



#### **Key Features:**

- +15 to 40VDC Supply Voltage
- H-Bridge, 2 Phase Bi-polar Micro-stepping Drive
  - Suitable for 2-phase, 4, 6 and 8 leads step motors, with Nema size 11 to17
- Output current selectable from 0.21 ~ 1.5A peak
  - Compact credit card size package
- Optically isolated single ended TTL inputs for Pulse, Direction and Enable signal inputs
- Selectable resolutions up to 12800 steps
- Over Voltage, Coil to Coil and Coil to Ground short circuit protection.

#### Introduction

2M415 is a bi-polar two-phase micro-stepping drive in a compact credit card size package. It is design for ultimate performance at a very cost efficient operation. It is best suited for two phase small size motor, which requires very little current, to deliver good speed and torque result. The single ended Pulse, Direction and Enable inputs with Opto-coupler pull up, interface perfectly with majority of the PLC output or PLC motion controller, shortening set up time.

With an automatic optimization speed control technique, the EDRIVE series drive output is very stable, with almost zero vibration and noise, performing close to a servo system, allowing the motor to operate smoothly. That helps to fulfill a design requirement of low noise, low heat and high performance.

Parameters	Min	Typical	Max	Unit
Output Current (Peak)	0.21	-	1.5	Amps
Supply voltage	15	36	40	VDC
Logic Input Current	7	10	16	mA
Pulse input frequency	0	-	200	KHz
Low Level Time	2.5			μsec

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Cooling	Natural Cooling or Forced Convection		
	Space	Avoid dust, oil frost and corrosive gases	
Environment	Ambient Temperature	0°C – 50°C	
	Humidity	40 – 80%RH	
	Vibration	5.9m/s <sup>2</sup> Max	
Storage Temp.	-10°C - 80°C		
Weight	Approx. 150 gram		



# Mechanical Dimensions (mm)





## **Current Setting**

Current Setting (A)	SW1	SW2	SW3
0.21	OFF	ON	ON
0.42	ON	OFF	ON
0.63	OFF	OFF	ON
0.84	ON	ON	OFF
1.05	OFF	ON	OFF
1.26	ON	OFF	OFF
1.50	OFF	OFF	OFF

### **Microstep Setting**

Step / Rev	SW4	SW5	SW6
200	ON	ON	ON
400	OFF	ON	ON
800	ON	OFF	ON
1600	OFF	OFF	ON
3200	ON	ON	OFF
6400	OFF	ON	OFF
12800	ON	OFF	OFF



### **P1 Terminal Assignment**

Signal	<b>Function and Descriptions</b>
PUL	Pulse or Step Input TTL single ended input with high-going pulse, 1.5 μs min width. For +12V or +24V operation, a current limiting resistor had to be pull up or connected in series between the PUL input and the controller pulse output
DIR	<u>Direction Input</u> Logic High = positive (CW) rotation— $4.0 \sim 5.0V$ Logic Low = negative (CCW) rotation— $0 \sim 0.5V$ The DIR signal must be stable for at least 5ms before the drive receives the first pulse.
ENA	Enable Input Logic High = Drive Enabled Logic Low = Drive Disabled This input, if left unconnected, is recognized as Logic High by the drive, and it will be enabled.
ОРТО	Opto-Coupler pull-up voltage for PUL, DIR and ENA signals. Typical voltage is +5VDC.

## **P2 Terminal Assignment**

P2 Signal	Function and Descriptions
GND	DC Power Ground
+V	DC Power Supply, +15VDC ~ +40VDC
A+, A-	$A^{+} \longrightarrow A^{+} \longrightarrow A^{+$
	 B+ B- B+ NCB- B+ B-
	4 Leads Motor Full Coil Half Coil
	6 Leads Motor
B+, B-	$A^{+} \longrightarrow M \qquad A^{+} \longrightarrow M \qquad A^{+$
	<b>        ⊢</b> →   B+ B- B+ B-
	Series Parallel
	8 Leads Motor

#### Wiring

rive



Note : **R=0** if VCC=**5**V **R=1K**(Power>0.125W) if VCC=**12V**; **R=2K**(Power>0.125W) if VCC=**24V**; R must be connected to control signal terminal.