## **YK600XG**

Standard type: Medium type

Arm length 600mm
Maximum payload 20kg

■ Ordering method

YK600XGH

**RCX240** 

BB

Note 1. Use N to N4 when NPN is selected on the I/O board, and P to P4 when PNP is selected. Note 2. Available only for the master.

■ Specifications							
			X-axis	Y-axis	Z-axis		R-axis
Axis	Arm length (mm)		200	400	200	400	-
specifications	Rotation angle (°)		+/-130	+/-150	-		+/-360
AC servo motor output (W)			750	400	400		200
Deceleration mechanism	Speed reducer		Harmonic drive	Harmonic drive	Ball screw		Harmonic drive
	Transmission method	Motor to speed reducer	Direct-coupled				
		Speed reducer to output	Direct-coupled				
Repeatability Note 1 (XYZ mm) (R °)			+/-0.02		+/-0.01		+/-0.004
Maximum speed (XYZ m/sec) (R °/sec)			7.7		2 3	1.7	920
Maximum payload (kg)			20				
Standard cycle time with 2kg payload Note 2 (sec)			0.47				
R-axis tolerable moment of inertia Note 3 (kgm²)			1.0				
User wiring (sq × wires)			0.2 × 20				
User tubing (Outer diameter)			ф6 × 3				
Travel limit			1.Soft limit 2.Mechanical stopper (X,Y,Z axis)				
Robot cable length (m)			Standard: 3.5 Option: 5,10				
Weight (kg) (Excluding robot cable)			Z axis200mm: 48 Z axis400mm: 50				

■ Controller Controller Power capacity (VA) Operation method Programming / I/O point trace / Remote command / Operation RCX240-R3 2500 using RS-232C communication

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
Note 2. When reciprocating 300mm in horizontal and 25mm in vertical directions.
Note 3. There are limits to acceleration coefficient settings. See P.432.
Note. Please consult YAMAHA when connecting other tubes and cables to the self-supporting machine harness.

