

Superior Clamping and Gripping



Product Information

Gripper for small components MPZ 30

Precise. Compact. Reliable. Gripper for small components MPZ

Small 3-finger centric gripper with base jaws guided on T-slots

Field of application

for universal use in clean to slightly dirty working environments, especially suitable for gripping small workpieces

Advantages – Your benefits

T-slot guidance for precise gripping at high moment loads

Finger position monitoring also possible via FPS

Air supply via hose-free direct connection or screw connections for flexible pressure supply in all automated systems

Compact dimensions for minimal interfering contours in handling













Functional description

The piston is moved up and down by compressed air. The angled active surfaces of the wedge-hook produce a synchronized, centric jaw movement.



- ① **T-slot guidance** for precise gripping with high moment loads
- ② Wedge-hook design for high force transmission and centric gripping
- 3 Housing is weight-optimized due to the use of high-strength aluminum alloy
- Orive pneumatic, efficient, and easy to handle

General notes about the series

Operating principle: Wedge-hook kinematics **Housing material:** Aluminum alloy, anodized

Base jaw material: Steel

Actuation: pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

Warranty: 24 months

Scope of delivery: Centering sleeves, centering pins, 0-rings for direct connection, assembly instructions (operating manual with declaration of incorporation is available online)

Gripping force maintenance device: possible by using the version with mechanical gripping force maintenance or pressure maintenance valve SDV-P

Gripping force: is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

Finger length: is measured from the reference surface as the distance P in direction to the main axis. The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher

nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

Repeat accuracy: is defined as a distribution of the end Position for 100 consecutive strokes.

Workpiece weight: is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.



Application example

Pneumatically driven 2-axis line gantry with centric gripper for gripping and repositioning small round workpieces.

- 3-finger centric gripper MPZ
- 2 Linear module LM

3 Pillar assembly system SAS

SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.

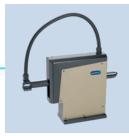








Linear module



Pick & Place Unit



Quick change system



Flexible position sensor



Micro valve



Pressure maintenance valve



Finger blank



Magnetic switches

① For more information on these products can be found on the following product pages or at schunk.com.

Options and special information

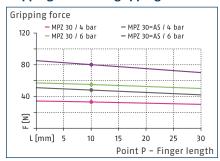
Gripping force maintenance version AS/IS: The mechanical gripping force maintenance version ensures minimum gripping force even in the event of a pressure drop. In the AS/S version this acts as a closing force, in the IS version as an opening force.

Version FPS for flexible position sensor: This version is prepared for the use with the flexible position sensor FPS, and allows monitoring of several gripping positions.

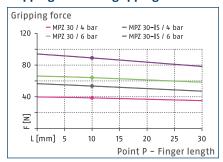
NEW: H1 grease version H1G: with H1 compliant lubrication as a solution for easy entry into medical technology, lab automation, the pharmaceutical industry and food industry



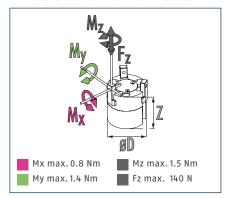
Gripping force 0.D. gripping



Gripping force I.D. gripping



Dimensions and maximum loads



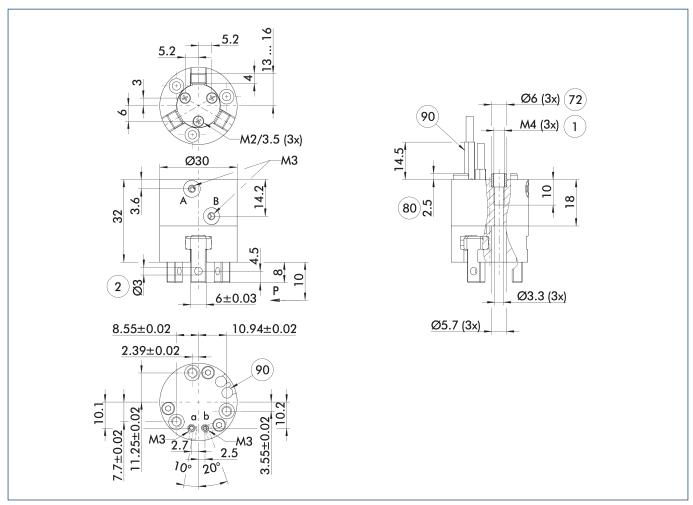
The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

Technical data

Description		MPZ 30	MPZ 30-FPS	MPZ 30-AS	MPZ 30-IS
ID		0340510	0340513	0340511	0340512
Stroke per jaw	[mm]	3	3	3	3
Closing/opening force	[N]	55/65	55/65	80/-	-/90
Min. spring force	[N]			25	25
Weight	[kg]	0.08	0.1	0.09	0.09
Recommended workpiece weight	[kg]	0.28	0.28	0.28	0.28
Fluid consumption double stroke	[cm³]	1.8	1.8	4.2	3.2
Min./nom./max. operating pressure	[bar]	21618	21618	4/6/6.5	4/6/6.5
Closing/opening time	[s]	0.02/0.02	0.02/0.02	0.02/0.04	0.04/0.02
Closing/opening time with spring	[s]			0.30	0.30
Max. permissible finger length	[mm]	30	30	30	30
Max. permissible mass per finger	[kg]	0.03	0.03	0.03	0.03
IP protection class		40	40	40	40
Min./max. ambient temperature	[°C]	5/90	5/90	5/90	5/90
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01
Cleanroom class ISO 14644-1:1999		5	5	5	5
Dimensions Ø D x Z	[mm]	30 x 32	30 x 46	30 x 45	30 x 45
Options and their characteristics					
H1 grease version		30028778	1475822	30075342	30041802

① It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

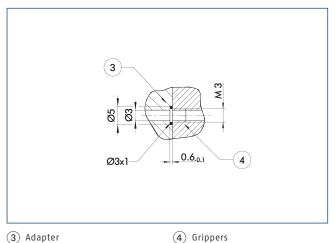
Main view



The drawing shows the gripper in the basic version with closed jaws, without dimensional consideration of the options described below.

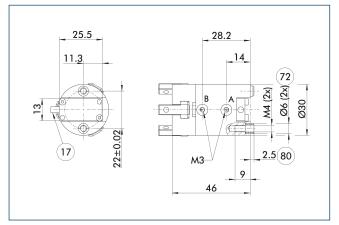
- ① The SDV-P pressure maintenance valve can also be used for I.D. or O.D. gripping alternatively or in addition to the spring-loaded, mechanical gripping force maintenance device (see catalog section on accessories).
- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- (1) Gripper connection
- 2 Finger connection
- 72 Fit for centering sleeves
- 80 Depth of the centering sleeve hole in the counter part
- 90 Sensor MMS 22..

Hose-free direct connection M3



The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

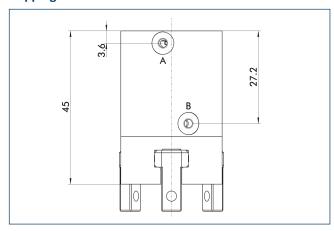
Flexible position sensor



- (17) Cable outlet
- 72) Fit for centering sleeves
- 80 Depth of the centering sleeve hole in the counter part

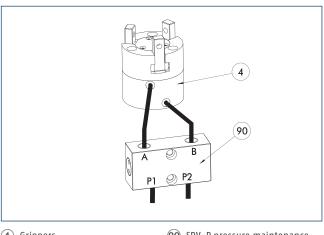
The following FPS position sensor can differentiate between five programmable areas or switching points for the stroke of a gripper, and can be used in connection with a PC as a measuring system.

Gripping force maintenance device AS / IS



The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. This acts as closing force in the AS / S version, and as opening force in the IS version. Besides this, the gripping force maintenance device can be used to increase the gripping force or for single actuated gripping.

SDV-P pressure maintenance valve



4 Grippers

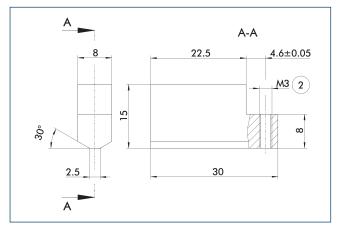
90 SDV-P pressure maintenance valve

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter
		[mm]
Pressure maintenance	e valve	
SDV-P 04	0403130	6
Pressure maintenance	valve with a	ir bleed screw
SDV-P 04-E	0300120	6

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

Finger blanks ABR-MPZ 30

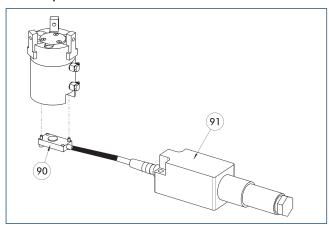


 $\widehat{\mathbf{2}}$ Finger connection

The drawing shows the finger blank which can be reworked by the customer. $% \label{eq:customer} % \label{eq:customer}$

Description	ID	Material	Scope of delivery
Finger blank			
ABR-MPZ 30	0340519	Aluminum	3

Flexible position sensor



90 FPS-S sensor

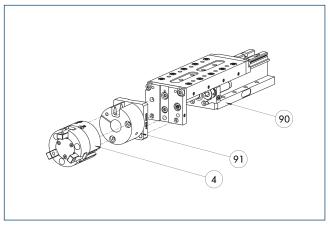
(91) FPS-F5 evaluation electronic

Flexible position monitoring of up to five positions.

Description	ID	Often combined
Sensor		
FPS-S 13	0301705	
Evaluation electronics		
FPS-F5	0301805	•
Cable extension		
KV BG08-SG08 3P-0050	0301598	
KV BG08-SG08 3P-0100	0301599	
Connection cables		
KA BG16-L 12P-1000	0301801	
clip for plug/socket		
CLI-M8	0301463	

When using an FPS system, an FPS sensor (FPS-S) as well as an electronic processor (FPS-F5 / F5 T) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are optionally available – see catalog chapter "Accessories."

Modular Assembly Automation



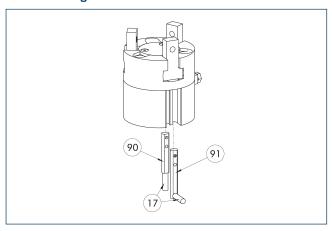
4 Grippers

91) ASG adapter plate

90 CLM/KLM/LM/ELP/ELM/ELS/HLM linear modules

Grippers and linear modules can be combined with standard adapter plates from the modular assembly system. For more information see our main catalog "Modular Assembly Automation".

Electronic magnetic switch MMS



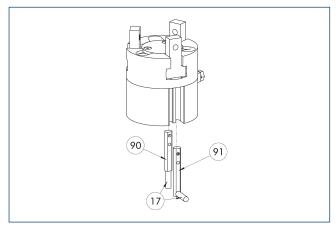
- $\widehat{17}$ Cable outlet
- 91) Sensor MMS 22...-SA
- 90 Sensor MMS 22..

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch	,	
MMS 22-S-M8-PNP	0301032	•
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with	lateral cable o	outlet
MMS 22-S-M8-PNP-SA	0301042	•
MMSK 22-S-PNP-SA	0301044	
Reed Switches		
RMS 22-S-M8	0377720	•
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
clip for plug/socket		
CLI-M8	0301463	
Wireless sensor system		
RSS-T2	0377715	
RSS-T2-US/CA	0377717	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
Sensor distributor		
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Programmable magnetic switch MMS 22-PI1



(17) Cable outlet

(91) Sensor MMS 22 ..-PI1-...-SA

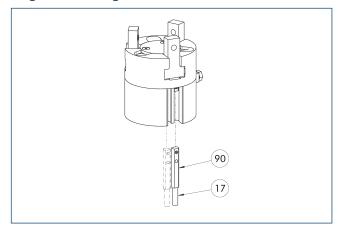
90 Sensor MMS 22 PI1-...

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch	l	
MMS 22-PI1-S-M8-PNP	0301160	•
MMSK 22-PI1-S-PNP	0301162	
Programmable magnetic switch	with lateral o	able outlet
MMS 22-PI1-S-M8-PNP-SA	0301166	•
MMSK 22-PI1-S-PNP-SA	0301168	
Programmable magnetic switch	with stainles	s steel housing
MMS 22-PI1-S-M8-PNP-HD	0301110	•
MMSK 22-PI1-S-PNP-HD	0301112	

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Programmable magnetic switch MMS 22-PI2



(17) Cable outlet

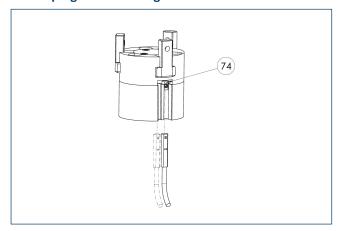
90 MMS 22...-PI2-... sensor

Position monitoring with two programmable positions per sensor and electronics built into the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI2-S-M8-PNP	0301180	•
MMSK 22-PI2-S-PNP	0301182	
Programmable magnetic switch	with lateral c	able outlet
MMS 22-PI2-S-M8-PNP-SA	0301186	•
MMSK 22-PI2-S-PNP-SA	0301188	
Programmable magnetic switch	with stainles	s steel housing
MMS 22-PI2-S-M8-PNP-HD	0301130	•
MMSK 22-PI2-S-PNP-HD	0301132	

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

MMS-P programmable magnetic switch



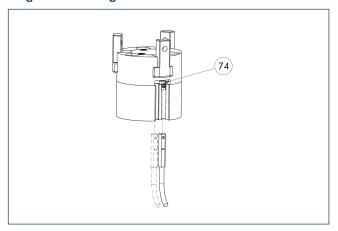
(74) Limit stop for sensor

Position monitoring with two programmable positions per sensor. End position monitoring for mounting in the C-slot.

ID	Often combined
h	
0301371	
0301370	•
0307767	•
0307768	
0307765	
0307766	
0301463	
0301380	
	h 0301371 0301370 0307767 0307768 0307765 0307766

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

Programmable magnetic switch MMS-I0-Link



74) Limit stop for sensor

Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. Sensor programming on the gripper takes place via the IO-Link interface or the MT magnetic teach tool (included in scope of delivery). An IO-Link master is required for operation.

Description	ID
Programmable mag	netic switch
MMS 22-I0L-M08	0315830
MMS 22-I0L-M12	0315835

① One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.



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