



CLOVER DISPLAY LTD.

LCD MODULE SPECIFICATION

Model : CG240128C - _ _ - _ _ - _ _ - _ _

| | |
|---------------|------------------|
| Revision | 01 |
| Engineering | NICK FOK |
| Date | 22 November 2012 |
| Our Reference | X9036 |

ADDRESS : 1st FLOOR, EFFICIENCY HOUSE, 35 TAI YAU STREET, SAN PO KONG,
KOWLOON, HONG KONG.

TEL : (852) 2341 3238 (SALES OFFICE) (852) 2342 8228 (GENERAL OFFICE)

FAX : (852) 2357 4237 (SALES OFFICE)

E-MAIL : cdl@cloverdisplay.com

URL : <http://www.cloverdisplay.com>

MODE OF DISPLAY**Display mode**

- STN : Yellow green
 Grey
 Blue (negative)
 FSTN positive
 FSTN negative

Display condition

- Reflective type
 Transflective type
 Transmissive type
 Others

Viewing direction

- 6 O' clock
 12 O' clock
 3 O' clock
 9 O' clock

LCD MODULE NUMBER NOTATION:

CG240128C- N N - S R - N 6 - T
| | | | | | | |
(1) (2) (3) (4) (5) (6) (7) (8)

* (1)---Model number of standard LCD Modules

* (2)---Backlight type

- N – No backlight
E – EL backlight
L – Side-lited LED backlight
M – Array LED backlight
C – CCFL

* (3)---Backlight color

- N – No backlight
A – Amber
B – Blue
O – Orange
W – White
Y – Yellow green

* (4)---Display mode

- T – TN
V – TN (Negative)
S – STN Yellow green
G – STN Grey
B – STN Blue (Negative)
F – FSTN
N – FSTN (Negative)

* (5)---Rear polarizer type

- R – Reflective
F – Transflective
T – Transmissive

* (6)---Temperature range

- N – Normal
W – Extended

* (7)---Viewing direction

- 6 – 6 O'clock
2 – 12 O'clock
3 – 3 O'clock
9 – 9 O'clock

* (8)---Special code for other requirements
(Can be omitted if not used)

GENERAL DESCRIPTION

Display mode : 240 X128 dots graphic COG LCD module
 Interface : 4/8 bit parallel(8080/6800) / 3 line or 4 line SPI
 Driving method : 1/128 duty, 1/12 bias
 Controller IC : ULTRA CHIP UC1608 or equivalent
 For the detailed information, please refer to the IC specifications.

MECHANICAL DIMENSIONS

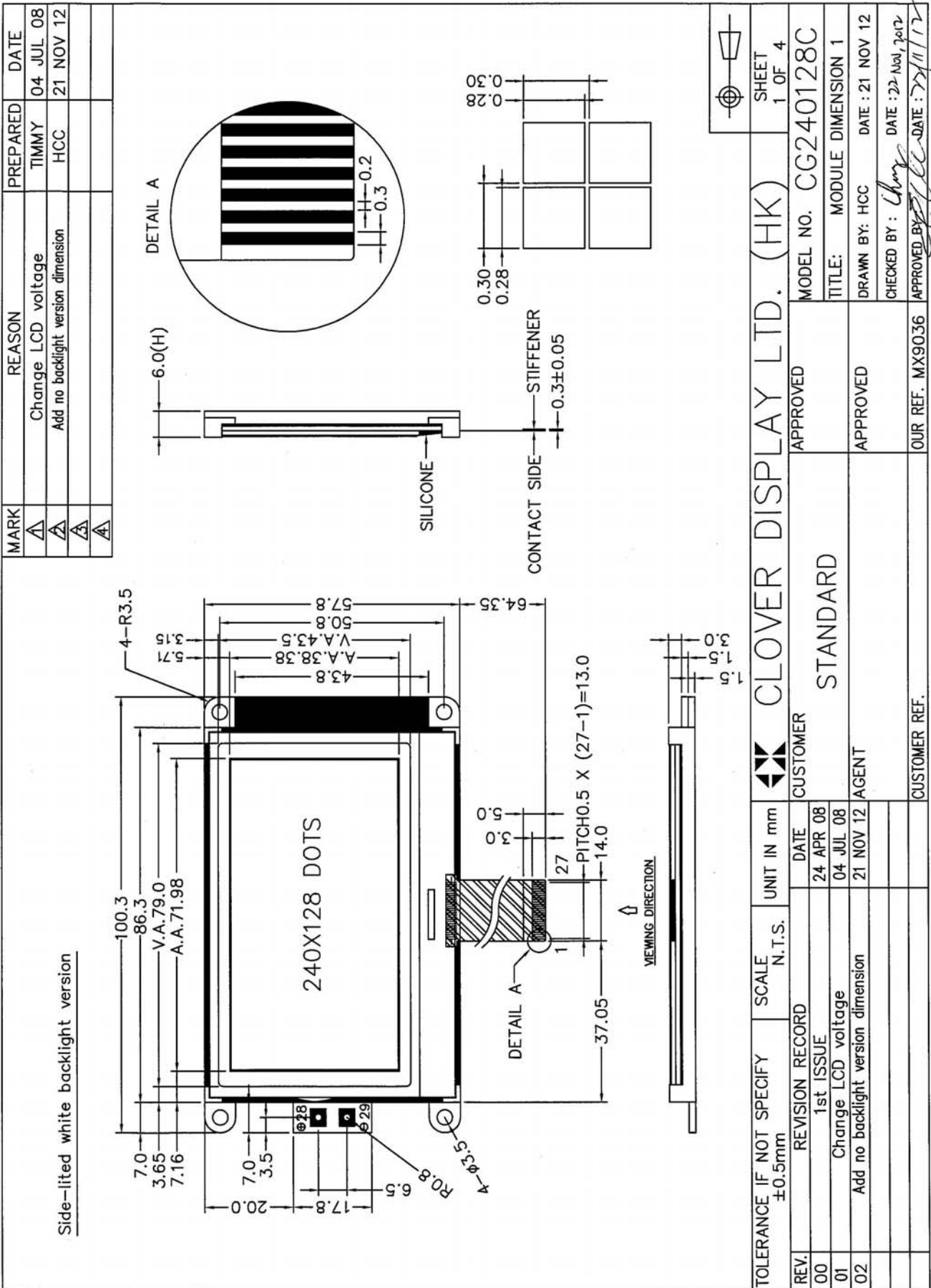
| Item | Dimension | Unit | Item | Dimension | Unit |
|------------------------|------------------------------|------|--------------|------------------|------|
| Outline Dimension | | | Viewing Area | 79.0 (L)x43.5(W) | mm |
| No Backlight (N) | 84.0(L)x55.5(W)x2.9 max. (H) | mm | Dot Pitch | 0.3(L)x0.3(W) | mm |
| LED Sided Backlight(L) | 100.3(L)x57.8(W)x6.0(H) | mm | Dot Size | 0.28(L)x0.28(W) | mm |

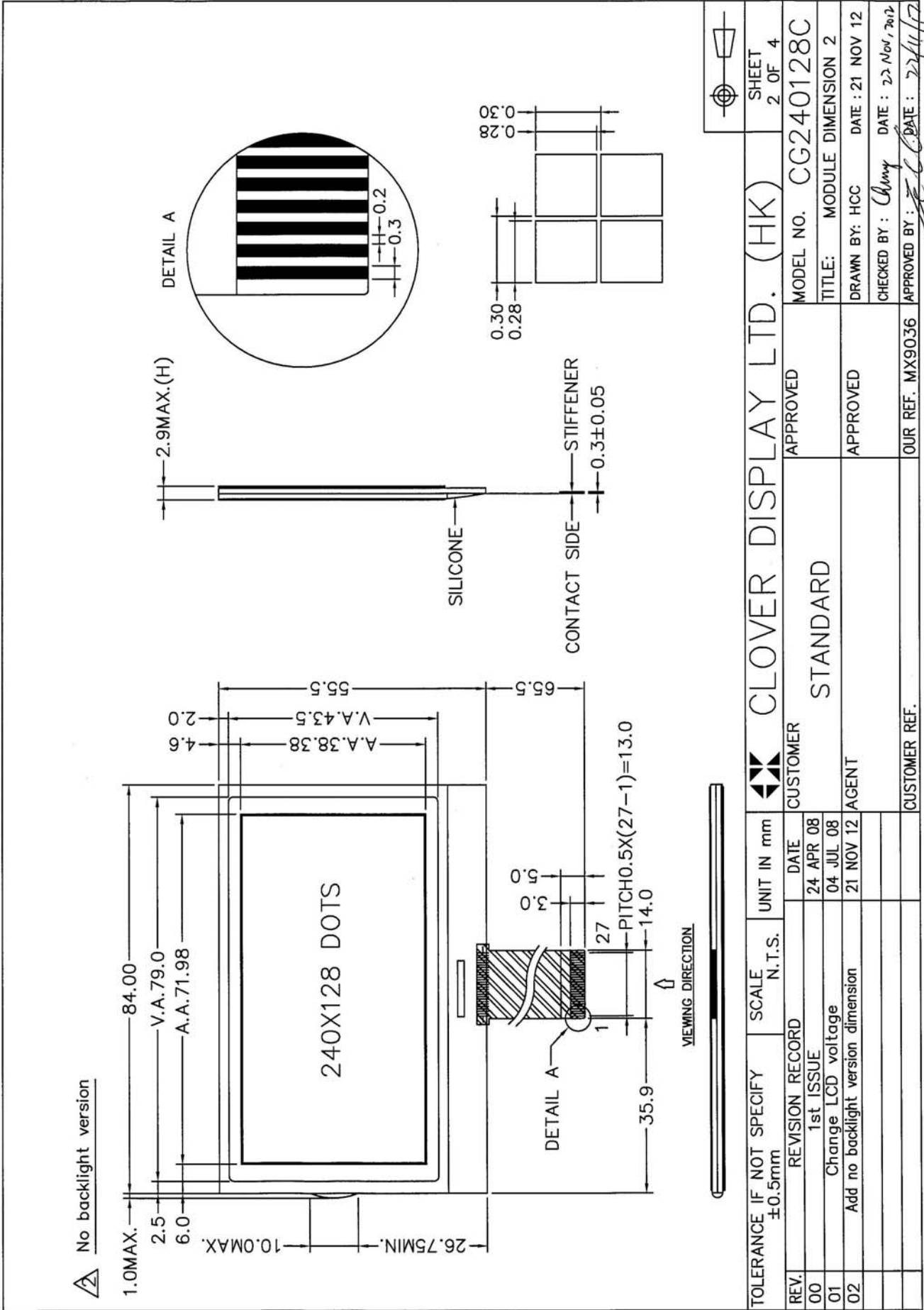
CONNECTOR PIN ASSIGNMENT

| Pin No. | Symbol | Function | Pin No. | Symbol | Function |
|---------|--------|---|-------------------|--------|------------------------------------|
| 1 | NC | No connection | 16 | D2 | Data bus |
| 2 | NC | | 17 | D1 | |
| 3 | VB1- | | Voltage converter | 18 | D0 |
| 4 | VB1+ | 19 | | WR1 | Controls Read/Write operation |
| 5 | VB0- | 20 | | WR0 | |
| 6 | VB0+ | 21 | | CD | Register select input |
| 7 | VLCD | Power supply for LCD | | 22 | RST |
| 8 | VBIAS | Reference voltage for SEG driving voltage | 23 | CS | Chip enable (Active High) |
| 9 | VSS | Ground | 24 | BM0 | Select the interface bus mode |
| 10 | VDD | Supply voltage for logic | 25 | BM1 | |
| 11 | D7 | Data bus | 26 | NC | No connection |
| 12 | D6 | | 27 | NC | |
| 13 | D5 | | *28 | A | |
| 14 | D4 | | *29 | K | Supply voltage for backlight (-VE) |
| 15 | D3 | | Data bus(SDA) | | |

Note (*) : Pin 28,29 are used for backlight version

COUNTER DRAWING OF MODULE DIMENSION

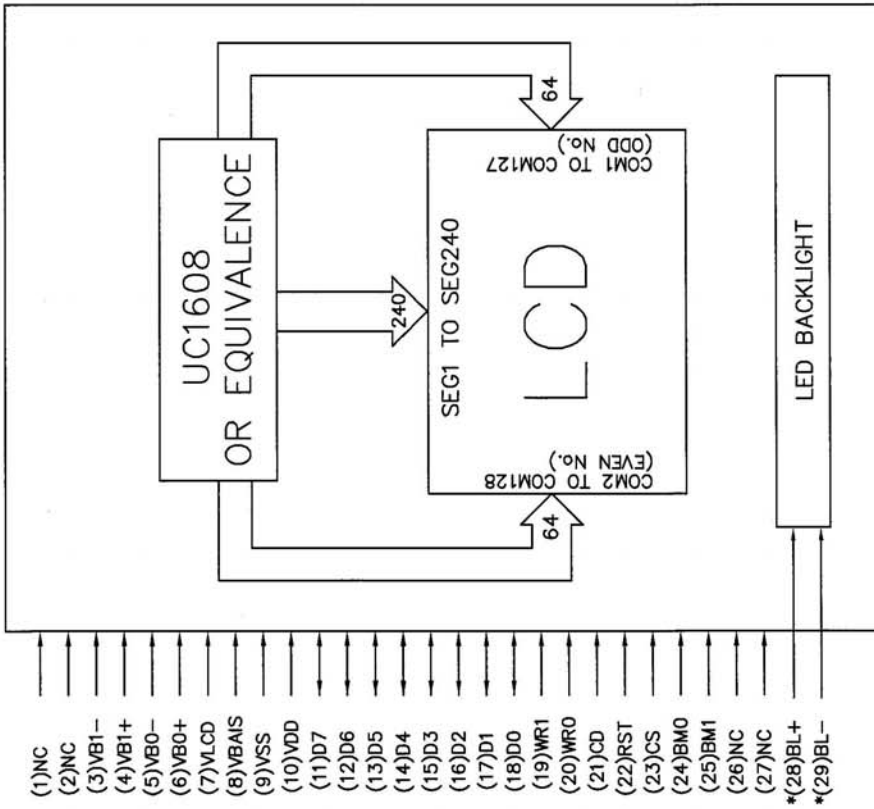




| | | | | | | |
|------------------------------------|------------------------------------|-----------------|---------------|--------------------------|--------------------|--------------------|
| TOLERANCE IF NOT SPECIFY ±0.5mm | | SCALE N.T.S. | UNIT IN mm | CLOVER DISPLAY LTD. (HK) | | SHEET 2 OF 4 |
| REV. | REVISION RECORD | DATE | CUSTOMER | MODEL NO. | CG240128C | |
| 00 | 1st ISSUE | 24 APR 08 | STANDARD | TITLE: | MODULE DIMENSION 2 | |
| 01 | Change LCD voltage | 04 JUL 08 | AGENT | DRAWN BY: | HCC | DATE: 21 NOV 12 |
| 02 | Add no backlight version dimension | 21 NOV 12 | | CHECKED BY: | Chmy | DATE: 22 Nov, 2012 |
| | | | CUSTOMER REF. | APPROVED BY: | | DATE: 22/11/12 |
| | | | | OUR REF. | MX9036 | |

COUNTER DRAWING OF PIN OUT & BLOCK DIAGRAM

| PIN NO. | SYMBOL | FUNCTION |
|---------|--------|---|
| 1 | NC | No connection |
| 2 | NC | No connection |
| 3 | VB1- | Voltage converter |
| 4 | VB1+ | |
| 5 | VB0- | |
| 6 | VB0+ | |
| 7 | VLCD | Power supply for LCD |
| 8 | VBIAS | Reference voltage for SEG driving voltage |
| 9 | VSS | Ground |
| 10 | VDD | Supply voltage for logic |
| 11 | D7 | Data bus |
| 12 | D6 | Data bus |
| 13 | D5 | Data bus |
| 14 | D4 | Data bus |
| 15 | D3 | Data bus(SDA) |
| 16 | D2 | Data bus |
| 17 | D1 | Data bus |
| 18 | D0 | Data bus(SCK) |
| 19 | WR1 | Controls Read/Write operation |
| 20 | WR0 | Register select input |
| 21 | CD | External reset input |
| 22 | RST | External reset input |
| 23 | CS | Chip enable (Active high) |
| 24 | BM0 | Select the interface bus mode |
| 25 | BM1 | |
| 26 | NC | No connection |
| 27 | NC | No connection |
| *28 | BL+ | Supply voltage for backlight (+) |
| *29 | BL- | Supply voltage for backlight (-) |



Note (*): Pin 28, 29 are use for backlight version only

| | | | | | | |
|------------------------------------|------------------------------------|-----------------|---------------|---|--|-----------------|
| TOLERANCE IF NOT SPECIFY ±0.5mm | | SCALE N.T.S. | UNIT IN mm | CLOVER DISPLAY LTD. (HK) | | SHEET 3 OF 4 |
| REV. | REVISION RECORD | DATE | CUSTOMER | APPROVED | | |
| 00 | 1st ISSUE | 24 APR 08 | STANDARD | MODEL NO. CG240128C | | |
| 01 | Change LCD voltage | 04 JUL 08 | AGENT | TITLE: PIN OUT & BLOCK DIAGRAM | | |
| 02 | Add no backlight version dimension | 21 NOV 12 | | DRAWN BY: HCC DATE: 21 NOV 12 | | |
| | | | | CHECKED BY: <i>Chung</i> DATE: 22 Nov 12 | | |
| | | | | APPROVED BY: <i>W. Lee</i> DATE: 27/11/12 | | |
| | | | CUSTOMER REF. | OUR REF. MX9036 | | |

ELECTRICAL CHARACTERISTICS

Conditions: VSS=0V, Ta=25°C

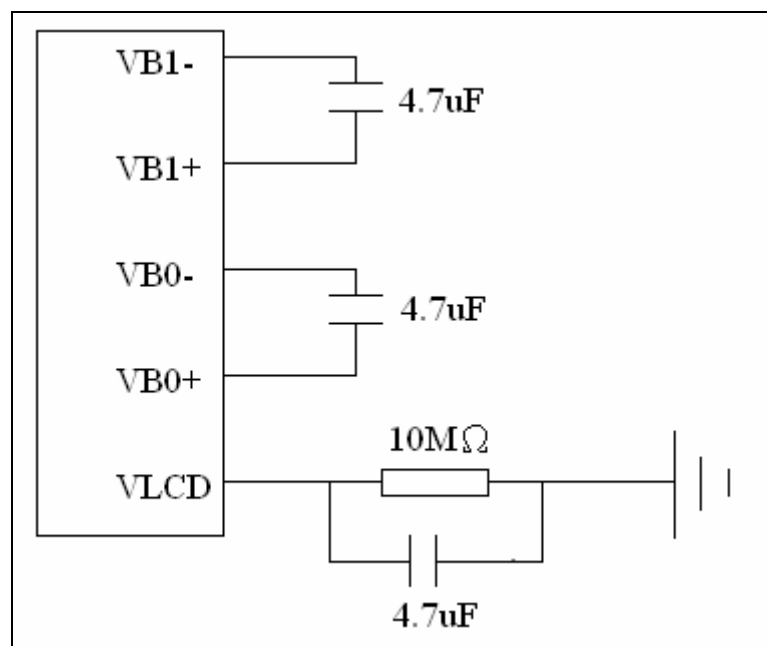
| Item | Symbol | MIN. | TYP. | MAX. | Unit |
|-------------------------------|--------|--------|------|--------|------|
| Supply Voltage for Logic | VDD | 3.05 | 3.30 | 3.55 | V |
| Supply Current for Logic | IDD | — | 0.66 | 0.99 | mA |
| Operating voltage for LCD (*) | VLCD | 13.3 | 14.0 | 14.7 | V |
| “H”Level Input Voltage | VIH | 0.8VDD | — | VDD | V |
| “L”Level Input Voltage | VIL | — | — | 0.2VDD | V |

Note (*): There is tolerance in optimum LCD driving voltage during production and it will be within the specified range.

Side-lited LED

Constant current driving:

| Item | Symbol | MIN. | TYP. | MAX. | Unit | Condition |
|-------------------------|-----------------|------|------|------|------|------------------------|
| White Backlight Voltage | V _{BL} | 4.8 | 5.0 | 5.2 | V | I _{BL} = 45mA |

REFERENCE CIRCUIT EXAMPLE**ABSOLUTE MAXIMUM RATINGS**

Please make sure not to exceed the following maximum rating values under the worst application conditions

| Item | Symbol | Rating (for normal temperature) | Rating (for wide temperature) | Unit |
|-----------------------|------------------|---------------------------------|-------------------------------|------|
| Supply Voltage | VDD | -0.3 to 4.0 | -0.3 to 4.0 | V |
| Input Voltage | VT | -0.4 to VDD +0.5 | -0.4 to VDD +0.5 | V |
| Operating Temperature | T _{opr} | 0 to 50 | -20 to 70 | °C |
| Storage Temperature | T _{stg} | -10 to 60 | -30 to 80 | °C |

COMMANDS TABLE

| | Command | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | Action | Default |
|----|---|-----|-----|----|----|----|----|----|-----|-----|----|------------------------------------|-------------------|
| 1 | Write Data Byte | 1 | 0 | # | # | # | # | # | # | # | # | Write 1 byte | N/A |
| 2 | Read Data Byte | 1 | 1 | # | # | # | # | # | # | # | # | Read 1 byte | N/A |
| 3 | Get Status | 0 | 1 | BZ | MX | DE | RS | WA | GN1 | GN0 | 1 | Get Status | N/A |
| 4 | Set Column Address LSB | 0 | 0 | 0 | 0 | 0 | 0 | # | # | # | # | Set CA[3:0] | 0 |
| | Set Column Address MSB | 0 | 0 | 0 | 0 | 0 | 1 | # | # | # | # | Set CA[7:4] | 0 |
| 5 | Set Mux Rate and temperature compensation. | 0 | 0 | 0 | 0 | 1 | 0 | 0 | # | # | # | Set {MR, TC[1:0]} | MR: 1b TC: 00b |
| 6 | Set Power Control | 0 | 0 | 0 | 0 | 1 | 0 | 1 | # | # | # | Set PC[2:0] | 101b |
| 7 | Set Adv. Program Control. (double byte command) | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 0 | R | For UltraChip only. Do not use. | N/A |
| | | 0 | 0 | # | # | # | # | # | # | # | # | | |
| 8 | Set Start Line | 0 | 0 | 0 | 1 | # | # | # | # | # | # | Set SL[5:0] | 0 |
| 9 | Set Gain and Potentiometer (double-byte command) | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | Set {GN[1:0], PM[5:0]} | GN=3 PM=0 |
| | | 0 | 0 | # | # | # | # | # | # | # | # | | |
| 10 | Set RAM Address Control | 0 | 0 | 1 | 0 | 0 | 0 | 1 | # | # | # | Set AC[2:0] | 001b |
| 11 | Set All-Pixel-ON | 0 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 0 | # | Set DC[1] | 0=disable |
| 12 | Set Inverse Display | 0 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 1 | # | Set DC[0] | 0=disable |
| 13 | Set Display Enable | 0 | 0 | 1 | 0 | 1 | 0 | 1 | 1 | 1 | # | Set DC[2] | 0=disable |
| 14 | Set Fixed Lines | 0 | 0 | 1 | 0 | 0 | 1 | # | # | # | # | Set FL[3:0] | 0 |
| 15 | Set Page Address | 0 | 0 | 1 | 0 | 1 | 1 | # | # | # | # | Set PA[3:0] | 0 |
| 16 | Set LCD Mapping Control | 0 | 0 | 1 | 1 | 0 | 0 | # | # | # | # | Set LC[3:0] | 0 |
| 17 | System Reset | 0 | 0 | 1 | 1 | 1 | 0 | 0 | 0 | 1 | 0 | System Reset | N/A |
| 18 | NOP | 0 | 0 | 1 | 1 | 1 | 0 | 0 | 0 | 1 | 1 | No operation | N/A |
| 19 | Set LCD Bias Ratio | 0 | 0 | 1 | 1 | 1 | 0 | 1 | 0 | # | # | Set BR[1:0] | 10b=12 |
| 20 | Reset Cursor Mode | 0 | 0 | 1 | 1 | 1 | 0 | 1 | 1 | 1 | 0 | AC[3]=0, CA=CR | N/A |
| 21 | Set Cursor Mode | 0 | 0 | 1 | 1 | 1 | 0 | 1 | 1 | 1 | 1 | AC[3]=1, CR=CA | N/A |
| 22 | Set Test Control (double byte command) | 0 | 0 | 1 | 1 | 1 | 0 | 0 | 1 | TT | | For UltraChip only. Do not use. | N/A |
| | | 0 | 0 | # | # | # | # | # | # | # | # | | |

* Other than commands listed above, all other bit patterns may result in undefined behavior.

COMMAND DESCRIPTION

(1) Write data to display memory

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------------|-----|-----|--------------------------|----|----|----|----|----|----|----|
| Write data | 1 | 0 | 8bits data write to SRAM | | | | | | | |

(2) Read data to display memory

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-----------|-----|-----|----------------------|----|----|----|----|----|----|----|
| Read data | 1 | 1 | 8bits data from SRAM | | | | | | | |

Write/Read Data Byte (command 1,2) operations access display buffer RAM based on Page Address (PA) register and Column Address (CA) register. To minimize bus interface cycles, PA and CA will be incremented automatically depending on the setting of Access Control (AC) registers. PA and CA can also be programmed directly by issuing *Set Page Address* and *Set Column Address* commands.

If Wrap-Around (WA) is OFF (AC[0] = 0), CA will stop increasing after reaching the end of page (MC), and system programmers need to set the values of PA and CA explicitly. If WA is ON (AC[0]=1), when CA reaches end of page, CA will be reset to 0 and PA will be increased or decrease by 1, depending on the setting of Page Increment Direction (PID, AC[2]). When PA reaches the boundary of RAM (i.e. PA = 0 or 15), PA will be wrapped around to the other end of RAM and continue.

(3) Get Status

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------------|-----|-----|----|----|----|----|----|-----|-----|----|
| Get Status | 0 | 1 | BZ | MX | DE | RS | WA | GN1 | GN0 | 1 |

Status flag definitions:

BZ: Busy with internal process.

MX: Status of register LC[2], mirror X.

DE: Display enable flag. DE=1 when display enabled

RS: Reset in progress. If RS=1, host interface will be inaccessible.

WA: status of register AC[0]. Automatic column/page wrap around.

GN0, 1: GN[1:0]. register Gain

(4) Set Column Address

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------------------------------|-----|-----|----|----|----|----|-----|-----|-----|-----|
| Set Column Address LSB CA[3:0] | 0 | 0 | 0 | 0 | 0 | 0 | CA3 | CA2 | CA1 | CA0 |
| Set Column Address MSB CA[7:4] | 0 | 0 | 0 | 0 | 0 | 1 | CA7 | CA6 | CA5 | CA4 |

Set the SRAM column address before Write/Read memory from host interface.

CA possible value=0-239

(5) Set Multiplex Rate and Temperature Compensation

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------------------------------------|-----|-----|----|----|----|----|----|----|-----|-----|
| Set Multiplex Rate MR | 0 | 0 | 0 | 0 | 1 | 0 | 0 | MR | TC1 | TC0 |
| Set Temperature Compensation TC[1:0] | 0 | 0 | 0 | 0 | 1 | 0 | 0 | MR | TC1 | TC0 |

Set the multiplex ratio (number of rows) and temperature compensation.

MUX ratio definition: 0b=96 1b=128

Temperature compensation curve definition:

00b= -0.00%/C 01b= -0.05%/C 10b= -0.10%/C 11b= -0.20%/C

(6) Set Power Control

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------------------|-----|-----|----|----|----|----|----|-----|-----|-----|
| Set Panel Loading PC[2:0] | 0 | 0 | 0 | 0 | 1 | 0 | 1 | PC2 | PC1 | PC0 |

Set PC[1:0], according to the capacitance loading of LCD panel.

Panel loading definition:

00b: LCD < 26 nF

01b: 26 nF < LCD < 43 nF

10b: 43 nF < LCD < 60nF

11b: 60nF < LCD < 90 nF

Set PC[2] to program to use internal charge pump of external V_{LCD} source.

Pump control definition:

0b=External V_{LCD}

1b=Internal V_{LCD}

(7) Set Advanced Program Control

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------------------------------|-----|-----|------------------------|----|----|----|----|----|----|----|
| Set APC[0] (Double byte command) | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 0 | 0 | R |
| | 0 | 0 | APC register parameter | | | | | | | |

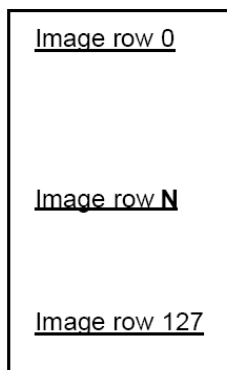
For UltraChip only. Please Do NOT use.

(8) Set Start Line

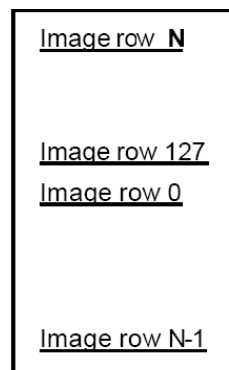
| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------------------------|-----|-----|----|----|-----|-----|-----|-----|-----|-----|
| Set Start Line SL[5:0] | 0 | 0 | 0 | 1 | SL5 | SL4 | SL3 | SL2 | SL1 | SL0 |

Set the start line number

Start line setting will scroll the displayed image up by SL rows. The valid value is between 0 (no scrolling) and 63. One example of the visual effect on LCD is illustrated in the figure below.



SL=0



SL=N

(9) Set Gain and Potentiometer

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| Set Gain and Potentiometer GN [1:0] PM [5:0] (Double byte command) | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| | 0 | 0 | GN1 | GN0 | PM5 | PM4 | PM3 | PM2 | PM1 | PM0 |

Program Gain (GN[1:0]) and Potentiometer (PM[5:0]). See section LCD VOLTAGE SETTING for more detail.

Effective range of GN = 0 ~ 3

PM value = 0 ~ 63

(10) Set RAM Address Control

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------------|-----|-----|----|----|----|----|----|-----|-----|-----|
| Set AC [2:0] | 0 | 0 | 1 | 0 | 0 | 0 | 1 | AC2 | AC1 | AC0 |

Program registers AC[2:0] for RAM address control.

AC[0] - WA, Automatic column/page wrap around.

0: CA or PA (depends on AC[1]= 0 or 1) will stop incrementing after reaching boundary

1: CA or PA (depends on AC[1]= 0 or 1) will restart, and PA or CA will increment by one step.

AC[1] – Reserved (always set to 0)

AC[2] – PID, page address (PA) auto increment direction (0/1 = +/- 1)

When WA=1, controls whether page address will be adjusted by +1 or -1, when CA reached CA boundary.
No effect when WA=0.

CA boundary is 239 and PA boundary is 15 when PID=0, PA boundary is 0 when PID=1.

(11) Set All Pixel ON

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------------------|-----|-----|----|----|----|----|----|----|----|-----|
| Set All Pixel On DC [1] | 0 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 0 | DC1 |

Set DC[1] to force all SEG drivers to output ON signals. This function has no effect on the existing data stored in display RAM.

(12) Set Inverse Display

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|----------------------------|-----|-----|----|----|----|----|----|----|----|-----|
| Set Inverse Display DC [0] | 0 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 1 | DC0 |

Set DC[0] to force all SEG drivers to output the inverse of the data stored in display memory. This function has no effect on the existing data stored in display RAM.

(13) Set Display Enable

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------------------------|-----|-----|----|----|----|----|----|----|----|-----|
| Set Display Enable DC[2] | 0 | 0 | 1 | 0 | 1 | 0 | 1 | 1 | 1 | DC2 |

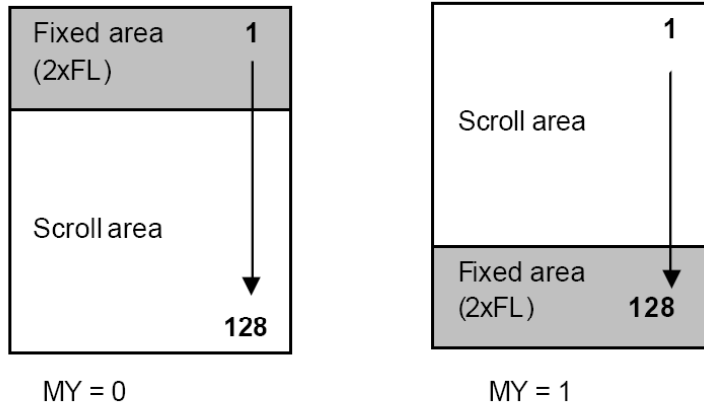
This command is for programming registers DC[2].

When DC[2] is set to 0, the IC will put itself into Sleep mode. All drivers, voltage generation circuit and timing circuit will be halted to conserve power. When DC[2] is set to 1, UC1608 will first exit from Sleep mode, restore the power and then turn on COM drivers and SEG drivers. There is no other explicit user action or timing sequence required to enter or exit the Sleep mode.

(14) Set Fixed Lines

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------------------------|-----|-----|----|----|----|----|-----|-----|-----|-----|
| Set Fixed Lines FL [3:0] | 0 | 0 | 1 | 0 | 0 | 1 | FL3 | FL2 | FL1 | FL0 |

The fixed line function is used to implement the partial scroll function by dividing the screen into scroll and fixed area. Set Fixed Lines command will define the fixed area, which will not be affected by the SL scroll function. The fixed area covers the top 2xFL rows for mirror Y (MY) is 0 and bottom 2xFL rows for MY=1. One example of the visual effect on LCD is illustrated in the figure below.

**(15) Set Page Address**

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------------------------|-----|-----|----|----|----|----|-----|-----|-----|-----|
| Set Page Address LSB PA [3:0] | 0 | 0 | 1 | 0 | 1 | 1 | PA3 | PA2 | PA1 | PA0 |

Set the SRAM page address before write/read memory from host interface.
Effective range of value = 0 ~ 15

(16) Set LCD Mapping Control

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------------------------|-----|-----|----|----|----|----|----|----|----|-----|
| Set LCD Mapping Control LC[3:0] | 0 | 0 | 1 | 1 | 0 | 0 | MY | MX | 0 | MSF |

Set LC[3:0] for COM (row) mirror (MY), SEG (column) mirror (MX) and MSB first or LSB first options (MSF).

MY is implemented by reversing the mapping order between RAM and COM (row) electrodes. The data stored in RAM is not affected by MY command. MY will have immediate effect on the display image.

MX is implemented by selecting the CA or 239-CA as write/read (from host interface) display RAM column address so this function will only take effect after rewriting the RAM data.

MSF is implemented by MSB-LSB swapping. When MSB first (LC[0]) bit is set, data D[7:0] will be re-aligned as D[0:7] then be stored to RAM.

(17) System Reset

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------------|-----|-----|----|----|----|----|----|----|----|----|
| System Reset | 0 | 0 | 1 | 1 | 1 | 0 | 0 | 0 | 1 | 0 |

This command will activate the system reset. The system will take about 15ms to reset

(18) NOP

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------------|-----|-----|----|----|----|----|----|----|----|----|
| No operation | 0 | 0 | 1 | 1 | 1 | 0 | 0 | 0 | 1 | 1 |

This command is used for "no operation".

(19) Set LCD Bias Ratio

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------------------|-----|-----|----|----|----|----|----|----|-----|-----|
| Set Bias Ratio BR [1:0] | 0 | 0 | 1 | 1 | 1 | 0 | 1 | 0 | BR1 | BR0 |

Bias ratio definition:

00b= 10.7

01b=11.3

10b=12.0

11b=12.7

(20) Reset Cursor Mode

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|----------------------------------|-----|-----|----|----|----|----|----|----|----|----|
| Return to Cursor. AC[3]=0, CA=CR | 0 | 0 | 1 | 1 | 1 | 0 | 1 | 1 | 1 | 0 |

This command is used to reset cursor update mode function. See description below.

(21) Set Cursor Mode

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-------------------|-----|-----|----|----|----|----|----|----|----|----|
| Set AC[3]=1 CR=CA | 0 | 0 | 1 | 1 | 1 | 0 | 1 | 1 | 1 | 1 |

Set Cursor Mode command is used to turn on cursor update mode function. AC[3] will be set to 1, register CR will be set to the value of register CA

When AC[3]=1, column address (CA) will only increment with write RAM operation but not on read RAM operation. The address CA wraps around will also be suspended no matter what WA setting is. The purpose of this combination of features is to support "Read-Modify-Write" for cursor implementation.

Reset Cursor Mode command will clear cursor update mode flag (AC[3]=0), CA will be restored to previous CA value which is stored in CR, and CA, PA increment will return to its normal condition.

(22) Set Test Control

| Action | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-----------------------|-----|-----|-------------------|----|----|----|----|----|----|----|
| Set TT | 0 | 0 | 1 | 1 | 1 | 0 | 0 | 1 | TT | |
| (Double byte command) | 0 | 0 | Testing parameter | | | | | | | |

This command is used for UltraChip production testing. For UltraChip Only. Please do not use.

RECOMMENDED INITIAL SETTINGS

Set Power Control : 2FH

Set Multiplex Rate And Temperature Compensation: 27H

Set LCD Mapping Control : C8H

Set LCD Bias Ratio : EAH

Set Gain Potentiometer : 4DH

Set RAM Address Control : 89H

Set Start Line : 40H

Set Display Enable : AFH

THE ADDRESS CIRCUIT

| MSF | | Line Address | [Grid] | | | | | | | | | | | | | | | | MY=0 | | MY=1 | | | |
|-----|----|--------------|--------|--|--|--|--|--|--|--|--|--|--|--|--|--|--|--|--------|--------|--------|-------|--------|-------|
| 0 | 1 | | [Grid] | | | | | | | | | | | | | | | | SL=0 | SL=16 | SL=0 | SL=0 | SL=16 | SL=16 |
| D0 | D7 | 00H | [Grid] | | | | | | | | | | | | | | | | COM1 | COM113 | COM128 | COM96 | COM16 | -- |
| D1 | D6 | 01H | [Grid] | | | | | | | | | | | | | | | | COM2 | COM114 | COM127 | COM95 | COM15 | -- |
| D2 | D5 | 02H | [Grid] | | | | | | | | | | | | | | | | COM3 | COM115 | COM126 | COM94 | COM14 | -- |
| D3 | D4 | 03H | [Grid] | | | | | | | | | | | | | | | | COM4 | COM116 | COM125 | COM93 | COM13 | -- |
| D4 | D3 | 04H | [Grid] | | | | | | | | | | | | | | | | COM5 | COM117 | COM124 | COM92 | COM12 | -- |
| D5 | D2 | 05H | [Grid] | | | | | | | | | | | | | | | | COM6 | COM118 | COM123 | COM91 | COM11 | -- |
| D6 | D1 | 06H | [Grid] | | | | | | | | | | | | | | | | COM7 | COM119 | COM122 | COM90 | COM10 | -- |
| D7 | D0 | 07H | [Grid] | | | | | | | | | | | | | | | | COM8 | COM120 | COM121 | COM89 | COM9 | -- |
| D0 | D7 | 08H | [Grid] | | | | | | | | | | | | | | | | COM9 | COM121 | COM120 | COM88 | COM8 | -- |
| D1 | D6 | 09H | [Grid] | | | | | | | | | | | | | | | | COM10 | COM122 | COM119 | COM87 | COM7 | -- |
| D2 | D5 | 0AH | [Grid] | | | | | | | | | | | | | | | | COM11 | COM123 | COM118 | COM86 | COM6 | -- |
| D3 | D4 | 0BH | [Grid] | | | | | | | | | | | | | | | | COM12 | COM124 | COM117 | COM85 | COM5 | -- |
| D4 | D3 | 0CH | [Grid] | | | | | | | | | | | | | | | | COM13 | COM125 | COM116 | COM84 | COM4 | -- |
| D5 | D2 | 0DH | [Grid] | | | | | | | | | | | | | | | | COM14 | COM126 | COM115 | COM83 | COM3 | -- |
| D6 | D1 | 0EH | [Grid] | | | | | | | | | | | | | | | | COM15 | COM127 | COM114 | COM82 | COM2 | -- |
| D7 | D0 | 0FH | [Grid] | | | | | | | | | | | | | | | | COM16 | COM128 | COM113 | COM81 | COM1 | -- |
| D0 | D7 | 10H | [Grid] | | | | | | | | | | | | | | | | COM17 | COM1 | COM112 | COM80 | COM128 | -- |
| D1 | D6 | 11H | [Grid] | | | | | | | | | | | | | | | | COM18 | COM2 | COM111 | COM79 | COM127 | -- |
| D2 | D5 | 12H | [Grid] | | | | | | | | | | | | | | | | COM19 | COM3 | COM110 | COM78 | COM126 | -- |
| D3 | D4 | 13H | [Grid] | | | | | | | | | | | | | | | | COM20 | COM4 | COM109 | COM77 | COM125 | -- |
| D4 | D3 | 14H | [Grid] | | | | | | | | | | | | | | | | COM21 | COM5 | COM108 | COM76 | COM124 | -- |
| D5 | D2 | 15H | [Grid] | | | | | | | | | | | | | | | | COM22 | COM6 | COM107 | COM75 | COM123 | -- |
| D6 | D1 | 16H | [Grid] | | | | | | | | | | | | | | | | COM23 | COM7 | COM106 | COM74 | COM122 | -- |
| D7 | D0 | 17H | [Grid] | | | | | | | | | | | | | | | | COM24 | COM8 | COM105 | COM73 | COM121 | -- |
| D0 | D7 | 18H | [Grid] | | | | | | | | | | | | | | | | COM25 | COM9 | COM104 | COM72 | COM120 | COM96 |
| D1 | D6 | 19H | [Grid] | | | | | | | | | | | | | | | | COM26 | COM10 | COM103 | COM71 | COM119 | COM95 |
| D2 | D5 | 1AH | [Grid] | | | | | | | | | | | | | | | | COM27 | COM11 | COM102 | COM70 | COM118 | COM94 |
| D3 | D4 | 1BH | [Grid] | | | | | | | | | | | | | | | | COM28 | COM12 | COM101 | COM69 | COM117 | COM93 |
| D4 | D3 | 1CH | [Grid] | | | | | | | | | | | | | | | | COM29 | COM13 | COM100 | COM68 | COM116 | COM92 |
| D5 | D2 | 1DH | [Grid] | | | | | | | | | | | | | | | | COM30 | COM14 | COM99 | COM67 | COM115 | COM91 |
| D6 | D1 | 1EH | [Grid] | | | | | | | | | | | | | | | | COM31 | COM15 | COM98 | COM66 | COM114 | COM90 |
| D7 | D0 | 1FH | [Grid] | | | | | | | | | | | | | | | | COM32 | COM16 | COM97 | COM65 | COM113 | COM89 |
| D0 | D7 | 70H | [Grid] | | | | | | | | | | | | | | | | COM113 | COM97 | COM16 | -- | COM32 | -- |
| D1 | D6 | 71H | [Grid] | | | | | | | | | | | | | | | | COM114 | COM98 | COM15 | -- | COM31 | -- |
| D2 | D5 | 72H | [Grid] | | | | | | | | | | | | | | | | COM115 | COM99 | COM14 | -- | COM30 | -- |
| D3 | D4 | 73H | [Grid] | | | | | | | | | | | | | | | | COM116 | COM100 | COM13 | -- | COM29 | -- |
| D4 | D3 | 74H | [Grid] | | | | | | | | | | | | | | | | COM117 | COM101 | COM12 | -- | COM28 | -- |
| D5 | D2 | 75H | [Grid] | | | | | | | | | | | | | | | | COM118 | COM102 | COM11 | -- | COM27 | -- |
| D6 | D1 | 76H | [Grid] | | | | | | | | | | | | | | | | COM119 | COM103 | COM10 | -- | COM26 | -- |
| D7 | D0 | 77H | [Grid] | | | | | | | | | | | | | | | | COM120 | COM104 | COM9 | -- | COM25 | -- |
| D0 | D7 | 78H | [Grid] | | | | | | | | | | | | | | | | COM121 | COM105 | COM8 | -- | COM24 | -- |
| D1 | D6 | 79H | [Grid] | | | | | | | | | | | | | | | | COM122 | COM106 | COM7 | -- | COM23 | -- |
| D2 | D5 | 7AH | [Grid] | | | | | | | | | | | | | | | | COM123 | COM107 | COM6 | -- | COM22 | -- |
| D3 | D4 | 7BH | [Grid] | | | | | | | | | | | | | | | | COM124 | COM108 | COM5 | -- | COM21 | -- |
| D4 | D3 | 7CH | [Grid] | | | | | | | | | | | | | | | | COM125 | COM109 | COM4 | -- | COM20 | -- |
| D5 | D2 | 7DH | [Grid] | | | | | | | | | | | | | | | | COM126 | COM110 | COM3 | -- | COM19 | -- |
| D6 | D1 | 7EH | [Grid] | | | | | | | | | | | | | | | | COM127 | COM111 | COM2 | -- | COM18 | -- |
| D7 | D0 | 7FH | [Grid] | | | | | | | | | | | | | | | | COM128 | COM112 | COM1 | -- | COM17 | -- |

| | | | | | | | | | | | | | | | |
|----|---|--------|--------|--------|--------|--------|--------|--------|--------|---------|---------|---------|---------|---------|---------|
| MX | 0 | SEG01 | SEG02 | SEG03 | SEG04 | SEG05 | SEG06 | SEG07 | SEG08 | SEG0206 | SEG0206 | SEG0237 | SEG0238 | SEG0239 | SEG0240 |
| | 1 | SEG240 | SEG239 | SEG238 | SEG237 | SEG236 | SEG235 | SEG234 | SEG233 | | SEG05 | SEG04 | SEG03 | SEG02 | SEG01 |

| | | | |
|-----|----|-----|----|
| 128 | 96 | 128 | 96 |
| MUX | | | |

Example for memory mapping: let MX = 0, MY = 0, SL = 0, MSF = 0, according to the data shown in the above table:

- ⇒ Page 0 SEG 1: 00011110b
- ⇒ Page 0 SEG 2: 01111000b

TIMING CHARACTERISTICS OF COMPATIBLE CONTROLLER CHIPS

AC CHARACTERISTICS

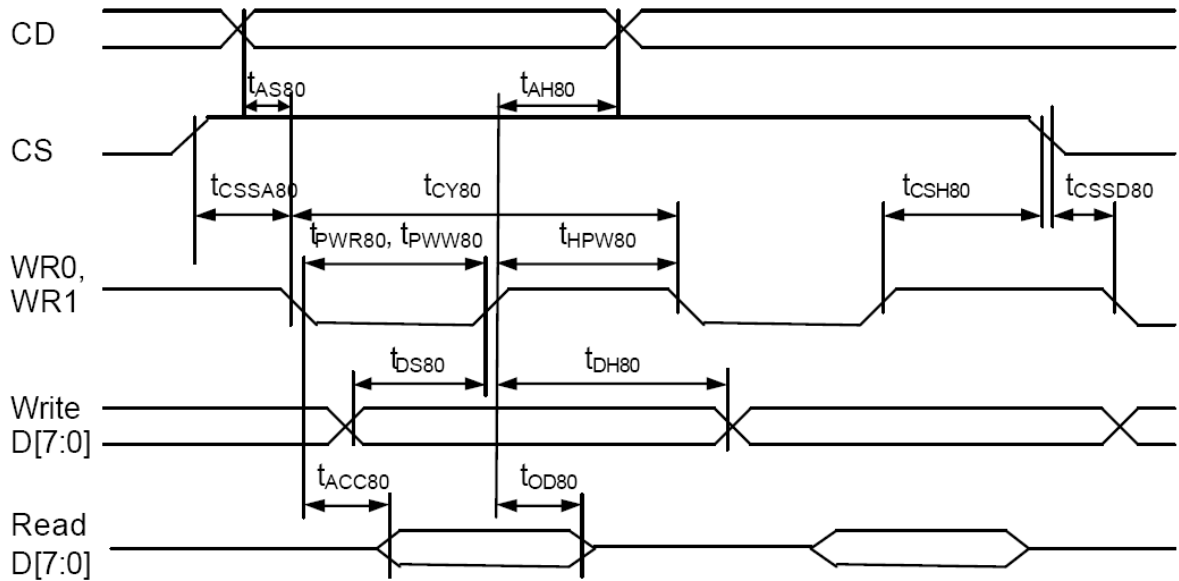


FIGURE 15: Parallel Bus Timing Characteristics (for 8080 MCU)

| Symbol | Signal | Description | Condition | Min. | Max. | Units |
|--------------|----------|------------------------|----------------|------|------|-------|
| t_{AS80} | CD | Address setup time | | 0 | – | nS |
| t_{AH80} | | Address hold time | | 20 | – | nS |
| t_{CY80} | | System cycle time | | | – | nS |
| | | 8 bits bus (read) | | 140 | | |
| | | (write) | | 140 | | |
| | | 4 bits bus (read) | | 140 | | |
| | | (write) | | 140 | | |
| t_{PWR80} | WR1 | Pulse width | 8 bits (read) | 65 | – | nS |
| | | | 4 bits | 65 | | |
| t_{PWW80} | WR0 | Pulse width | 8 bits (write) | 35 | – | nS |
| | | | 4 bits | 35 | | |
| t_{HPW80} | WR0, WR1 | High pulse width | | | – | nS |
| | | 8 bits bus (read) | | 65 | | |
| | | (write) | | 35 | | |
| | | 4 bits bus (read) | | 65 | | |
| | | (write) | | 35 | | |
| t_{DS80} | D0~D7 | Data setup time | | 30 | – | nS |
| t_{DH80} | | Data hold time | | 20 | | |
| t_{ACC80} | | Read access time | $C_L = 100pF$ | – | 60 | nS |
| t_{OD80} | | Output disable time | | 12 | 20 | |
| t_{SSA80} | CS1/CS0 | Chip select setup time | | 10 | | nS |
| t_{CSSD80} | | | | 10 | | |
| t_{CSh80} | | | | 20 | | |

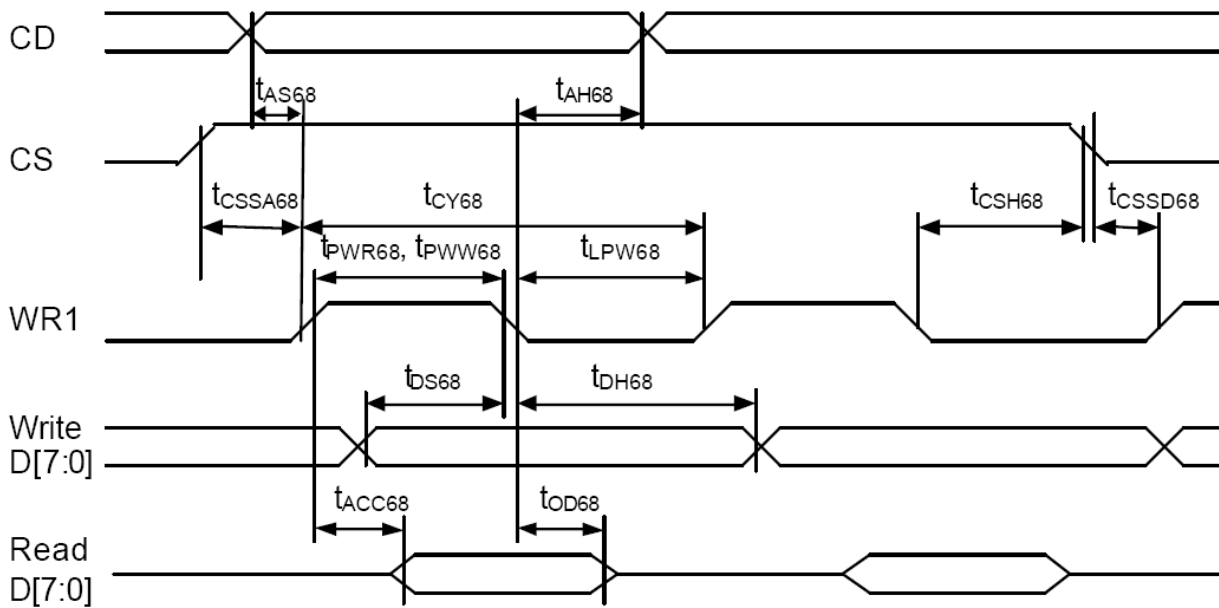


FIGURE 16: Parallel Bus Timing Characteristics (for 6800 MCU)

| Symbol | Signal | Description | Condition | Min. | Max. | Units |
|--------------|---------|----------------------------|---------------|------|------|-------|
| t_{AS68} | CD | Address setup time | | 0 | - | nS |
| t_{AH68} | | Address hold time | | 20 | | nS |
| T_{CY68} | | System cycle time | | | | nS |
| | | 8 bits bus (read) | | 140 | | |
| | | (write) | | 140 | | |
| | | 4 bits bus (read) | | 140 | | |
| | | (write) | | 140 | | |
| t_{PWR68} | WR1 | Pulse width 8 bits (read) | | 65 | | nS |
| | | 4 bits | | 65 | - | nS |
| t_{PWW68} | | Pulse width 8 bits (write) | | 35 | | nS |
| | | 4 bits | | 35 | | nS |
| t_{LPW68} | | Low pulse width | | | | nS |
| | | 8 bits bus (read) | | 65 | | |
| | | (write) | | 35 | | |
| | | 4 bits bus (read) | | 65 | | |
| | | (write) | | 35 | | |
| t_{DS68} | D0~D7 | Data setup time | | 30 | | nS |
| t_{DH68} | | Data hold time | | 20 | | nS |
| t_{ACC68} | | Read access time | $C_L = 100pF$ | | 60 | nS |
| t_{OD68} | | Output disable time | | 12 | 20 | nS |
| t_{CSSA68} | CS1/CS0 | Chip select setup time | | 10 | | nS |
| t_{CSSD68} | | | | 10 | | nS |
| t_{CSh68} | | | | 20 | | nS |

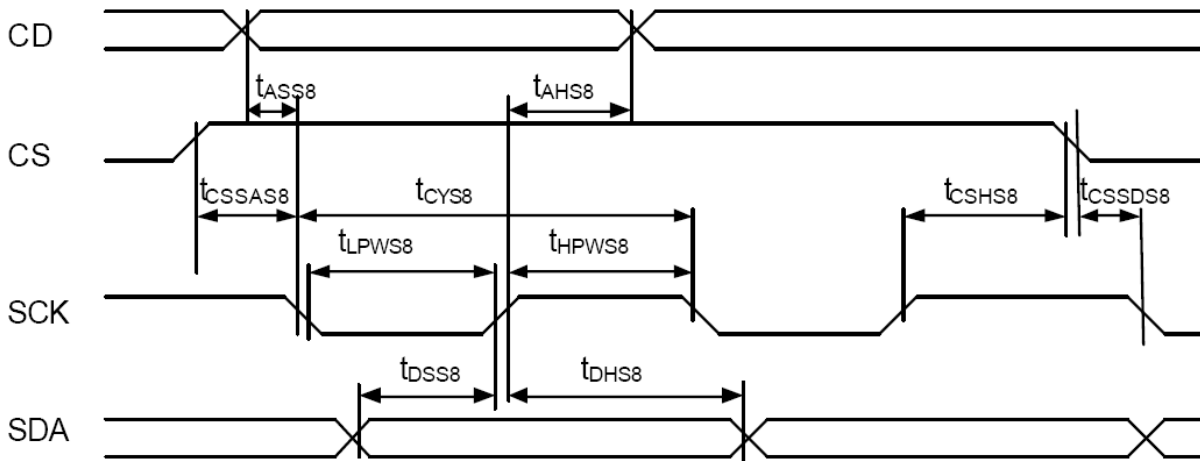


FIGURE 17: Serial Bus Timing Characteristics (for S8)

| Symbol | Signal | Description | Condition | Min. | Max. | Units |
|--|--------|------------------------|-----------|----------------|------|-------|
| t_{ASS8} | CD | Address setup time | | 0 | – | nS |
| t_{AHS8} | | Address hold time | | 20 | – | nS |
| t_{CYS8} | SCK | System cycle time | | 140 | – | nS |
| t_{LPWS8} | | Low pulse width | | 65 | – | nS |
| t_{HPWS8} | | High pulse width | | 65 | – | nS |
| t_{DSS8} | SDA | Data setup time | | 30 | – | nS |
| t_{DHS8} | | Data hold time | | 20 | – | nS |
| t_{CSSAS8} t_{CSSDS8} t_{CHS8} | CS | Chip select setup time | | 10 20 10 | | nS |

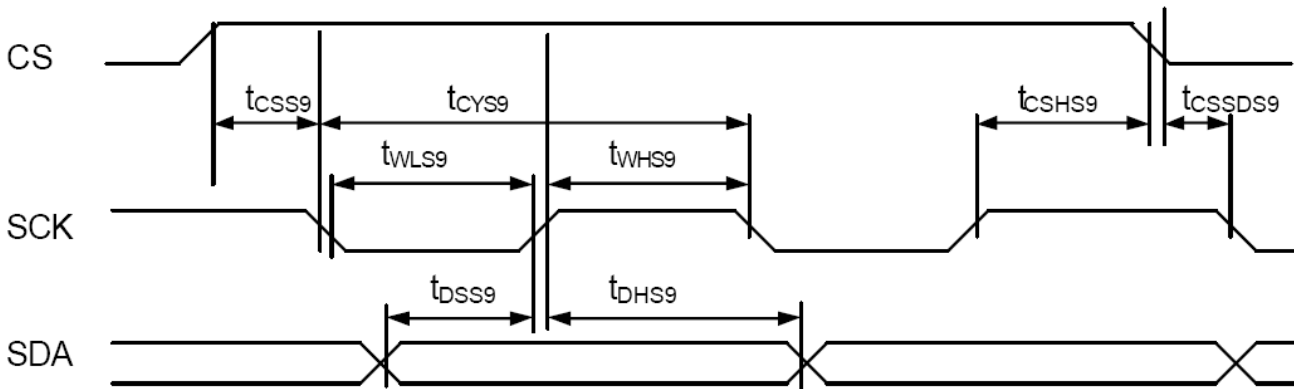


FIGURE 18: Serial Bus Timing Characteristics (for S9)

| Symbol | Signal | Description | Condition | Min. | Max. | Units |
|--|--------|------------------------|-----------|----------------|------|-------|
| t_{CYS9} | SCK | System cycle time | | 140 | – | nS |
| t_{LPWS9} | | Low pulse width | | 65 | – | nS |
| t_{HPWS9} | | High pulse width | | 65 | – | nS |
| t_{DSS9} | SDA | Data setup time | | 30 | – | nS |
| t_{DHS9} | | Data hold time | | 20 | – | nS |
| t_{CSSAS9} t_{CSSDS9} t_{CHS9} | CS | Chip select setup time | | 10 20 10 | | nS |

RESET TIMING

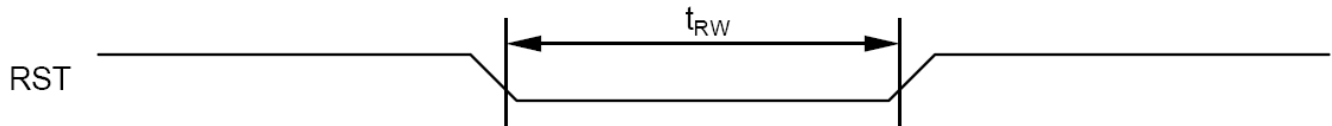


FIGURE 19 : Reset Characteristics

| Symbol | Signal | Description | Condition | Min. | Max. | Units |
|----------|--------|-----------------------|-----------|------|------|-------|
| t_{RW} | RST | Reset low pulse width | | 1000 | – | nS |

INITIALIZATION METHOD

POWER-UP

| Type | C/D | W/R | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | Chip action | Comments |
|------|------------------|------------------|------------------|------------------|------------------|------------------|------------------|------------------|------------------|------------------|---------------------------|--|
| R | – | – | – | – | – | – | – | – | – | – | Automatic Power-ON-Reset. | Wait 15mS after V_{DD} is ON |
| C | 0 | 0 | 0 | 0 | 1 | 0 | 0 | # | # | # | (5) Set MR and TC | |
| C | 0 | 0 | 1 | 1 | 0 | 0 | # | # | # | # | (15) Set LCD Mapping | Set up LCD specific parameters such as format, MX, MY, MSF, etc. |
| C | 0 | 0 | 1 | 1 | 1 | 0 | 1 | 0 | # | # | (18) Set Bias Ratio | |
| R | 0 0 | 0 0 | 1 # | 0 # | 0 # | 0 # | 0 # | 0 # | 0 # | 1 # | (9) Set Gain & PM | |
| C | 1 . . 1 | 0 . . 0 | # . . # | # . . # | # . . # | # . . # | # . . # | # . . # | # . . # | # . . # | Write display RAM | Set up display image |
| R | 0 | 0 | 1 | 0 | 1 | 0 | 1 | 1 | 1 | 1 | (13) Set Display Enable | |

ELECTRO-OPTICAL CHARACTERISTICS

MEASURING CONDITION: POWER SUPPLY = $V_{OP} / 64 \text{ Hz}$
 TEMPERATURE = $23 \pm 5 \text{ }^\circ\text{C}$
 RELATIVE HUMIDITY = $60 \pm 20 \%$

| ITEM | SYMBOL | UNIT | TYP. TN | TYP. STN |
|--------------------------------|--------|----------|---------|----------|
| RESPONSE TIME | Ton | ms | - | 290 |
| | Toff | ms | - | 370 |
| CONTRAST RATIO | Cr | - | - | 9 |
| VIEWING ANGLE (Cr \geq 2) | V3:00 | $^\circ$ | - | 40 |
| | V6:00 | $^\circ$ | - | 60 |
| | V9:00 | $^\circ$ | - | 40 |
| | V12:00 | $^\circ$ | - | 40 |

THE ELECTRO-OPTICAL CHARACTERISTICS ARE MEASURED VALUE BUT NOT GUARANTEED ONES.

RELIABILITY OF LCD MODULE

| ITEM | TEST CONDITION FOR NORMAL TEMPERATURE | TEST CONDITION FOR WIDE TEMPERATURE | TIME |
|------------------------------|--|--|-----------|
| High temperature operating | 50°C | 70°C | 240 hours |
| Low temperature operating | 0°C | -20°C | 240 hours |
| High temperature storage | 60°C | 80°C | 240 hours |
| Low temperature storage | -10°C | -30°C | 240 hours |
| Temperature-humidity storage | 40°C 90% R.H. | 60°C 90% R.H. | 96 hours |
| Temperature cycling | -10°C to 60°C 30 Min Dwell | -30°C to 80°C 30 Min Dwell | 5 cycle |
| Vibration Test at LCM Level | Freq 10-55 Hz Sweep rate: 10-55-10 at 1 min Sweep mode Linear Displacement: 2 mm p-p 1 Hour each for X, Y, Z | Freq 10-55 Hz Sweep rate: 10-55-10 at 1 min Sweep mode Linear Displacement: 2 mm p-p 1 Hour each for X, Y, Z | — |

QUALITY STANDARD OF LCD MODULE

| | | | |
|---------------------------|---|--|--|
| 1.0 | Sampling Method | | |
| | Sampling Plan : MIL STD 105 E Class of AQL : Level II/Single Sampling Critical : 0.25% Major 0.65% Minor 1.5% | | |
| 2.0 | Defect Group | Failure Category | Failure Reasons |
| | Critical Defect 0.25%(AQL) | Malfunction | Open Short Burnt or dead component Missing part/improper part P.C.B. Broken |
| | Major Defect 0.65%(AQL) | Poor Insulation | Potential short High current Component damage or scratched or Lying too close improper coating |
| | | Poor Conduction | Damage joint Wrong polarity Wrong spec. part Uneven/intermittent contact Loose part Copper peeling Rust or corrosion or dirt's |
| Minor Defect 1.5%(AQL) | Cosmetic Defect | Minor scratch Flux residue Thin solder Poor plating Poor marking Crack solder Poor bending Poor packing Wrong size | |

SAMPLING METHOD

SAMPLING PLAN: MIL-STD 105E

CLASS OF AQL: LEVEL II/ SINGLE SAMPLING
 MAJOR-0.65% MINOR – 1.5%

QUALITY STANDARD

| DEFECT | CRITERIA | TYPE | FIGURE |
|------------------------|---|-------|--------|
| SHORT CIRCUIT | - | MAJOR | - |
| MISSING SEGMENT | - | MAJOR | - |
| UNEVEN / POOR CONTRAST | - | MAJOR | - |
| CROSS TALK | - | MAJOR | - |
| PIN HOLE | $MAX(a,b) \leq 1 / 3 W$ | MINOR | 1 |
| EXCESS SEGMENT | $MAX(c,d) \leq 1 / 3 T$ | MINOR | 1 |
| BUBBLES | $d^* \geq 0.5$ QTY=0 | MINOR | 2 |
| SPOTS | $d \leq 0.6$ N.A.** $0.6 < d \leq 0.7$ QTY \leq 2 $0.7 < d$ QTY=0 | MINOR | 2 |
| LINE SCRATCHES | $x \geq 0.7$ $y \geq 0.05$ QTY=0 | MINOR | 3 |
| BLACK LINE | $x \geq 0.7$ $y \geq 0.05$ QTY=0 | MINOR | 3 |

*d = MAX (d₁,d₂)

** N. A . = NOT APPLICABLE

DEFECT TABLE : E

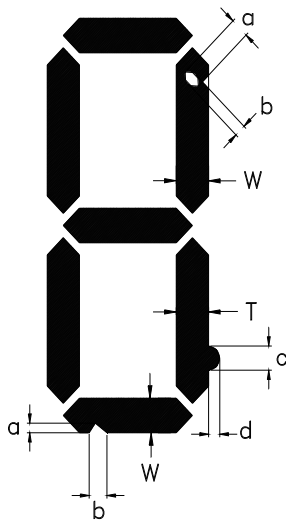
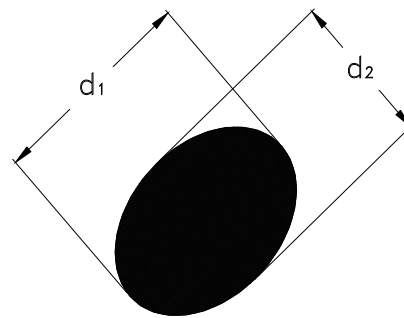
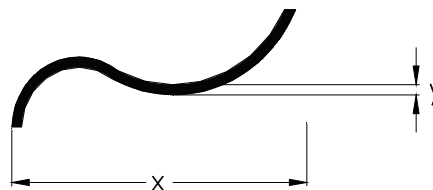


fig . 1



POLARIZER BUBBLES / SPOTS

fig . 2



LINE SCRATCHES / BLACK LINE

fig . 3

QUALITY STANDARD (CONT .)

| DEFECT | | CRITERIA | TYPE | FIGURE |
|------------------|--------------|---------------------------------------|-------|--------|
| CHIPS | CONTACT EDGE | $e \leq T$ $f \leq 1/2W$ $g: N.A.$ | MINOR | 4 |
| | BOTTOM GLASS | $p \leq V.A.***$ $q: N.A.$ $r \leq T$ | | 4 |
| | CORNER | $a: N.A.$ $b \leq W$ | | 4 |
| | TOP GLASS | $a: N.A.$ $b \leq T$ $c \leq W$ | | 5 |
| GLASS PROTRUSION | | $a \leq 1/3 W$ | MINOR | 6 |
| RAINBOW | | - | MINOR | - |

UNLESS STATE OTHERWISE , ALL UNIT ARE IN MILLIMETER .

***CANNOT EXTEND IN V.A.

DEFECT TABLE : E

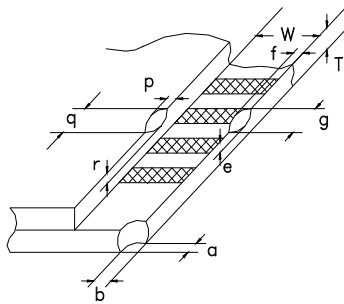


fig . 4

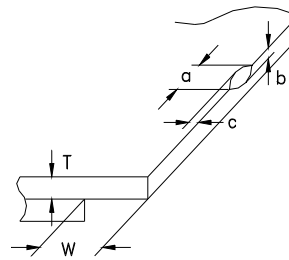


fig . 5

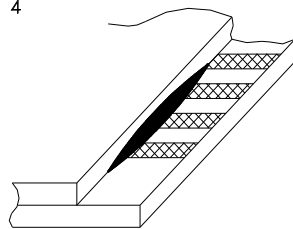


fig . 6

HANDLING PRECAUTIONS

(1) CAUTION OF LCD HANDLING & CLEANING

Use soft cloth with solvent (recommended below) to clean the display surface and wipe lightly.

- Isopropyl alcohol, ethyl alcohol, trichlorotrifluoroethane

Do not wipe the display surface with dry or hard materials that will damage the polarizer surface. Do not use the following solvent;

-water, ketone, aromatics

(2) CAUTION AGAINST STATIC CHARGE

The LCD modules use CMOS LSI drivers, so customers are recommended that any unused input terminal would be connected to V_{DD} or V_{SS} , do not input any signals before power is turned on, and ground your body, work/assembly areas, assembly equipment to protect against static electricity.

Remove the protective film slowly and, if possible, under ESD control device like ion blower and humidity of working room should be kept over 50%RH to reduce risk of static charge.

(3) PACKAGING

Avoid intense shock and falls from a height and do not operate or store them exposed direct to sunshine or high temperature/humidity.

(4) CAUTION FOR OPERATION

It is an indispensable condition to drive LCD's within the specified voltage limit since the higher voltage than the limit causes the shorter LCD life. The use of direct current drive should be avoided because an electrochemical reaction due to direct current causes LCD's undesirable deterioration.

Response time will be extremely delayed at low temperature, and LCD's show dark color at high temperature. However those phenomena do not mean malfunction or out of order with LCD's.

Some font will be abnormally displayed when the display area is pushed hard during operation. But it resumes normal condition after turning off once.

(5) SAFETY

For crash damaged or unnecessary LCD's, it is recommended to wash off liquid crystal by either of solvents such as acetone and ethanol and should be burned up later.

When any liquid leaked out of a damaged glass cell comes in contact with your hands, wash it off with soap and water.

WARRANTY

CLOVER will replace or repair any of her LCD module in accordance with her LCD specification for a period of one year from date of shipment. The warranty liability of Clover is limited to repair and/or replacement. Clover will not be responsible for any subsequent or consequential event.