

YK250XGC

- Arm length 250mm
- Maximum payload 4kg



Ordering method

YK250XGC - 150				RCX240S						BB
Model	Z axis stroke	Tool flange	Cable length	Controller	Usable for CE	Expansion I/O ^{Note 1}	Network option	iVY System	Gripper	Battery
	150: 150mm	No entry: None F: With tool flange	3L: 3.5m 5L: 5m 10L: 10m		No entry: Standard E: CE marking	N, P: Standard I/O 16/8 N1, P1: 40/24 N2, P2: 64/40 N3, P3: 88/56 N4, P4: 112/72	No entry: None CC: CC-Link DN: DeviceNet PB: Profibus EN: Ethernet EP: EtherNet/IP ^{Note 2} YC: YC-Link	No entry: None VY: iVY (Vision) TR: iVY+Light +Tracking LC: iVY+Light	No entry: None GR: Gripper	BB: 4 pcs

Note 1. Use N to N4 when NPN is selected on the I/O board, and P to P4 when PNP is selected.
 Note 2. Available only for the master. See P.39 for details on YC-Link system.

Basic specifications

	X axis	Y axis	Z axis	R axis
Axis specifications				
Arm length (mm)	100	150	150	-
Rotation angle (°)	+/-129	+/-134	-	+/-360
AC servo motor output (W)	200	150	50	100
Repeatability ^{Note 1} (XYZ: mm) (R: °)	+/-0.01		+/-0.01	+/-0.004
Maximum speed (XYZ: m/sec) (R: °/sec)	4.5		1.1	1020
Maximum payload (kg)	4			
Standard cycle time: with 2kg payload (sec) ^{Note 2}	0.57			
R-axis tolerable moment of inertia ^{Note 3} (kgm ²)	0.05			
User wiring (sq x wires)	0.2x10			
User tubing (Outer diameter)	φ4x4			
Travel limit	1.Soft limit, 2.Mechanical stopper (X, Y, Z axes)			
Robot cable length (m)	Standard: 3.5 Option: 5, 10			
Weight (kg)	21.5			
Degree of cleanliness	Class ISO 3 (ISO 14644-1) ^{Note 4} +ESD ^{Note 5}			
Intake air (Nℓ/min)	30 ^{Note 6}			

Note 1. This is the value at a constant ambient temperature. (X,Y axes)
 Note 2. When reciprocating 25mm in vertical direction and 300mm in horizontal direction (rough-positioning arch motion).
 Note 3. There are limits to acceleration coefficient settings. See P.477.
 Note 4. Class 10 (0.1µm) equivalent to FED-STD-209D
 Note 5. ESD (ElectroStatic Discharge) prevention is an option. Please contact our distributor.
 Note 6. The necessary intake amount varies depending on the use conditions and environment.

Controller

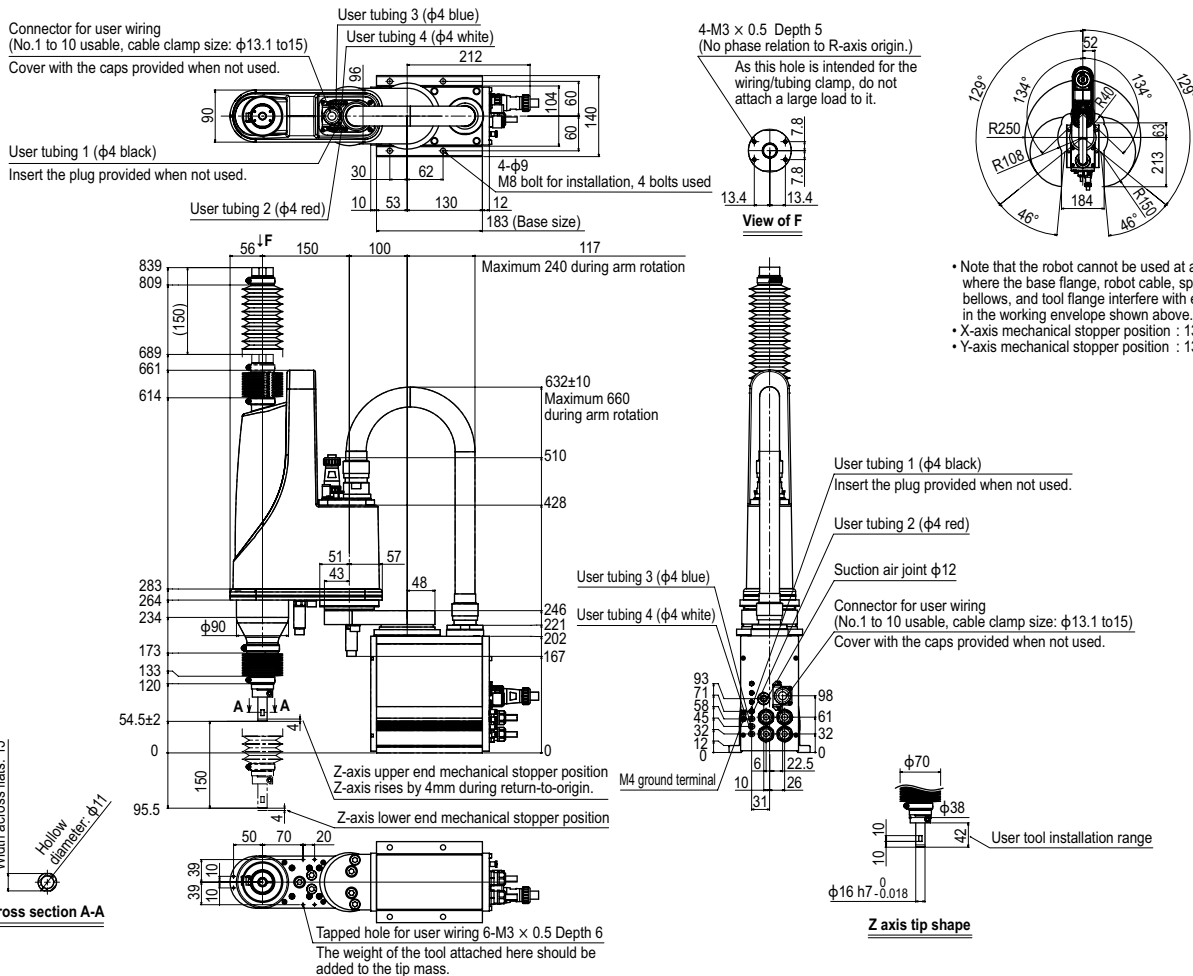
Controller	Power capacity (VA)	Operation method
RCX240S	1000	Programming / I/O point trace / Remote command / Operation using RS-232C communication

Note. The movement range can be limited by changing the positions of X and Y axis mechanical stoppers. (The movement range is set to the maximum at the time of shipment.)
 See our robot manuals (installation manuals) for detailed information.

Note. To set the standard coordinates with high accuracy, use a standard coordinate setting jig (option). Refer to the user's manual (installation manual) for more details.

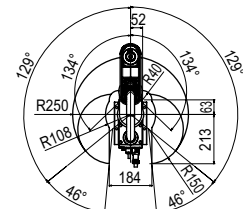
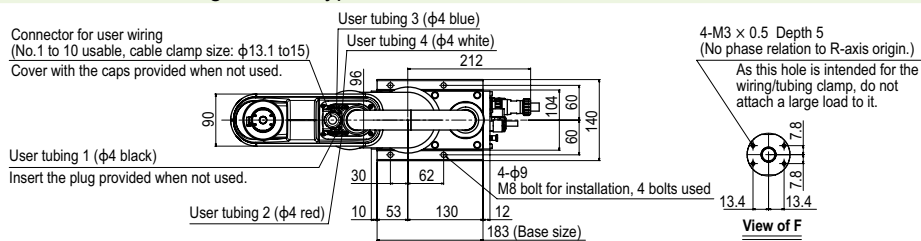
Our robot manuals (installation manuals) can be downloaded from our website at the address below:
<http://www.yamaha-motor.co.jp/global/industrial/robot/>

YK250XGC



- Note that the robot cannot be used at a position where the base flange, robot cable, spline, bellows, and tool flange interfere with each other in the working envelope shown above.
- X-axis mechanical stopper position : 131°
- Y-axis mechanical stopper position : 136°

YK250XGC Tool flange mount type



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- Y-axis mechanical stopper position : 136°

