

Note 1. The robot cable is standard cable (3L/5L/10L), but can be changed to flexible cable

■ Specifications				
AC servo motor	30			
Repeatability Note 1 (mm)		+/-0.02		
Deceleration mechanism		Ball screw $\phi$ 12 (Class C10)		
Ball screw lead (mm)		20	12	6
Maximum speed Note 2 (mm/sec)		1200	800	400
Maximum	Horizontal	3	5	9
payload (kg)	Vertical	-	1.2	2.4
Rated thrust (N)		19	32	64
Stroke (mm)		50 to 800 (50mm pitch)		
Overall length	Horizontal	Stroke+201.5		
(mm)	Vertical	Stroke+239.5		
Maximum dimensions of cross section of main unit (mm)		W55×H52		
Cable length (m)		Standard: 3.5 / Option: 5,10		
Linear guide type		2 rows of gothic arch grooves × 1 rail		
Position detector		Resolvers Note 3		
Resolution (Pulse/rotation)		16384		

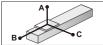
Positioning repeatability in one direction.

When the stroke is longer than 600mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed settling on the program by referring to the maximum speeds shown in the table below.

Position detectors (resolvers) are common to incremental and absolute specifications. If the controller has a backup function then it will be absolute specifications.

## Allowable overhang Note

С



A B

105 294

Horizontal installation

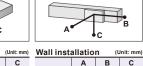
**3kg** 1194

2kg 916 159 398

20 1kg 967 324 598

Lead 3kg 429 104 226

Lead 5kg 436 60 152







	Vei	(Unit: mm)		
ı			Α	С
	Lead 12	1.2kg	240	239
	Lead 6	2.4kg	109	110

624 31 89 50 15 385 9ka 9ka Note. Distance from center of slider top to center of gravity of object being carried at a guide service

87 950

1kg 551 304 925

3kg 185 89 378

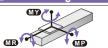
2kg 347 141 800

5kg 119 44 355

3kg 259

life of 10,000 km. Note. Service life is calculated for 600mm stroke models.

## Static loading moment



(Unit: N·m)

	MY		MP	MR
	30		34	40
■ Controller				
	Controller Operation method			

	Conti	Controller		
Ì	Controller	Operation method		
	SR1-X05	Programming / I/O point trace / Remote command / Operation using RS-232C communication		
	TS-X105	I/O point trace /		
	TS-X205	Remote command		
	RDX-05	Pulse train control		

