

# RCS2-SA4C

ROBO Cylinder, Slider Type, Actuator Width 40mm, 200-V Servo Motor, Coupled

Model Specification Items	<b>RCS2</b>	<b>SA4C</b>	<input type="checkbox"/>	<b>20</b>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
	Series	Type	Encoder type	Motor type	Lead	Stroke	Applicable controller	Cable length	Options
			I: Incremental A: Absolute	20: Servo motor, 20W	16: 16mm 10: 10mm 5: 5mm 2.5: 2.5mm	50: 50mm ? 400: 400 mm (50mm pitch increments)	T1: XSEL-J/K T2: SCON MSCON SSEL XSEL-P/Q XSEL-R/S	N: None P: 1m S: 3m M: 5m X <input type="checkbox"/> : Custom length R <input type="checkbox"/> <input type="checkbox"/> : Robot cable	See Options below.

\* See page Pre-47 for details on the model descriptions.



\*CE compliance is optional.

**For High Acceleration/Deceleration**

(excluding the 2.5-mm lead model)



\*This product is equipped with a position adjusting screw at the A area shown above. (See dimensional drawing on the page to the right.)

- POINT**  
Notes on selection
- (1) When the stroke increases, the maximum speed will drop to prevent the ball screw from reaching the critical rotational speed. Use the actuator specification table below to check the maximum speed at the stroke you desire.
  - (2) The load capacity is based on operation of the standard model at 0.3G (0.2G for 2.5mm-lead), and the high acceleration/deceleration model at 1G (excluding the 2.5mm-lead model). (Even when the acceleration/deceleration is dropped, the maximum load capacity values shown in the table below are the upper limits.)
  - (3) See page A-71 for details on push motion.

### Actuator Specifications

#### Leads and Payloads

Model number	Motor output (W)	Lead (mm)	Maximum payload		Rated thrust (N)	Stroke (mm)
			Horizontal (kg)	Vertical (kg)		
RCS2-SA4C-①-20-16-②-③-④-⑤	20	16	2.5	0.6	12.25	50 to 400 (every 50mm)
RCS2-SA4C-①-20-10-②-③-④-⑤		10	4	1	19.6	
RCS2-SA4C-①-20-5-②-③-④-⑤		5	6	2.5	39.2	
RCS2-SA4C-①-20-2.5-②-③-④-⑤		2.5	8	4.5	78.4	

#### Stroke and Maximum Speed

Stroke Lead	50~400 (every 50mm)	
	16	1060
10	665	
5	330	
2.5	165	

Code explanation ① Encoder type ② Stroke ③ Applicable Controller ④ Cable length ⑤ Options \*See page A-71 for details on push motion. (Unit: mm/s)

#### ① Encoder Type / ② Stroke

② Stroke (mm)	Standard price	
	① Encoder type	
	Incremental <b>I</b>	Absolute <b>A</b>
50	—	—
100	—	—
150	—	—
200	—	—
250	—	—
300	—	—
350	—	—
400	—	—

#### ④ Cable Length

Type	Cable symbol	Standard price
Standard type	<b>P</b> (1m)	—
	<b>S</b> (3m)	—
	<b>M</b> (5m)	—
Special length	<b>X06</b> (6m) ~ <b>X10</b> (10m)	—
	<b>X11</b> (11m) ~ <b>X15</b> (15m)	—
	<b>X16</b> (16m) ~ <b>X20</b> (20m)	—
	<b>R01</b> (1m) ~ <b>R03</b> (3m)	—
Robot cable	<b>R04</b> (4m) ~ <b>R05</b> (5m)	—
	<b>R06</b> (6m) ~ <b>R10</b> (10m)	—
	<b>R11</b> (11m) ~ <b>R15</b> (15m)	—
	<b>R16</b> (16m) ~ <b>R20</b> (20m)	—

\* See page A-59 for cables for maintenance.

#### ⑤ Options

Name	Option code	Page	Standard Price
Brake	<b>B</b>	→ A-42	—
CE compliance	<b>CE</b>	→ A-42	—
Foot bracket	<b>FT</b>	→ A-47	—
For High Acceleration/Deceleration	<b>HA</b>	→ A-50	—
Home sensor	<b>HS</b>	→ A-50	—
Non-motor end specification	<b>NM</b>	→ A-52	—
Slider Roller specification	<b>SR</b>	→ A-55	—
Slider spacer	<b>SS</b>	→ A-55	—

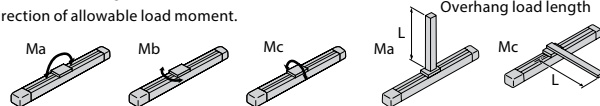
\* The high-acceleration/deceleration option and the slider roller option cannot be used together.  
\* The high-acceleration/deceleration option cannot be used on the 2.5mm-lead model.

#### Actuator Specifications RCS3P specifications are shown in []. (Other items are the same.)

Item	Description
Drive method	Ball screw, ø8mm, rolled C10
Positioning repeatability	±0.02mm
Lost motion	0.1mm or less
Base	Material: Aluminum, white alumite treatment
Allowable static moment	Ma: 6.9 N·m, Mb: 9.9 N·m, Mc: 17.0 N·m
Allowable dynamic moment (*)	Ma: 2.7 N·m, Mb: 3.9 N·m, Mc: 6.8 N·m
Overhang load length	Ma direction: 120mm or less Mb/Mc directions: 120mm or less
Ambient operating temperature/humidity	0 to 40°C, 85% RH max. (Non-condensing)

(\*) When the traveling life is assumed as 5,000km.

Direction of allowable load moment.



Dimensional Drawings

CAD drawings can be downloaded from the website.

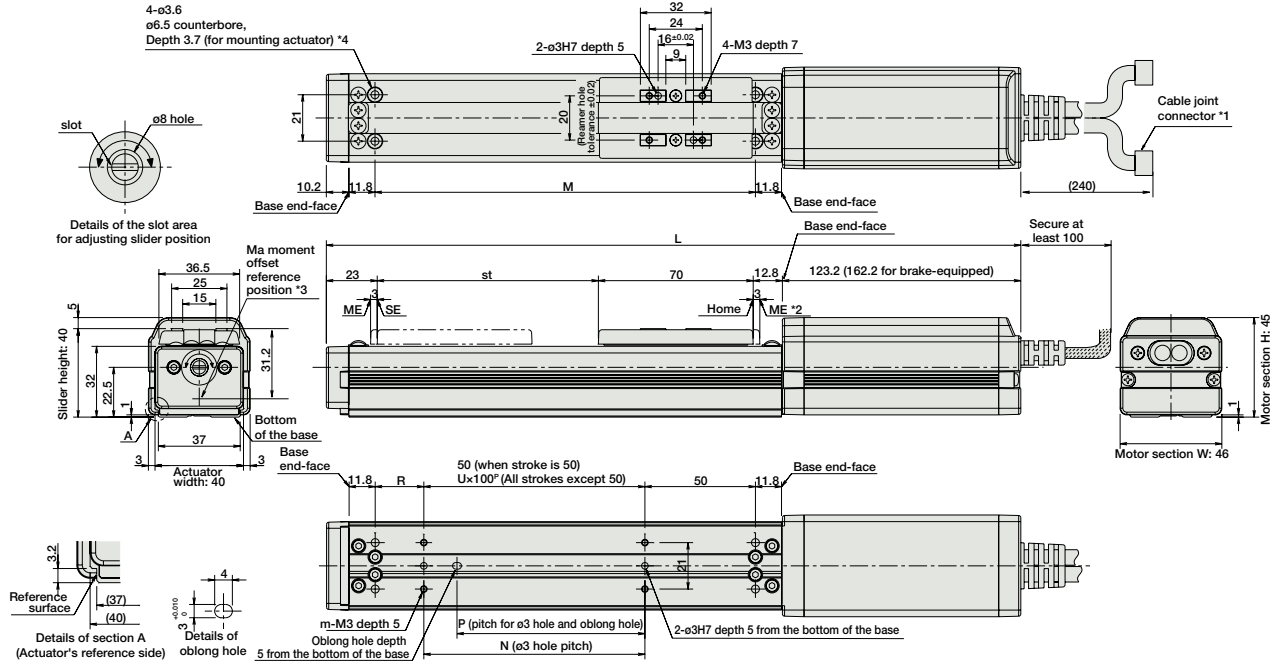
[www.intelligentactuator.com](http://www.intelligentactuator.com)

For Special Orders

Appendix P.15



- (\*1) Connect the motor and encoder cables here. See page A-59 for details on cables.
- (\*2) After homing, the slider moves to the ME, therefore, please watch for any interference with surrounding objects.  
ME : Mechanical end  
SE : Stroke end
- (\*3) Reference position for calculating the Ma moment
- (\*4) If the actuator is secured using only the mounting holes provided on the top surface of the base, the base may twist to cause abnormal sliding of the slider, or may produce abnormal noise. Therefore, when using the mounting holes on the top surface of the base, keep the stroke at 200mm or less.



■ Dimensions and Weights by Stroke \* Brake-equipped models are heavier by 0.3kg.

Stroke	50	100	150	200	250	300	350	400
L	without brake	279	329	379	429	479	529	579
	with brake	318	368	418	468	518	568	618
M	122	172	222	272	322	372	422	472
N	35	100	150	200	250	300	350	400
P	22	134	184	234	284	334	384	434
R	8	8	10	10	12	12	14	14
U	—	1	1	2	2	3	3	4
m	4	4	4	6	6	8	8	10
Weight (kg)	0.7	0.8	0.9	1	1.1	1.2	1.3	1.4

③ Applicable Controllers

RCS2-series actuators can be operated with the following controllers. Select an appropriate controller type according to your application.

Name	External view	Model number	Features	Maximum number of positioning points	Input power	Power supply capacity	Standard price	Reference page
Positioner mode		SCON-CA-20①②③-NP-2-④⑤	Up to 512 positioning points are supported.	512 points	Single-phase 100VAC	106 VA max.	—	→ P643
Solenoid valve mode			Actuators can be operated through the same control used for solenoid valves.	7 points				
Field network type			Movement by numerical specification is supported.	768 points				
Pulse-train input control type			Dedicated pulse-train input type	(—)				
Positioner multi-axis, network type		MSCON-C-1-20①②③-④⑤-0-⑥⑦	Up to 6 axes can be operated. Movement by numerical specification is supported.	256 points	3-phase 200VAC (XSEL-P/Q/R/S ONLY)	*Power supply capacity will vary depending on the controller, so please refer to the instruction manual for details.	—	→ P655
Program control type, 1 to 2 axes		SSEL-CS-1-20①②③-NP-2-④⑤	Program operation is supported. Up to 2 axes can be operated.	20,000 points	—		—	→ P685
Program control type, 1 to 8 axes		XSEL-④⑤-1-20①②③-N1-EEE-2-④⑤	Program operation is supported. Up to 8 axes can be operated.	Varies depending on the number of axes connected	—		—	→ P695

\* This is for the single-axis MSCON, SSEL, and XSEL. \* ① indicates the encoder type (I: Incremental / A: Absolute). \* Enter the code "HA" in ④ when the high-acceleration/deceleration option is specified.  
 \* ② indicates the power-supply voltage type (1: 100V / 2: Single-phase 200V). \* ③ indicates the XSEL type (J / K / P / Q / R / S).  
 \* ④ indicates the power-supply voltage type (1: 100V / 2: Single-phase 200V / 3: Three-phase 200V). \* ⑤ indicates field network specification symbol.

Slider Type

Mini

Standard

Controllers Integrated

Rod Type

Mini

Standard

Controllers Integrated

Table/ Arm/ Flat Type

Mini

Standard

Gripper/ Rotary Type

Linear Servo Type

Linear Servo Type

Clean-room Type

Splash-Proof Type

Splash-Proof Type

Pulse Motor

Servo Motor (24V)

Servo Motor (200V)

Linear Servo Motor

Linear Servo Motor