Superior Clamping and Gripping

Product Information

Sealed universal gripper DPZ-plus 64

Fully encapsulated. Reliable. Precise.

Sealed gripper DPZ-plus

Despite the high moment load of the base jaws, this sealed 3-finger centric gripper meets the requirements of IP67 and does not permit the ingress of any substances from the working environment into the interior of the component.

Field of application

The gripper is ideally suitable for handling of rough or dirty workpieces. Its field of application extends from the loading and unloading of machines, such as in the case of sanitary blocks, grinding machines, lathes or milling machines, to handling tasks in painting plants, in powder-processing or underwater.

Advantages – Your benefits

Robust interior multi-tooth guidance for the precise handling of different workpieces

Lip seal at the outside round guidance for permanent, secure gripper sealing

High maximum moments possible suitable for using long gripper fingers

Sealed 3-finger centric gripper complies to IP67 requirements despite a high moment load

Fastening at one gripper side in two screw directions for universal and flexible gripper assembly

Maximum gripping forces at a compact design for a wide range of applications

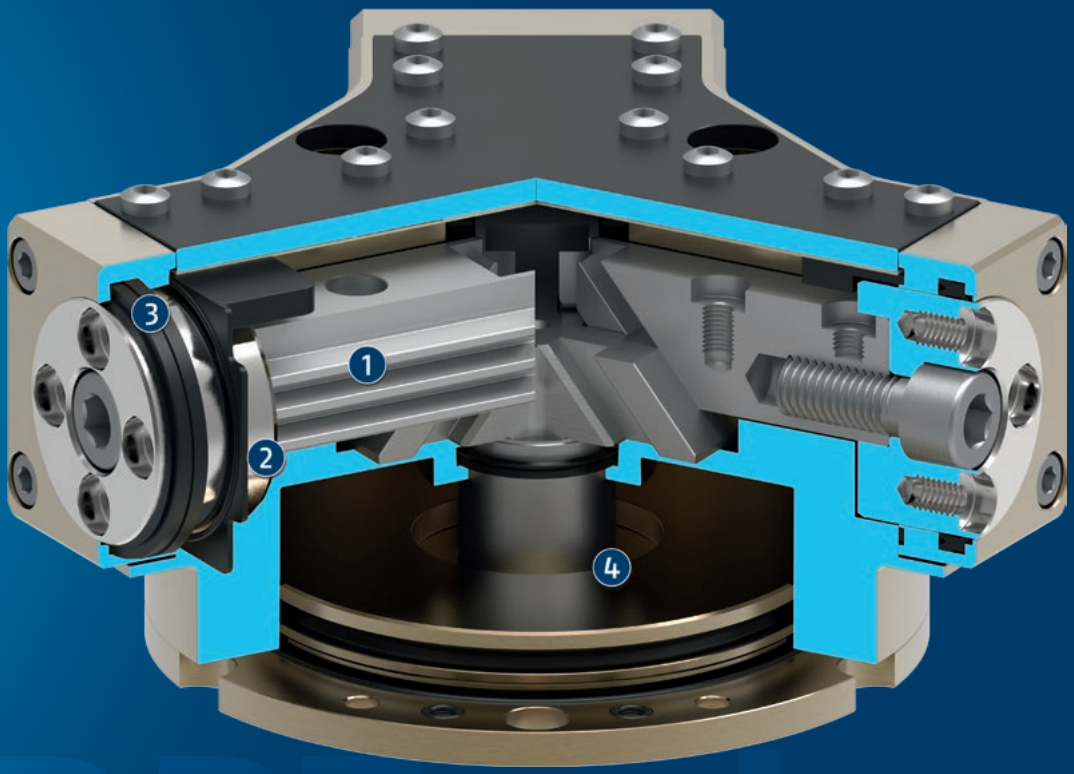
Air supply via hose-free direct connection or screw connections for flexible pressure supply in all automated systems

Compact dimensions for minimal interfering contours in handling

Sizes	Weight	Gripping force	Stroke per jaw	Workpiece weight
Quantity: 8	0.2 .. 20.1 kg	230 .. 16500 N	2 .. 25 mm	1.15 .. 60 kg

Functional description

The piston is moved up and down by compressed air. The angled active surfaces of the wedge-hook produce a synchronized, centric jaw movement.



① **Inner base jaw with multi-tooth guidance**
for high moment loads

② **External round base jaw**
providing a sealable, round surface

③ **Lip seal**
for permanent, secure gripper sealing

④ **Round piston with rod and wedge-hook**
for power generation

General notes about the series

Operating principle: Wedge-hook kinematics

Housing material: Aluminum alloy, anodized

Base jaw material: Steel

Actuation: pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

Warranty: 36 months

Scope of delivery: Centering sleeves, centering pins, O-rings for direct connection, assembly instructions (operating manual with declaration of incorporation is available online)

Gripping force maintenance device: possible by using the version with mechanical gripping force maintenance or pressure maintenance valve SDV-P

Finger length: is measured from the reference surface as the distance P in direction to the main axis.
The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

Note – tightness: Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

Gripping force: is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

Repeat accuracy: is defined as a distribution of the end Position for 100 consecutive strokes.

Workpiece weight: is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.

Application example

Insertion tool for assembly of small to medium-sized workpieces. The tool can be used in both clean and dirty environments. Due to its quick-change system, other tools can alternately be fixed to the robot flange.

1. 3-finger centric gripper DPZ-plus
2. Quick-change system SWS

SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.

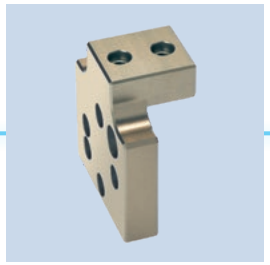
Compensation unit

Tolerance compensation unit

Pressure maintenance valve

Universal intermediate jaw

Magnetic switches



Intermediate jaw

Jaw quick-change system

ⓘ For more information on these products can be found on the following product pages or at schunk.com.

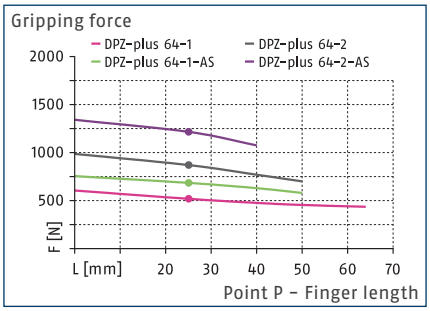
Options and special information

Gripping force maintenance version AS/IS: The mechanical gripping force maintenance version ensures minimum gripping force even in the event of a pressure drop. In the AS/S version this acts as a closing force, in the IS version as an opening force.
Power booster version KVZ: if higher gripping forces are required
ATEX version EX: for explosive environments
Additional versions: Various options can be combined with each other. Numerous additional options are also available – just tell us what your task is!
Integrated air purge connection: impedes the ingress of dirt into the inside of the gripper
Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

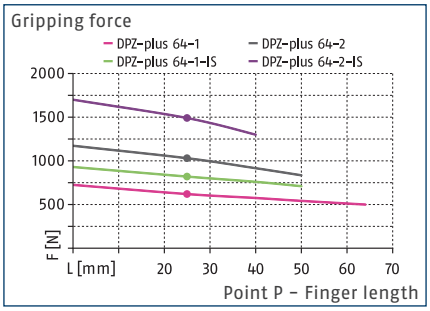
DPZ-plus 64

Sealed universal gripper

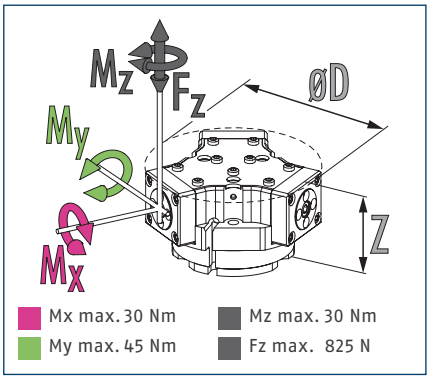
Gripping force O.D. gripping



Gripping force I.D. gripping



Dimensions and maximum loads



ⓘ The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

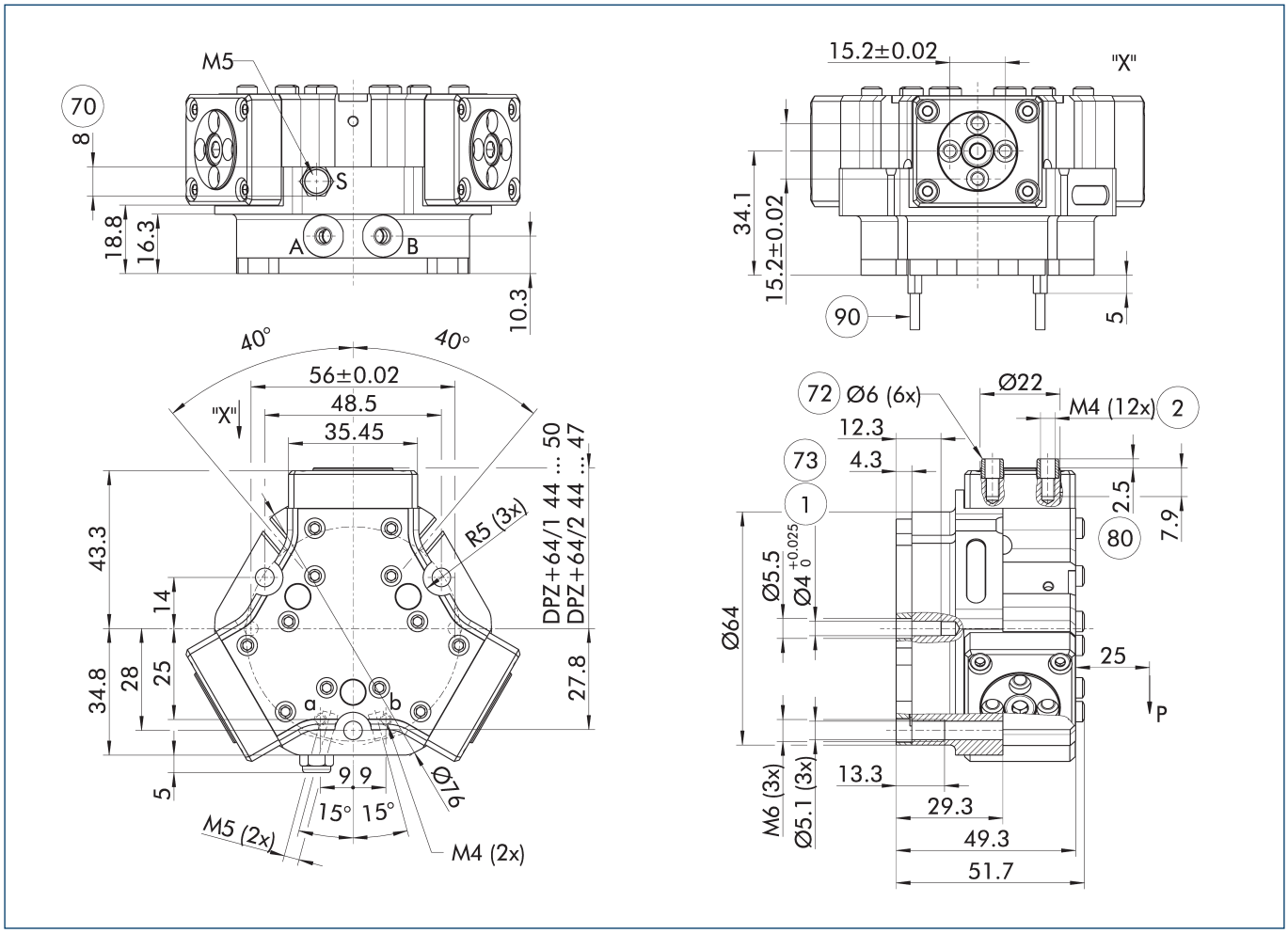
Technical data

Description		DPZ-plus 64-1	DPZ-plus 64-2	DPZ-plus 64-1-AS	DPZ-plus 64-2-AS	DPZ-plus 64-1-IS	DPZ-plus 64-2-IS
ID		1316280	0304412	1316283	0304414	0304415	0304416
Stroke per jaw	[mm]	6	3	6	3	6	3
Closing/opening force	[N]	520/620	870/1030	685/-	1215/-	-/820	-/1490
Min. spring force	[N]			165	345	200	460
Weight	[kg]	0.62	0.62	0.75	0.75	0.75	0.75
Recommended workpiece weight	[kg][g]	2.6	4.35	2.6	4.35	2.6	4.35
Fluid consumption double stroke	[cm³]	25	25	48	48	48	48
Min./nom./max. operating pressure	[bar]	2.5/6/8	2.5/6/8	4/6/6.5	4/6/6.5	4/6/6.5	4/6/6.5
Min./max. air purge pressure	[bar]	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5	0.2/0.5
Closing/opening time	[s]	0.04/0.04	0.04/0.04	0.03/0.05	0.03/0.05	0.05/0.03	0.05/0.03
Max. permissible finger length	[mm]	64	50	50	40	50	40
Max. permissible mass per finger	[kg]	0.3	0.3	0.3	0.3	0.3	0.3
IP protection class		67	67	67	67	67	67
Min./max. ambient temperature	[°C]	5/90	5/90	5/90	5/90	5/90	5/90
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01
Cleanroom class ISO 14644-1:1999		5	5	5	5	5	5
Dimensions Ø D x Z	[mm]	93.6 x 49.2	93.6 x 49.2	93.6 x 62.7	93.6 x 62.7	93.6 x 62.7	93.6 x 62.7
Options and their characteristics							
Power booster version		0304417					
Closing/opening force	[N]	849/935					
Weight	[kg]	0.92					
Maximum pressure	[bar]	6					
Max. permissible finger length	[mm]	40					

ⓘ Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

Main view



For finger connection, we recommend only to use two of the four centering bores for each finger. The drawing shows the gripper in the basic version with closed jaws, the dimensions do not include the options described below.

ⓘ The SDV-P pressure maintenance valve can also be used for I.D. or O.D. gripping alternatively or in addition to the spring-loaded, mechanical gripping force maintenance device (see catalog section on accessories).

A, a Main / direct connection, gripper opening

B, b Main / direct connection, gripper closing

S, E Air purge connection, or deaeration bore

(1) Gripper connection

(2) Finger connection

(70) Wrench size

(72) Fit for centering sleeves

(73) Fit for centering pins

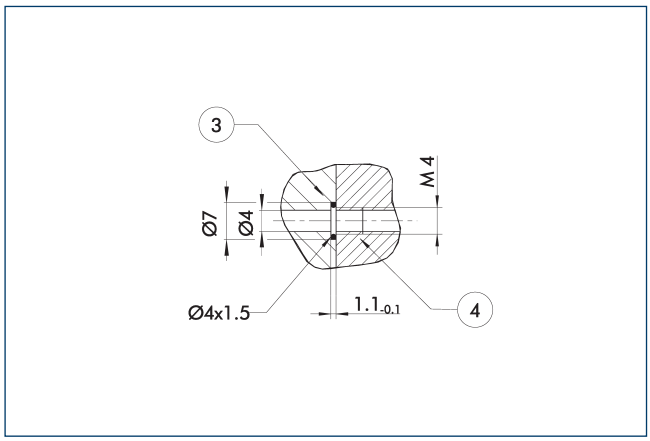
(80) Depth of the centering sleeve hole in the counter part

(90) Sensor MMS 22..

DPZ-plus 64

Sealed universal gripper

Hose-free direct connection M4

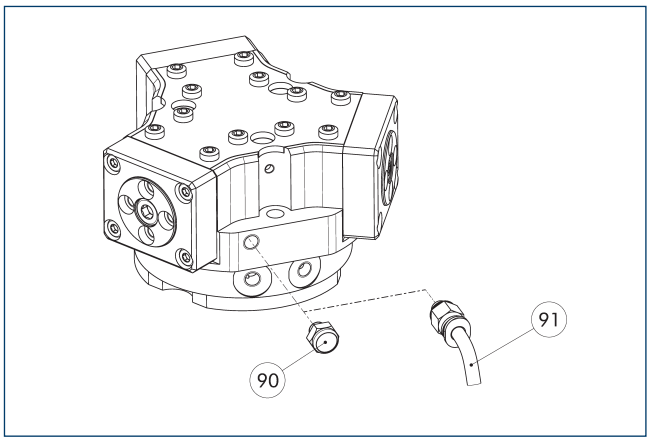


(3) Adapter

(4) Grippers

The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

Connect the air purge connection

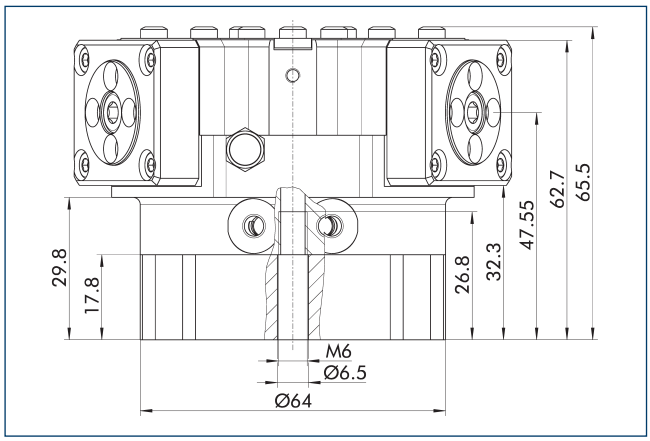


(90) Sinter filter

(91) Hose for ventilation or air purge connection

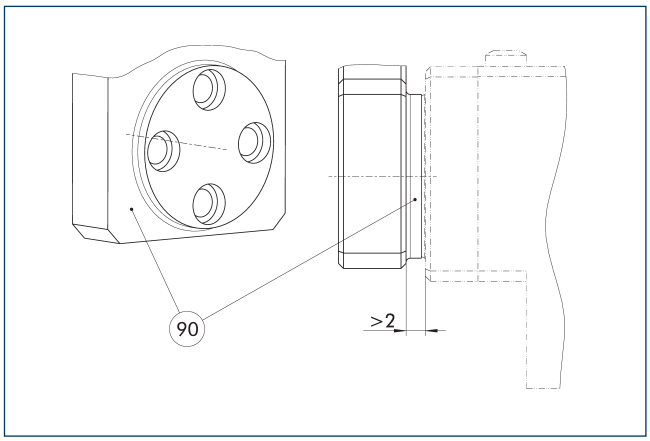
Please note that to achieve an IP 67 protection class, the gripper requires an additional hose for ventilation or a switchable air purge connection. For detailed information, please refer to the assembly and operating manual. Alternatively, a sinter filter (supplied) mounted on the air purge connection can prevent the penetration of dirt particles > 0.12 mm. However, this reduces the protection class to IP 54.

Gripping force maintenance device AS / IS



The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. This acts as closing force in the AS / S version, and as opening force in the IS version. Besides this, the gripping force maintenance device can be used to increase the gripping force or for single actuated gripping.

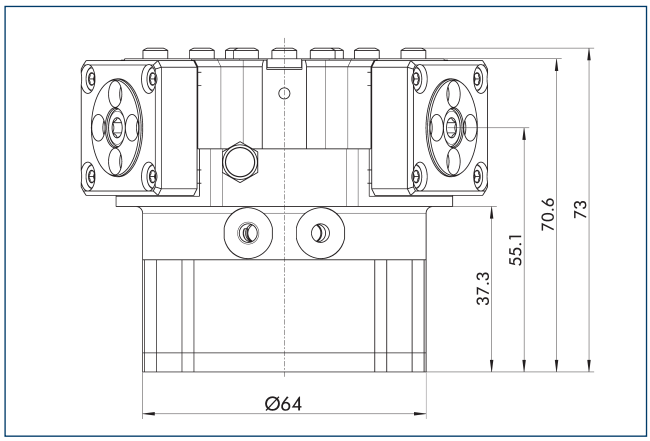
Proposed jaw design



(90) Step

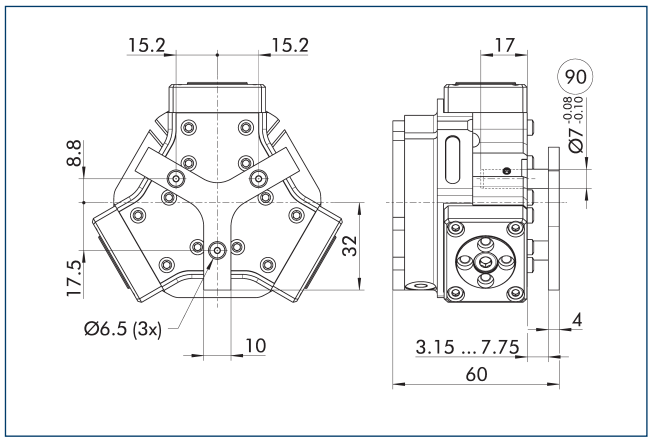
In order to avoid impairment of the stroke due to contamination or chips, there should be a sufficient distance between the top jaws and the gripper.

Power booster version



The KVZ cylinder increases the gripping forces during opening and closing. A second, in series-connected piston also increases the force on the wedge hook. Please consider that grippers which are equipped with a gripping force maintenance device are higher.

Spring-loaded pressure piece

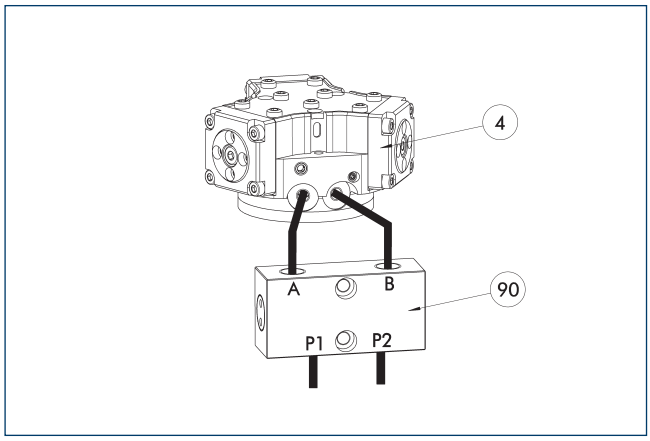


90 Guide pin

For spring-supported positioning of the workpiece against a stop after the gripper has opened. Especially developed for loading machines.

Description	ID	Stroke	Min. force
		[mm]	[N]
Spring-loaded pressure piece			
A-PZN-plus/DPZ-plus 64	0303720	4.6	11

SDV-P pressure maintenance valve



4 Grippers

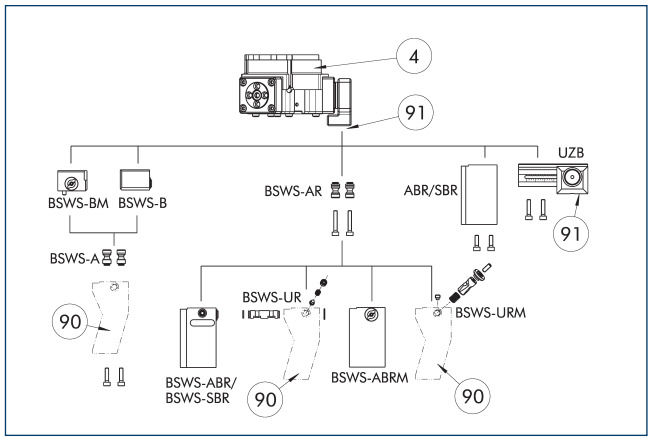
90 SDV-P pressure maintenance valve

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter
		[mm]
Pressure maintenance valve		
SDV-P 04	0403130	6
SDV-P 07	0403131	8
Pressure maintenance valve with air bleed screw		
SDV-P 04-E	0300120	6
SDV-P 07-E	0300121	8

ⓘ In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

Intermediate jaw interface



4 Grippers

90 Customized gripper fingers

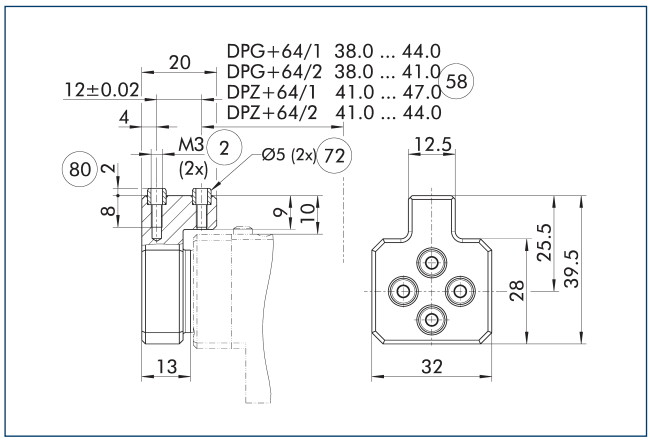
91 Uniform screw connection pattern

By using the intermediate jaw, you have the possibility of directly connecting a wide range of accessories directly. This includes jaw quick-change systems, finger blanks, and universal intermediate jaws.

DPZ-plus 64

Sealed universal gripper

ZBA DPG-plus/DPZ-plus 64-50 intermediate jaw

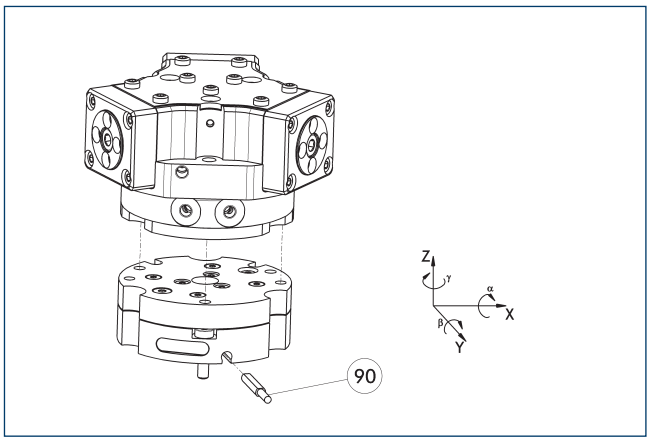


(2) Finger connection
(58) Distance from center of gripper
(72) Fit for centering sleeves
(80) Depth of the centering sleeve hole in the counter part

Optionally intermediate jaws can be used, enabling direct connection and alignment of top jaws and various standard accessories in Z-direction.

Description	ID	Material	Finger interface	Scope of delivery
Intermediate jaw				
ZBA-DPG-DPZ-plus 64-50	0300192	Aluminum	PGN-plus 50	1

Tolerance compensation unit TCU

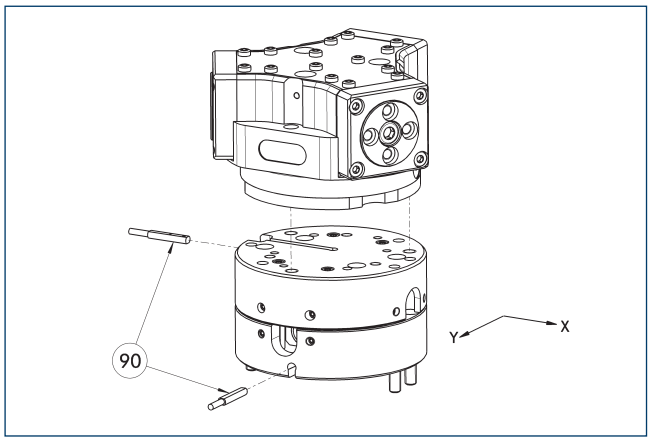


(90) Monitoring of locking

Grippers can be directly mounted without an adapter plate. Tolerance compensation unit and gripper have an identical screw connection diagram. Therefore the tolerance compensation units can be assembled later. Please consider the additional assembly height of the tolerance compensation unit. For details please refer to our catalog robot accessories.

Description	ID	Locking	Deflection	Often combined
Compensation unit				
TCU-Z-064-3-MV	0324766	yes	±1°/±1°/±1°	●
TCU-Z-064-3-OV	0324767	no	±1°/±1°/±1°	

Compensation unit AGE-F

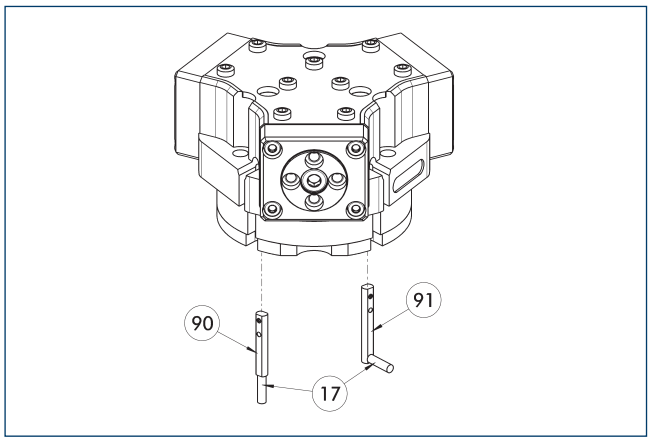


(90) Monitoring

Grippers can be directly mounted without an adapter plate. For details see our catalog Gripping or Robot Accessories.

Description	ID	Compensation XY	Reset force	Often combined
		[mm]	[N]	
Compensation unit				
AGE-F-XY-063-1	0324940	± 4	12	
AGE-F-XY-063-2	0324941	± 4	16	
AGE-F-XY-063-3	0324942	± 4	20	●

Electronic magnetic switch MMS



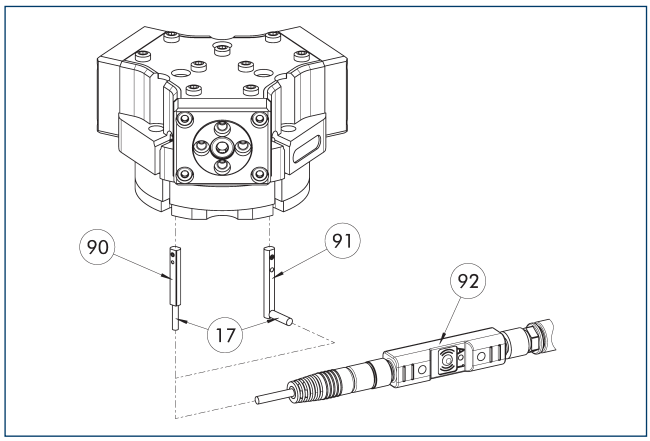
(17) Cable outlet
(91) Sensor MMS 22...-SA
(90) Sensor MMS 22..

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	●
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with lateral cable outlet		
MMS 22-S-M8-PNP-SA	0301042	●
MMSK 22-S-PNP-SA	0301044	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	●
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
clip for plug/socket		
CLI-M8	0301463	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	●
Sensor distributor		
V2-M8	0301775	●
V4-M8	0301746	
V8-M8	0301751	

ⓘ Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Programmable magnetic switch MMS 22-PI1



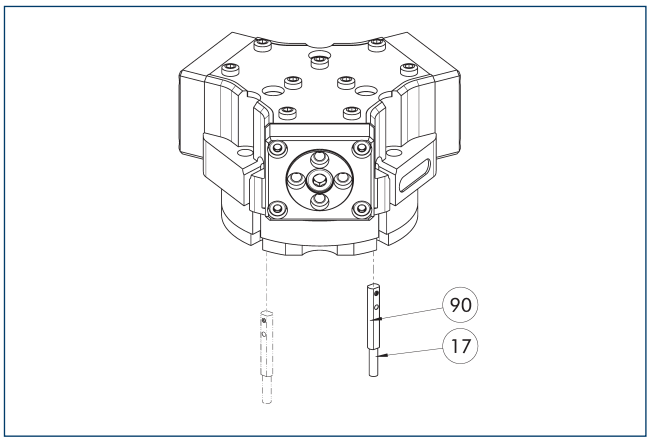
(17) Cable outlet
(91) Sensor MMS 22 ..-PI1-...-SA
(90) Sensor MMS 22 PI1-...
(92) Connector teaching tool ST

Position monitoring with one programmable switching point per sensor, directly mountable in the C-slot. The electronics are built into the sensor. The cable outlet can be located either axially or laterally (MMS 22...-SA). Programmed using the plug teaching tool ST (to be ordered separately).

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI1-S-M8-PNP	0301160	●
MMSK 22-PI1-S-PNP	0301162	
Programmable magnetic switch with lateral cable outlet		
MMS 22-PI1-S-M8-PNP-SA	0301166	●
MMSK 22-PI1-S-PNP-SA	0301168	
Programmable magnetic switch with stainless steel housing		
MMS 22-PI1-S-M8-PNP-HD	0301110	●
MMSK 22-PI1-S-PNP-HD	0301112	
Plug teaching tool		
ST-MMS 22-PI1-PNP	0301025	

ⓘ Two sensors (closer/S) are required for each unit and extension cables are available as an option.

Programmable magnetic switch MMS 22-PI2



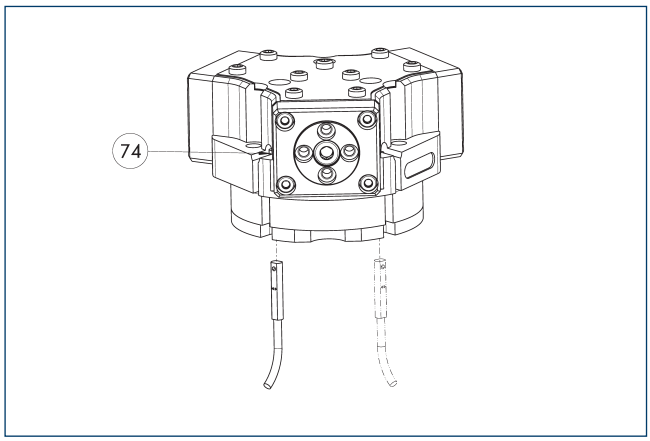
(17) Cable outlet
(90) MMS 22...-PI2-... sensor

Position monitoring with two programmable positions per sensor and electronics built into the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI2-S-M8-PNP	0301180	●
MMSK 22-PI2-S-PNP	0301182	
Programmable magnetic switch with lateral cable outlet		
MMS 22-PI2-S-M8-PNP-SA	0301186	●
MMSK 22-PI2-S-PNP-SA	0301188	
Programmable magnetic switch with stainless steel housing		
MMS 22-PI2-S-M8-PNP-HD	0301130	●
MMSK 22-PI2-S-PNP-HD	0301132	

ⓘ One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

MMS-P programmable magnetic switch



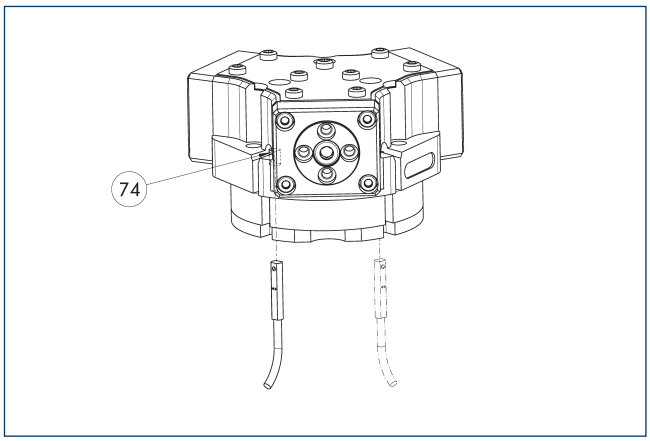
74 Limit stop for sensor

Position monitoring with two programmable positions per sensor and electronics built into the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMSK-P 22-S-PNP	0301371	
MMS-P 22-S-M8-PNP	0301370	●
Connection cables		
KA BG08-L 4P-0500	0307767	●
KA BG08-L 4P-1000	0307768	
KA BW08-L 4P-0500	0307765	
KA BW08-L 4P-1000	0307766	
clip for plug/socket		
CLI-M8	0301463	
Sensor distributor		
V2-M8-4P-2XM8-3P	0301380	

ⓘ One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

Programmable magnetic switch MMS-IO-Link



74 Limit stop for sensor

Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. Sensor programming on the gripper takes place via the IO-Link interface or the MT magnetic teach tool (included in scope of delivery). An IO-Link master is required for operation.

Description	ID	
Programmable magnetic switch		
MMS 22-IOL-M08	0315830	
MMS 22-IOL-M12	0315835	

ⓘ One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.

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