLT[®] Energy Box software you can easily get a complete financial analysis for pumps including payback time – download it here:

www.danfoss.com/ vltenergybox

Control your centrifugal pump or blower with VLT® AQUA Drive

In a system using centrifugal or rotodynamic pumps or blowers and predominated with friction loss, major energy savings can be obtained by using VLT® AQUA Drives. Just 20% reduction in pump speed/flowrate can offer up to 50% energy reduction, for example.





Benefits of using VLT® AQUA Drive in wastewater treatment

Blowers or surface aerators typically consume 40-70% of the total energy used in wastewater treatment plants. Controlling the aeration equipment with VLT® AQUA Drives can deliver energy savings of up to 30-50%.

Beside these major benefits, a drive control of the aeration system will also offer:

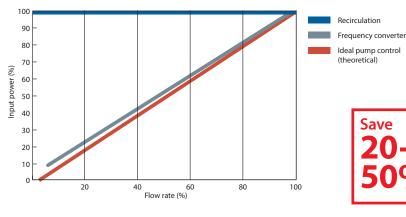
- · Correct DO level, independent of load variations, reducing the risk that outlet values are outside permission level
- Regulation of nitrification capacity, as a function of temperature and load variations and limit energy and carbon use (giving more carbon for electricity production)
- Secure effective de-nitrification process by avoiding excessive DO
- Reduced wear on aeration equipment

Control your positive displacement blower or pump with VLT® AQUA Drive

In a system using positive displacement blowers or pumps, high energy savings can be obtained by using VLT® AQUA

Drives. 30% reduction in speed will offer 30% energy savings (assuming constant pressure).

Save



Go to www.danfoss.com for case stories.





Maximum flexibility with VLT® Cascade Controller – customised for up to 3, 6 or 8 pumps

The controller provides accurate flow, pressure, and level control that make your multiple pump systems work in an optimised efficient way.

The VLT[®] drives have a basic cascade function embedded in the drive itself that controls up to three pumps.



Cascade control of more than three pumps requires the Multi-function Cascade Controller option.

The VLT[®] Cascade Controller controls speed and sequence of up to eight pumps or blowers in three modes.

Standard cascade mode

 Variable speed of one motor and on/ off control of the remainder

Mixed pump mode

- Variable speed of a few pumps and on/off control of the remainder
- Support of unequal size pumps.

Master/Follower mode

- Controls all pumps with optimised speed. This mode is the most energy optimised solution.
- Ensures maximum performance with minimum pressure surges.

In all three modes, pumps are staged on or off depending on the need.

Run-time balancing

The cascade controller can be used to balance the run-time for each pump in a system.



Cascade Controller or for Mixed pump applications -or for Master follower applications

Easy commissioning and service

The VLT® Cascade Controller can be commissioned from the drive display or using MCT10 PC software in its freeof-charge download version. The MCT 10 configuration tool makes setup of the cascade controller parameters very easy.

The pump status can be followed in the drive display during operation and the run-time of each pump together with the number of starts are logged. System performance is easily tracked.

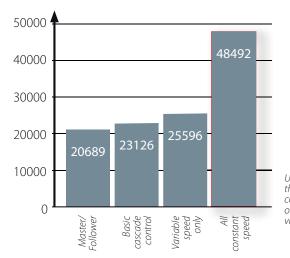
Built-in

The Multi-function Cascade Controller option is mounted directly within the drive and includes a host of pump control features. This often eliminates the need for PLC's and other external control equipment.

Easy upgrade

With the VLT[®] plug and play flexibility in adding option cards in the drive, it is very easy to expand the Basic Cascade Controller. Minimum time and no extra space is required.

Energy consumption [kWh]



Using Master/Follower mode can reduce the energy consumption to less than half compared to traditional across the line on/off cycling of pumps/blowers and valve throttling.

Built for: Water distribution and booster pumps Wastewater Lift stations (normal or inverse)

Aeration blowers Irrigation pumps

Who benefits?

- Pump and blower OEMs with multiple pump/blower systems
- System integrators/installers booster set manufacturers
- pump skid manufacturers Anyone interested in a high level of process control and energy conservation in multipump or blower systems

Same hardware up to 2 MW

The same cascade controller hardware is common to the entire power range up to 2 MW.

Lead pump alternation is possible with all VLT® Cascade Controllers, even the built-in Basic Cascade Controller.

The feature ensures that up to eight pumps or blowers are used equally and ensures that pumps will not run for extended periods.

Alternation can be programmed to take place on digital input, when in sleep mode, when a pump is destaged, or at preset times.

Pump Interlocking

In case a pump or blower is out of order or being serviced the VLT[®] Cascade Controller can be set – manually or by digital input - in "Pump Interlocking".

The cascade controller will then skIPthe specific pump or blower in its staging sequences.

Free choice of motor technology Easy commissioning and algorithms for optimal efficiency

As an independent manufacturer of drive solutions, Danfoss is committed to supporting all commonly used motor types and fostering ongoing development.

Danfoss frequency converters have traditionally offered control algorithms for high efficiency with standard induction motors and permanent magnet (PM) motors, and now they also support synchronous reluctance motors. In this way Danfoss offers you to combine your favorite motor technology like asynchronous-, permanent magnet- or synchronous reluctance motors with a VLT® AQUA Drive.

Furthermore, the VLT® AQUA Drive makes commissioning just as easy as with standard induction motors by combining ease of use with additional helpful functions such as SmartStart and automatic motor adaptation, which measures the motor characteristics and optimises the motor parameters accordingly. This way the motor always operates at the highest possible efficiency, allowing users to reduce energy consumption and cut costs.



The most comprehensive programme to cover all your applications

With the introduction of the new generation VLT® AQUA Drive, you now get the most comprehensive dedicated AQUA programme in the market. Now you can cover all your applications with the same product series and user interface, whether you need a 0.25 kW or 2 MW drive, IP00 or IP66 protection, different overload ratings, AC, PM or synchronous reluctance motor controls – or any of our dedicated water features.



A world of experience with a focus on water

The new generation VLT[®] AQUA Drive represents the best combination of know how and experience – based on in depth understanding of the changing nature of the water and wastewater industries. No matter where in the world, or what your water project, AQUA Drives are there for you.



Water supply, Wertheim, Germany Raw water from deep wells is treated in a three stage process. VLT® AQUA Drives make it possible to balance these three processes to maximise treatment performance.



Wastewater treatment, Hanoi, Vietnam The wastewater treatment plant, Yen So Park, treats 50% of Hanoi's wastewater. More than 90 VSDs are installed, of which 12 450 kW VLT® AQUA Drives control the blowers.



Sincrondraiv srl, Romania 10 high power VLT® AQUA Drives secure optimal energy and water control in major irrigation facility in Romania.

Control motors down to 0.25 kW without a step-down transformer on 690 V mains.

> 50°C ambient temperature without derating

Training based on experience

Keep up to date on trends, methods and features that save additional energy or offer new technical opportunities to increase your product quality or decrease the downtime of your plant.

Receive the same quality training anywhere in the world with Danfossdeveloped material and trainers. Training can take place at one of Danfoss' facilities or directly at the customer's own facility. Teaching is conducted by local trainers who have broad experience in the many conditions that may affect performance, so you get the most out of your Danfoss solution.

Additionally, the online platform Danfoss Learning offers you the opportunity to extend your knowledge in small and compact lessons up to extensive training courses, when and wherever you want.

Read more at learning.danfoss.com

Flexible, modular and adaptable Built to last

A VLT[®] AQUA Drive is built on a flexible, modular design concept to provide an extraordinarily versatile motor control solution. The drive is equipped with a wide range of features dedicated to the water/ wastewater business. Optimal process control, higher quality output and reduce costs related to spare parts and service, and much more can be achieved.

Up to 2 MW

Available in a performance range from 0.25 kW to 2 MW the VLT® AQUA Drive FC 202 series can control nearly all standard industrial motor technologies, including permanent magnet motors, synchronous reluctance motors, copper rotor motors and direct line PM.

The frequency converter is designed to work with all common supply voltage ranges: 200-240 V, 380-480 V, 525-600 V and 525-690 V This means that system designers, OEMs and end users are free to connect the drive to their chosen motor and remain confident that the system will perform to the highest possible standards.

690 V

The 690 V versions of VLT® AQUA Drive units can control motors down to 0.25 kW without stepdown transformer. This enables you to choose from a broad variety of compact, reliable and efficient drives for demanding applications operating from 690 V mains networks.

Reduce costs with compact drives

A compact design and efficient heat management enable the drives to take

up less space in control rooms and panels, thereby reducing initial costs. Compact dimensions are also an advantage in applications where drive space is restricted. This makes it possible for designers to develop smaller applications without being forced to compromise on protection and grid quality. For example, the D frame versions of the VLT[®] AQUA Drive FC 202 from 75-400 kW are 25-68% smaller than equivalent drives.

Especially impressive are the 690 V versions, which are among the smallest in its power class on the market today, and are available in an IP54 enclosure.

Despite the compact dimensions, all units are nevertheless equipped with integrated DC link chokes and EMC filters, which help to reduce grid pollution and reduce cost and efforts for external EMC-components and wiring.

The IP20 version is optimized for cabinet mounting and features covered power terminals to prevent accidental contact. The unit can also be ordered with optional fuses or circuit breakers in the same package size. Control and power cables are fed in separately at the bottom.

The frequency converters combine a flexible system architecture, which allows them to be adapted to specific applications, with a uniform user interface across all power classes. This allows you to adapt the drive to the exact needs of your specific application. As a result project work and costs are subsequently reduced. The easy to use interface reduces training requirements. The integrated SmartStart guides users quickly and efficiently through the setup process, which results in fewer faults due to configuration.



VLT[®] platform highlights

- Versatile, flexible, configurable
- Up to 2 MW in common voltages
- Asynchronous, Synchronous Reluctance and PM motor control
- 7 fieldbuses supported
- Unique user interface
- Globally supported
- EMC filters integrated as standard

Configure for cost savings via intelligent heat management, compactness and protection

All Danfoss VLT[®] frequency converters follow the same design principle for fast, flexible and fault-free installation and efficient cooling.

VLT® AQUA Drives are available in a broad range of enclosures sizes and protection ratings from IP00 to IP66 to enable easy installation in all environments: mounted in panels, switch rooms or as stand-alone units in the production area.

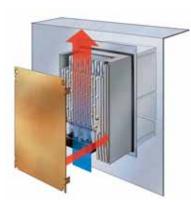
Cost saving heat management

In VLT® AQUA Drives there is total separation between cooling air and the internal electronics. It protects electronics from contaminants. At the

same time it removes heat efficiently which helps to prolong product life, increase the overall availability of the system and reduce faults related to high temperatures.

For example, by exhausting heat directly outside it is possible to reduce the size of the cooling system in the panel or switch room. This can be achieved with Danfoss' panel through cooling system or the extremely efficient back channel cooling concept, that also allows to conduct the heat into the outside of the control room. Both methods make it possible to reduce the initial cost of the panel or switch room.

In daily use the benefits are equally clear as the energy consumption related to cooling can be reduced significantly. This means that designers can reduce the size of the air conditioning system, or even eliminate it entirely.



Panel through cooling

An accessory mounting kit for small and mid -range drives enables heat losses to be directed directly outside the panel room.



Back-channel cooling

By directing air through a rear cooling channel up to 85-90% of the drive's heat loss is removed directly outside the installation room.



No air over electronics Complete separation between cooling air and the internal electronics ensures efficient cooling. VLT[®] AQUA Drives are available in IP20 enclosures optimized for installation in panels. For use in harsh environments choose IP55 or IP66 enclosures.

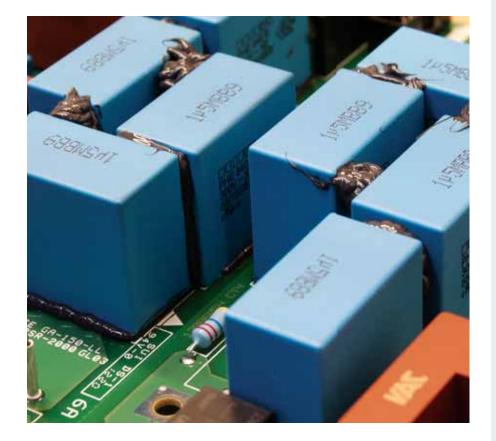
Coated circuit boards

The VLT® AQUA Drive is as standard conforming to class 3C2 (IEC 60721-3-3). If used in especially harsh conditions it is possible to order a special coating that complies with class 3C3.

From 90 kW the VLT® AQUA Drive comes as standard with 3C3 PCB coating to ensure long lifetime even in harsh wastewater environments.

Ruggedized for extra protection

The VLT® AQUA Drive is available in a 'ruggedized' version, that ensures that components remain firmly in place in environments characterized by high degrees of vibration such as Marine and mobile equipment.





Retrofitting. Fast upgrade to newest technology platform

As technologies evolve and newer, smaller and more efficient models replace old drives, it is important to Danfoss that you can change and upgrade as easily as possible. Minimize downtime in your production and update your installation in a few minutes with prepared tools from Danfoss. With a Danfoss conversion kit it is easy and fast to prepare your application for the future:

- Mechanical adaptation
- Electric adaptation
- Parameter adaptation with VLT[®] Motion Control Tool MCT 10

Optimize performance and grid protection

Built-in protection as standard

The VLT® AQUA Drive FC 202 contains all modules necessary for compliance with EMC standards.

A built-in, scalable RFI filter minimizes electromagnetic interference and the integrated DC link chokes reduce the harmonic distortion in the mains network, in accordance with IEC 61000-3-2. Furthermore, they increase the lifetime of the DC link capacitors and therefore also the drive's overall efficiency.

The solutions save cabinet space, as they are integrated in the drive from the factory. Efficient EMC mitigation also enables the use of cables with smaller cross-sections, which again reduces installation costs.

Danfoss VLT® AQUA Drives are equipped with DC chokes that reduce mains interference to a THDi of

40%



Expand grid and motor protection with filter solutions

If needed, Danfoss' wide range of solutions for harmonic mitigation can provide additional protection, such as the

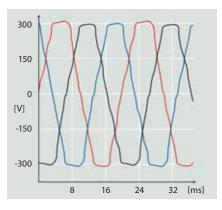
- VLT® Advanced Harmonic Filter AHF
- VLT® Advanced Active Filter AAF
- VLT[®] Low Harmonic Drives
- VLT[®] 12-pulse Drives

Provide motor protection with:

- VLT[®] Sine Wave Filter
- VLT[®] dU/dt Filter
- VLT[®] Common Mode Filters

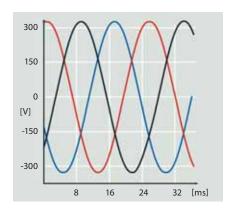
With this solutions you may achieve optimum performance for your application, even in weak or unstable grids. Use motor cables up to 300 m

The design of the VLT® AQUA Drive makes it a perfect choice in applications that require long motor cables. Without needing additional components the drive provides trouble free operation with cable lengths of up to 150 m screened or 300 m unscreened. This allows the drive to be installed in a central control room a distance away from the application without affecting motor performance.



Harmonic distortion

Electrical interference reduces efficiency and risks harming equipment.



Optimised Harmonic performance Efficient harmonic mitigation protects electronics and increases efficiency.

EMC Standards		Conducted emission		
Standards and requirements	EN 55011 Facility operators must comply with EN 55011	Class B Housing and light industries	Class A Group 1 Industrial environment	Class A Group 2 Industrial environment
	EN/IEC 61800-3 Converter manufacturers must conform to EN 61800-3	Category C1 First enviroment, home and office	Category C2 First enviroment, home and office	Category C3 Second enviroment
FC 202 compliance ¹⁾				

Porturner details see the VLI® AQUA Drive Design Guide © Compliance to mentioned EMC classes depends on the selected filter

Adverse effects of harmonics

- Limitations on supply and network utilization
- Increased transformer, motor and cable heating
- Reduced equipment lifetime
- Costly equipment downtime
- Control system malfunctions
- Pulsating and reduced motor torque
- Audible noise

For technical details and further information please see also VLT® High Power Drive Selection Guide.



Solutions for harmonics mitigation

The mains voltage supplied by electricity utilities to homes, businesses and industry should be a uniform sinusoidal voltage with a constant amplitude and frequency.

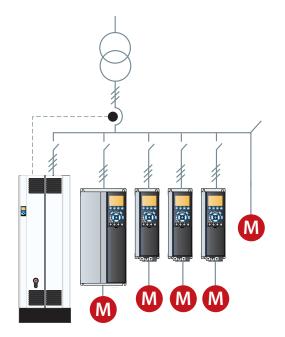
This ideal situation is no longer found in any power grid due to harmonics. This is mainly because consumers take non-sinusoidal current from the grid or have a nonlinear characteristic, e.g. strlPlights, light dampers, energysaving bulbs and frequency converters. Because of the constantly increasing use of non-linear loads, deviations become increasingly serious. Irregular power supplies influence the performance and operation of electrical equipment, so motors, frequency converters and transformers must be more highly rated to maintain proper operation.

VLT[®] Advanced Active Filter AAF 006

VLT® Advanced Active Filters identify harmonic distortion from non-linear loads and inject counter-phase harmonic and reactive currents into the AC line to cancel out the distortion, resulting in distortion levels of no more than 5% THvD. The optimal sinusoidal waveform of the AC power is restored and the power factor of the system is reestablished at 1.

Advanced Active Filters follow the same design principles as all our other drives. The modular platform provides high energy efficiency, user friendly operation, efficient cooling and high enclosure ratings.

VLT® Advanced Active Filter AAF 006 Voltage range: 380-480 V Corrective current range: 190-400 A



VLT[®] Advanced Harmonic Filter AHF 005/010

The Danfoss harmonic filters AHF 005/010 are specially designed to be connected in front of a VLT[®] frequency converter, and ensure that the harmonic current distortion generated back to the mains is reduced to a minimum.

One filter can be used for several frequency converters, helping owners reduce system costs. Easy commissioning saves installation costs, and due to the filter's maintenance free design running expenses for the units are eliminated.

VLT® Advanced Harmonic Filter AHF 005 (5% THDi) VLT® Advanced Harmonic Filter AHF 010 (10% THDi) Voltage range: 380-690 V Filter current range: 10-480 A

VLT[®] Low Harmonic Drive

The VLT® Low Harmonic Drive continuously regulates the network and load conditions without affecting the connected motor.

The drive combines the well-known performance and reliability of standard VLT[®] drives with a VLT[®] Advanced Active Filter. The result is a powerful, motor friendly solution that provides the highest possible harmonic mitigation with THDi (total harmonic current distortion) of maximum 5%.

VLT[®] Low Harmonic Drive Voltage range: 380-480 V Power range: 160-710 kW

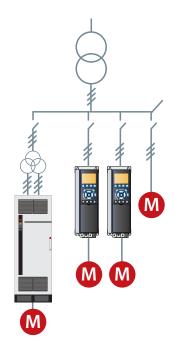
VLT[®] 12-Pulse Drive

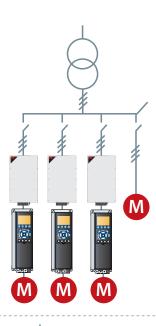
Robust and cost effective harmonic solution for the higher power range. The VLT[®] 12-pulse drive offers reduced harmonics for demanding industry applications above 315 kW.

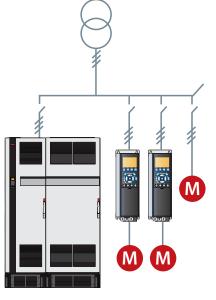
The VLT® 12-pulse is a high efficiency variable frequency converter which isbuilt with the same modular design as the popular 6-pulse VLT® drives. It is offered with similar drive options and accessories and can be configured according to customer need.

The VLT® 12-pulse drive provides harmonic reduction without adding capacitive or inductive components which often require network analysis to avoid potential system resonance problems.

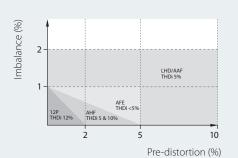
VLT® 12-Pulse Drive Voltage range: 380-480 V Power range 315 kW – 1.0 MW







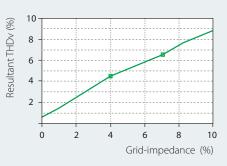
Cost effective mitigation

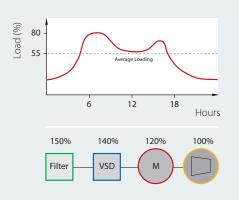


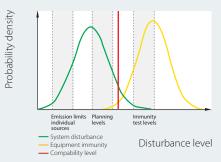
Imbalance and pre-distortion

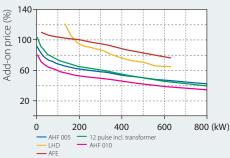
The harmonic mitigation performance of the different solutions depends on the grid quality.

The higher the imbalance and pre-distortion, the more harmonic the equipment has to suppress. The graph shows at what pre-distortion and imbalance level each technology can keep its guaranteed THDi performance.









Over-sizing

Published filter data are all given at 100% loading but filters are seldom run at full load due to over-sizing and load profile.

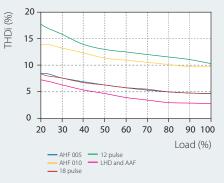
Serial mitigation equipment must always be sized for the maximum current, but be aware of the duration of part load operation and evaluate the different filter types accordingly. Oversizing gives poor mitigation performance and high running costs. It is also a waste of money.

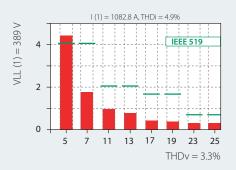
Standards compliance

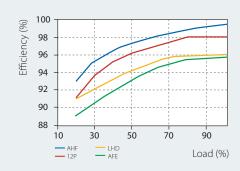
Keeping equipment immunity higher than system distortion ensures trouble free operation.

Most standards set restrictions on total voltage distortion according to a planned level, often between 5% and 8%.

Equipment immunity is, in most cases, far higher: for drives, between 15-20%. However, this influences product life adversely.







Power size vs. initial costs

Compared to the frequency converter, the different solutions have different add-on prices depending on power size. The passive solutions in general offer the lowest initial cost and as the complexity of the solutions increase, so does the price.

System impedance

As an example, a 400 kW FC 202 drive on a 1000 kVA transformer with 5% impedance results in ~5% THDv (total harmonic voltage distortion) at ideal grid conditions, whereas the same drive on a 1000 kVA, 8% imp. transformer leads to 50% higher THDv, namely 7.5%.



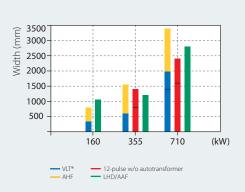
Total Harmonic distortion

Each drive generates its own total harmonic current distortion (THDi) which depends on the grid conditions. The bigger the drive is in relation to the transformer the smaller the THDi.

Harmonic performance

Each harmonic mitigation technology has its own THDi characteristic which is load dependent.

These characteristics are set at ideal grid conditions without pre-distortion and with balanced phases. Variations hereof will result in higher THDi values.



Wall space

In many applications the amount of available wall space is limited and must be utilized to the greatest extent possible. Based on different technologies, the various harmonic solutions each have their optimum size and power relationship.

Fulfilling the standards

To determine whether or not the harmonic pollution of a given application/grid exceeds a specific standard, many complex calculations must be done. With the help from free Danfoss MCT31 harmonic calculation software, this is made easy and less time consuming.

System efficiency

The running cost is mainly determined by the overall system efficiency. This depends on the individual products, true power-factors and efficiencies. Active solutions tend to keep the true power-factor independent of load and grid variations. On the other hand, active solutions are less efficient than passive solutions.



Support common fieldbusses

Increase productivity

With the wide range of fieldbus options the VLT® AQUA Drive can be easily connected to the fieldbus system of your choice. This makes the AQUA Drive a future-ready solution that can easily be expanded and updated if your needs change. See the complete list of fieldbuses on

page 39.

Danfoss fieldbus options can also be installed as a plug-and-play solution at a later stage, if the production layout demands a new communication platform. This way, you can be confident that you can optimize your plant without being forced to replace your existing drive system.

Download drivers for easy PLC integration

Integrating a drive into an existing bus system can be time consuming and complicated. To make this process easy and more efficient, Danfoss provides all necessary fieldbus drivers and instructions, which can be downloaded for free from the Danfoss website.

After installation the bus parameters, typically only a few, can be set directly in the VLT[®] drive via the local control panel, the VLT[®] MCT 10 or the fieldbus itself.















Energy documentation

VLT[®] Energy Box software is the most modern and advanced energy calculation tool available.

It allows energy consumption calculations and comparisons of AQUA pumps applications driven by Danfoss drives and alternative methods of flow control.

The program compares the total operational costs of various traditional systems to operation of the same systems with a VLT® AQUA Drive.

With this program it is easy to evaluate the savings by comparing a VLT® AQUA Drive over other types of capacity control systems in both new installations as well as retrofit situations.

Complete financial analysis

VLT[®] Energy Box provides a complete financial analysis including:

- Initial cost for the drive system and the alternative system
- Installation and hardware costs
- Annual maintenance costs and any utility company incentives for energy conservation products
- Payback time and accumulated savings
- Upload of actual energy consumption (kWh) and duty cycle from the VLT[®] AQUA Drive

VLT[®] Energy Box makes it possible to capture actual energy data from the drives and monitor energy consumption and overall system efficiency.

Energy audit

The VLT® AQUA Drive coupled with Energy Box software enables the package to be used as the Energy Audit equipment for both the estimation and validation of savings. VLT® AQUA Drive can be interrogated remotely for full energy data, making it easy to monitor your energy savings and return on investment. Monitoring via fieldbus often makes energy meters omissible.



Software tools

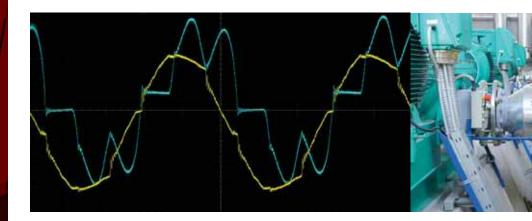
Easy engineering and setup with VLT® Motion Control Tool MCT 10

In addition to operating the drive via LCP (local control panel), VLT[®] drives can also be configured and monitored with Danfoss own PC software. This provides plant managers with a comprehensive overview of the system at any point in time, adding a new level of flexibility in configuration, monitoring and troubleshooting.

MCT 10 is a windows based engineering tool with a clearly structured interface that provides an instant overview of all the drives in a system of any size. The software runs under Windows and enables data exchange over a traditional RS485 interface, fieldbus (Profibus, Ethernet, etc.) or via USB. Parameter configuration is possible both online on a connected drive and offline in the tool itself. Additional documentation, such as electrical diagrams or operating manuals, can be embedded in MCT 10. This reduces the risk of incorrect configuration while offering fast access to troubleshooting.

Analyse harmonic distortion with VLT[®] Harmonic Calculation Software HCS

This is an advanced simulation program that makes calculating harmonic distortion in your mains network fast and easy. It is the ideal solution both if you are planning to extend your existing plant or installation or if you are planning a new installation from scratch.





The user-friendly interface allows you to configure the mains environment as desired and returns simulation results, which you can use to optimize your network.

Contact your local Danfoss sales office or visit our website for more information or visit directly at www.danfoss-hcs.com

VLT[®] Motion Control Tool MCT 31 Harmonics Calculation Software

VLT® MCT 31 calculates system harmonic distortion for both Danfoss and non-Danfoss drives. It is also able to calculate the effects of using various additional harmonic reduction measures, including Danfoss harmonic filters. With VLT[®] Motion Control Tool MCT 31, you can determine whether harmonics will be an issue in your installation, and if so, what strategies will be most cost-effective in addressing the problem.

VLT[®] Motion Control Tool MCT 31 features include:

- Short circuit current ratings can be used instead of transformer size and impedance when transformer data is unknown
- Project oriented for simplified calculations on several transformers
- Easy to compare different harmonic solutions within the same project
- Supports current Danfoss product line as well as legacy drive models



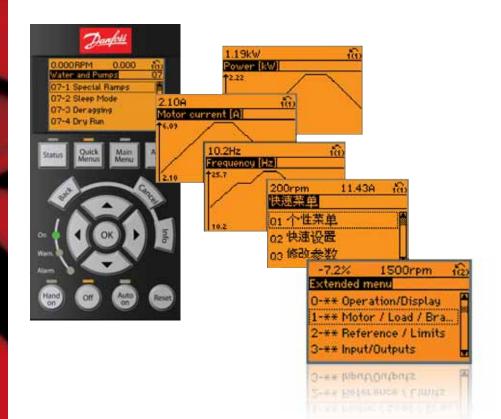
Intuitive setup with graphical interface

The VLT® AQUA Drive features a user-friendly, hot pluggable local control panel (LCP) for easy setup and parameter configuration.

After choosing language navigate through setup parameters individually. Alternatively, use a pre-defined quick menu or a SmartStart guide for application specific setup.

The LCP can be detached and used to copy settings to other AQUA Drives in the system. It can also be mounted remotely on a control panel fascia. This enables the user to take full advantage of the LCP, eliminating the need for additional switches and instrumentation.

My Personal Menu allows direct access to up to 50 user-selectable parameters.



Save commissioning time with SmartStart

SmartStart is a setup wizard that is activated at the first power up of the drive, or after a factory reset. Using easy to understand language, SmartStart guides users through a series of easy steps to ensure correct and efficient motor control. The wizard can also be started directly via the Quick Menu on the graphical control panel.

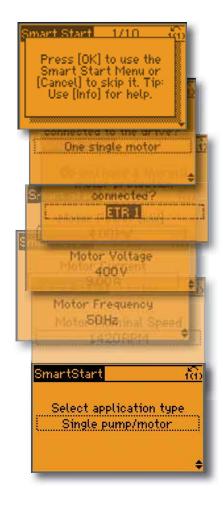
First, users are asked to set which type of motor setup is used in the application:

- Single pump/motor in open or closed loop
- Motor alternation: when two motors share one drive
- **Basic cascade control:** speed control a single pump in a multi pump system. This is a cost attractive solution in for example booster sets
- **Master-follower:** Control up to 8 drives and pumps to ensure smooth operation of the overall pump system
- Automatic Motor Adaptation: SmartStart also guarantees an optimised motor performance due to the adjustment of efficient settings regardless of the motor type. After entering the basic motor data,

the Automatic Motor Adaptation function measures the motor parameters and optimises the drive settings at standstill without the need to disconnect the load.

The guide then continues to dedicated water and pump features:

- Flow compensation: the drive adapts the set point according to the flow
- **Deragging:** removes clogs from impellers by reversing the direction of the flow in cycles. This can be used as proactive measure to avoid damaging the pump
- **Pipe fill:** helps to avoid water hammering by filling pipes smoothly
- Dry run/end of curve detection: protects the pump from damage. If a set point is not reached, the drive assumes that the pipe is dry or there is a leakage
- **Sleep mode:** saves energy by stopping the pump when there is no demand
- **Special ramps:** dedicated startup and stop ramps for specific applications







Dedicated water and pump features

Dedicated, integrated features that save energy and increase efficiency in all water and pump applications.

Embedded multi-pump controller

The Pump Cascade Controller distributes operation hours evenly across all pumps. Wear and tear on individual pumps is therefore reduced to a minimum, extending their lifetime expectancy and reliability considerably.

High overload capability

For high inertia or high friction loads, extra torque is available for undersized motors. The current can be set to a maximum of up to 160% for a limited amount of time.

1. End of curve detection

This feature is triggered if the pump runs without reaching a predefined set point. The drive then either sets off an alarm or performs another preprogrammed action. This happens for example when a pipe leaks.

2. Auto tuning of the 4 PI controllers

Auto tuning enables the drive to learn how the system reacts to corrections made by the drive. Using what it has measured, the drive calculates the P and I values to restore precise and stable operation.

3. Flow compensation

A pressure sensor mounted close to the fan or pump provides a reference point that enables pressure to be kept constant at the discharge end of the system. The drive constantly adjusts the pressure reference to follow the system curve. This method both saves energy and reduces installation costs.

4. No/low flow detection and sleep mode

In situations with low or no flow, the drive enters sleep mode to conserve energy. When the pressure falls below the predefined set-point, the drive starts automatically. Compared to continuous operation this method reduces energy costs and equipment wear and helps extend the lifetime of the application.

5. Deragging feature

This VLT® AQUA Drive software feature offers proactive pump protection. The deragging can be configured as either a preventative or reactive action. It optimises the efficiency of the pump by constantly monitoring the motor shaft power consumption relative to flow. In the reactive mode, the drive senses the beginning of a pump clog and will reverse spin the pump to ensure a clear path for the water. As a preventative action, the drive will periodically reverse the pump to ensure a clean pump, or screen.

6. Pipe fill mode

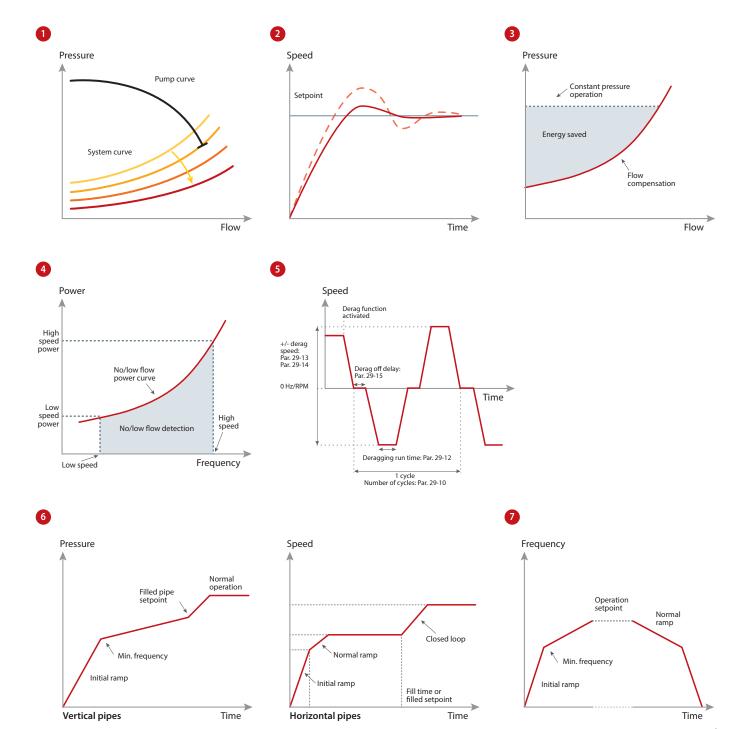
Useful in all applications where controlled pipe filling is essential, such as irrigation and water supply systems. Contolled (closed loop) filling of pipes prevents water hammering, bursting water pipes or blowing off sprinkler heads. Pipe fill mode can be used in both vertical and horizontal pipe systems.

7. Initial/final ramp

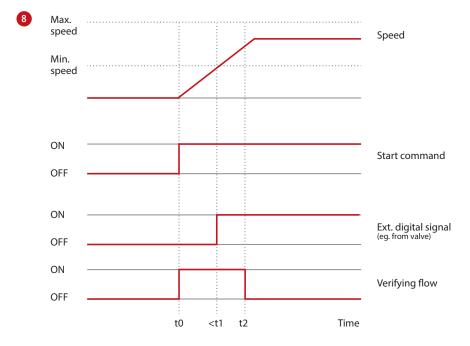
The initial ramp provides fast acceleration of pumps to minimum speed, from where the normal ramp takes over. This prevents damage to the thrust bearings on the pump. The final ramp decelerates pumps from the minimum speed to stop.

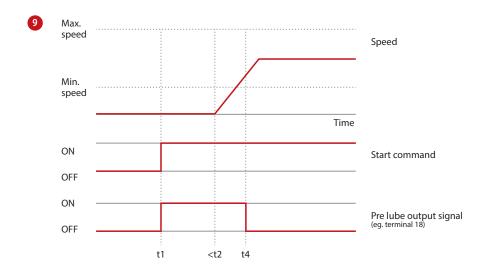
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8. Flow confirmation

The flow confirmation monitor protects equipment from unexpected flow stoppage. The monitor communicates on an ongoing basis with an external device such as a valve or flow switch. If the signal from the external device times out, the monitor trips the frequency converter.

9. Pre/post lubrication

Some machines require lubrication of their mechanical parts before and during operation to prevent damage and reduce wear. During lubrication certain equipment must remain active, for example exhaust fans. To achieve this, the Pre Lube feature supports a signal to an external device to perform a specific action for a user-defined time period. Configurations available: "Pre Lube Only", "Pre & Running" and "Pre & Running & Post".

10. Freely programmable texts

This function supports versatile adaptation to the application. Use freely programmable text messages, based on internal or external events, for information, warnings or alerts. The function also supports actions based on events, for example initiation of a ramp down triggered by a valve opening.



11. Advanced minimum speed monitor

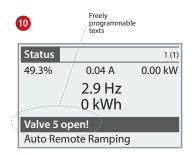
Submersible pumps can suffer from insufficient cooling and lubrication when pump speed is too low. The advanced minimum speed monitor protects the pump by monitoring and adjusting the trlPspeed to reduce wear and tear. Downtime for maintenance is minimised, with no need for external monitoring equipment.

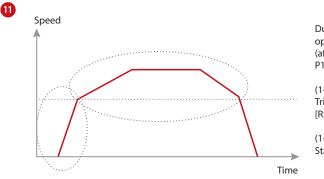
12. High/normal overload

Use the overload rating functionality to adapt to different patterns of loading typical for water and wastewater applications. Normal overload is suitable for most centrifugal loads. Use high overload for loading involving periods of temporarily higher torque.

13. Check valve ramp

The check valve ramp prevents water hammering when stopping the pump, by ensuring slow pump speed ramp down just as the check valve ball is almost shut.

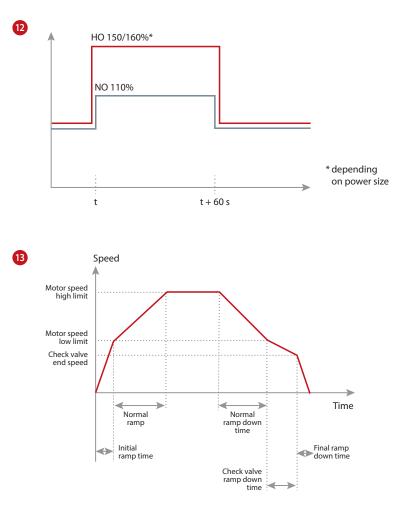


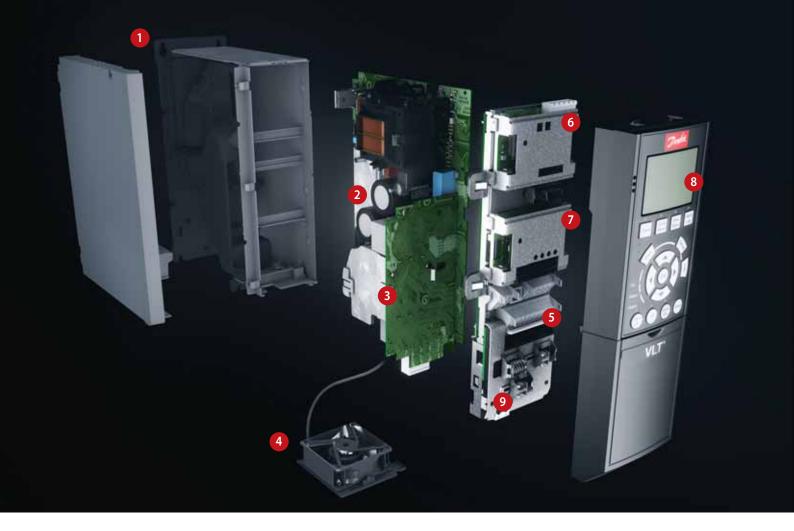


During normal operation (after ramping up) P1-86/1-87

(1-86/1-87) Trip speed low [RPM, Hz]

(1-79) Start max. time to trip





Modular simplicity

Delivered fully assembled and tested to meet your specific requirements

1. Enclosure

The drive meets requirements for enclosure class IP20/Chassis. IP21/ Type 1, IP54/Type 12, IP55/Type 12 or IP66/Type 4X.

2. EMC and Network effects

All versions of VLT® AQUA Drive comply as standard with EMC limits B, A1 or A2 according to the EN 55011 norm. The standard integrated DC coils ensure low harmonic load on the network according to EN 61000-3-12 and increase the lifetime of the DC link capacitors.

3. Protective coating

The electronic components are, as standard, coated as per IEC 60721-3-3, class 3C2. For harsh and aggressive environments, coating as per IEC 60721-3-3, class 3C3 is available.

4. Removable fan

Like most of the elements, the fan can be quickly removed and remounted for easy cleaning.

5. Control terminals

Double-stack, spring-loaded cage clamps enhance reliability and facilitate easy commissioning and service.

6. Fieldbus option

See complete list of available fieldbus options on page 39.

7. Cascade controller and I/O extensions

Controls multiple pumps. See also pages 12 and 13.

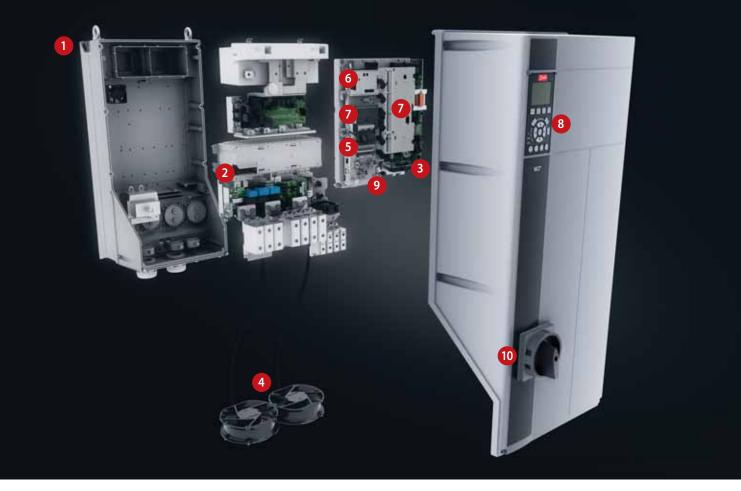
A wide range of I/O options are available either factory-mounted or as retrofit.

8. Display option

Danfoss Drives' removable Local Control Panel is available with a variety of language packs.

English is available in all drives.

Alternatively the drive can be commissioned via the built-in USB/ RS485 connection or a fieldbus from with VLT® Motion Control Tool MCT 10 setup software.



9. 24 V external power supply

The external 24 V supply keeps the VLT® AQUA Drive logic "alive" when the AC mains is removed.

10. Mains disconnect

This switch interrupts the mains supply and has a free useable auxiliary contact.

Safety

The VLT® AQUA Drive can optionally be delivered with the Safe Torque Off (Safe Stop) functionality suitable for category 3, performance level d according to EN 13849-1 and SIL 2 according to IEC 62061/IEC 61508. This feature prevents the drive from starting unintended.

Built-in Smart Logic Controller

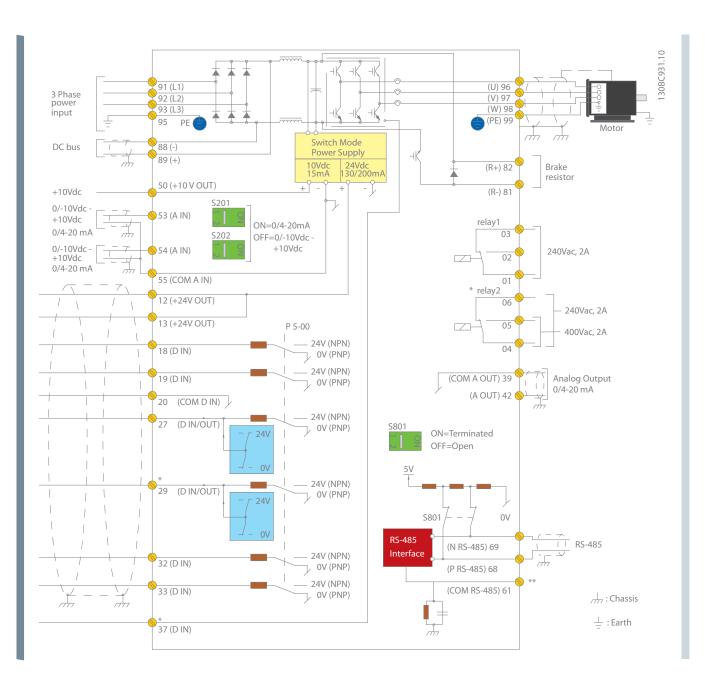
The Smart Logic Controller is a clever way to add customerspecific functionality to the drive and increase the opportunities for the drive, motor and application working together.

The controller monitors a specified event. When an event occurs, the controller performs a pre-defined action and then starts monitoring for the next pre-defined event. 20 steps of events and resulting actions are available before returning to the first set. Logic functions can be selected and run independent from the sequence control. This enables drives to monitor variables or signal defined events in an easy and flexible way independently of the motor control.



Connection example

The numbers represent the terminals on the drive



This diagram shows a typical installation of the VLT[®] AQUA Drive. Power is connected to the terminals 91 (L1), 92 (L2) and 93 (L3) and the motor is connected to 96 (U), 97 (V) and 98 (W).

Terminals 88 and 89 are used for load sharing between drives. Analogue inputs can be connected to the 53 (V or mA), and for 54 (V or mA) terminals. These inputs can be set up as either reference, feedback or thermistor inputs.

There are 6 digital inputs to be connected to terminals 18, 19, 27, 29, 32, and 33. Two digital input/output terminals (27 and 29) can be set up as digital outputs to show an actual status or warning or can be used as pulse reference signal. The terminal 42 analogue output can show process values such as 0 - I^{max}.

On the 68 (P+) and 69 (N-) terminals' RS 485 interface, the drive can be controlled and monitored via serial communication.

VLT® AQUA Drive technical data

Basic unit without extensions

Main supply (L1, L2, L3)	
	1 x 200 – 240 V AC 1.1 – 22 kW
	1 x 380 – 480 V AC 7.5 – 37 kW
Supply voltage	3 x 200 – 240 V AC 0.25 – 45 kW 3 x 380 – 480 V AC0.37 – 1000 kW
	3 x 525 – 600 V AC 0.75 – 90 kW
	3 x 525 – 690 V AC 11 – 1400 kW*
Supply frequency	50/60 Hz
Displacement power factor	> 0.98
(cos φ) near unity True power factor (λ)	≥ 0.9
Switching on input supply	
L1, L2, L3	1–2 times/min.
Harmonic disturbance	Meets EN 61000-3-12
* Up to 2000 kW available on reque	st
Output data (U, V, W)	
Output voltage	0 – 100% of supply voltage
Output frequency (dependent on power size)	0-590 Hz
Switching on output	Unlimited
Ramp times	0.1 – 3600 sec.
	110%, 150% or 160% current for 1 minute,
achieved by oversizing the drive.	meter settings. Higher overload rating is
Digital inputs	
Programmable digital inputs	6*
Changeable to digital output	2 (terminal 27, 29)
Logic	PNP or NPN
Voltage level	0 – 24 V DC
Maximum voltage on input	28 V DC
Input resistance, Ri	Approx. 4 kΩ
Input resistance, Ri Scan interval	Approx. 4 kΩ 5 ms
Input resistance, Ri Scan interval * Two of the inputs can be used as c	Approx. 4 kΩ 5 ms
Input resistance, Ri Scan interval *Two of the inputs can be used as c Analog inputs	Approx. 4 kΩ 5 ms ligital outputs.
Input resistance, Ri Scan interval * <i>Two of the inputs can be used as c</i> Analog inputs Analogue inputs	Approx. 4 kΩ 5 ms ligital outputs. 2
Input resistance, Ri Scan interval * Two of the inputs can be used as c Analog inputs Analogue inputs Modes	Approx. 4 kΩ 5 ms ligital outputs. 2 Voltage or current
Input resistance, Ri Scan interval * Two of the inputs can be used as a Analog inputs Analogue inputs Modes Voltage level	Approx. 4 kΩ 5 ms ligital outputs. 2 Voltage or current 0 to +10 V (scaleable)
Input resistance, Ri Scan interval * Two of the inputs can be used as of Analog inputs Analogue inputs Modes Voltage level Current level	Approx. 4 kΩ 5 ms ligital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable)
Input resistance, Ri Scan interval * Two of the inputs can be used as a Analog inputs Analogue inputs Modes Voltage level	Approx. 4 kΩ 5 ms ligital outputs. 2 Voltage or current 0 to +10 V (scaleable)
Input resistance, Ri Scan interval * Two of the inputs can be used as a Analog inputs Analogue inputs Modes Voltage level Current level Accuracy of analog inputs	Approx. 4 kΩ 5 ms ligital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable)
Input resistance, Ri Scan interval * Two of the inputs can be used as a Analog inputs Analogue inputs Modes Voltage level Current level Accuracy of analog inputs Pulse inputs	Approx. 4 kΩ 5 ms ligital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable) Max. error: 0.5% of full scale
Input resistance, Ri Scan interval * Two of the inputs can be used as of Analog inputs Analogue inputs Modes Voltage level Current level Accuracy of analog inputs Pulse inputs Voltage level Pulse input accuracy	Approx. 4 kΩ 5 ms ligital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable) Max. error: 0.5% of full scale 2* 0 – 24 V DC (PNP positive logic)
Input resistance, Ri Scan interval * Two of the inputs can be used as of Analog inputs Analogue inputs Modes Voltage level Current level Accuracy of analog inputs Pulse inputs Programmable pulse inputs Voltage level Pulse input accuracy (0.1 – 1 kHz)	Approx. 4 kΩ 5 ms ligital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable) Max. error: 0.5% of full scale 2* 0 – 24 V DC (PNP positive logic) Max. error: 0.1% of full scale
Input resistance, Ri Scan interval * Two of the inputs can be used as a Analog inputs Analogue inputs Modes Voltage level Current level Accuracy of analog inputs Pulse inputs Programmable pulse inputs Voltage level Pulse input accuracy (0.1 – 1 kHz) * Two of the digital inputs can be use	Approx. 4 kΩ 5 ms ligital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable) Max. error: 0.5% of full scale 2* 0 – 24 V DC (PNP positive logic) Max. error: 0.1% of full scale
Input resistance, Ri Scan interval * Two of the inputs can be used as of Analog inputs Analogue inputs Modes Voltage level Current level Accuracy of analog inputs Pulse inputs Programmable pulse inputs Voltage level Pulse input accuracy (0.1 – 1 kHz) * Two of the digital inputs can be us Digital outputs	Approx. 4 kΩ 5 ms ligital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable) Max. error: 0.5% of full scale 2* 0 – 24 V DC (PNP positive logic) Max. error: 0.1% of full scale
Input resistance, Ri Scan interval * Two of the inputs can be used as of Analog inputs Analogue inputs Modes Voltage level Current level Accuracy of analog inputs Pulse inputs Programmable pulse inputs Voltage level Pulse input accuracy (0.1 – 1 kHz) * Two of the digital inputs can be us Digital outputs Programmable	Approx. 4 kΩ 5 ms ligital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable) Max. error: 0.5% of full scale 2* 0 – 24 V DC (PNP positive logic) Max. error: 0.1% of full scale
Input resistance, Ri Scan interval * Two of the inputs can be used as of Analog inputs Analogue inputs Modes Voltage level Current level Accuracy of analog inputs Pulse inputs Programmable pulse inputs Voltage level Pulse input accuracy (0.1 – 1 kHz) * Two of the digital inputs can be us Digital outputs Programmable digital/pulse outputs Voltage level at	Approx. 4 kΩ 5 ms iigital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable) 0/4 to 20 mA (scaleable) Max. error: 0.5% of full scale 2* 0 – 24 V DC (PNP positive logic) Max. error: 0.1% of full scale red for pulse inputs.
Input resistance, Ri Scan interval * Two of the inputs can be used as of Analog inputs Analogue inputs Modes Voltage level Current level Accuracy of analog inputs Pulse inputs Voltage level Pulse input accuracy (0.1 – 1 kHz) * Two of the digital inputs can be us Digital outputs Programmable digital/pulse outputs Voltage level at digital/pulse outputs	Approx. 4 kΩ 5 ms ligital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable) Max. error: 0.5% of full scale 2* 0 - 24 V DC (PNP positive logic) Max. error: 0.1% of full scale sed for pulse inputs.
Input resistance, Ri Scan interval * Two of the inputs can be used as of Analog inputs Analogue inputs Modes Voltage level Current level Accuracy of analog inputs Pulse inputs Voltage level Pulse input accuracy (0.1 – 1 kHz) * Two of the digital inputs can be us Digital outputs Programmable digital/pulse outputs Voltage level at digital/frequency output Max. output current (sink or source) Maximum output frequency	Approx. 4 kΩ 5 ms ligital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable) Max. error: 0.5% of full scale 2* 0 - 24 V DC (PNP positive logic) Max. error: 0.1% of full scale sed for pulse inputs. 2 0 - 24 V DC
Input resistance, Ri Scan interval * Two of the inputs can be used as of Analog inputs Analogue inputs Modes Voltage level Current level Accuracy of analog inputs Programmable pulse inputs Voltage level Pulse input accuracy (0.1 – 1 kHz) * Two of the digital inputs can be us Digital outputs Programmable digital/pulse outputs Voltage level at digital/pulse outputs Voltage level at digital/frequency output Max. output current (sink or source) Maximum output frequency at frequency output	Approx. 4 kΩ 5 ms ligital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable) Max. error: 0.5% of full scale 2* 0 - 24 V DC (PNP positive logic) Max. error: 0.1% of full scale 2 0 - 24 V DC (PNP positive logic) Max. error: 0.1% of full scale 2 0 - 24 V DC (PNP positive logic) Max. error: 0.1% of full scale
Input resistance, Ri Scan interval * Two of the inputs can be used as of Analog inputs Analogue inputs Modes Voltage level Current level Accuracy of analog inputs Programmable pulse inputs Voltage level Pulse input accuracy (0.1 – 1 kHz) * Two of the digital inputs can be us Digital outputs Programmable digital/pulse outputs Voltage level at digital/pulse outputs Voltage level at digital/frequency output Max. output current (sink or source) Maximum output frequency at frequency output	Approx. 4 kΩ 5 ms ligital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable) 0/4 to 20 mA (scaleable) Max. error: 0.5% of full scale 2* 0 – 24 V DC (PNP positive logic) Max. error: 0.1% of full scale 2 0 – 24 V DC 40 mA
Input resistance, Ri Scan interval * Two of the inputs can be used as of Analog inputs Analogue inputs Modes Voltage level Current level Accuracy of analog inputs Pulse inputs Programmable pulse inputs Voltage level Pulse input accuracy (0.1 – 1 kHz) * Two of the digital inputs can be us Digital outputs Programmable digital/pulse outputs Voltage level at digital/frequency output Max. output current (sink or source) Maximum output frequency at frequency output Accuracy on frequency output Analogue output	Approx. 4 kΩ 5 ms ligital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable) Max. error: 0.5% of full scale 2* 0 - 24 V DC (PNP positive logic) Max. error: 0.1% of full scale 2 0 - 24 V DC (PNP positive logic) Max. error: 0.1% of full scale 2 0 - 24 V DC (PNP positive logic) Max. error: 0.1% of full scale
Input resistance, Ri Scan interval * Two of the inputs can be used as of Analog inputs Analogue inputs Modes Voltage level Current level Accuracy of analog inputs Programmable pulse inputs Voltage level Pulse input accuracy (0.1 – 1 kHz) * Two of the digital inputs can be us Digital outputs Programmable digital/pulse outputs Voltage level at digital/frequency output Max. output current (sink or source) Maximum output frequency at frequency output Accuracy on frequency output Accuracy on frequency output Analogue outputs Current range at	Approx. 4 kΩ 5 ms iigital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable) Max. error: 0.5% of full scale 2* 0 – 24 V DC (PNP positive logic) Max. error: 0.1% of full scale 2 0 – 24 V DC 40 mA 0 to 32 kHz Max. error: 0.1% of full scale
Input resistance, Ri Scan interval * Two of the inputs can be used as of Analog inputs Analogue inputs Modes Voltage level Current level Accuracy of analog inputs Pulse inputs Voltage level Pulse input accuracy (0.1 – 1 kHz) * Two of the digital inputs can be us Digital outputs Programmable digital/pulse outputs Voltage level at digital/frequency output Max. output current (sink or source) Maximum output frequency at frequency output Accuracy on frequency output Accuracy on frequency output Analogue outputs Current range at analogue output Max. load to common at	Approx. 4 kΩ 5 ms iigital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable) Max. error: 0.5% of full scale 2* 0 - 24 V DC (PNP positive logic) Max. error: 0.1% of full scale 2 0 - 24 V DC 40 mA 0 to 32 kHz Max. error: 0.1% of full scale 1 0/4 - 20 mA
Input resistance, Ri Scan interval * Two of the inputs can be used as of Analog inputs Analogue inputs Modes Voltage level Current level Accuracy of analog inputs Pulse inputs Programmable pulse inputs Voltage level Pulse input accuracy (0.1 – 1 kHz) * Two of the digital inputs can be us Digital outputs Programmable digital/pulse outputs Voltage level at digital/frequency output Max. output current (sink or source) Maximum output frequency at frequency output Accuracy on frequency output Analogue outputs Current range at analogue output	Approx. 4 kΩ 5 ms iigital outputs. 2 Voltage or current 0 to +10 V (scaleable) 0/4 to 20 mA (scaleable) Max. error: 0.5% of full scale 2* 0 – 24 V DC (PNP positive logic) Max. error: 0.1% of full scale 2 0 – 24 V DC 40 mA 0 to 32 kHz Max. error: 0.1% of full scale



	2 - 100 M (2) - 11
USB interface	1.1 (Full Speed)
USB plug	Type "B"
RS485 interface	Up to 115 kBaud
Max. load (10 V)	15 mA
Max. load (24 V)	200 mA
Relay output	
Programmable relay outputs	2
Max. terminal load (AC) on 1-3 (break), 1-2 (make), 4-6 (break) power card	240 V AC, 2 A
Max. terminal load (AC) on 4-5 (make) power card	400 V AC, 2 A
Min. terminal load on 1-3 (break), 1-2 (make), 4-6 (break), 4-5 (make) power card	24 V DC 10 mA, 24 V AC 20 mA
Surroundings/external	
Enclosure	IP: 00/20/21/54/55/66 UL Type: Chassis/1/12/4x Outdoor
Vibration test	1.0 g (D, E & F-enclosures: 0.7 g)
Max. relative humidity	5% – 95% (IEC 721-3-3; Class 3K3 (non-condensing) during operation
Ambient temperature	Up to 55°C (50°C without derating; D- frame 45°C)
Galvanic isolation of all	I/O supplies according to PELV
Aggressive environment	Designed for coated/uncoated 3C3/3C (IEC 60721-3-3)
Fieldbus communication	
Standard built-in:	Optional:
FC Protocol Modbus RTU	VLT® PROFIBUS DP V1 MCA 101 VLT® DeviceNet MCA 104 VLT® PROFINET MCA 120 VLT® EtherNet/IPMCA 121 VLT® Modbus TCP MCA 122
Ambient temperature	
 Electronic thermal motor pro 	3
 Up to 55°C (50°C without der 	5.
converter trips in case of ove	1
 The frequency converter is p 	rotected against short-circuits on motor
terminals U, V, W	retected against earth faults on motor
	rotected against earth faults on motor
 The frequency converter is p terminals U, V, W Protection against mains pha 	-
 The frequency converter is p terminals U, V, W Protection against mains pha Application options 	ase loss
 The frequency converter is p terminals U, V, W Protection against mains pha Application options Extend the functionality of the VLT® General Purpose I/O MC VLT® Extended Cascade Cont VLT® Advanced Cascade Cont VLT® Sensor Input MCB 114 VLT® PTC Thermistor Card MC VLT® Extended Relay Card MC 	ase loss drive with integrated options: B 101 croller MCO 101 troller MCO 102 B 112 CB 113
 The frequency converter is p terminals U, V, W Protection against mains pha Application options Extend the functionality of the VLT® General Purpose I/O MC VLT® Extended Cascade Cont VLT® Advanced Cascade Cont VLT® Sensor Input MCB 114 VLT® PTC Thermistor Card MC VLT® Extended Relay Card MC VLT® 24 V External Supply MC 	ase loss e drive with integrated options: EB 101 croller MCO 101 troller MCO 102 CB 112 CB 113 EB 107
 The frequency converter is p terminals U, V, W Protection against mains phate Application options Extend the functionality of the VLT® General Purpose I/O MC VLT® Extended Cascade Cont VLT® Advanced Cascade Cont VLT® Sensor Input MCB 114 VLT® TC Thermistor Card MC VLT® Extended Relay Card MC VLT® 24 V External Supply MC Relay and analogue I/O optice 	ase loss e drive with integrated options: EB 101 croller MCO 101 troller MCO 102 CB 112 CB 113 EB 107
 The frequency converter is p terminals U, V, W Protection against mains phate the functionality of the VLT® General Purpose I/O MC VLT® Extended Cascade Cont VLT® Advanced Cascade Cont VLT® Sensor Input MCB 114 VLT® PTC Thermistor Card MC VLT® Extended Relay Card MC VLT® 24 V External Supply MC Relay and analogue I/O option VLT® Relay Card MCB 105 VLT® Analog I/O MCB109 	ase loss e drive with integrated options: EB 101 croller MCO 101 troller MCO 102 CB 112 CB 113 EB 107
 The frequency converter is p terminals U, V, W Protection against mains pha Application options Extend the functionality of the VLT® General Purpose I/O MC VLT® Extended Cascade Cont VLT® Advanced Cascade Cont VLT® Sensor Input MCB 114 VLT® PTC Thermistor Card MC VLT® Extended Relay Card MC VLT® 24 V External Supply MC Relay and analogue I/O optic VLT® Relay Card MCB 105 VLT® Analog I/O MCB109 Power options 	ase loss addive with integrated options: E 101 croller MCO 101 troller MCO 102 EB 112 CB 113 EB 107 con external power options for use with our polications: ter
 The frequency converter is p terminals U, V, W Protection against mains pha Application options Extend the functionality of the VLT® General Purpose I/O MC VLT® Extended Cascade Cont VLT® Sensor Input MCB 114 VLT® Sensor Input MCB 114 VLT® Extended Relay Card MC VLT® Extended Relay Card MC VLT® Extended Relay Card MC VLT® 24 V External Supply MC Relay and analogue I/O optic VLT® Relay Card MCB 105 VLT® Analog I/O MCB109) Power options Choose from a wide range of e drive in critical networks or appi VLT® Advanced Harmonic Filter VLT® Advanced Harmonic Filter VLT® Advanced Harmonic Filter VLT® Sine wave filter (LC filter High power options 	external power options for use with our polications:
 The frequency converter is p terminals U, V, W Protection against mains pha Application options Extend the functionality of the VLT® General Purpose I/O MC VLT® Extended Cascade Cont VLT® Advanced Cascade Cont VLT® Sensor Input MCB 114 VLT® PTC Thermistor Card MC VLT® Extended Relay Card MC VLT® Extended Relay Card MC VLT® textended Relay Card MC VLT® Relay Card MCB 105 VLT® Relay Card MCB 105 VLT® Relay Card MCB 105 VLT® Conse from a wide range of e drive in critical networks or app VLT® Advanced Harmonic Filter VLT® Advanced Harmonic Filter VLT® Advanced Harmonic Filter VLT® Sine wave filter (LC filter High power options 	ase loss addive with integrated options: E 101 croller MCO 101 troller MCO 102 EB 112 CB 113 EB 107 con external power options for use with our polications: ter
 The frequency converter is p terminals U, V, W Protection against mains pha Application options Extend the functionality of the VLT® General Purpose I/O MC VLT® Extended Cascade Cont VLT® Sensor Input MCB 114 VLT® Sensor Input MCB 114 VLT® Extended Relay Card MC VLT® Extended Relay Card MC VLT® Extended Relay Card MC VLT® 24 V External Supply MC Relay and analogue I/O optic VLT® Relay Card MCB 105 VLT® Analog I/O MCB109) Power options Choose from a wide range of e drive in critical networks or appi VLT® Advanced Harmonic Filter VLT® Advanced Harmonic Filter VLT® Advanced Harmonic Filter VLT® Sine wave filter (LC filter High power options 	external power options for use with our oblications: ter external power options for use with our oblications: ter) Selection Guide for a complete list.

Electrical data

VLT[®] AQUA Drive 1 x 200-240 V AC

		P20/Chassis	A3								
Enclosure		IP21/Type 1				B1			B2	C1	C2
	IP55/Type 12 + IP	66/NEMA 4X	A5						02		
			P1K1	P1K5	P2K2	P3K0	P3K7	P5K5	P7K5	P15K	P22K
Typical shaft output		[kW]	1.1	1.5	2.2	3	3.7	5.5	7.5	15	22
Typical shaft output at 240	V	[HP]	1.5	2.0	2.9	4.0	4.9	7.5	10	20	30
Output current											
Continuous (3x200-240 V)		[A]	6.6	7.5	10.6	12.5	16.7	24.2	30.8	59.4	88
Intermittent (3x200-240 V)	[A]	7.3	8.3	11.7	13.8	18.4	26.6	33.4	65.3	96.8
Output power											
Continuous (208 V AC)		[kVA]	2.4	2.7	3.8	4.5	6.0	8.7	11.1	21.4	31.7
Maximum input current											
Continuous (1 x 200-240 \	/)	[A]	12.5	15	20.5	24	32	46	59	111	172
Intermittent (1 x 200-240)	/)	[A]	13.8	16.5	22.6	26.4	35.2	50.6	64.9	122.1	189.2
Max. pre-fuses		[A]	20	30	4	40	60	80	100	150	200
Additional specifications											
Estimated power loss at ra	ted max. load 3)	[W]	44	30	44	60	74	110	150	300	440
Efficiency 4)							0.98				
Max. cable cross-section Mains, motor, brake		[mm²] ([AWG])			0.2-4 (4-10)			10 (7)	35 (2)	50 (1/0)	95 (4/0)
Max. cable cross-section Mains with disconnect swite	h	[mm²] ([AWG])	5.26 (10)			16 (6)			25 (3)	50 (1/0)	2 x 50 (2 x 1/0) 9) 10)
Max. cable cross-section Mains without disconnect sy	vitch	[mm²] ([AWG])	5.26 (10)			16 (6)			25 (3)	50 (1/0)	95 (4/0)
Cable insulation temperat	ure ratings	[°C]					75				
Weight	1										
IP20/Chassis		[kg] (lbs)	4.9 (10.8)								
IP21/Type 1		[kg] (lbs)				23 (50.7)			27 (59.5)	45 (99.2)	65 (143.3
IP55/Type 12, IP66/NEMA	4X	[kg] (lbs)				23 (50.7)			27 (59.5)	45 (99.2)	65 (143.3

Mains supply 1 x 200-240 V AC – normal overload = 110% torque during 60 s, P1K1-P22K. 9 Two wires are required. ¹⁰ Variant not available in IP21.

VLT[®] AQUA Drive 1 x 380-480 V AC

IF Enclosure	21/Type 1 IP55/Type 12 IP66/NEMA 4X	B1	B2	C1	C2
		P7K5	P11K	P18K	P37K
Typical shaft output	[kW]	7.5	11	18.5	37
Typical shaft output 240 V	[HP]	10	15	25	50
Output current					
Continuous (3 x 380-440 V)	[A]	16	24	37.5	73
Intermittent (3 x 380-440 V)	[A]	17.6	26.4	41.2	80.3
Continuous (3 x 441-480 V)	[A]	14.5	21	34	65
ntermittent (3 x 441-480 V)	[A]	15.4	23.1	37.4	71.5
Output power					
Continuous at 400 V AC	[kVA]	11.0	16.6	26	50.6
Continuous at 460 V AC	[kVA]	11.6	16.7	27.1	51.8
Maximum input current					
Continuous (1 x 380-440 V)	[A]	33	48	78	151
ntermittent (1 x 380-440 V)	[A]	36	53	85.5	166
Continuous (1 x 441-480 V)	[A]	30	41	72	135
ntermittent (1 x 441-480 V)	[A]	33	46	79.2	148
Max. pre-fuses	[A]	63	80	160	250
Additional specifications					
Estimated power loss at rated max. I	oad 3) [W]	300	440	740	1480
Efficiency ⁴⁾			. 0	.96	
Max. cable cross-section Mains, motor and brake	[mm²] ([AWG])	10 (7)	35 (2)	50 (1/0)	120 (4/0)
Weight					
- IP21/Type 1, IP55/Type 12, IP66/NEM	IA 4X [kg] (lbs)	23 (50.7)	27 (59.5)	45 (99.2)	65 (143.3)

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2) 3)

High overload = 150% or 160% torque for a duration of 60 s. Normal overload = 110% torque for a duration of 60 s. The 3 values for the max. cable cross-section indicate single core, flexible wire, and flexible wire with sleeve, respectively. The typical power loss is at normal load conditions and expected to be within ± 15% (tolerance relates to variations in voltage and cable conditions). Values are based on a typical motor efficiency. Lower efficiency motors will also add to the power loss in the frequency converter and vice versa. If the switching frequency is raised from nominal, the power losses may rise significantly. LCP and typical control card power consumptions are included. Further options and customer load may add up to 30 W to the losses. (Though typical) years were consumptions are included. Further options for a duration of a duration of (± 5%). Although measurements are made with state of the art equipment, some measurement inaccuracy must be allowed for (± 5%). Measured using 5 m screened motor cables at rated load and rated frequency. Enclosure types A2 + A3 can be converted to IP21 using a conversion kit. See also Mechanical mounting and IP21/Type 1 enclosure kit in the Design Guide. Enclosure types B3 + B4 and C3 + C4 can be converted to IP21 using a conversion kit. See also Mechanical mounting and IP21/Type 1 enclosure kit in the Design Guide. , 5) 6)

	IP20/Chassis 5), If	P21/Type 1	e 1 A2												A3		
Enclosure	IP55/Type 12, IP66	5/NEMA 4X						A4 -	+ A5							A5	
			PK	25	PK3	7	PK55	PK	75	P1K	1	P1K5	P2	K2	P3K0	Р	3K7
	High/normal	overload 1)	но	NO	НО	NO	HO NO	но	NO	HO	NO	HO NO	HO	NO	HO NO	HO	NO
Typical shaft output		[kW]	0.2	25	0.37	7	0.55	0.	75	1.1		1.5	2.	2	3.0		3.7
Typical shaft output 208	3 V	[HP]	0.3	34	0.5		0.75		1	1.5		2	3		4		5
Output current																	
Continuous (3 x 200-240) V)	[A]	1.	.8	2.4		3.5	4	.6	6.6		7.5	10	.6	12.5	1	16.7
Intermittent (3 x 200-24	0 V)	[A]	2.7	2.0	3.6	2.6	5.3 3.9	6.9	5.1	9.9	7.3	11.3 8.3	15.9	11.7	18.8 13.8	25	18.4
Output power																	
Continuous at 208 V AC		[kVA]	0.6	55	0.86	5	1.26	1.0	66	2.3	8	2.70	3.8	32	4.50	6	5.00
Maximum input current																	
Continuous (3 x 200-240) V)	[A]	1.	.6	2.2		3.2	4	.1	5.9)	6.8	9.	5	11.3	1	15.0
Intermittent (3 x 200-24	0 V)	[A]	2.4	1.8	3.3	2.4	4.8 3.5	6.2	4.5	8.9	6.5	10.2 7.5	14.3	10.5	17.0 12.4	22.5	5 16.5
Max. pre-fuses		[A]				1(0					20				32	
Additional specification	S																
Estimated power loss at	rated max. load 3)	[W]	2	1	29		42	5	4	63		82	11	6	155		185
Efficiency 4)				0.9	94		0.	95					0.9	96			
Max. cable cross-section Mains, motor, brake and lo		[mm²] ([AWG])								4, 4 (12, (min. 0.2							
Max. cable cross-section Disconnect ²⁾	1	[mm²] ([AWG])								6, 4, (10, 12							
Weight																	
IP20/Chassis		[kg] (lbs)						4.9 (10.8)						6.6	(14.6)	
IP21/Type 1		[kg] (lbs)						5.5 (12.1)						7.5	(16.5)	
IP55/Type 12, IP66/NEM	A 4X	[kg] (lbs)				13.5 (29.8)											

VLT[®] AQUA Drive 3 x 200-240 V AC

	IP2	0/Chassis 6)						B	34			C	3		C4					
Enclosure	IP21/Type 1 IP IP6	55/Type 12 6/NEMA 4X			В	1			B	2			c	:1				c	2	
			P5	K5	P7	K5	P1	1K	P1	5K	P1	8K	P2	2K	P3	0K	P3	7K	P4	5K
	High/normal	overload 1)	но	NO	НО	NO	но	NO	но	NO	НО	NO	но	NO	но	NO	HO	NO	НО	NO
Typical shaft output		[kW]	3.7	5.5	5.5	7.5	7.5	11	11	15	15	18.5	18.5	22	22	30	30	37	37	45
Typical shaft output 208 V		[HP]	5.0	7.5	7.5	10	10	15	15	20	20	25	25	30	30	40	40	50	50	60
Output current																				
Continuous (3 x 200-240 V)	[A]	16.7	24.2	24.2	30.8	30.8	46.2	46.2	59.4	59.4	74.8	74.8	88.0	88.0	115	115	143	143	170
Intermittent (3 x 200-240 V	/)	[A]	26.7	26.6	38.7	33.9	49.3	50.8	73.9	65.3	89.1	82.3	112	96.8	132	127	173	157	215	187
Output power																				
Continuous at 208 V AC		[kVA]	6.0	8.7	8.7	11.1	11.1	16.6	16.6	21.4	21.4	26.9	26.9	31.7	31.7	41.4	41.4	51.5	51.5	61.2
Maximum input current																				
Continuous (3 x 200-240 V)	[A]	15.0	22.0	22.0	28.0	28.0	42.0	42.0	54.0	54.0	68.0	68.0	80.0	80.0	104	104	130	130	154
Intermittent (3 x 200-240 V	/)	[A]	24.0	24.2	35.2	30.8	44.8	46.2	67.2	59.4	81.0	74.8	102	88.0	120	114	156	143	195	169
Max. pre-fuses		[A]			6	3			8	0		12	25		10	50	20	00	25	50
Additional specifications																				
Estimated power loss at rat	ted max. load 3)	[W]	239	310	239	310	371	514	463	602	624	737	740	845	874	1140	1143	1353	1400	1636
Efficiency 4)							0.9	96								0.	97			
IP20 max. cable cross-secti Mains, motor, brake and load		[mm ²] ([AWG])				10, - 8, -)			35, (2,	-, - -, -)	3	5 2)		5 (*	0 1)			15 (300	50 MCM)	
IP21 max. cable cross-secti Mains, brake and load sharing		[mm²] ([AWG])			16, 1 (6, 8	0, 16 3, 6)			35, (2,	-, - -, -)						_				
IP21 max. cable cross-secti Motor ²⁾	ion	[mm ²] ([AWG])				10, - 8, -)				15, 25 4, 4)			-	-				-	-	
IP21, IP55, IP66 max. cable Mains and motor	cross-section	[mm²] ([AWG])				-				-				0 1)				15 (300 I		
IP21, IP55, IP66 max. cable Brake and load sharing	cross-section	[mm²] ([AWG])				-				_				0 1)				9 (3,		
Max. cable cross-section Disconnect ²⁾		[mm²] ([AWG])	16, 10, 10 (6, 8, 8)			3 (.	5 2)	50, 35, 35 (1, 2, 2)				(3/0	0, 70 , 2/0, 0)	12 (350 I	150, 20 MCM, MCM, /0)					
Weight																				
IP20/Chassis		[kg] (lbs)			12 (2	26.5)		23.5 (51.8) 35 (77.				77.2)			50 (1	10.3)				
IP21/Type 1, IP55/Type 12,	IP66/NEMA 4X	[kg] (lbs)			23 (50.7)			27 (59.5)			45 (9	99.2)				65 (1	43.3)	

	IP20	D/Chassis 5)								А	2								A3	
Enclosure	IP55/Type 12, IP66	/NEMA 4X								A4 -	+ A5								A5	
			PK:	37	PK5	5	PK	75	P1	K1	P1	K5	P2	K2	P3	K0	P4K0	P5K5	P	P7K5
	High/normal	overload 1)	но	NO	HO I	NO	но	NO	но	NO	но	NO	но	NO	но	NO	HO NO	HO N	о но	ON C
Typical shaft output		[kW]	0.3	37	0.55	5	0.7	75	1.	.1	1	.5	2.	2	3.	0	4.0	5.5		7.5
Typical shaft output 460	V	[HP]	0.	5	0.75	5	1		1.	.5		2	2.	9	4.	0	5.3	7.5		10
Output current																				
Continuous (3 x 380-440	V)	[A]	1.	3	1.8		2.	4	3.	.0	4	.1	5.	б	7.	2	10	13		16
Intermittent (3 x 380-44	0 V)	[A]	2.0	1.4	2.7	2.0	3.6	2.6	4.5	3.3	6.2	4.5	8.4	6.2	10.8	7.9	15.0 11.0	19.5 14	.3 24.	.0 17.6
Continuous (3 x 441-480	V)	[A]	1.	2	1.6		2.	1	2.	.7	3	.4	4.	8	6.	3	8.2	11		14.5
Intermittent (3 x 441-48	0 V)	[A]	1.8	1.3	2.4	1.8	3.2	2.3	4.1	3.0	5.1	3.7	7.2	5.3	9.5	6.9	12.3 9.0	16.5 12	.1 21.	.8 16.0
Output power																				
Continuous at 400 V AC		[kVA]	0.9 1.3 1.7 2.1					2.8 3		3.	9	5.	0	6.9	9.0		11.0			
Continuous at 460 V AC		[kVA]	0.9 1.3 1.7 2.4				2.7 3.8				5.	0	6.5	8.8		11.6				
Maximum input current																				
Continuous (3 x 380-440	V)	[A]	1.	2	1.6		2.	2	2.	.7	3.7 5.0			0	6.	5	9.0	11.7		14.4
Intermittent (3 x 380-44	0 V)	[A]	1.8	1.3	2.4	1.8	3.3	2.4	4.1	3.0	5.6	4.1	7.5	5.5	9.8	7.2	13.5 9.9	17.6 12	.9 21.	.6 15.8
Continuous (3 x 441-480	V)	[A]	1.	0	1.4		1.	9	2.	.7	3	.1	4.	3	5.	7	7.4	9.9		13.0
Intermittent (3 x 441-48	0 V)	[A]	1.5	1.1	2.1	1.5	2.9	2.1	4.1	3.0	4.7	3.4	6.5	4.7	8.6	6.3	11.1 8.1	14.9 10	.9 19.	.5 14.3
Max. pre-fuses		[A]					10	0							2	C			30	
Additional specification	s																			
Estimated power loss at	rated max. load 3)	[W]	35	5	42		4	5	5	8	6	52	8	8	11	6	124	187		225
Efficiency 4)			0.9	93	0.95	5		0.9	96							0.9	97			
IP20, IP21 max. cable cro Mains, motor, brake and lo		[mm²] ([AWG])										4, 4 (1) (min. 0								
IP55, IP66 max. cable cro Mains, motor, brake and lo		[mm²] ([AWG])	4, 4, 4 (12, 12, 12)																	
Max. cable cross-section Disconnect ²⁾		[mm²] ([AWG])																		
Weight																				
IP20/Chassis		[kg] (lbs)	(lbs) 4.9 (10.8) 4.8 (10.6) 4.9 (10.8)						6.6 (14.6))									
IP55/Type 12, IP66/NEM	A 4X	[kg] (lbs)	lbs) 13.5 (29.8)						14	.2 (31.3	3)									

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High overload = 150% or 160% torque for a duration of 60 s. Normal overload = 110% torque for a duration of 60 s. The 3 values for the max. cable cross-section indicate single core, flexible wire, and flexible wire with sleeve, respectively. The typical power loss is at normal load conditions and expected to be within ± 15% (tolerance relates to variations in voltage and cable conditions). Values are based on a typical motor efficiency. Lower efficiency motors will also add to the power loss in the frequency converter and vice versa. If the switching frequency is raised from nominal, the power losses may rise significantly. LCP and typical control card power consumptions are included. Further options and customer load may add up to 30 W to the losses. (Though typical) only 4W extra for a fully loaded control card or options for slot A or slot B, each). Although measurements are made with state of the art equipment, some measurement inaccuracy must be allowed for (±5%). Measured using 5 m screened motor cables at rated load and rated frequency. Enclosure types A2 + A3 can be converted to IP21 using a conversion kit. See also Mechanical mounting and IP21/Type 1 enclosure kit in the Design Guide. Enclosure types B3 + B4 and C3 + C4 can be converted to IP21 using a conversion kit. See also Mechanical mounting and IP21/Type 1 enclosure kit in the Design Guide. 2) 3)

4) 5) 6)

	IP20/Chass	S 6)		E	33			E	34	E	34	
Enclosure	IP21/Type 1, IP55/Type IP66/NEMA			E	31				B	32		
		F	911K	P1	5K	P1	8K	P2	22K	P3	30K	
	High/normal overloa	d 1) HO	NO	НО	NO	HO	NO	НО	NO	НО	NO	
Typical shaft output	[kW]	7.5	11	11	15	15	18.5	18.5	22.0	22.0	30	
Typical shaft output 460	V [HP]	10	15	15	20	20	25	25	30	30	40	
Output current												
Continuous (3 x 380-440	V) [A]	16	24	24	32	32	37.5	37.5	44	44	61	
Intermittent (3 x 380-440	V) [A]	25.6	26.4	38.4	35.2	51.2	41.3	60	48.4	70.4	67.1	
Continuous (3 x 441-480	V) [A]	14.5	21	21	27	27	34	34	40	40	52	
Intermittent (3 x 441-480	V) [A]	23.2	23.1	33.6	29.7	43.2	37.4	54.4	44	64	61.6	
Output power												
Continuous at 400 V AC	[kVA]	11	16.6	16.6	22.2	22.2	26	26	30.5	30.5	42.3	
Continuous at 460 V AC	[kVA]	11.6	16.7	16.7	21.5	21.5	27.1	27.1	31.9	31.9	41.4	
Maximum input current												
Continuous (3 x 380-440	V) [A]	14.4	22	22	29	29	34	34	40	40	55	
Intermittent (3 x 380-440	V) [A]	23	24.2	35.2	31.9	46.4	37.4	54.4	44	64	60.5	
Continuous (3 x 441-480	V) [A]	13	19	19	25	25	31	31	36	36	47	
Intermittent (3 x 441-480	V) [A]	20.8	20.9	30.4	27.5	40	34.1	49.6	39.6	57.6	51.7	
Max. pre-fuses	[A]					63					80	
Additional specifications												
Estimated power loss at	rated max. load 3) [W]	225	278	291	392	379	465	444	525	547	739	
Efficiency 4)						0.	98					
IP20 max. cable cross-see Mains, motor, brake and lo					10,- 8,-)				35 (2,	, -, - -, -)		
IP21, IP55, IP66 max. cab Motor ²⁾	le cross-section [mm ² ([AWG				10,- 8,-)				25, 25 4, 4)			
IP21, IP55, IP66 max. cab Mains, brake and load shar					0, 16 8, 6)		35, -, - (2, -, -)					
Max. cable cross-section Disconnect ²⁾	[mm² ([AWG						0, 10 8, 8)					
Weight		1										
IP20/Chassis	[kg] (lb	s) 12	(26.5)		23.5	(51.8)			35 (77.2)		
IP21/Type 1, IP55/Type 1	2, IP66/NEMA 4X [kg] (lb	s) 23	(50.7)	27 (59.5)		45 (99.2)					

	IP20/Chassis 6)	ĺ	34		C	3			C	4			
Enclosure IP21	/Type 1, IP55/Type 12 IP66/NEMA 4X			c	1				с	2			
		P3	37K	P4	5K	P5	55K	P7	′5K	P9	ок		
Hi	gh/normal overload 1)	НО	NO	HO	NO	НО	NO	НО	NO	НО	NO		
Typical shaft output	[kW]	30	37	37	45	45	55	55	75	75	90		
Typical shaft output 460 V	[HP]	40	50	50	60	60	75	75	100	100	125		
Output current													
Continuous (3 x 380-440 V)	[A]	61	73	73	90	90	106	106	147	147	177		
Intermittent (3 x 380-440 V)	[A]	91.5	80.3	110	99	135	117	159	162	221	195		
Continuous (3 x 441-480 V)	[A]	52	65	65	80	80	105	105	130	130	160		
Intermittent (3 x 441-480 V)	[A]	78	71.5	97.5 88		120	116	158	143	195	176		
Output power													
Continuous at 400 V AC	[kVA]	42.3	50.6	50.6	62.4	62.4	73.4	73.4	102	102	123		
Continuous at 460 V AC	[kVA]	41.4	51.8	51.8	63.7	63.7	83.7	83.7	103.6	103.6	128		
Maximum input current													
Continuous (3 x 380-440 V)	[A]	55	66	66	82	82	96	96	133	133	161		
Intermittent (3 x 380-440 V)	[A]	82.5	72.6	99	90.2	123	106	144	146	200	177		
Continuous (3 x 441-480 V)	[A]	47	59	59	73	73	95	95	118	118	145		
Intermittent (3 x 441-480 V)	[A]	70.5	64.9	88.5	80.3	110	105	143	130	177	160		
Max. pre-fuses	[A]	1	00	1.	25	1	60		2	50			
Additional specifications													
Estimated power loss at rated max. loa	d 3) [W]	570	698	697	843	891	1083	1022	1384	1232	1474		
Efficiency 4)					0.9	98				0.	99		
IP20 max. cable cross-section Mains and motor	[mm²] ([AWG])		35 (2)			0 1)				50 MCM)			
IP20 max. cable cross-section Brake and load sharing	[mm²] ([AWG])		35 (2)			0 1)			9 (4,	5 /0)			
IP21, IP55, IP66 max. cable cross-section Motor and mains	([AWG])	50								50 MCM)			
IP21, IP55, IP66 max. cable cross-sectio Brake and load sharing	([AWG])	50								5/0)			
Max. cable cross-section Mains disconnect ²	[mm²] ([AWG])								70, 70 /0, 2/0)	185, 150, 12 (350 MCN 300 MCM, 4			
Weight													
IP20/Chassis	[kg] (lbs)	23.5	(51.8)		35 (7	77.2)		50 (110.3)					
IP21/Type 1, IP55/Type 12, IP66/NEMA	4X [kg] (lbs)			45 (99.2)				65 (1	43.3)			

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High overload = 150% or 160% torque for a duration of 60 s. Normal overload = 110% torque for a duration of 60 s. The 3 values for the max. cable cross-section indicate single core, flexible wire, and flexible wire with sleeve, respectively. The typical power loss is at normal load conditions and expected to be within ± 15% (tolerance relates to variations in voltage and cable conditions). Values are based on a typical motor efficiency. Lower efficiency motors will also add to the power loss in the frequency converter and vice versa. If the switching frequency is raised from nominal, the power losses may rise significantly. LCP and typical control card power consumptions are included. Further options and customer load may add up to 30 W to the losses. (Though typical) only 4W extra for a fully loaded control card or options for slot A or slot B, each). Although measurements are made with state of the art equipment, some measurement inaccuracy must be allowed for (±5%). Measured using 5 m screened motor cables at rated load and rated frequency. Enclosure types A2 + A3 can be converted to IP21 using a conversion kit. See also Mechanical mounting and IP21/Type 1 enclosure kit in the Design Guide. Enclosure types B3 + B4 and C3 + C4 can be converted to IP21 using a conversion kit. See also Mechanical mounting and IP21/Type 1 enclosure kit in the Design Guide. 2) 3)

4) 5) 6)

		IP20			D	3h					D	4h		
Enclosure		IP21, IP54			D1h + D	5h + D6ł	ı				D2h + D	07 + D8h	1	
			N1	10	N1	32	N1	60	N2	.00	N2	250	N3	815
	High/normal	overload*	HO	NO	НО	NO	HO	NO	НО	NO	НО	NO	HO	NO
Typical shaft output 400 V		[kW]	90	110	110	132	<mark>132</mark>	<mark>160</mark>	160	200	200	250	250	315
Typical shaft output 460 V		[HP]	125	150	150	200	200	250	250	300	300	350	350	450
Output current														
Continuous (at 400 V)		[A]	177	212	212	260	260	<mark>315</mark>	315	395	395	480	480	588
Intermittent (60 s overload) (at 400 V)		[A]	266	233	318	286	390	347	473	435	593	528	720	647
Continuous (at 460/480 V)		[A]	160 190 190 240 240 30.						302	361	361	443	443	535
Intermittent (60 s overload) (at 460/480 V)		[A]	[A] 240 209 285 264 360 33						453	397	542	487	665	588
Output power														
Continuous (at 400 V)		[kVA]	123	147	147	180	180	218	218	274	274	333	333	407
Continuous (at 460 V)		[kVA]	127	151	151	191	191	241	241	288	288	353	353	426
Maximum input current														
Continuous (at 400 V)		[A]	171	204	204	251	251	304	304	381	381	463	463	567
Continuous (at 460/480 V)		[A]	154	183	183	231	231	291	291	348	348	427	427	516
Max. cable cross-section Mains, motor, brake and load sharing $^{1) (2)}$		[mm²] ([AWG])			2 x (2 x	95 3/0)						185 0 MCM)		
Max. external mains fuses 3)		[A]	31	5	3	50	4(00	55	50	6	30	8	00
Additional specifications														
Estimated power loss at 400 V ^{4) 5)}		[W]	2031	2555	2289	2949	2923	3764	3093	4109	4039	5129	5005	6663
Estimated power loss at 460 V 4) 5)		[W]	1828	2257	2051	2719	2089	3622	2872	3561	3575	4558	4458	5703
Efficiency 5)								0.	98					
Output frequency		0-590 Hz												
Heatsink overtemperature trip								11()°C					
Control card ambient trip								75	°C					
Weight														
IP20, IP21, IP54		[kg] (lbs)	trg] (lbs) D1h + D3h: 62 (136.7) D2h + D4h: 125 (275.6) D5h: 166 (366), D6h: 129 (284.4) D7h: 200 (441), D8h: 225 (496.1)											

*High overload = 150% torque during 60 s, normal overload = 110% torque during 60 s

Technical specifications, D-frames 380-480 V, mains supply 3 x 380-480 V AC
 American Wire Gauge.
 Wiring terminals on N132, N160, and N315 frequency converters cannot receive cables one size larger.
 For fuse traings, check reference.
 Typical power loss is at normal conditions and expected to be within ±15% (tolerance relates to variety in voltage and cable conditions).
 These values are based on a typical motor efficiency (IE/IE) borderline). Lower efficiency motors add to the power loss in the frequency converter. If the switching frequency is raised from nominal, the power losses rise significantly. LCP and typical control card power consumptions are included. Options and customer load can add up to 30 W to the losses, though usually a fully loaded control card and options for slots A and B each add only 4 W.
 Measured using 5 m screened motor cables at rated load and rated frequency.
 Additional frame size weights are as follows: D5h – 166 (255) / D6h – 129 (285) / D7h – 200 (440) / D8h – 225 (496). Weights are in kg (lbs).

	IP00			E	2			
Enclosure	IP21, IP54			E	1			
		Р	355	P4	100	P4	50	
	High/normal overload*	НО	NO	но	NO	НО	NO	
Гурical shaft output 400 V	[kW]	315	355	355	400	400	450	
Typical shaft output 460 V	[HP]	450	500	500	600	550	600	
Dutput current								
Continuous (at 400 V)	[A]	600	658	658	745	695	800	
ntermittent (60 s overload) (at 400 V)	[A]	900	724	987	820	1043	880	
Continuous (at 460/480 V)	[A]	540	590	590	678	678	730	
ntermittent (60 s overload) (at 460/480 V)	[A]	810	649	885	746	1017	803	
Dutput power								
Continuous (at 400 V)	[kVA]	416	456	456	516	482	554	
Continuous (at 460 V)	[kVA]	430	470	470	540	540	582	
Maximum input current								
Continuous (at 400 V)	[A]	590	647	647	733	684	787	
Continuous (at 460/480 V)	[A]	531	580	580	667	667	718	
Aax. cable cross-section Aains, motor and load sharing ^{1) 2)}	[mm²] ([AWG])				240 0 MCM)			
Max. cable cross-section Brake 1)	[mm²] ([AWG])				185 0 MCM)			
Max. external mains fuses 3)	[A]			9	00			
Additional specifications								
Estimated power loss at 400 V 4) 5)	[W]	6794	7532	7498	8677	7976	9473	
stimated power loss at 460 V 4) 5)	[W]	6118	6724	6672	7819	7814	8527	
fficiency ⁵⁾				0.	98			
Output frequency				0-59	90 Hz			
leatsink overtemperature trip				11	0 °C			
Control card ambient trip				85	°C			
Veight								
P00	[kg] (lbs)	234	(516)	236 (520.4)	277 (610.8)		
P21, IP54	[kg] (lbs)	270	(595.4)	272 (599.8)	313 (6	590.2)	

*High overload = 160% torque during 60 s, normal overload = 110% torque during 60 s

Technical specifications for VLT® Low Harmonic Drive, VLT® Advanced Active Filter AAF 006 and VLT® 12-pulse Please see the VLT® High Power Drive Selection Guide.

Technical specifications, E-frames 380-480 V, mains supply 3 x 380-480 V AC
 American Wire Gauge.
 Wiring terminals on N132, N160, and P315 frequency converters cannot receive cables one size larger.
 For fuse ratings, check reference.
 Typical power loss is at normal conditions and expected to be within ±15% (tolerance relates to variety in voltage and cable conditions).
 These values are based on a typical motor efficiency (IE/IE borderline). Lower efficiency motors add to the power loss in the frequency converter. If the switching frequency is raised from nominal, the power losses rise significantly loaded control card and options for slots A and B each add only 4 W.
 Measured using 5 m screened motor cables at rated load and rated frequency.

		IP21, IP54				F1,	/F3					F2	/F4	
Enclosure	without/with opti		P5	00	P5	60	P6	30	P7	10	P8	00	P1	MO
	High/norma	l overload*	но	NO	но	NO	НО	NO	но	NO	но	NO	но	NO
Typical shaft output 400 V		[kW]	450	500	500	560	560	630	630	710	710	800	800	1000
Typical shaft output 460 V		[HP]	600	650	650	750	750	900	900	1000	1000	1200	1200	1350
Output current														
Continuous (at 400 V)		[A]	800	880	880	990	990	1120	1120	1260	12260	1460	1460	1720
Intermittent (60 s overload) (at 40	0 V)	[A]	1200	968	1320	1089	1485	1232	1680	1386	1890	1606	2190	1892
Continuous (at 460/480 V)		[A]	730	780	780	890	890	1050	1050	1160	1160	1380	1380	1530
Intermittent (60 s overload) (at 46	60/480 V)	[A]	1095	858	1170	979	1335	1155	1575	1276	1740	1518	2070	1683
Output power														
Continuous (at 400 V)		[kVA]	554	610	610	686	686	776	776	873	873	1012	1012	1192
Continuous (at 460 V)		[kVA]	582	621	621	709	709	837	837	924	924	1100	1100	1219
Maximum input current														
Continuous (at 400 V)		[A]	779 857 857 964 964 1090 1090 1227								1227	1422	1422	1675
Continuous (at 460/480 V)		[A]	711	759	759	867	867	1022	1022	1129	1129	1344	1344	1490
Max. cable cross-section Motor ¹⁾		[mm²] ([AWG])	8 x 150 (8 x 300 MCM) (12 x 300 MCM)											
Max. cable cross-section Mains F1/F2 1)		[mm²] ([AWG])						8 x (8 x 500	240) MCM)					
Max. cable cross-section Mains F3/F4 1)		[mm²] ([AWG])							456) MCM)					
Max. cable cross-section Load sharing 1)		[mm²] ([AWG])						4 x (4 x 250	120) MCM)					
Max. cable cross-section Brake 1)		[mm²] ([AWG])				4 x (4 x 350	185) MCM)						185 0 MCM)	
Max. external mains fuses 3)		[A]		16	00			20	00			25	00	
Additional specifications														
Estimated power loss at 400 V ^{3) 4)}		[W]	9031	10162	10146	11822	10649	12512	12490	14674	14244	17293	15466	19278
Estimated power loss at 460 V ^{3) 4)}		[W]	8212	8876	8860	10424	9414	11595	11581	13213	13005	16229	14556	16624
F3/F4 max. added losses A1 RFI, CB or disconnect and contactor F	3/F4	[W]	893	963	951	1054	978	1093	1092	1230	2067	2280	2236	2541
Max. panel options losses		[W]						4(00					
Efficiency 4)								0.9	98					
Output frequency								0-59	0 Hz					
Heatsink overtemperature trip								95	°C					
Control card ambient trip								85	°C					
Weight														
IP21, IP54		[kg] (lbs)			10	17/1318	(2243/29	06)			12	60/1561	(2778/34	42)
Rectifier module		[kg] (lbs)	102 (224.9)	102 (2	224.9)	102 (2	224.9)	102 (2	224.9)	136 (299.9)	136 (2	299.9)
Inverter module		[kg] (lbs)	102 (224.9)	102 (2	224.9)	102 (2	224.9)	136 (2	299.9)	102 (.	224.9)	102 (2	224.9)

*High overload = 160% torque during 60 s, normal overload = 110% torque during 60 s

Technical specifications, F-frames 380-480 V, mains supply 3 x 380-480 V AC
 American Wire Gauge.
 For fuse traings, check reference.
 Typical power loss is at normal conditions and expected to be within ±15% (tolerance relates to variety in voltage and cable conditions). These values are based on a typical motor efficiency (IE/IE3 borderline). Lower efficiency motors add to the power loss in the frequency converter. If the switching frequency is raised from nominal, the power losses rise significantly. LCP and typical control card and options for slots A and B each add only 4 W.
 Measured using 5 m screened motor cables at rated load and rated frequency.

Technical specifications for VLT® Low Harmonic Drive, VLT® Advanced Active Filter AAF 006 and VLT® 12-pulse Please see the VLT® High Power Drive Selection Guide.

	IP20/Chassis, I	P21/Type 1				A	3							1	43			
Enclosure	IP	55/Type 12								P	\5							
			Pł	(75	P1	K1	P1	K5	P2	K2	P3	K0	P4	1K0	P	5K5	P7	7K5
	High/normal	overload 1)	HO	NO	но	NO	НО	NO	HO	NO	но	NO	HO	NO	но	NO	но	NO
Typical shaft output		[kW]	0.	75	1	.1	1	.5	2	.2	3	.0	4	1.0	1	5.5	7	7.5
Typical shaft output		[HP]		1	1	.5		2		3		4		5		7.5	1	10
Output current																		
Continuous (3 x 525-550 V)	[A]	1	.8	2	.6	2	.9	4	.1	5	.2	6	i.4	9	9.5	1	1.5
Intermittent (3 x 525-550 \	/)	[A]	2.7	2.0	3.9	2.9	4.4	3.2	6.2	4.5	7.8	5.7	9.6	7.0	14.3	10.5	17.3	12.7
Continuous (3 x 551-600 V)	[A]	1	.7	2	.4	2	.7	3	.9	4	.9	6	5.1	9	9.0	1	1.0
Intermittent (3 x 551-600 \	/)	[A]	2.6	1.9	3.6	2.6	4.1	3.0	5.9	4.3	7.4	5.4	9.2	6.7	13.5	9.9	16.5	12.1
Output power																		
Continuous at 550 V AC			1	.7	2	.5	2	.8	3	.9	5	.0	6	5.1	9	9.0	1	1.0
Continuous at 575 V AC		[kVA]	1	.7	2	.4	2	.7	3	.9	4	.9	6	5.1	9	9.0	1	1.0
Maximum input current																		
Continuous (3 x 525-600 V)	[A]	1	.7	2	.4	2	.7	4	.1	5	.2	5	5.8	8	3.6	10	0.4
Intermittent (3 x 525-600 \	/)	[A]	2.6	1.9	3.6	2.6	4.1	3.0	6.2	4.5	7.8	5.7	8.7	6.4	12.9	9.5	15.6	11.4
Max. pre-fuses		[A]			1	0					2	20				3	32	
Additional specifications																		
Estimated power loss at ra	ted max. load 3)	[W]	3	35	5	0	6	5	ç	2	1	22	1	45	1	95	2	61
Efficiency 4)										0.	97							
Max. cable cross-section Mains, motor, brake and load	sharing ²⁾	[mm ²] ([AWG])							4	, 4, 4 (1 (min. (2, 12, 1).2 (24))							
Max. cable cross-section Disconnect ²⁾		[mm²] ([AWG])									4, 4 2, 12)							
Weight																		
IP20/Chassis		[kg] (lbs)						6.5 (14.3)							6.6 ((14.6)	
IP21/Type 1, IP55/Type 12		[kg] (lbs)						13.5	(29.8)							14.2	(31.3)	

VLT[®] AQUA Drive 3 x 525-600 V AC

	IP20/Chassis			B	3					B	4		
Enclosure IF	21/Type 1, IP55/Type 12 IP66/NEMA 4X			B	31				B	2		c	1
		P1	1K	P1	5K	P1	8K	P2	2K	P3	ок	P3	37K
	High/normal overload ¹⁾	HO	NO	НО	NO	НО	NO	НО	NO	НО	NO	HO	NO
Typical shaft output	[kW]	7.5	11	11	15	15	18.5	18.5	22	22	30	30	37
Typical shaft output	[HP]	10	15	15	20	20	25	25	30	30	40	40	50
Output current													
Continuous (3 x 525-550 V)	[A]	11.5	19	19	23	23	28	28	36	36	43	43	54
Intermittent (3 x 525-550 V)	[A]	18.4	21	30	25	37	31	45	40	58	47	65	59
Continuous (3 x 551-600 V)	[A]	11	18	18	22	22	27	27	34	34	41	41	52
Intermittent (3 x 551-600 V)	[A]	17.6	20	29	24	35	30	43	37	54	45	62	57
Output power													
Continuous at 550 V AC	[kVA]	11	18.1	18.1	21.9	21.9	26.7	26.7	34.3	34.3	41.0	41.0	51.4
Continuous at 575 V AC	[kVA]	11	17.9	17.9	21.9	21.9	26.9	26.9	33.9	33.9	40.8	40.8	51.8
Maximum input current													
Continuous at 550 V	[A]	10.4	17.2	17.2	20.9	20.9	25.4	25.4	32.7	32.7	39	39	49
Intermittent at 550 V	[A]	16.6	19	28	23	33	28	41	36	52	43	59	54
Continuous at 575 V	[A]	9.8	16	16	20	20	24	24	31	31	37	37	47
Intermittent at 575 V	[A]	15.5	17.6	26	22	32	27	39	34	50	41	56	52
Max. pre-fuses	[A]		2	0		5	50	6	0	8	0	1	00
Additional specifications													
Estimated power loss at rated max.	load 3) [W]	220	300	220	300	300	370	370	440	440	600	600	740
Efficiency 4)							0.	98					
IP20 max. cable cross-section Mains, motor, brake and load sharing ²⁾	[mm²] ([AWG])				10,- 8,-)					35 (2,	, -,- -,-)		
IP21, IP55, IP66 max. cable cross-sec Mains, brake and load sharing ²⁾	tion [mm ²] ([AWG])				0, 10 8, 8)					35 (2,	, -,- -,-)		
IP21, IP55, IP66 max. cable cross-sec Motor ²⁾	tion [mm²] ([AWG])				10,- 8,-)						5, 25 4, 4)		
Max. cable cross-section Disconnect ²⁾	[mm²] ([AWG])						0, 10 8, 8)						35, 35 2, 2)
Weight													
IP20/Chassis	[kg] (lbs)		12 (26.5)					23.5	(51.8)			
IP21/Type 1, IP55/Type 12, IP66/NEM	MA 4X [kg] (lbs)		23 (50.7)					27 (59.5)			

	IP20/Chas	sis		С3			(24	
Enclosure	IP21/Type 1, IP55/Type IP66/NEMA	12 4X		C1			([2	
			P45K	Р	55K	PZ	75K	PS	0K
	High/normal overloa	d 1) HO	NO	HO	NO	НО	NO	НО	NO
Typical shaft output	[kW]	37	45	45	55	55	75	75	90
Typical shaft output	[HP]	50	60	60	75	75	100	100	125
Output current									
Continuous (3 x 525-550 V)	[A]	54	65	65	87	87	105	105	137
Intermittent (3 x 525-550 V) [A]	81	72	98	96	131	116	158	151
Continuous (3 x 551-600 V)	[A]	52	62	62	83	83	100	100	131
Intermittent (3 x 551-600 V) [A]	78	68	93	91	125	110	150	144
Output power									
Continuous at 550 V AC	[kVA]	51.4	61.9	61.9	82.9	82.9	100	100	130.5
Continuous at 575 V AC	[kVA]	51.8	61.7	61.7	82.7	82.7	99.6	99.6	130.5
Maximum input current									
Continuous at 550 V	[A]	49	59	59	78.9	78.9	95.3	95.3	124.3
Intermittent at 550 V	[A]	74	65	89	87	118	105	143	137
Continuous at 575 V	[A]	47	56	56	75	75	91	91	119
Intermittent at 575 V	[A]	70	62	85	83	113	100	137	131
Max. pre-fuses	[A]		150		160	2	25	2	50
Additional specifications									
Estimated power loss at rat	ed max. load 3) [W]	740	900	900	1100	1100	1500	1500	1800
Efficiency 4)					0.	.98			
IP20 max. cable cross-section Mains and motor	on [mm² ([AWG		5	0 (1)			150 (30	00 MCM)	
IP20 max. cable cross-section Brake and load sharing	on [mm² ([AWG		5	0 (1)			95	(4/0)	
IP21, IP55, IP66 max. cable Mains and motor	cross-section [mm ² ([AWG		5	0 (1)			150 (30	00 MCM)	
IP21, IP55, IP66 max. cable Brake and load sharing	cross-section [mm ² ([AWG		5	0 (1)			95	(4/0)	
Max. cable cross-section Disconnect ²⁾	[mm² ([AWG			35, 35 , 2, 2)			70, 70 2/0, 2/0)		50, 120 00 MCM, 4/0)
Weight									
IP20/Chassis	[kg] (lb	s)	35	(77.2)			50 (*	110.3)	
IP21/Type 1, IP55/Type 12,	IP66/NEMA 4X [kg] (lb	s)	45	(99.2)			65 (1	143.3)	

VLT[®] AQUA Drive 3 x 525-690 V AC

	IP20/Chassis							A	3						
Enclosure		P	1K1	P1	K5	P2	K2	P3	К0	P4	K0	P5	K5	P7	7K5
	High/normal overload 1)	но	NO	НО	NO	НО	NO	НО	NO	НО	NO	но	NO	но	NO
Typical shaft output	[kW]		1.1	1.	.5	2	.2	3	.0	4	.0	5	.5	7	7.5
Typical shaft output	[HP]		.5	2	2		3		1		5	7	.5	1	10
Output current															
Continuous (3 x 525-550 V)	[A]	1	2.1	2.	.7	3	.9	4	.9	6	.1	9	.0	1	1.0
Intermittent (3 x 525-550 V)	[A]	3.2	2.3	4.1	3.0	5.9	4.3	7.4	5.4	9.2	6.7	13.5	9.9	16.5	12.1
Continuous (3 x 551-690 V)	[A]		.6	2.	.2	3	.2	4	.5	5	.5	7	.5	1	0.0
Intermittent (3 x 551-690 V)	[A]	2.4	1.8	3.3	2.4	4.8	3.5	6.8	5.0	8.3	6.1	11.3	8.3	15.0	11.0
Output power															
Continuous at 525 V AC	[kVA]		.9	2.	.5	3	.5	4	.5	5	.5	8	.2	1	0.0
Continuous at 690 V AC	[kVA]		.9	2.	.6	3	.8	5	.4	6	.6	9	.0	1.	2.0
Maximum input current															
Continuous (3 x 525-550 V)	[A]		.9	2.	.4	3	.5	4	.4	5	.5	8	.1	ç	9.9
Intermittent (3 x 525-550 V)	[A]	2.9	2.1	3.6	2.6	5.3	3.9	6.6	4.8	8.3	6.1	12.2	8.9	14.9	10.9
Continuous (3 x 551-690 V)	[A]		.4	2.	.0	2	.9	4	.0	4	.9	6	.7	ç	9.0
Intermittent (3 x 551-690 V)	[A]	2.1	1.5	3.0	2.2	4.4	3.2	6.0	4.4	7.4	5.4	10.1	7.4	13.5	9.9
Additional specifications															
Estimated power loss at rated ma	ax. load 3) [W]		44	6	0	8	8	1.	20	10	50	22	20	3	00
								0.	96						
Max. cable cross-section Mains, motor, brake and load sharin	ig ²⁾ [mm ²] ([AWG])								2, 12, 12).2 (24))					
Max. cable cross-section Disconnect ²⁾	[mm²] ([AWG])								4, 4 2, 12)						
Weight															
IP20/Chassis	[kg] (lbs)					6.5 (14.3)						6.6 (14.6)	

	IP20/Chassis					B	4				
Enclosure IP21/Type	1, IP55/Type 12					E	2				
		P1	1K	P1	5K	P1	8K	P2	2K	P3	0K
High/nor	rmal overload 1)	НО	NO	НО	NO	НО	NO	НО	NO	но	NO
Typical shaft output at 550 V	[kW]	5.9	7.5	7.5	11	11	15	15	18.5	18.5	22
Typical shaft output at 550 V	[HP]	7.5	10	10	15	15	20	20	25	25	30
Typical shaft output at 690 V	[kW]	7.5	11	11	15	15	18.5	18.5	22	22	30
Typical shaft output at 690 V	[HP]	10	15	15	20	20	25	25	30	30	40
Output current											
Continuous (3 x 525-550 V)	[A]	11	14	14	19	19	23	23	28	28	36
Intermittent (3 x 525-550 V)	[A]	17.6	15.4	22.4	20.9	30.4	25.3	36.8	30.8	44.8	39.6
Continuous (3 x 551-690 V)	[A]	10	13	13	18	18	22	22	27	27	34
Intermittent (3 x 551-690 V)	[A]	16	14.3	20.8	19.8	28.8	24.2	35.2	29.7	43.2	37.4
Output power											
Continuous at 550 V AC	[kVA]	10	13.3	13.3	18.1	18.1	21.9	21.9	26.7	26.7	34.3
Continuous at 690 V AC	[kVA]	12	15.5	15.5	21.5	21.5	26.3	26.3	32.3	32.3	40.6
Maximum input current											
Continuous at 550 V	[A]	9.9	15	15	19.5	19.5	24	24	29	29	36
Intermittent at 550 V	[A]	15.8	16.5	23.2	21.5	31.2	26.4	38.4	31.9	46.4	39.6
Continuous at 690 V	[A]	9	14.5	14.5	19.5	19.5	24	24	29	29	36
Intermittent at 690 V	[A]	14.4	16	23.2	21.5	31.2	26.4	38.4	31.9	46.4	39.6
Additional specifications											
Estimated power loss at rated max. load ³⁾	[W]	150	220	150	220	220	300	300	370	370	440
Efficiency 4)						0.	98				
Max. cable cross-section Mains, motor, brake and load sharing 2	[mm²] ([AWG])						25, 25 4, 4)				
Max. cable cross-section Mains disconnect 2)	[mm²] ([AWG])						0,10 8, 8)				
Weight											
IP20/Chassis	[kg] (lbs)					23.5	(51.8)				
IP21/Type 1, IP55/Type 12	[kg] (lbs)					27 (59.5)				

VLT[®] AQUA Drive 3 x 525-690 V AC

	IP20/Chassis	E	34		0	3					
Enclosure I	P21/Type 1, IP55/Type 12					(2				
		P3	37K	P4	5K	P5	55K	P7	75K	PS	0K
	High/normal overload 1)	НО	NO	НО	NO	НО	NO	НО	NO	НО	NO
Typical shaft output at 550 V	[kW]	22	30	30	37	37	45	45	55	55	75
Typical shaft output at 550 V	[HP]	30	40	40	50	50	60	60	75	75	100
Typical shaft output at 690 V	[kW]	30	37	37	45	45	55	55	75	75	90
Typical shaft output at 690 V	[HP]	40	50	50	60	60	75	75	100	199	125
Output current											
Continuous (3 x 525-550 V)	[A]	36	43	43	54	54	65	65	87	87	105
Intermittent (3 x 525-550 V)	[A]	54	47.3	64.5	59.4	81	71.5	97.5	95.7	130.5	115.5
Continuous (3 x 551-690 V)	[A]	34	41	41	52	52	62	62	83	83	100
Intermittent (3 x 551-690 V)	[A]	51	45.1	61.5	57.2	78	68.2	93	91.3	124.5	110
Output power											
Continuous at 550 V AC	[kVA]	34.3	41	41	51.4	51.4	61.9	61.9	82.9	82.9	100
Continuous at 690 V AC	[kVA]	40.6	49	49	62.1	62.1	74.1	74.1	99.2	99.2	119.5
Maximum input current											
Continuous at 550 V	[A]	36	49	49	59	59	71	71	87	87	99
Intermittent at 550 V	[A]	54	53.9	72	64.9	87	78.1	105	95.7	129	108.9
Continuous at 690 V	[A]	36	48	48	58	58	70	70	86	-	-
Intermittent at 690 V	[A]	40	52.8	72	63.8	87	77	105	94.6	-	-
Additional specifications											
Estimated power loss at rated max.	. load 3) [W]	600	740	740	900	900	1100	1100	1204	1500	1477
Efficiency 4)						0.	.98				
Max. cable cross-section Mains and motor	[mm²] ([AWG])						50 MCM)				
Max. cable cross-section Brake and load sharing	[mm²] ([AWG])						95 5/0)				
Max. cable cross-section Mains disconnect ²⁾	[mm²] ([AWG])				/5 /0)			(350	50, 120 MCM, CM, 4/0)		_
Weight											
IP20/Chassis	[kg] (lbs)			35 (77.2)				D3h: 62	2 (136.7)	
IP21/Type 1, IP55/Type 12	[kg] (lbs)				45	(99.2) (C3) ·	- 65 (143.3)	(C2)			

		IP20					D	3h								D	4h			
Enclosure		IP21, IP54				D1	h + D	5h + [D6h						D2	2h + D	7 + D	8h		
			N7	'5K	N9	ок	N1	10	N1	32	N1	60	N2	200	N2	50	N3	315	N4	400
	High/nor	nal overload*	но	NO	но	NO	но	NO	но	NO	но	NO	но	NO	но	NO	но	NO	но	NO
Typical shaft output 550 V		[kW]	45	55	55	75	75	90	90	110	110	132	132	160	160	200	200	250	250	315
Typical shaft output 575 V		[HP]	60	75	75	100	100	125	125	150	150	200	200	250	250	300	300	350	350	400
Typical shaft output 690 V		[kW]	55	75	75	90	90	110	110	132	132	160	160	200	200	250	250	315	315	400
Output current																				
Continuous (at 550 V)		[A]	76	90	90	113	113	137	137	162	162	201	201	253	253	303	303	360	360	418
Intermittent (60 s overload) (a	at 550 V)	[A]	122	99	135	124	170	151	206	178	243	221	302	278	380	333	455	396	540	460
Continuous (at 575/690 V)		[A]	73	86	86	108	108	131	131	155	155	192	192	242	242	290	290	344	344	400
Intermittent (60 s overload) (a	at 575/690 V)	[A]	117	95	129	119	162	144	197	171	233	211	288	266	363	319	435	378	516	440
Output power																				
Continuous (at 550 V)		[kVA]	72	86	86	108	108	131	131	154	154	191	191	241	241	289	289	343	343	398
Continuous (at 575 V)		[kVA]	73	86	86	108	108	130	130	154	154	191	191	241	241	289	289	243	243	398
Continuous (at 690 V)		[kVA]	87	103	103	129	129	157	157	185	185	229	229	289	289	347	347	411	411	478
Maximum input current																				
Continuous (at 550 V)		[A]	77	89	89	110	110	130	130	158	158	198	198	245	245	299	299	355	355	408
Continuous (at 575 V)		[A]	74	85	85	106	106	124	124	151	151	189	189	234	234	286	286	339	339	390
Continuous (at 690 V)		[A]	77	87	87	109	109	128	128	155	155	197	197	240	240	296	296	352	352	400
Max. cable cross-section Mains, motor, brake and load sh	naring ¹⁾	[mm²] ([AWG])				2	x 95 (2 x 3/	D)						2:	x 185	(2 x 35	50)		
Max. external mains fuses 2)		[A]	10	50	3	15	3	15	3	15	31	15				5	50			
Additional specifications																				
Estimated power loss at 575	3) 4)	[W]	1098	1162	1162	1428	1430	1739	1742	2099	2080	2646	2361	3071	3012	3719	3642	4460	4146	5023
Estimated power loss at 690 \	3) 4)	[W]	1057	1204	1205	1477	1480	1796	1800	2165	2159	2738	2446	3172	3123	3848	3771	4610	4258	5150
Efficiency 4)											0.9	98								
Output frequency										0-59	0 Hz								0-52	25 Hz
Heatsink overtemperature tri	ip		110°C																	
Control card ambient trip							75	°C								80	°C			
Weight																				
IP20, IP21, IP54		[kg] (lbs)			D5h	D1h 166 (ı: 62 (1 D6h: 1		84.4)					D2h - n: 200					

*High overload = 150% torque during 60 s, normal overload = 110% torque during 60 s

 Technical specifications, D-frames 525-690 V, mains supply 3 x 525-690 V AC

 P
 American Wire Gauge.

 P
 For fuse ratings, check reference.

 Typical power loss is at normal conditions and expected to be within ±15% (tolerance relates to variety in voltage and cable conditions).

 These values are based on a typical motor efficiency (IE/IE3 borderline). Lower efficiency motors add to the power loss in the frequency converter. If the switching frequency is raised from nominal, the power losses rise significantly. LOP and typical control card power consumptions are included. Options and customer load can add up to 30 W to the losses, though usually a fully loaded control card and options for slots A and B each add only 4 W.

 Measured using 5 m screened motor cables at rated load and rated frequency.

Technical specifications for VLT® Low Harmonic Drive, VLT® Advanced Active Filter AAF 006 and VLT® 12-pulse Please see the VLT® High Power Drive Selection Guide.

	IP00				E	2			
Enclosure	IP21, IP54				E	1			
		P4	150	P5	500	P5	60	P6	30
	High/normal overload*	но	NO	HO	NO	НО	NO	НО	NO
Typical shaft output 550 V	[kW]	315	355	315	400	400	450	450	500
Typical shaft output 575 V	[HP]	400	450	400	500	500	600	600	650
Typical shaft output 690 V	[kW]	355	450	400	500	500	560	560	630
Output current									
Continuous (at 550 V)	[A]	395	470	429	523	523	596	596	630
Intermittent (60 s overload) (at 550 V)	[A]	593	517	644	575	785	656	894	693
Continuous (at 575/690 V)	[A]	380	450	410	500	500	570	570	630
Intermittent (60 s overload) (at 575/690 V)	[A]	570	495	615	550	750	627	855	693
Output power									
Continuous (at 550 V)	[kVA]	376	448	409	498	498	568	568	600
Continuous (at 575 V)	[kVA]	378	448	408	498	498	568	568	627
Continuous (at 690 V)	[kVA]	454	538	490	598	598	681	681	753
Maximum input current									
Continuous (at 550 V)	[A]	381	453	413	504	504	574	574	607
Continuous (at 575 V)	[A]	366	434	395	482	482	549	549	607
Continuous (at 690 V)	[A]	366	434	395	482	482	549	549	607
Max. cable cross-section Mains, motor and load sharing 1)	[mm²] ([AWG])					240 0 MCM)			
Max. cable cross-section Brake 1)	[mm²] ([AWG])					185 0 MCM)			
Max. external mains fuses 2)	[A]		7	00			ç	000	
Additional specifications	1								
Estimated power loss at 600 V ^{3) 4)}	[W]	4424	5323	4795	6010	6493	7395	7383	8209
Estimated power loss at 690 V ^{3) 4)}	[W]	4589	5529	4970	6239	6707	7653	7633	8495
Efficiency 4)	1				0.	98			
Output frequency					0-52	25 Hz			
Heatsink overtemperature trip		11	0 °C		95	°C		110)°C
Power card ambient trip				80)°C			85	°C
Weight									
IPOO	[kg] (lbs)		221 (487.3)		236 (520.4)	277 (510.8)
IP21, IP54	[kg] (lbs)		263 (579.9)		272 (599.8)	313 (590.2)
*High overload = 160 % torque during 60 s, normal	l overload = 110 % toraue durir	na 60 s							

*High overload = 160 % torque during 60 s, normal overload = 110 % torque during 60 s

Technical specifications, E-frames 525-690 V, mains supply 3 x 525-690 V AC
 American Wire Gauge
 For fuse ratings, check reference.
 Typical power loss is at normal conditions and expected to be within ±15% (tolerance relates to variety in voltage and cable conditions).
 Typical power loss is at normal control card power consumptions are included. Options and customer load can add up to 30 W to the losses, though usually a fully loaded control card and options for slots A and B each add only 4 W.
 Measured using 5 m screened motor cables at rated load and rated frequency.

Technical specifications for VLT® Low Harmonic Drive, VLT® Advanced Active Filter AAF 006 and VLT® 12-pulse Please see the VLT® High Power Drive Selection Guide.

		IP21, IP54			F1.	/F3					F <u>2</u>	/F4		
Enclosure	without/with optio		P7	10	P8	00	P9	00	P1	M0	P1	M2	P1	M4
	High/normal	overload*	но	NO	но	NO	но	NO	но	NO	но	NO	но	NO
Typical shaft output 550 V		[kW]	500	560	560	670	670	750	750	850	850	1000	1000	1100
Typical shaft output 575 V		[HP]	650	750	750	950	950	1050	1050	1150	1150	1350	1350	1550
Typical shaft output 575 V		[kW]	630	710	710	800	800	900	900	1000	1000	1200	1200	1400
Output current														
Continuous (at 550 V)		[A]	659	763	763	889	889	988	988	1108	1108	1317	1317	1479
Intermittent (60 s overload) (at	: 550 V)	[A]	989	839	1145	978	1334	1087	1482	1219	1662	1449	1976	1627
Continuous (at 575/690 V)		[A]	630	730	730	850	850	945	945	1060	1060	1260	1260	1415
Intermittent (60 s overload) (at	: 575/690 V)	[A]	945	803	1095	935	1275	1040	1418	1166	1590	1386	1890	1557
Output power														
Continuous (at 550 V)		[kVA]	628	727	727	847	847	941	941	1056	1056	1255	1255	1409
Continuous (at 575 V)		[kVA]	627	727	727	847	847	941	941	1056	1056	1255	1255	1409
Continuous (at 690 V)		[kVA]	753	872	872	1016	1016	1129	1129	1267	1267	1506	1506	1691
Maximum input current									L					
Continuous (at 550 V)		[A]	642	743	743	866	866	962	962	1079	1079	1282	1282	1440
Continuous (at 575 V)		[A]	613	711	711	828	828	920	920	1032	1032	1227	1227	1378
Continuous (at 690 V)		[A]	613	711	711	828	828	920	920	13032	1032	1227	1227	1378
Max. cable cross-section Motor 1)		[mm²] ([AWG])				150) MCM)						: 150 10 MCM)		
Max. cable cross-section Mains F1/F2 1)		[mm²] ([AWG])							240 D MCM)					
Max. cable cross-section Mains F3/F4 1)		[mm²] ([AWG])							456 D MCM)					
Max. cable cross-section		[mm²] ([AWG])							120 0 MCM)					
Max. cable cross-section Brake 10		[mm ²] ([AWG])			4 x (4 x 350	185) MCM)						185 0 MCM)		
Max. external mains fuses 3		[A]					00				1	00	25	00
Additional specifications	1													
Estimated power loss at 600 V	3) 4)	[W]	8075	9500	9165	10872	10860	12316	12062	13731	13269	16190	16089	18536
Estimated power loss at 690 V ³	3) 4)	[W]	8388	9863	9537	11304	11291	12798	12524	14250	13801	16821	16179	19247
F3/F4 max. added losses A1 RF CB or disconnect and contactor		[W]	342	427	419	532	519	615	556	665	863	861	1044	
Max. panel options losses		[W]			1			4(00			1	1	
Efficiency ⁴⁾								0.	98					
Output frequency								0-50	0 Hz					
Heatsink overtemperature trip			95	°C	105	5°C	95	°C	95	°C	105	5°C	95	°C
Power card ambient trip								85	°C					
Weight														
IP21, IP54		[kg] (lbs)			1017, (2243,	/1318 /2906)					/1561 /3442)			/1595 /3517)
Rectifier module		[kg] (lbs)	102 (2	224.9)	102 (2	224.9)	102 (2	224.9)	136 (2	299.9)	136 (.	299.9)	136 (2	299.9)
Inverter module		[kg] (lbs)	102 (2	224.9)	102 (2	224.9)	136 (2	299.9)		224.9)	102 (224.9)	136 (2	299.9)

*High overload = 160% torque during 60 s, normal overload = 110% torque during 60 s

Technical specifications, F-frames 525-690 V, mains supply 3 x 525-690 V AC
 American Wire Gauge.
 For fuse traings, check reference.
 Typical power loss is at normal conditions and expected to be within ±15% (tolerance relates to variety in voltage and cable conditions). These values are based on a typical motor efficiency (IE/IE3 borderline). Lower efficiency motors add to the power loss in the frequency converter. If the switching frequency is raised from nominal, the power losses rise significantly, LCP and typical control card power consumptions are included. Options and customer load can add up to 30 W to the losses, though usually a fully loaded control card and options for slots A and B each add only 4 W.
 Measured using 5 m screened motor cables at rated load and rated frequency.

Technical specifications for VLT® Low Harmonic Drive, VLT® Advanced Active Filter AAF 006 and VLT® 12-pulse Please see the VLT® High Power Drive Selection Guide.

Enclosure overview

3 phases

VLT® A	QUA Di	rive		T2 200	– 240 V	/			T4 380	– 480 V				T6 5	525 - 60	00 V			T7 5	525 - 69	90 V	
	k'	W																				
FC 200	но	NO	IP20	IP21	IP55	1P66	IP00	IP20	IP21	IP54	IP55	1P66	IP20	IP21	IP54	IP55	IP66	1P00	IP20	IP21	IP54	IP55
PK25	0.2																					
PK37	0.3																					
PK55	0.				A5	A5																
PK75	0.1		A2	A2	A4/A5	A4/A5		4.2	A2		A4/A5	A4/A5										
P1K1 P1K5	1.							A2	∢		A4/	A4/	A3	A3		A5	A5					
P1K3 P2K2	2.												AD	AS		AJ	AJ		A3			A5
P3K0	3.																					
P3K7	3.		A3	A3	A5	A5																
P4K0	4.							A2	A2		A4/	A5										
P5K5	3.7	5.5						4.2	4.2		4.5		A3	A3		A5	A5		A3			A5
P7K5	5.5	7.5	B3		B1	B1		A3	A3		A5	A5										
P11K	7.5	11																				
P15K	11	15	B4	B2	B2	B2		B3			B1	B1	B3			B1	B1					
P18K	15	18.5																	B4	B2		B2
P22K	18.5	22	C3		C1	C1			B2		B2	B2		B2		B2	B2					
P30K	22	30						B4			_		B4									
P37K	30	37	C4		C2	C2			<i>C</i> 1		C1					C1	<i>C</i> 1					
P45K P55K	37 45	45 55						C3			C1	C1	C3			C1	C1		C3			C2
P75K	55	75																				C2
P90K	75	90						C4			C2	C2	C4			C2	C2					
N75K	55	75																				
N90K	75	90																		D1h	D1h	
N110	90	110							D1h	D1h									D3h	D5h	D5h	
N132	110	132						D3h	D5h D6h	D5h D6h										D6h	D6h	
N160	132	160							D6h	D6h												
N200	160	200							D2h	D2h												
N250	200	250						D4h	D7h	D7h									D4h	D2h D7h	D2h D7h	
N315	250	315							D8h	D8h									<u> </u>	D8h	D8h	
N400	315	400																				
P315	250	315																				
P355 P400	315 355	355 400					E2		E1	E1												
P400 P450	400	400																				
P500	450	500																				
P560	500	560																E2		E1	E1	
P630	560	630							F1/F3	F1/F3												
P710	630	710																				
P800	710	800							F2/F4	F2/F4										F1/F3	F1/F3	
P900	800	900							-F2/F4	F2/F4												
P1M0	900	1000																				
P1M2	1000	1200																		F2/F4	F2/F4	
P1M4	1200	1400																				

1 phas	se							
VLT® A	QUA Drive		S2 200	- 240 \	/	S4 3	380 - 4	80 V
FC 200	kW	IP20	IP21	IP55	IP66	IP21	IP55	IP66
PK25	0.25							
PK37	0.37							
PK55	0.55							
PK75	0.75							
P1K1	1.1	A3	A3	A5	A5			
P1K5	1.5							
P2K2	2.2							
P3K0	3.0			B1	B1			
P3K7	3.7							
P5K5	5.5							
P7K5	7.5		B2	B2	B2	B1	B1	B1
P11K	11					B2	B2	B2
P15K	15		C1	C1	C1			
P18K	18.5					C1	C1	C1
P22K	22		C2	C2	C2			
P37K	37					C2	C2	C2

■ IP00/Chassis

■ IP20/Chassis

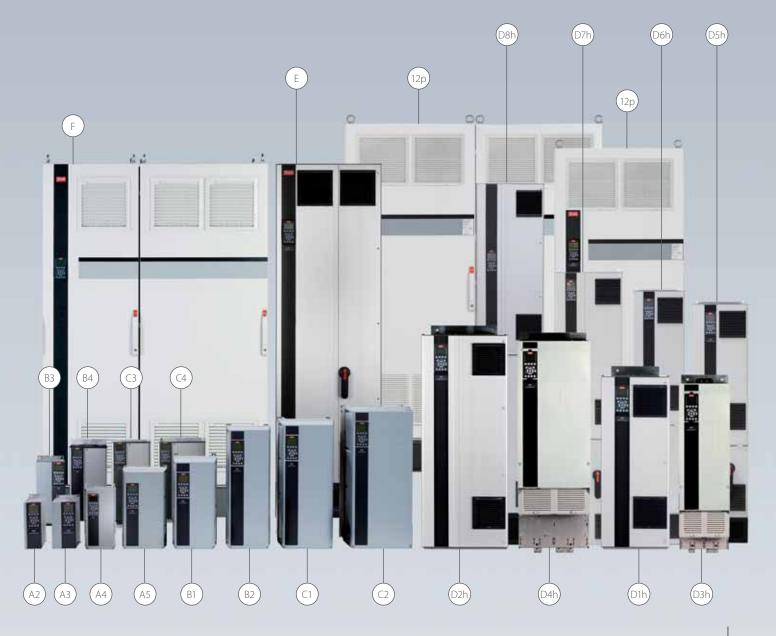
■ IP21/Type 1

IP21 with upgrade kit – available in US only

■ IP54/Type 12

■ IP55/Type 12

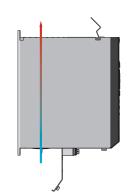
■ IP66/NEMA 4X



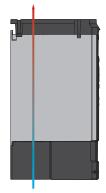
Dimensions and air flow



A2 IP20

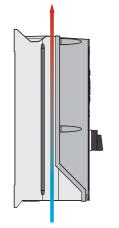






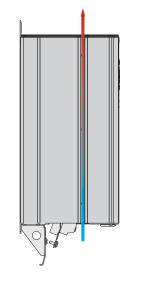
A3 with IP21/Type 12 NEMA 1 Kit

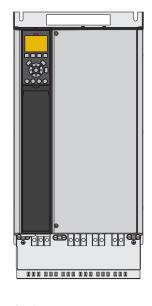




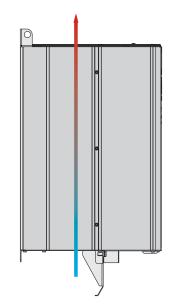
A4 IP55 with mains disconnect







B3 IP20



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B4 IP20

C3 IP20

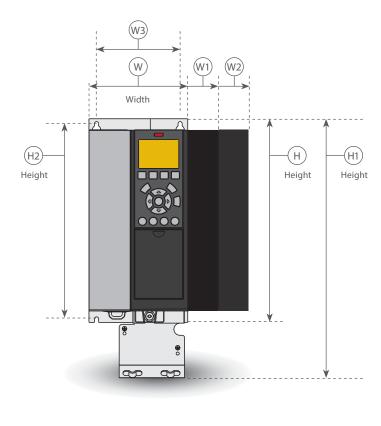
Please see the VLT® AQUA Drive Design Guide for other frames, available at http://vlt-drives.danfoss.com/Support/Technical-Documentation-Database/.

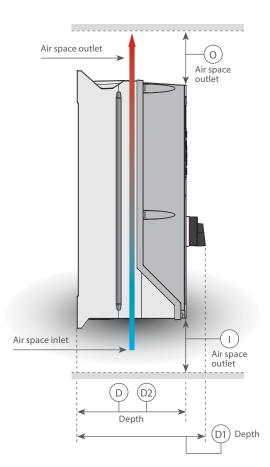
A, B and C frames

								VLT® AQ	UA Drive						
Frame		A	.2	A	13	A4	A5	B1	B2	B3	B4	C1	C2	C3	C4
Enclos	sure	IP20	IP21	IP20	IP21	IP55	/IP66	IP21/ IP	'IP55/ 66	IP	20	IP21/ IP		IP	20
H mm Height	of back plate	268	375	268	375	390	420	480	650	399	520	680	770	550	660
H1 mn With d	n e-coupling plate for fieldbus cables	374	-	374	-	-	-	-	-	420	595	-	-	630	800
H2 mm Distand	n ce to mounting holes	254	350	257	350	401	402	454	624	380	495	648	739	521	631
W mm	ı	90	90	130	130	200	242	242	242	165	230	308	370	308	370
W1 mi With o	m ne C option	130	130	170	170	-	242	242	242	205	230	308	370	308	370
W2 mi With tw	m wo C options	150	150	190	190	-	242	242	242	225	230	308	370	308	370
W3 mi Distano	m ce between mounting holes	70	70	110	110	171	215	210	210	140	200	272	334	270	330
D mm Depth	without option A/B	205	207	205	207	175	195	260	260	249	242	310	335	333	333
D1 mm With m	n nains disconnect	-	-	-	-	206	224	289	290	-	-	344	378	-	-
D2 mm With o	n ption A/B	220	222	220	222	175	195	260	260	262	242	310	335	333	333
Air cooling	l (air space inlet) mm	100	100	100	100	100	100	200	200	200	200	200	225	200	225
A	O (air space outlet) mm	100	100	100	100	100	100	200	200	200	200	200	225	200	225
Weigh	nt (kg)	4.9	5.3	6.6	7	9.7	13.5/ 14.2	23	27	12	23.5	45	65	35	50

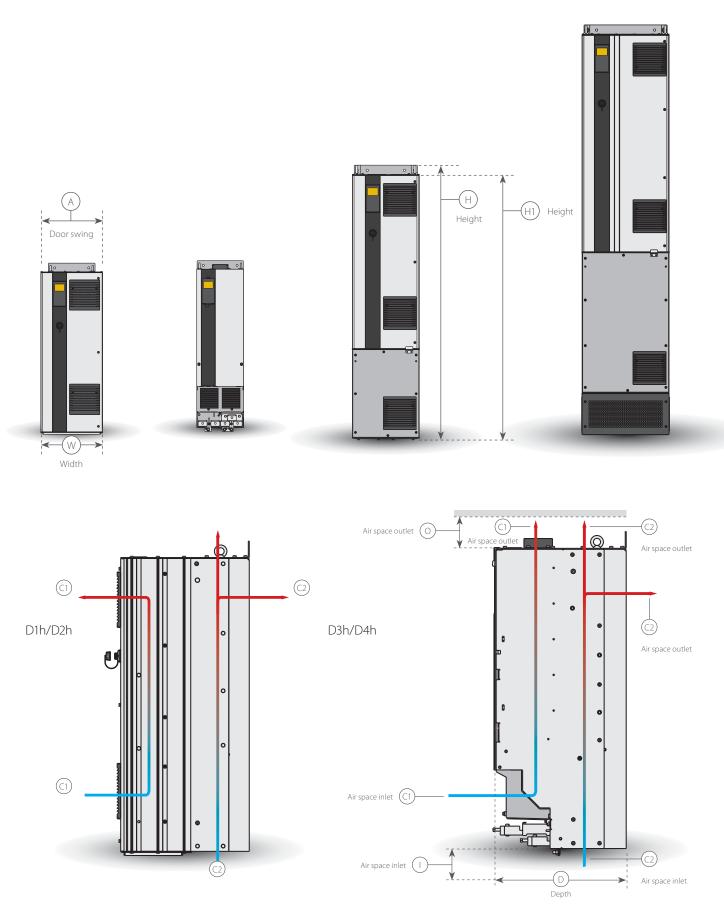
A3 IP20 with option C

A4 IP55 with mains disconnect





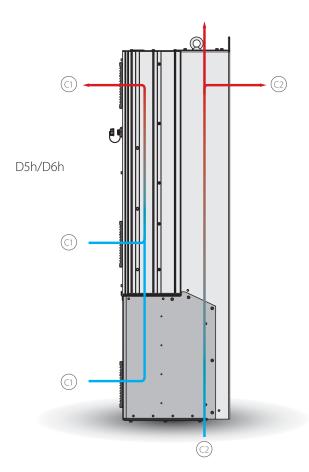
Dimensions and air flow

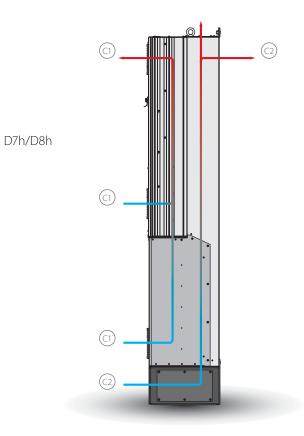


Please see the VLT® High Power Design Guide for other frames, available at http://vlt-drives.danfoss.com/Support/Technical-Documentation-Database/.

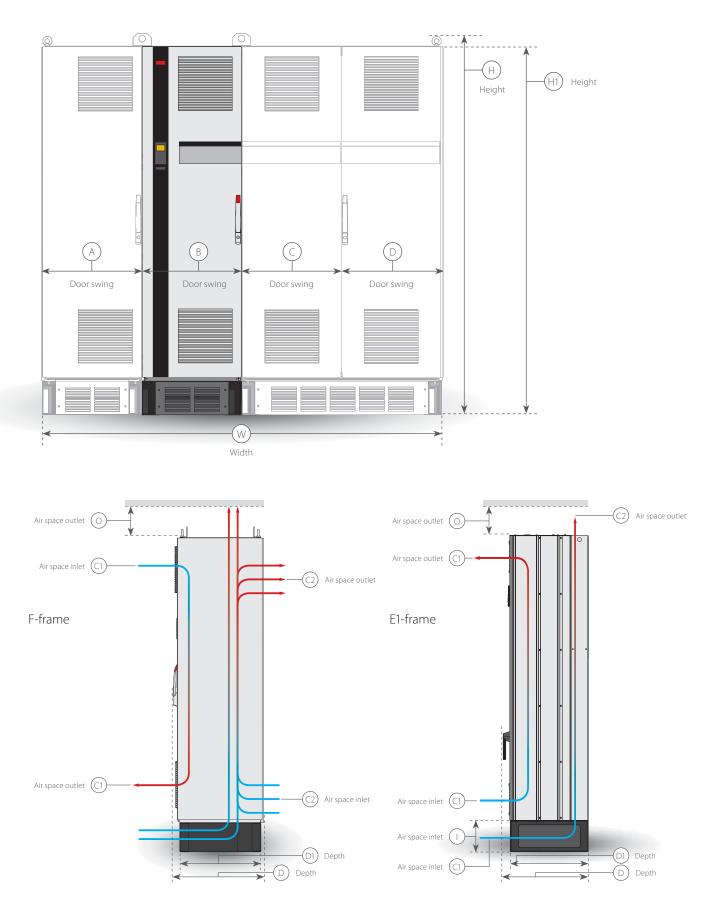
D frames

					VLT [®] AQ	UA Drive				
Fra	me	D1h	D2h	D3h	D4h	D5h	D6h	D7h	D8h	
End	losure	IP21,	/IP54	IP	20		IP21/	/IP54		
H n Hei	nm ght of back plate	901	1107	909	1122	1324	1665	1978	2284	
	mm ght of product	844	1050	844	1050	1277	1617	1931	2236	
Wı	nm	325	420	250	350	325	325	420	420	
Dn	nm	378	378	375	375	381	381	384	402	
	mm h mains disconnect	-	-	-	-	426	426	429	447	
Do	or swing A mm	298	395	n/a	n/a	298	298	395	395	
	l (air space inlet) mm	225	225	225	225	225	225	225	225	
oling	O (air space outlet) mm	225	225	225	225	225	225	225	225	
Air cooling	C1	102 m³/hr (60 cfm)	204 m³/hr (120 cfm)	102 m³/hr (60 cfm)	204 m³/hr (120 cfm)	102 r (60			204 m³/hr (120 cfm)	
	C2	420 m³/hr (250 cfm)	840 m³/hr (500 cfm)	420 m³/hr (250 cfm)	840 m³/hr (500 cfm)	420 r (250		840 m³/hr (500 cfm)		





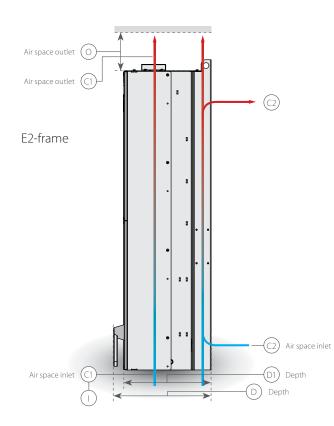
Dimensions and air flow



Please see the VLT® High Power Design Guide for other frames, available at http://vlt-drives.danfoss.com/Support/Technical-Documentation-Database/.

E and F frames

				VLT [®] AQ	UA Drive		
Fra	me	E1	E2	F1	F3	F2	F4
Ene	losure	IP21/IP54	IP00		(F1 + options cabinet)		(F2 + options cabinet)
Hn	nm (inches)	2000 (79)	1547 (61)	2280 (90)	2280 (90)	2280 (90)	2280 (90)
H1	mm (inches)	n/a	n/a	2205 (87)	2205 (87)	2205 (87)	2205 (87)
Wı	nm (inches)	600 (24)	585 (23)	1400 (55)	1997 (79)	1804 (71)	2401 (94)
Dn	nm (inches)	538 (21)	539 (21)	n/a	n/a	n/a	n/a
D1	mm (inches)	494 (19)	498 (20)	607 (24)	607 (24)	607 (24)	607 (24)
Door swing A mm (inches)		579 (23)	579 (23)	578 (23)	578 (23)	578 (23)	578 (23)
Do mn	or swing B n (inches)	n/a	n/a	778 (31)	578 (23)	624 (25)	578 (23)
	or swing C n (inches)	n/a	n/a	n/a	778 (31)	579 (23)	624 (25)
	or swing D n (inches)	n/a	n/a	n/a	n/a	n/a	578 (23)
	l (air space inlet) mm (inches)	225 (9)	225 (9)	n/a	n/a	n/a	n/a
	O (air space outlet) mm (inches)	225 (9)	225 (9)	225 (9)	225 (9)	225 (9)	225 (9)
Air cooling	C1	340 m³/hr (200 cfm)	255 m³/hr (150 cfm)		(412 IP54/N	n³/hr cfm) EMA 12 n³/hr	
	C2	1105 m³/hr (650 cfm) or 1444 m³/hr (850 cfm)	1105 m³/hr (650 cfm) or 1444 m³/hr (850 cfm)		985 r (580	n³/hr cfm)	



Dimension and air flow for VLT® Low Harmonic Drive and VLT® 12-pulse Please see the VLT® High Power Drive Selection Guide.



A options: Fieldbusses

Available for the full product range

Fieldbus

A VLT® PROFIBUS DP V1 MCA 101 VLT® DeviceNet MCA 104 VLT® PROFINET MCA 120 VLT® EtherNet/IPMCA 121 VLT® Modbus TCP MCA 122

VLT[®] PROFIBUS DP MCA 101

Operating the frequency converter via a fieldbus enables you to reduce the cost of your system, communicate faster and more efficiently, and benefit from an easier user interface.

- VLT® PROFIBUS DP MCA 101 provides wide compatibility, a high level of availability, support for all major PLC vendors, and compatibility with future versions
- Fast, efficient communication, transparent installation, advanced diagnosis and parameterisation and auto-configuration of process data via GSD-file
- A-cyclic parameterisation using PROFIBUS DP-V1, PROFIdrive or Danfoss FC profile state machines, PROFIBUS DP-V1, Master Class 1 and 2

Ordering number

130B1100 standard, 130B1200 coated

VLT[®] DeviceNet MCA 104

VLT® DeviceNet MCA 104 offers robust, efficient data handling thanks to advanced Producer/Consumer technology.

- This modern communications model offers key capabilities that let you effectively determine what information is needed and when
- Benefit also from ODVA's strong conformance testing policies, which ensure that products are interoperable

Ordering number

130B1102 standard, 130B1202 coated

VLT[®] PROFINET MCA 120

VLT® PROFINET MCA 120 uniquely combines the highest performance with the highest degree of openness. The MCA120 gives the user access to the power of Ethernet. The option is designed so that many of the features from the PROFIBUS MCA 101 can be reused, minimising user effort to migrate PROFINET, and securing the investment in PLC program.

Other features:

- Built-in web server for remote diagnosis and reading out of basic drive parameters
- Support of DP-V1 Diagnostic allows easy, fast and standardized handling of warning and fault information into the PLC, improving bandwidth in the system

PROFINET encompasses a suite of messages and services for a variety of manufacturing automation applications, including control, configuration and information.

Ordering number

130B1135 standard, 130B1235 coated

VLT® EtherNet/IPMCA 121

Ethernet is the future standard for communication at the factory floor. The VLT® EtherNet/ IPMCA 121 is based on the newest technology available for industrial use and handles even the most demanding requirements. EtherNet/ IPextends commercial off-the-shelf Ethernet to the Common Industrial Protocol (CIP™) – the same upper-layer protocol and object model found in DeviceNet.

- The VLT[®] MCA 121 offers advanced features as:
- Built-in high performance switch enabling line-topology, and eliminating the need for external switches
- Advanced switch and diagnoses functionsBuilt-in web server
- E-mail client for service notification
- Unicast and Multicast communication

Ordering number

130B1119 standard, 130B1219 coated

VLT[®] Modbus TCP MCA 122

Modbus TCP is the first industrial Ethernet based protocol for automation. The VLT® Modbus TCP MCA 122 connects to Modbus TCP based networks. It is able to handle connection interval down to 5 ms in both directions, positioning it among the fastest performing Modbus TCP devices in the market. For master redundancy it features hot swapping between two masters.

Other features:

- Built-in web-server for remote diagnosis and reading out basic drive parameters
- An e-mail notificator can be configured for sending an e-mail message to one or several receivers, if certain warnings or alarms occurs, or has cleared again

Ordering number

130B1196 standard, 130B1296 coated



I/O	Built-in	VLT® General Purpose MCB 101	VLT® Relay Option MCB 105	VLT [®] Analog I/O Option MCB 109	VLT® PTC Thermistor Card MCB 112	VLT® Extended Relay Card MCB 113	VLT® Sensor Input Card MCB 114
Digital inputs	6 1)	+ 3 (0-24 V, NPN/PNP)				+7 (0-24 V, NPN/PNP)	
Digital outputs	2 1)	+ 2 (NPN/PNP)					
Analog inputs	2	+ 2 (0-10 V)		+3 (0-10 V)			+1 (4-20mA)
Analog outputs	1	+1 (0/4-20 mA)		+3 (0-10 V)		+2 (0/4 -20 mA)	
Relays	2		+ 3 (NO/NC)			+4 (NO/NC)	
Real Time Clock Battery back-up				1			
РТС	2)				1 input for up to 3-6 PTCs in series ³⁾		
PT100/PT1000							+3 (2 or 3 wire)

1) 2 Digital Inputs can be configured as outputs

²⁾ Available analogue and digital inputs can be configured as PTC input

3) ATEX-certified protective relay. The relay monitors a PTC-sensor circuit and activates the STO of the drive by opening the control circuits when necessary.

B options: Funcional extensions

Available for the full product range

Funcional extensions

B

VLT® General Purpose MCB 101 VLT® Relay Option MCB 105 VLT® Analog I/O Option MCB 109 VLT® PTC Thermistor Card MCB 112 VLT® Sensor Input Card MCB 114

VLT® Extended Cascade Controller MCO 101

VLT[®] General Purpose I/O **MCB 101**

This I/O option offers an extended number of control inputs and outputs:

- 3 digital inputs 0-24 V: Logic '0' < 5 V; Logic '1' > 10V
 2 analogue inputs 0-10 V:

- Resolution 10 bit plus sign 2 digital outputs NPN/PNP push pull 1 analogue output 0/4-20 mA
- Spring loaded connection

Ordering number

130B1125 standard, 130B1212 coated

VLT[®] Relay Option MCB 105

Makes it possible to extend relay functions with 3 additional relay outputs.

Max. terminal load:

AC-1 Resistive load	
AC-15 Inductive	
load @cos fi 0.4	240 V AC 0.2 A
DC-1 Resistive load	
DC-13 Inductive	
load @cos fi 0.4	

Min. terminal load:

- 10 mA DC 5 V. Max switch rate at rated load/min.load6 min-1/20 sec-1
- Protects control cable connection Spring-loaded control wire connection

Ordering number 130B1110 standard, 130B1210 coated

VLT[®] Analog I/O Option MCB 109

This analogue input/output option is easily fitted in the frequency converter for upgrading to advanced performance and control using the additional in/outputs. This option also upgrades the frequency converter with a battery Ďack-up supply for the frequency converter's built-in clock. This provides stable use of all frequency converter clock functions as timed actions etc.

- 3 analogue inputs, each configurable as both voltage and temperature input
- Connection of 0-10 V analogue signals as well as PT1000 and NI1000 temperature inputs
- 3 analogue outputs each configurable as 0-10 V outputs
- Incl. back-up supply for the standard clock function in the frequency converter

The back-up battery typically lasts for 10 years, depending on environment.

Ordering number

130B1143 standard, 130B1243 coated

VLT® PTC Thermistor Card MCB 112

With the VLT[®] PTC Thermistor Card MCB 112, the VLT[®] AQUA Drive FC 202 enables improved surveillance of the motor condition compared to the built-in ETR function and thermistor terminal

Protects the motor from overheating ATEX approved for use with Ex d and Ex e motors (EX e only FC 302)

Uses Safe Stop function, which is approved in accordance with SIL 2 IEC 61508

Ordering number NA standard, 130B1137 coated

VLT® Sensor Input Card MCB 114

The option protects the motor from being overheated by monitoring the bearings and windings temperature in the motor. Both limits as well action are adjustable, and the individual sensor temperature is visible as a read-out on the display or by fieldbus.

- Protects the motor from overheating
- Three self-detecting sensor inputs for 2 or 3
- wire PT100/PT1000 sensors
- One additional analogue input 4-20 mA

Ordering number

130B1172 standard, 130B1272 coated

VLT® Extended Cascade Controller MCO 101

Easily fitted and upgrades the built-in cascade controller to operate more pumps and more advanced pump control in master/follower mode.

- Up to 6 pumps in standard cascade setup
- Up to 5 pumps in master/follower setup
- Technical specifications: See VLT® Relay Option MCB 105
- Ordering number

130B1118 standard, 130B1218 coated

C options: Cascade controller and relay card

Available for the full product range

Option slot С

VLT® Advanced Cascade Controller MCO 102 VLT® Extended Relay Card MCB 113

VLT[®] Advanced Cascade **Controller MCO 102**

Easy to fit, the VLT® Advanced Cascade Controller MCO 102 upgrades the built-in cascade controller to operate up to 8 pumps and more advanced pump control in master/follower mode.

The same cascade controller hardware goes for for the entire power range up to 2 MW.

- Up to 8 pumps in standard cascade setup
- Up to 8 pumps in master/follower setup

Ordering number

130B1154 standard, 130B1254 coated

VLT[®] Extended Relay Card **MCB 113**

The VLT® Extended Relay Card MCB 113 adds inputs/outputs to VLT® AQUA Drive for increased flexibility.

- 7 digital inputs2 analogue outputs
- 4 SPDT relays
- Meets NAMUR recommendations Galvanic isolation capability

Ordering number

130B1164 standard, 130B1264 coated

D option: External power supply

Available for the full product range

Option slot

D

VLT® 24 V DC Supply Option MCB 107

VLT[®] 24 V DC Supply **MCB 107**

The option is used to connect an external DC supply to keep the control section and any installed option alive during power failure.

Input voltage

range24 V DC +/- 15% (max. 37 V in 10 sec.)	
Max. input current	
Max. cable length	
■ Input capitance load < 10 µF	

	input cupiturice i	000	< 10 ui
l	Power-up delay		< 0.6 s

Ordering number

130B1108 uncoated, 130B1208 coated

64 Danfoss Drives · DKDD.PB.202.A3.02 · VLT® AQUA Drive · 0.25 kW – 2 MW







VLT[®] high power drive kits

Kits to fit your applications	Available on frames
USB in the door kit	D1h, D2h, D3h, D4h, D5h, D6h, D7h, D8h, E1, F
F frame top entry kit motor cables	F
F frame top entry kit mains cables	F
Common motor terminal kits	F1/F3, F2/F4
Adaptor plate	D1h, D2h, D3h, D4h
Back-channel duct kit	D1h, D2h, D3h, D4h, E2
NEMA-3R Rittal and welded enclosures	D3h, D4h, E2
Back-channel cooling kits for non-Rittal enclosures	D3h, D4h
Back-channel cooling kit – in the bottom out the top of the drive	D1h, D2h, D3h, D4h, E2
Back-channel cooling kit – in and out the back of the drive	D1h, D2h, D3h, D4h, E, F
Pedestal kit with in and out the back back-channel cooling	D1h, D2h
Pedestal kit	D1h, D2h, D5h, D6h, D7h, D8h, E1, E2
Input-plate option kit	D, E
IP20 conversion kit	E2
Top entry of fieldbus cables	

USB in the door kit

Available on all frame sizes, this USB extension cord kit allows access to the drive controls via laptop computer without opening the drive. The kits can only be applied to drives manufactured after a certain date. Drives built prior to these dates do not have the provisions to accommodate the kits. Reference the following table to determine which drives the kits can be applied to.

F frame top entry kit motor cables

To use this kit, the drive must be ordered with the common motor terminal option. The kit includes everything to install a top entry cabinet on the motor side (right side) of the F frame VLT[®] drive.

F-frame top entry kit mains cables

The kits include everything required to install a top entry section onto the mains side (left side) of a Danfoss F-frame VLT® frequency converter.

Common motor terminal kits

The common motor terminal kits provide the bus bars and hardware required to connect the motor terminals from the paralleled inverters to a single terminal (per phase) to accommodate the installation of the motor-side top entry kit. This kit is equivalent to the common motor terminal option of a drive. This kit is not required to install the motor-side top entry kit if the common motor terminal option was specified when the drive was ordered.

This kit is also recommended to connect the output of a drive to an output filter or output contactor. The common motor terminals eliminate the need for equal cable lengths from each inverter to the common point of the output filter (or motor).

Adaptor plate

The adaptor plate is used to replace an old Dframe drive with the new D-frame drive using the same mounting.

Back-channel duct kit

Back-channel duct kits are offered for conversion of the D and E frames. They are offered in two configurations – top and bottom venting and top only venting. Available for the D3h, D4h and E2 frames.

NEMA-3R Rittal and welded enclosures

The kits are designed to be used with the IP00/ IP20/Chassis drives to achieve an enclosure rating of NEMA-3R or NEMA-4. These enclosures are intended for outdoor use to provide a degree of protection against inclement weather.

Back-channel cooling kits for non-Rittal enclosures

The kits are designed to be used with the IP20/Chassis drives in non-Rittal enclosures for in and out the back cooling. Kits do not include plates for mounting in the enclosures

Back-channel cooling kit – in

VLT[®] high power drive options

the bottom and out the back of the drive

Kit for directing the back-channel air flow in the bottom of the drive and out the back.

Back-channel cooling kit – in and out the back of the drive

These kits are designed to be used for redirecting the back-channel air flow. Factory backchannel cooling directs air in the bottom of the drive and out the top. The kit allows the air to be directed in and out the back of the drive.

Pedestal kit with in and out the back back-channel cooling

See additional documents 177R0508 and 177R0509.

Pedestal kit

The pedestal kit is a 400 mm high pedestal for the D1h and D2h and 200 mm high for the D5h and D6h frames that allow the drives to be floor mounted. The front of the pedestal has openings for input air to the power components.

Input-plate option kit

Input-plate option kits are available for D and E frames. The kits can be ordered to add fuses, disconnect/fuses, RFI, RFI/Fuses, and RFI/ Disconnect/Fuses. Please consult the factory for kit ordering numbers.

IP20 conversion kit

This kit is for use with the E2 (IP00) frames. After installation, the drive will have an enclosure rating of IP20.

Top entry of fieldbus cables

The top entry kit provides the ability to install fieldbus cables through the top of the drive. The kit is IP20 when installed. If an increased rating is desired, a different mating connector can be used.

Option type	Available on frames
Enclosure with 304 stainless steel back-channel	D, E2, F1-F4, F8-F13
Mains shielding	D1h, D2h, D5h, D6h, D7h, D8h, E1
Space heaters and thermostat	D1h, D2h, D5h, D6h, D7h, D8h, F
Cabinet light with power outlet	F
RFI filters	D, E, F3, F4
Residual Current Device (RCD)	F
nsulation Resistance Monitor (IRM)	F3, F4
Safe Stop with Pilz Safety Relay	F
Emergency Stop with Pilz Safety Relay	F1-F4
Brake Chopper (IGBTs)	D, E, F
Regeneration terminals	D3h, D4h, E, F
Loadsharing terminals	D, E, F
Disconnect	D5h, D7h, E, F3, F4
Circuit breakers	D6h, D8h, F
Contactors	D6h, D8h, F3, F4
Manual motor starters	F
30 Amp, fuse-protected terminals	F
24 VDC power supply	F
External temperature monitoring	F

Enclosure with 304 stainless steel back-channel

For additional protection from corrosion in harsh environments, units can be ordered in an enclosure that includes a stainless steel back-channel, heavier plated heatsinks and an upgraded fan.

This option is recommended in salt-air environments near the ocean.

Mains shielding

Lexan[®] shielding mounted in front of incoming power terminals and input plate to protect from accidental contact when the enclosure door is open.

Space heaters and thermostat

Mounted on the cabinet interior of D and F frames, space heaters controlled via automatic thermostat prevents condensation inside the enclosure.

The thermostat default settings turn on the heaters at $10^{\circ}C$ (50° F) and turn them off at $15.6^{\circ}C$ (60° F).

Cabinet light with power outlet

A light can be mounted on the cabinet interior of F frames to increase visibility during servicing and maintenance. The light hous-

ing includes a power outlet for temporarily powering laptop computers or other devices. Available in two voltages:

230 V, 50 Hz, 2.5 A, CE/ENEC

120 V, 60 Hz, 5 A, UL/cUL

RFI filters

VLT® Series drives feature integrated Class A2 RFI filters as standard. If additional levels of RFI/EMC protection are required, they can be obtained using optional Class A1 RFI filters, which provide suppression of radio frequency interference and electromagnetic radiation in accordance with EN 55011.

On F-frame drives, the Class A1 RFI filter requires the addition of the options cabinet. Marine use RFI filters are also available.

Residual Current Device (RCD)

Uses the core balance method to monitor ground fault currents in grounded and high-resistance grounded systems (TN and TT systems in IEC terminology). There is a pre-warning (50% of main alarm set-point) and a main alarm set-point. Associated with each setpoint is an SPDT alarm relay for external use. Requires an external "window-type" current transformer(supplied and installed by customer).

- Integrated into the drive's safe-stop circuit IEC 60755 Type B device monitors, pulsed DC, and pure DC ground fault currents
- LED bar graph indicator of the ground fault current level from 10-100% of the setpoint
- Fault memory
 TEST / RESET button

Insulation Resistance Monitor (IRM)

Monitors the insulation resistance in ungrounded systems (IT systems in IEC terminology) between the system phase conductors and ground. There is an ohmic pre-warning and a main alarm setpoint for the insulation level. Associated with each setpoint is an SPDT alarm relay for external use. Note: only one insulation résistance monitor can be connected to each ungrounded (IT) system.

- Integrated into the drive's safe-stop circuit
- LCD display of insulation resistance
- Eault memory
- INFO, TEST, and RESET buttons

Safe Stop with **Pilz Safety Relay**

Available on F frame. Enables the Pilz Relay to fit in the F frames without requiring an option cabinet. The Relay is used in the external temperature monitoring option. If PTC monitoring is required, the MCB 112 PTC thermistor option must be ordered.

Emergency Stop with Pilz Safety Relay

Includes a redundant 4-wire emergency-stop pushbutton mounted on the front of the enclosure and a Pilz relay that monitors it in conjunction with the drive's safe-stop circuit and contactor position. Requires a contactor and the F frame options cabinet.

Brake Chopper (IGBTs)

Brake terminals with an IGBT brake chopper circuit allow for the connection of external brake resistors. For detailed data on brake resistors

Regeneration terminals

Allow connection of regeneration units to the DC bus on the capacitor bank side of the DC-link reactors for regenerative braking. The F-frame regeneration terminals are sized for approximately 1/2 the power rating of the drive. Consult the factory for regeneration power limits based on the specific drive size and voltage.

Loadsharing terminals

These terminals connect to the DC-bus on the rectifier side of the DC-link reactor and allow for the sharing of DC bus power between multiple drives. The F-frame loadsharing terminals are sized for approximately 1/3 the power rating of the drive. Consult the factory for loadsharing limits based on the specific drive size and voltage.

Disconnect

A door-mounted handle allows for the manual operation of a power disconnect switch to enable and disable power to the drive, increasing safety during servicing. The disconnect is interlocked with the cabinet doors to prevent them from being opened while power is still applied.

Circuit breakers

A circuit breaker can be remotely tripped but must be manually reset. Circuit breakers are interlocked with the cabinet doors to prevent them from being opened while power is still applied. When a circuit breaker is ordered as an option, fuses are also included for fast-acting current overload protection of the variable frequency drive.

Contactors

An electrically controlled contactor switch allows for the remote enabling and disabling of power to the drive. An auxiliary contact on the contactor is monitored by the Pilz Safety if the IEC Emergency Stop option is ordered.

Manual motor starters

Provide 3-phase power for electric cooling blowers often required for larger motors. Power for the starters is provided from the load side of any supplied contactor, circuit breaker, or disconnect switch and from the input side of the Class 1 RFI filter (if an RFI filter option is ordered). Power is fused before each motor starter, and is off when the incoming power to the drive is off. Up to two starters are allowed (one if a 30-amp, fuse-protected circuit is ordered). Integrated into the drive's safe-stop circuit.

Unit features include:

- Operation switch (on/off)
 Short-circuit and overload protection with test function
- Manual reset function

30 Amp, fuse-protected terminals

- 3-phase power matching incoming mains voltage for powering auxiliary customer equipment
- Not available if two manual motor starters are selected
- Terminals are off when the incoming power to the drive is off
- Power for the fused protected terminals will be provided from the load side of any sup-plied contactor, circuit breaker, or disconnect switch and from the input side of the Class 1 RFI filter (if a RFI filter is ordered as an option).

24 VDC power supply

- 5 Amp, 120 W, 24 VDC
- Protected against output overcurrent, overload, short circuits, and overtemperature
- For powering customer-supplied accessory devices such as sensors, PLC I/O, contactors, temperature probes, indicator lights, and/or
- other electronic hardware
 Diagnostics include a dry DC-ok contact, a green DC-ok LED, and a red overload LED

External temperature monitoring

Designed for monitoring temperatures of external system components, such as the motor windings and/or bearings. Includes eight universal input modules plus two dedicated thermistor input modules. All ten modules are integrated into the drive's safe-stop circuit and can be monitored via a fieldbus network (requires the purchase of a separate module/ bus coupler). A Safe Stop brake option must be ordered to choose External temperature monitoring.

Universal inputs (5)

- Signal types RTD inputs (including Pt100), 3-wire or
- 4-wire
- Thermocouple
- Analogue current or analog voltage

Additional features:

- One universal output, configurable for analog voltage or analogue current
- Two output relays (N.O.)
- Dual-line LC display and LED diagnostics Sensor lead wire break, short-circuit, and incorrect polarity detection
- Interface setup software
- If 3 PTC are required, MCB112 control card option must be added.
- Additional external temperature monitors: This option is provided in case you need more than the MCB114 and MCB 112 provides.

Accessories

Available for the full product range

LCP
VLT® Control Panel LCP 101 (Numeric) Ordering number: 130B1124
VLT® Control Panel LCP 102 (Graphical) Ordering number: 130B1107
LCP Panel Mounting Kit Ordering number for IP20 enclosure 13081113: With fasteners, gasket, graphical LCP and 3 m cable 13081114: With fasteners, gasket, numerical LCP and 3 m cable 13081117: With fasteners, gasket and without LCP and with 3 m cable 13081170: With fasteners, gasket and without LCP
Ordering number for IP55 enclosure 130B1129: With fasteners, gasket, blind cover and 8 m "free end" cable
Power Options*
VLT [®] Sine-Wave Filter MCC 101
VLT® dU/dt Filter MCC 102
VLT® Common Mode Filters MCC 105
VLT® Advanced Harmonic Filter AHF 005/010
VLT® Brake Resistors MCE 101
Accessories
Profibus SUB-D9 Adapter IP20, A2 and A3
Ordering number: 130B1112
Option Adapter Ordering number: 130B1130 standard, 130B1230 coated
Adapter Plate for VLT® 3000 and VLT® 5000 Ordering number: 130B0524 – to be used only for IP20/NEMA type 1 units up to 7.5 kW
USB Extension Ordering number: 130B1155: 350 mm cable 130B1156: 650 mm cable
IP21/Type 1 (NEMA 1) kit Ordering number 13081122: For frame size A1 13081123: For frame size A2 13081183: For frame size B3 13081189: For frame size B4 13081191: For frame size C3 13081193: For frame size C4
NEMA 3R outdoor weather shield Ordering number 176F6302: For frame size D1h 176F6303: For frame size D2h
NEMA 4X outdoor weather shield Ordering number 13084598: For frame size A4, A5, B1, B2 13084597: For frame size C1, C2
Motor connector Ordering number: 130B1065: frame A2 to A5 (10 pieces)
Mains connector Ordering number: 13081066: 10 pieces mains connectors IP55 13081067: 10 pieces mains connectors IP20/21
Relays 1 terminal Ordering number: 130B1069 (10 pieces 3 pole connectors for relay 01)
Relays 2 terminal Ordering number: 130B1068 (10 pieces 3 pole connectors for relay 02)
Control card terminals Ordering number: 13080295 VLT® Leakage Current Monitor Module RCMB20/RCMB35 Ordering number: 13085764: A2-A3 13085764: B3 13085765: B4 13085765: C3 13085764: C4
*Ordering number: See relevant Design Guide



Ordering typecode

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		JA Drive FC 20	n			S2			V AC (1.					R5X	IP54/Typ light and	be 12 with LIEC	space he	ater, the	rmostat,
		haracter 7-10)	2			T2			V AC (0.2						230 V po	wer outlet	t (F frame	only)	
	0.25 kW/					54			V AC (0.2							pe 1 with s	pace hea	ter, therr	nostat,
	0.37 kW/					T4			V AC (0.					R2A	light and 115 V pov	i NAM, wer outlet	(F frame	only)	
	0.55 kW/					T6			V AC (0.)						ID54 /Tur	pe 12 with	space be	ator the	rmostat
	0.75 kW/					Τ7			V AC (11					R5A	light and	INAM,		,	mostat,
P1K1	1.1 kW/1	.5 HP			1	4] Enc	losur	e (chard	acter 13-1	15)					1	wer outlet	(F frame)	oniy)	
P1K5	1.5 kW/2	2.0 HP			I	For cab	binet I	mounti	ing:					Specia	l designs:				
P2K2	2.2 kW/3	8.0 HP				E00		/Chassis	5					E5S		Ready IP5 cover (D1			th the
РЗКО	3.0 kW/4	I.O HP				LUU	(fram	ne E2)						P20		ne B4, C3, (te)
P3K7	3.7 kW/5	5.0 HP				C00			s with sta el (frame		teel				IP21/Tvp	pe 1 with n	nains shie	اط	
P4K0	4.0 kW /	5.5 HP						/Chassis		,				E2M	(frame D	1h, D2h, D v Harmoni	5h, D6h, I	D7h, D8h	ı, E1,
P5K5	5.5 kW/7	7.5 HP				E20			, 3, B3, B4	, C3, C4,	D3h, D4	1h)					c Drive D	IS + E9)	
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	11 kW/1					50.			(frame						IP54/Typ	be 12 with	mains sh	ield	
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	30 kW/4 37 kW/5					E2D			Dh1 fra	me)/55	IP55				
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	55 kW/7					C20	IP20,	/Chassi	s					Y66	IP66/NEN				
	75 kW/1					C2S	IP20,	/Chassi	s + Stair	nles						s Z66 – wit	,	-	
	90 kW/1					P3R	NEM.	A 3R wi	ith back	plate (U.	S only)					minal and 00-3 (chai			tions
	75 kW/1										2h, D5h,	D6h, D7	h,	1.14	RFI-Filter	Class A1/E	3 (C1)		
N90K	90 kW/1	25 HP				E54			F1, F2, F armonic		13 F9 F1	18)		H1		C frames o			
N110	110 kW/	150 HP				E55			A5, B1, B			,		H2	RFI-Filter,	, Class A2 (C3)		
N132	132 kW/	200 HP							X outdo		-/			H3		Class A1/E C frames o			
N160	160 kW/	250 HP				E66			1, B2, C1										
N200	200 kW/	300 HP				Z55	IP55/	/Type 12	2 (frame	A4)				H4		, Class A1 (nd F frames			
N250	250 kW/	350 HP				Z66	IP66/	/NEMA ·	4X (fram	e A4)				H5	RFI-Filter,	, Class A2 (C3)		
N315	315 kW/	450 HP				H21			with sp (F frame		ter and			сп	Marine ru	uggedized			
	315 kW/													HG		T mains wi 1, F2, F3, F4		A2 RFI	
	355 kW/					H54			2 with s <i>(F frame</i>		ater and	1							זרו
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	450 kW/					L2X	IEC 2	230 V pc	ower out	tlet (F fra	ime only)		ΗX	No RFI-Fi	lter			
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P560 P630												/				1, F2, F3, F4			
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P800						L5A	IP54,	/Type 1	2 with c	abinet l	ight and	ł		VLT®1		onic Drive	,		
	900 kW/					LJA	NAM	1, 115 V _I	power o	utlet (F	frame or	nly)				v Harmoni		ctive filte	er
	1.0 MW/					DDV		/Type 1		ace hea	ter, ther	mostat,		N2		ith Class A		cave mite	
P1M2						R2X			r outlet	(F frame	only)			N4		v Harmoni		ctive filte	≥r
P1M4	1.4 MW/	1900 HP													based wi	ith Class A	t RFI		

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LT® 1	2-Pulse F8	s, F9, F10, F11, F12	2, F13 frames				Euror	and la	oad sha	ving to	rmina	le			J	E	External t	emperat	ure moni	toring	
B2	12-Pulse	with Class A2 RFI			_	А			0 and F.				only)		K	. (Commor	motor te	erminals		
B4	12-Pulse	with Class A1 RFI													L	5	5 A 24 V s	upply + a	ommon	motor te	erminals
BE	12-Pulse	with RCD/A2 RFI	l		_	D	Load (B1, B,	sharin 2, C1, C	g termi 2. D-fra	inals 1 <i>me onl</i>	lv IP20	and F.	3, F4, F9,		М			emperat	ure moni	toring +	commo
BF	12-Pulse	with RCD/A1 RFI					F11, F	14, F18 f	frames	only)	-					r	notor ter				
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6] Bra	aking and	safety (character	r 18)			4			actor +							_		eased sta			
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В	Brake IGE	3T							nnect -			⊢ fuse			[19]			language		a includi	na
С	Safe Stop (frame F1	with Pilz Safety I, F2, F3, F4)	Relay			E	(D, E c	and F3,	F4, F9, I	F11, F14,			nly)		Х	E	nglish, G	ierman, F nnish anc	rench, Sp	anish, D	anish,
D	Safe Stop and brak	with Pilz Safety	Relay			J			ker + fu <i>F4, F9, I</i>		, F18 fra	ame or	nly)		Con	ntact	factory	^f or other	languag	e optior	is
		I, F2, F3, F4)			_	F			it break				uses		[14]	Fiel	dbus (ch	aracter 29	-30)		
	Safe Stop	with Pilz Safety	Relay and						11, F14, F						A>	X N	lo optio	٦			
E		ition terminals			_	G			nnect, nd fuse		tor, lo	adshai	ring		AC) (/LT® PRO	FIBUS DP	V1 MCA	101	
Т		without brake			_	0			11, F14, F		ne only)			A4	4 \	/LT® Dev	iceNet M	CA 104		
R		ation terminals (E) and E frama a	ophy					it break		itactor	, loads	haring		AL			FINET MC			
S	5	ation terminals (2			_	Н			nd fuse: 11, F14, F		ne onlv	<i>(</i>)			AN			rNet/IPN			
U	5	BT plus Safe Stop	nu biake chop	pper			. ,					,			AC			lbus TCP			
	, F18 frame				_	К			it break 1 <i>1, F14, F</i>				uses					1 (charad			
		gency Stop Push	button			т	Cable	e conne	ection	cabine	t				BX			ation op			
Μ		Pilz Relay)	button			I		ıme onl							Bk			eral Purp			
	IEC Emer	gency Stop Push	button with b	orake	_	W			ection	cabine	t and f	fuse			BF			y Option			
Ν	IGBT and	brake terminals Pilz Safety Relay)				[4 0] I I		ıme onl <u>j</u>		• 1					BC			og I/O O			
					- 1		_		ion A (ter 22)				B2			Thermist			
Р		gency Stop Push ition terminals	button with			X			ble ent						B4			sor Input			
		Pilz Safety Relay)				O S			e entrie	25					BY		/LI®Exte //CO 101	nded Ca	scade Co	ntroller	
7] LC	P Display ((character 19)			- 1		_	able en	itnes F11, F12	D E12 a	and E1	0 fram			[16]	App	lication	2 (charad	ter 33-34))	
Х	Blank face	eplate, no LCP ins	stalled			г 1, г 2 , Е		, ,	rotecte	,			ies.		Х		lo optio				
Ν	Numerica	al Local Control Pa	anel (LCP 101)						rotecte				and		-	١	/LT® Adv	anced Ca	scade Co	ntroller	
G	Graphica	l Local Control Pa	inel (LCP 102)		_	F			nual mo			1111015 0	anu		5	Ν	ACO 102				
) fran	nes IP21/54	•				G			rotecte			ninals a	and		R			nded Rel	·		
J	No Local	Control Panel + l	JSB through de	loor		G	4-6.3	A man	nual mo	otor sta	rter				[19]] Con	trol Pow	ver Back	ıp Input	(charact	er 38-39)
Κ	Numerica + USB thr	al Local Control Pa rough door	anel (LCP 101)			Н	30 A f 6.3-10	fuse pr 0 A ma	rotecte nual m	d powe	er tern arter	ninals	and					out instal DC Supp		MCB 10	17
L		l Local Control Pa rough door	inel (LCP 102)			J			rotecte nual mo			ninals	and					cable len		I WICD IC	1
8] PC	B Coating	– IEC 721-3-3 (c	haracter 20)			К	Two 2	2.5-4 A	manua	al moto	or start	ers			Plea	co ho	ware the	t not all	omhina	tions	
Х		coated PCB Class				L	Two	4-6.3 A	manua	al moto	or start	ters			are p	oossil	ole. Find	help con	figuring y		e with t
С	Coated P	CB Class 3C3				М	Two 6	5.3-10 A	A manu	ual mot	tor star	rters					nfigurato ig.danfo	or found ss.com	inder:		
R	Coated P	CB Class 3C3 + ru	uggedized			Ν	Two 1	10-16 A	manu	al moto	or star	ters									
9] Ma	ins input	(character 21)				[11] H	ardwai	re opti	ion B (d	charact	ter 23)										
Х	No mains	s option				Х	No ad	daptati	on												
1	Mains dis					Q	Heat-	sink ac	cess pa	anel (D	frame	only)									
		1, B2, C1 and C2 fro				F1, F2	F3, F4,	, F10, F	F11, F12	2, F13 a	and F1	8 fran	nes:								
7		E and F frame onl				G			ply (cu												
8		sconnect and load 1 and C2 frames or					exter	nal ten	nperati	ure mo	nitorir	ng									

- 8 Mains disconnect and load sharing (B1, B2, C1 and C2 frames only)
- H 5 A 24 V supply (customer use)



ENGINEERING TOMORROW



The Danfoss water world

In a competitive world nothing beats know how and experience

Danfoss has produced more than 10 million drives over the last 45 years. We are now among the world's top three low voltage drive producers and are the world's largest dedicated drive provider. We're a solid company you can trust to deliver. As the first company to ever produce a dedicated VLT® AQUA Drive, we have a wealth of know how and experience to share with our customers in the demanding water and wastewater segments.

Freedom of choice

Our philosophy has always been to be motor independent, so you are free to select not only the best drive, but also the best motor on the market. This philosophy has recently resulted in the major benefits of our unique VVC+ technology for high speed PM motor applications, which are increasingly being used to maximize blower efficiency.

Quality for a longer life

Quality has always been a corner stone for Danfoss. With AQUA Drives the design rule has always been to only load components to 80% of their maximum tolerance. Combine this with a unique cooling system which reduces dust and contamination by a factor of 10, and you get a drive that offers you extremely high reliability and a longer life.

Factory tested for reliability

Because our reputation is based on reliability, we test our drives like noone else: Each single VLT® AQUA Drive is connected to a motor and real-life tested 100%, so you can be confident that it will work on commission.

Local backup – globally

VLT® motor controllers operate in applications all over the world and Danfoss Drives' experts located in more than 100 countries are ready to support you with application advice and service wherever you may be. Danfoss Drives' experts won't stop until your drive challenges are solved.



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