APPLICATION
TRANSERVO — Compact single-axis robots
FLIP-X — Single-axis robots
PHASER — Linear motor single-axis robots
XY-X — Cartesian robots
YK-XG — SCARA robots
YP-X — Pick & place robots
CLEAN
CONTROLLER
INFORMATION
Arm type
Gantry type
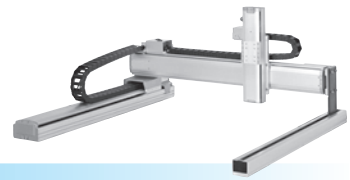Moving arm type
Pole type
XZ type

HXYx 3 axes / ZL

● Gantry type   ● Cable carrier   ● Z-axis: clamped base / moving table type (200W)

■ Ordering method

HXYx - C ☐ ☐ ☐ ZL ☐ ☐ RCX240 ☐ R ☐ ☐ BB

Model	Cable	Combination	X-axis stroke	Y-axis stroke	ZR-axis	Z-axis stroke	Cable length	Controller	Usable for CE	Regenerative unit	Option I/O Note 1	Network option	Battery
		G1 G2 G3 G4	25 to 125cm	25 to 105cm		25 to 55cm	3L: 3.5m (Standard) 5L: 5m 10L: 10m		No entry: Standard E: CE marking	R: RGU-2	N, P: Standard I/O 16/8 N1, P1: 40/24 N2, P2: 64/40 N3, P3: 88/56 N4, P4: 112/72	No entry: None CC: CC-Link DN: DeviceNet PB: Profibus EN: Ethernet YC: YC-Link Note 2	BB: 4 pcs

Note 1. N to N4 if NPN was selected, or P to P4 if PNP was selected for the I/O board.
Note 2. Available only for the master.

■ Specification

	X-axis	Y-axis	Z-axis
Axis construction Note 1	F20	F17	F14H-BK
AC servo motor output (W)	600	400	200
Repeatability Note 2 (mm)	+/-0.01	+/-0 01	+/-0.01
Drive system	Ball screw (Class C7)	Ball screw (Class C7)	Ball screw (Class C7)
Ball screw lead (Deceleration ratio) (mm)	20	20	10
Maximum speed Note 3 (mm/sec)	1200	1200	600
Moving range (mm)	250 to 1250	250 to 1050	250 to 550
Robot cable length (m)	Standard: 3.5 Option: 5,10		

Note 1. Use caution that the flame machining (installation holes, tap holes) differs from single-axis robots'.
Note 2. Positioning repeatability in one direction.
Note 3. When the X-axis/Y-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table below.
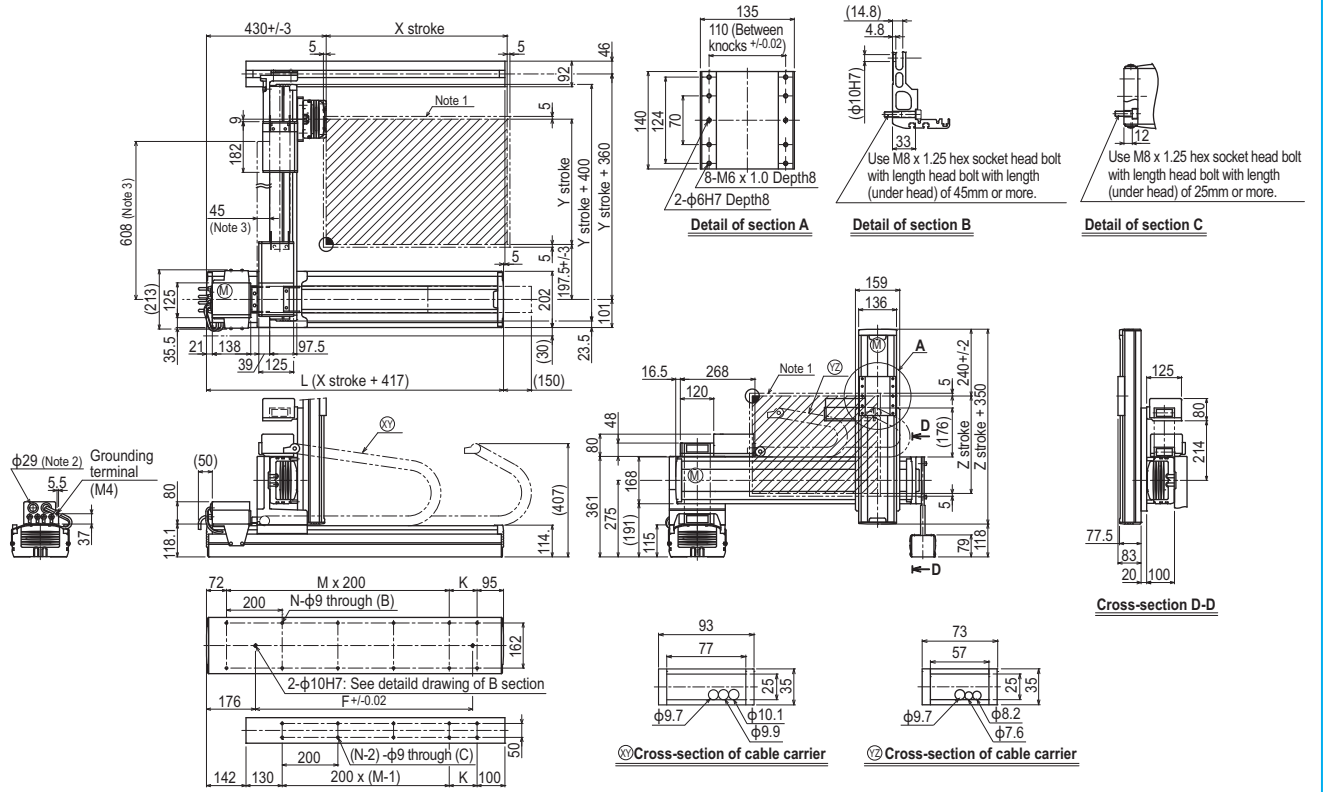
■ Maximum payload (kg)

	Z stroke (mm)
Y stroke (mm)	250 to 550
250 to 1050	20

■ Controller

Controller	Operation method
RCX240-R	Programming / /O point trace / Remote command / Operation using RS-232C communication

HXYx 3 axes / ZL G1

X stroke	250	350	450	550	650	750	850	950	1050	1150	1250
L	667	767	867	967	1067	1167	1267	1367	1467	1567	1667
K	100	200	100	200	100	200	100	200	100	200	100
F	420	420	600	600	780	780	960	960	1140	1320	1320
M	2	2	3	3	4	4	5	5	6	6	7
N	8	8	10	10	12	12	14	14	16	16	18

Y stroke	250	350	450	550	650	750	850	950	1050

Z stroke	250	350	450	550

Maximum speed for each stroke (mm/sec) Note 4	X-axis	1200						960	840	720	600	480
	Y-axis	1200						960	840	720		
	Speed setting	–						80%	70%	60%	50%	40%

Note 1. The moving range when returning to origin and the stop position when stopping by the mechanical stopper.
Note 2. User cable extraction port.
Note 3. Dimension of reinforced bracket (To be installed when the Y stroke is 750mm or longer)

Note 4. When the X-axis/Y-axis stroke is longer than 850mm, resonance of the ball screw may occur depending on the operation conditions (critical speed). In this case, reduce the speed setting on the program by referring to the maximum speeds shown in the table at the left.