Slider Type
Mini
Standard
Controllers Integrated
Rod Type
Mini
Standard
Controllers Integrated
Table/ Arm/ Flat Type
Mini
Standard
Gripper/ Rotary Type
Linear Servo Type
Clean- room Type
Splash- Proof Type

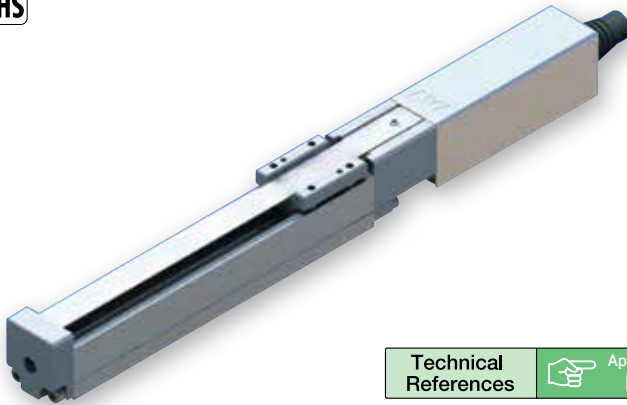## RCP3-SA2AC
ROBO Cylinder, Mini Slider Type, Coupled Motor, 22mm Width, Pulse Motor, Lead Screw

Model Specification Items	RCP3	SA2AC	I	20P	☐	☐	☐	☐	☐
	Series	Type	Encoder type	Motor type	Lead	Stroke	Applicable controller	Cable length	Options

I: Incremental
* The Simple absolute encoder is also considered type "I".

20P: Pulse motor, 20☐ size

4S : 4mm lead screw
2S : 2mm lead screw
1S : 1mm lead screw

25: 25mm ⌇ 100: 100mm (25mm pitch increments)

P1: PCON-PL/PO/SE PSEL
P3: PCON-CA PMEC/PSEP MSEP

N: None
P: 1m
S: 3m
M: 5m
X☐☐: Custom length

NM: Non-motor end

* See page Pre-47 for details on the model descriptions.

CE RoHS

POINT Notes on selection

(1) The load capacity is based on operation at an acceleration of 0.2G. This value is the upper limit for the acceleration.
(2) The actuator cannot be used on its side or in a vertical orientation.
(3) If used in a dusty environment, the service life will decrease significantly.
(4) This model uses a lead screw, therefore please ensure that your usage is appropriate for its characteristics. (See page Pre-52.)
(5) See page A-71 for details on push motion.

Technical References ☞ Appendix P.5

■ **Speed vs. Load Capacity**
Due to the characteristics of the pulse motor, the RCP3 series' load capacity decreases at high speeds. In the table below, check if your desired speed and load capacity are supported.

Horizontal
1mm lead
2mm lead
4mm lead

Load Capacity (kg) vs Speed (mm/s)
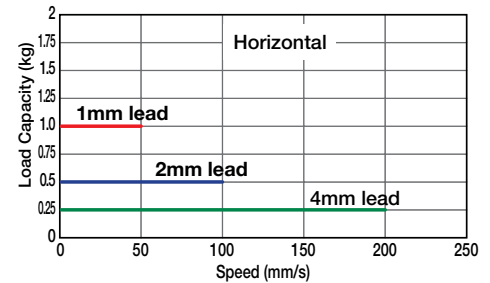
Actuator Specifications

■ **Leads and Payloads**

Model number	Feed screw	Lead (mm)	Max. Load Capacity Horizontal (kg)	Max. Load Capacity Vertical (kg)	Positioning Repeatability (mm)	Stroke (mm)
RCP3-SA2AC-I-20P-4S-①-P3-②-③-④	Lead screw	4	0.25	—	±0.05	25~100 (every 50mm)
RCP3-SA2AC-I-20P-2S-①-P3-②-③-④		2	0.5	—		
RCP3-SA2AC-I-20P-1S-①-P3-②-③-④		1	1	—		

Code explanation ① Stroke ② Applicable Controller ③ Cable length ④ Options *See page A-71 for details on push motion.

■ **Stroke and Maximum Speed**

Lead \ Stroke	25 (mm)	50~100 (mm)
4 (Lead screw)	180	200
2	100	
1	50	

(Unit: mm/s)

①Stroke

①Stroke (mm)	Standard price
25	—
50	—
75	—
100	—

③Cable Length

Type	Cable symbol	Standard price
Standard (Robot Cables)	**P** (1m)	—
	S (3m)	—
	M (5m)	—
Special length	**X06** (6m) ~ **X10** (10m)	—
	X11 (11m) ~ **X15** (15m)	—
	X16 (16m) ~ **X20** (20m)	—

* The standard cable for the RCP3 is the robot cable.
* See page A-59 for cables for maintenance.

④ Options

Name	Option code	See page	Standard price
Non-motor end specification	NM	→ A-52	—

Actuator Specifications

Item	Description
Drive System	Lead screw, ø4mm, rolled C10
Lost Motion	0.3mm or less (initial value)
Base	Material: Aluminum, white alumite treated
Guide (*)	Slide guide
Ambient Operating Temp./Humidity	0 to 40°C, 85% RH or less (Non-condensing)
Service Life	10 million cycles

* Offset load not supported.

Pulse Motor
Servo Motor (24V)
Servo Motor (200V)
Linear Servo Motor

Dimensional Drawings

CAD drawings can be downloaded from the website. **www.intelligentactuator.com**

For Special Orders ☞ Appendix **P.15**

2D CAD **3D CAD**
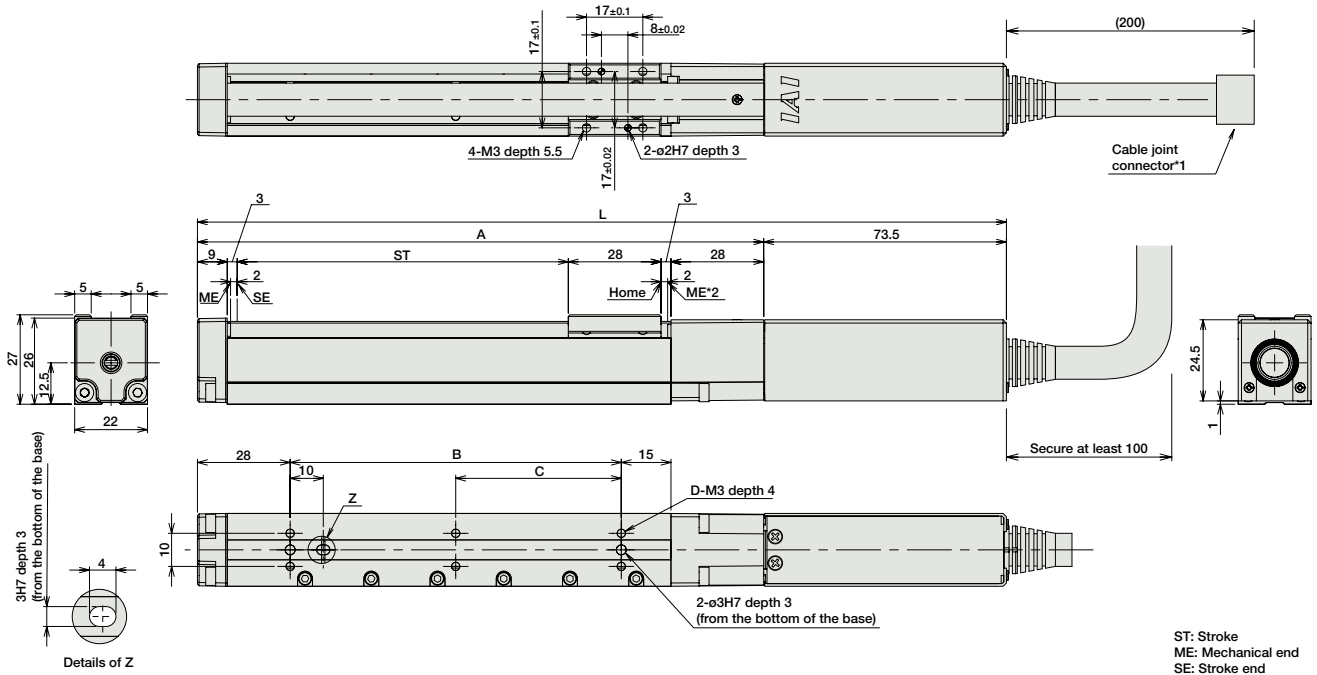
*1 Connect the motor-encoder integrated cable here. See page A-59 for details on cables.
*2 During the homing operation, the slider moves to actuator's mechanical end, and then reverses. Therefore, watch for any interference with its surroundings.

17±0.1
17±0.1
8±0.02
(200)
4-M3 depth 5.5
17±0.02
2-ø2H7 depth 3
Cable joint connector*1

3
L
3
A
73.5
9
ST
28
28
2
ME / SE
Home
2
ME*2
24.5
Secure at least 100
1
5 5
27
26
12.5
22
3H7 depth 3 (from the bottom of the base)
4
Details of Z

28
10
Z
B
C
15
10
D-M3 depth 4
2-ø3H7 depth 3 (from the bottom of the base)

ST: Stroke
ME: Mechanical end
SE: Stroke end

■ Dimensions and Mass by Stroke

Stroke	25	50	75	100
L	169.5	194.5	219.5	244.5
A	96	121	146	171
B	25	50	75	100
C	0	0	0	50
D	4	4	4	6
Weight (kg)	0.25	0.27	0.29	0.3

②Applicable Controllers

RCP3 series actuators can be operated with the controllers indicated below. Select the type according to your intended application.

Name	External view	Model number	Features	Maximum number of positioning points	Input power	Power-supply capacity	Standard price	Reference page
Solenoid Valve Type		PMEC-C-20PI-①-2-⑪	Easy-to-use controller, even for beginners	3 points	AC100V AC200V	Refer to P541	—	→ P537
		PSEP-C-20PI-①-2-0	Simple controller operable with the same signal as a solenoid valve		DC24V	Refer to P555	—	→ P547
Solenoid valve multi-axis type PIO specification		MSEP-C-⑪-~-①-2-0	Positioner type based on PIO control, allowing up to 8 axes to be connected			Refer to P572	—	→ P563
Solenoid valve multi-axis type Network specification		MSEP-C-⑪-~-Ⅳ-0-0	Field network-ready positioner type, allowing up to 8 axes to be connected	256 points			—	
Positioner type High-output specification		PCON-CA-20PI-①-2-0	Equipped with a high-output driver Positioner type based on PIO control	512 points		Refer to P618	—	→ P607
Pulse-train type High-output specification		PCON-CA-20PI-PL□-2-0	Equipped with a high-output driver Pulse-train input type	(—)			—	
Field network type High-output specification		PCON-CA-20PI-Ⅳ-0-0	Equipped with a high-output driver Supporting 7 major field networks	768 points			—	
Pulse Train Input Type (Differential Line Driver)		PCON-PL-20PI-①-2-0	Pulse train input type with differential line driver support	(—)		Refer to P628	—	→ P623
Pulse Train Input Type (Open Collector)		PCON-PO-20PI-①-2-0	Pulse train input type with open collector support				—	
Serial Communication Type		PCON-SE-20PI-N-0-0	Dedicated Serial Communication	64 points			—	
Program Control Type		PSEL-CS-1-20PI-①-2-0	Programmed operation is possible. Can operate up to 2 axes	1,500 points		Refer to P671	—	→ P665

* This is for the single-axis PSEL.   * ① indicates I/O type (NP/PN).   * ⑪ indicates power supply voltage (1: 100V / 2: 100~240V).
* ⑪ indicates number of axes (1 to 8). * Ⅳ indicates field network specification symbol. * □ indicates N (NPN specification) or P (PNP specification) symbol.

Slider Type
Mini
Standard
Controllers Integrated
Rod Type
Mini
Standard
Controllers Integrated
Table/Arm/Flat Type
Mini
Standard
Gripper/Rotary Type
Linear Servo Type
Clean-room Type
Splash-Proof Type
Pulse Motor
Servo Motor (24V)
Servo Motor (200V)
Linear Servo Motor