

Superior Clamping and Gripping



# **Product Information**

Universal gripper PZB-plus 80

# Robust. Flexible. Precise. Universal gripper PZB-plus

Universal 3-finger centric gripper with large gripping force and high maximum moments per finger, plus center bore

# Field of application

For universal use in clean and slightly dirty environments. Suitable for applications that require a center bore, e.g. for workpiece feeding, special sensor systems or optical recognition Systems.

# **Advantages - Your benefits**

Robust multi-tooth guidance for precise handling

**High maximum moments possible** suitable for using long gripper fingers

**High gripping forces achievable** for a wide range of applications

**Center through-hole** available with fitting and female thread, which facilitates assembly of customer attachments. Moreover, the center bore is used for feed-through of supply hoses and others.

Air supply via hose-free direct connection or screw connections for flexible pressure supply in all automated systems

**Manifold options** optional with mechanic gripping force maintenance













# **Functional description**

The piston is moved up and down by compressed air. The angled active surfaces of the wedge-hook produce a synchronized, centric jaw movement.



- Base Jaw for the connection of workpiece-specific gripper fingers
- ② Center bore

  for workpiece feeding, for sensor systems, actuators
  (ejectors) or optical workpiece recognition
- Wedge-hook design for high force transmission and centric gripping
- Multi-tooth guidance precise gripping through base jaw guidance with a high load capacity and a minimum Play
- S Housing is weight-optimized due to the use of high-strength aluminum alloy

# General notes about the series

**Operating principle:** Wedge-hook kinematics **Housing material:** Aluminum alloy, anodized

Base jaw material: Steel

Actuation: pneumatic, with filtered compressed air as per

ISO 8573-1:2010 [7:4:4].

Warranty: 36 months

**Scope of delivery:** Brackets for proximity switches, centering sleeves, 0-rings for direct connection, assembly instructions (operating manual with declaration of

incorporation is available online)

**Gripping force maintenance device:** possible by using the version with mechanical gripping force maintenance or

pressure maintenance valve SDV-P

**Gripping force:** is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

**Finger length:** is measured from the reference surface as the distance P in direction to the main axis.

The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher

nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

**Repeat accuracy:** is defined as a distribution of the end Position for 100 consecutive strokes.

**Workpiece weight:** is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

**Closing and opening times:** are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.

# **Application example**

Assembly aid for long shafts. Feeding is done space-saving via the center bores of gripper and rotary feed-through.

- **1** 3-finger centric gripper PZB-plus
- 2 Modified Rotary feed-through DDF with center bore



# SCHUNK offers more ...

The following components make the product even more productive - the suitable addition for the highest functionality, flexibility, reliability, and controlled production.











Compensation unit

Pressure maintenance valve

Universal intermediate jaw

Jaw quick-change system









Magnetic switches

Flexible position sensor

Analog position sensor

Finger blank



Inductive proximity switches

① For more information on these products can be found on the following product pages or at schunk.com.

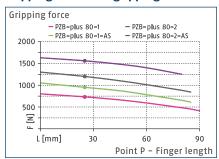
# Options and special information

Gripping force maintenance version AS/IS: The mechanical gripping force maintenance version ensures minimum gripping force even in the event of a pressure drop. In the AS/S version this acts as a closing force, in the IS version as an opening force.

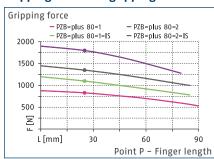
Due to the center bore, the PZB-plus series is the optimal standard solution for many fields of application.



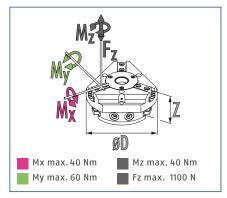
# Gripping force 0.D. gripping



# **Gripping force I.D. gripping**



#### **Dimensions and maximum loads**



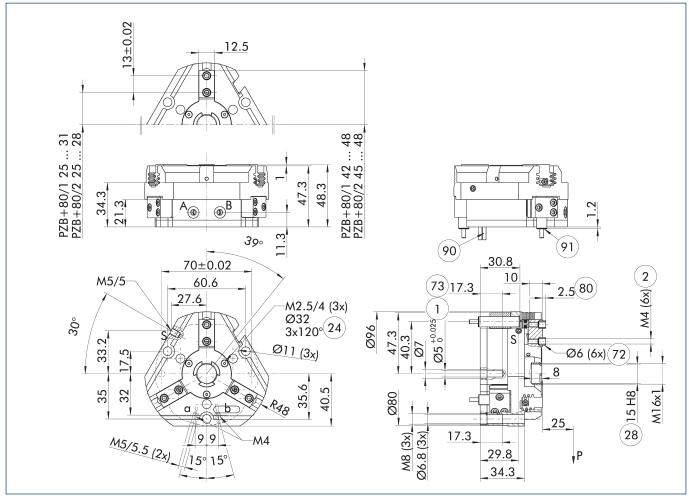
The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

#### **Technical data**

Description		PZB-plus 80-1	PZB-plus 80-2	PZB-plus 80-1-AS	PZB-plus 80-2-AS	PZB-plus 80-1-IS	PZB-plus 80-2-IS
ID		0305160	0305161	0305162	0305163	0305164	0305165
Stroke per jaw	[mm]	6	3	6	3	6	3
Closing/opening force	[N]	730/830	1200/1350	950/-	1560/-	-/1030	-/1750
Min. spring force	[N]			220	360	200	400
Weight	[kg]	0.8	0.8	1.1	1.1	1.1	1.1
Recommended workpiece weight	[kg]	3.6	6	3.6	6	3.6	6
Fluid consumption double stroke	[cm³]	42	42	75	75	75	75
Min./nom./max. operating pressure	[bar]	2/6/8	2/6/8	4/6/6.5	4/6/6.5	4/6/6.5	4/6/6.5
Min./max. air purge pressure	[bar]	0.5/1	0.5/1	0.5/1	0.5/1	0.5/1	0.5/1
Closing/opening time	[s]	0.05/0.05	0.05/0.05	0.03/0.05	0.03/0.05	0.06/0.04	0.06/0.04
Closing/opening time with spring	[s]			0.19	0.19	0.19	0.19
Max. permissible finger length	[mm]	90	85	85	80	85	80
Max. permissible mass per finger	[kg]	0.35	0.35	0.35	0.35	0.35	0.35
IP protection class		40	40	40	40	40	40
Min./max. ambient temperature	[°C]	5/90	5/90	5/90	5/90	5/90	5/90
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01
Diameter of center bore	[mm]	15	15	15	15	15	15
Dimensions Ø D x Z	[mm]	96 x 48.3	96 x 48.3	96 x 63	96 x 63	96 x 63	96 x 63

① It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

#### Main view

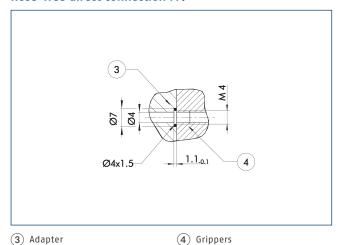


The drawing shows the gripper in the basic version with closed jaws, without dimensional consideration of the options described below.

- ① The SDV-P pressure maintenance valve can also be used for I.D. or O.D. gripping alternatively or in addition to the spring-loaded, mechanical gripping force maintenance device (see catalog section on accessories).
- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- S Air purge connection
- 1 Gripper connection
- (2) Finger connection
- 24) Bolt circle

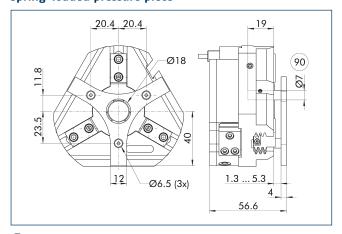
- 28 Through-hole
- 72 Fit for centering sleeves
- 73) Fit for centering pins
- 80 Depth of the centering sleeve hole in the counter part
- 90 Sensor MMS 22..
- 91) Sensor IN ...

#### Hose-free direct connection M4



The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

#### Spring-loaded pressure piece

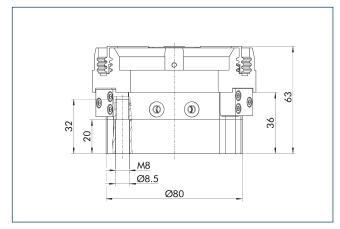


90 Guide pin

For spring-supported positioning of the workpiece against a stop after the gripper has opened. Especially developed for loading machines.

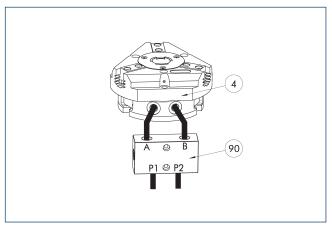
Description	ID	Stroke	Min. force	
		[mm]	[N]	
Spring-loaded pressure piece				
A-P7R-plus 80	0305166	4	11	

## Gripping force maintenance device AS / IS



The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. This acts as closing force in the AS / S version, and as opening force in the IS version. Besides this, the gripping force maintenance device can be used to increase the gripping force or for single actuated gripping.

#### SDV-P pressure maintenance valve



4 Grippers

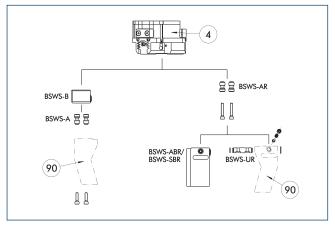
90 SDV-P pressure maintenance valve

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter		
		[mm]		
Pressure maintenance	Pressure maintenance valve			
SDV-P 04	0403130	6		
SDV-P 07	0403131	8		
Pressure maintenance valve with air bleed screw				
SDV-P 04-E	0300120	6		
SDV-P 07-E	0300121	8		
SDV-P 10-E	0300109	10		

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

# BSWS jaw quick-change jaw systems



4 Grippers

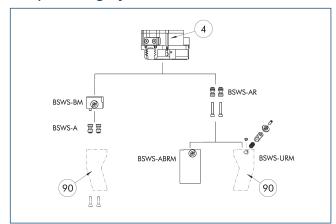
**90** Customized gripper fingers

There are various jaw quick-change systems available for the gripper. For detailed information, please refer to the corresponding product.

Description	ID	Scope of delivery					
Jaw quick-change system ada	Jaw quick-change system adapter pin						
BSWS-A 64	0303022	2					
BSWS-AR 64	0300092	2					
Quick-change jaw system base	Quick-change jaw system base						
BSWS-B 64	0303023	1					
Jaw quick-change system fing	Jaw quick-change system finger blank						
BSWS-ABR-PGZN-plus 64	0300072	1					
BSWS-SBR-PGZN-plus 64	0300082	1					
Jaw quick-change system locking mechanism							
BSWS-UR 64	0302991	1					

 $\ensuremath{\textcircled{\scriptsize 1}}$  Only systems that are listed in the table, can be used.

# Jaw quick-change system BSWS-M



4 Grippers

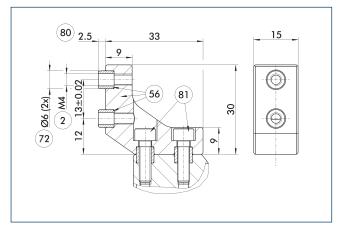
90 Customized gripper fingers

There are various jaw quick-change systems available for the gripper. For detailed information, please refer to the corresponding product.

Description	ID	Scope of delivery					
Jaw quick-change system adapter pin							
BSWS-A 64	0303022	2					
BSWS-AR 64	0300092	2					
Quick-change jaw system base	Quick-change jaw system base						
BSWS-BM 64	1313900	1					
Jaw quick-change system finger blank							
BSWS-ABRM-PGZN-plus 64	1420851	1					
Jaw quick-change system locking mechanism							
BSWS-URM 64	1398401	1					

① Only systems that are listed in the table, can be used.

## ZBA-L-plus 64 intermediate jaws

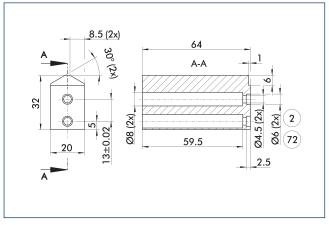


- 2 Finger connection
- (56) Included in the scope of delivery
- (72) Fit for centering sleeves
- 80 Depth of the centering sleeve hole in the counter part
- 81) Not included in the scope of delivery

The optional ZBA-L-plus intermediate jaws allow the screw connection diagram of the top jaws to be rotated by 90°. This makes it easier to design and produce top jaws (particularly for long versions) because no deep through-bores are required.

Description	ID		Finger interface	Scope of delivery
Intermediate jaw				
ZBA-L-plus 64	0311722	Aluminum	PGN-plus 64	1

# Finger blanks ABR- / SBR-PGZN-plus 64



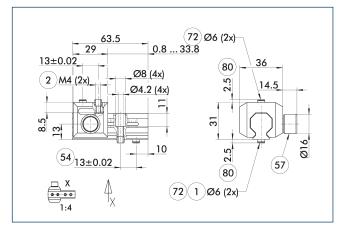
(2) Finger connection

72) Fit for centering sleeves

The drawing shows the finger blank which can be reworked by the customer.

Description	ID	Material	Scope of delivery
Finger blank			
ABR-PGZN-plus 64	0300010	Aluminum	1
SBR-PGZN-plus 64	0300020	Steel	1

## UZB 64 universal intermediate jaw

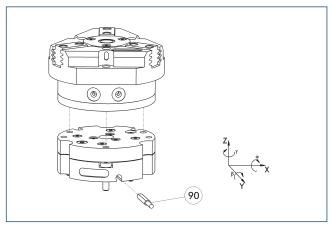


- 1 Gripper connection
- (2) Finger connection
- (54) Optional right or left connection
- 57 Locking
- 72) Fit for centering sleeves
- 80 Depth of the centering sleeve hole in the counter part

The drawing shows the UZB universal intermediate jaw.

		-
Description	ID	Grid dimension
		[mm]
Universal intermediate	jaw	
UZB 64	0300042	1.5
Finger blank		
ABR-PGZN-plus 64	0300010	
SBR-PGZN-plus 64	0300020	

# Tolerance compensation unit TCU

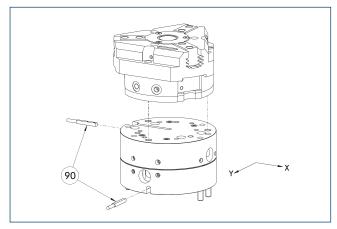


90 Monitoring of locking

Grippers can be directly mounted without an adapter plate. Tolerance compensation unit and gripper have an identical screw connection diagram. Therefore the tolerance compensation units can be assembled later. Please consider the additional assembly height of the tolerance compensation unit. For details please refer to our catalog robot accessories.

Description	ID	Locking	Deflection	Often combined
Compensation unit				
TCU-Z-080-3-MV	0324784	yes	±1°/±1°/±1°	•
TCU-Z-080-3-0V	0324785	no	±1°/±1°/±1°	

# Compensation unit AGE-F

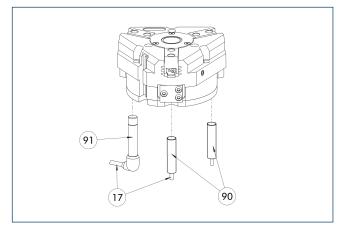


90 Monitoring

Grippers can be directly mounted without an adapter plate. For details see our catalog Gripping or Robot Accessories.

Description	ID	Compensation XY	Reset force	Often combined
		[mm]	[N]	
Compensation unit				
AGE-F-XY-063-1	0324940	± 4	12	
AGE-F-XY-063-2	0324941	± 4	16	
AGE-F-XY-063-3	0324942	± 4	20	•

# **Inductive Proximity Switches**



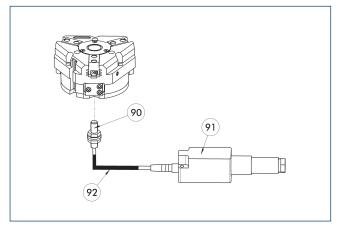
- 17) Cable outlet
- 91) Sensor IN..-SA
- 90 Sensor IN ...

Directly mounted end position monitoring.

Description	ID	Often combined
Inductive proximity switches		
IN 80-S-M12	0301578	
IN 80-S-M8	0301478	•
INK 80-S	0301550	
Inductive proximity switch with la	ateral cable ou	tlet
IN 80-S-M12-SA	0301587	
IN 80-S-M8-SA	0301483	•
INK 80-S-SA	0301566	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BG12-L 3P-0500-PNP	30016369	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
clip for plug/socket		
CLI-M12	0301464	
CLI-M8	0301463	
Cable extension		
KV BG12-SG12 3P-0030-PNP	0301999	
KV BG12-SG12 3P-0060-PNP	0301998	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	
Sensor distributor		
V2-M12	0301776	•
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

### Flexible position sensor

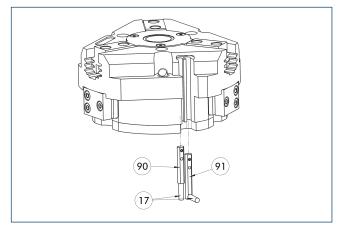


- 90 FPS-S sensor
- 92 Cable extension
- (91) FPS-F5 evaluation electronic

Flexible position monitoring of up to five positions.

When using an FPS system, an FPS sensor (FPS-S) as well as an electronic processor (FPS-F5 / F5 T) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are optionally available – see catalog chapter "Accessories."

# **Electronic magnetic switch MMS**



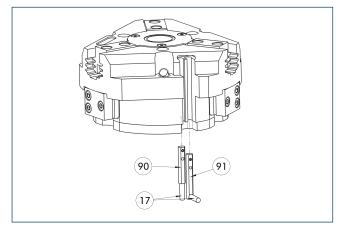
- 17) Cable outlet
- 91) Sensor MMS 22...-SA
- 90 Sensor MMS 22..

End position monitoring for mounting in the C-slot.

. 1		
Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	•
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with	lateral cable o	outlet
MMS 22-S-M8-PNP-SA	0301042	•
MMSK 22-S-PNP-SA	0301044	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
clip for plug/socket		
CLI-M8	0301463	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
Sensor distributor		
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

## Programmable magnetic switch MMS 22-PI1



(17) Cable outlet

(91) Sensor MMS 22 ..-PI1-...-SA

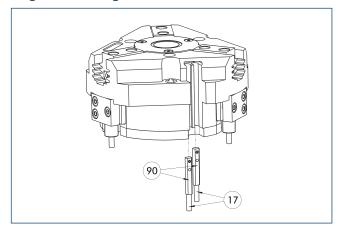
90 Sensor MMS 22 PI1-...

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI1-S-M8-PNP	0301160	•
MMSK 22-PI1-S-PNP	0301162	
Programmable magnetic switch	with lateral c	able outlet
MMS 22-PI1-S-M8-PNP-SA	0301166	•
MMSK 22-PI1-S-PNP-SA	0301168	
Programmable magnetic switch	with stainles	s steel housing
MMS 22-PI1-S-M8-PNP-HD	0301110	•
MMSK 22-PI1-S-PNP-HD	0301112	

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

#### Programmable magnetic switch MMS 22-PI2



(17) Cable outlet

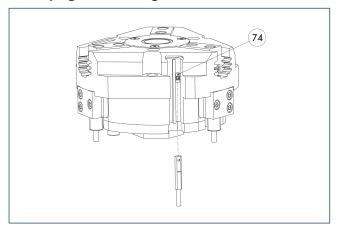
90 MMS 22...-PI2-... sensor

Position monitoring with two programmable positions per sensor and electronics built into the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI2-S-M8-PNP	0301180	•
MMSK 22-PI2-S-PNP	0301182	
Programmable magnetic switch	with lateral c	able outlet
MMS 22-PI2-S-M8-PNP-SA	0301186	•
MMSK 22-PI2-S-PNP-SA	0301188	
Programmable magnetic switch	with stainless	s steel housing
MMS 22-PI2-S-M8-PNP-HD	0301130	•
MMSK 22-PI2-S-PNP-HD	0301132	

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

#### MMS-P programmable magnetic switch



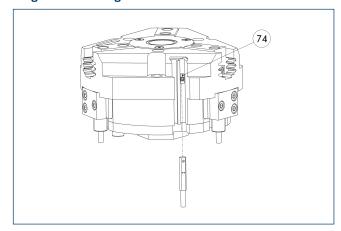
(74) Limit stop for sensor

Position monitoring with two programmable positions per sensor. End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Programmable magnetic switch	h	
MMSK-P 22-S-PNP	0301371	
MMS-P 22-S-M8-PNP	0301370	•
Connection cables		
KA GLN0804-LK-00500-A	0307767	•
KA GLN0804-LK-01000-A	0307768	
KA WLN0804-LK-00500-A	0307765	
KA WLN0804-LK-01000-A	0307766	
clip for plug/socket		
CLI-M8	0301463	
Sensor distributor		
V2-M8-4P-2XM8-3P	0301380	

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

#### Programmable magnetic switch MMS-I0-Link



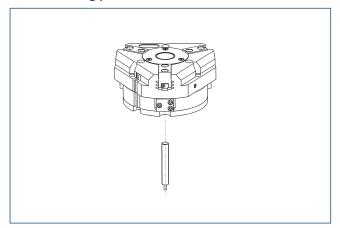
(74) Limit stop for sensor

Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. Sensor programming on the gripper takes place via the IO-Link interface or the MT magnetic teach tool (included in scope of delivery). An IO-Link master is required for operation.

Description	ID
Programmable magi	netic switch
MMS 22-I0L-M08	0315830
MMS 22-I0L-M12	0315835

① One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems. The sensor only works on the variants PZB-plus 80-1-AS, PZB-plus 80-1-AS, PZB-plus 80-2-AS and PZB-plus 80-2-IS. Other variants of the gripper are not compatible with the sensor.

# APS-Z80 analog position sensor

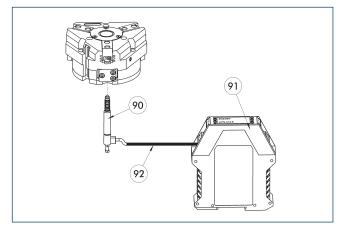


No–contact measuring, analog multi–position monitoring for any number of positions.

Description	ID	Often combined
Mounting kit for APS-Z80		
AS-APS-Z80-PGZN-plus 64-1	0302105	
AS-APS-Z80-PGZN-plus 64-2	0302106	
Analog position sensor		
APS-Z80-K	0302072	
APS-Z80-M8	0302070	•

When using an APS system, one mounting kit (AS-APS-Z80) and one APS-Z80 sensor is required per gripper. The resolution of the sensor can be lower in the peripheral areas of the gripper. You can find further information on the product in the operating manual.

## APS-M1 analog position sensor



- 90 APS-M1S sensor
- **92** APS-K extension cable
- (91) APS-M1E electronic processor

Analog multi position monitoring for any desired positions

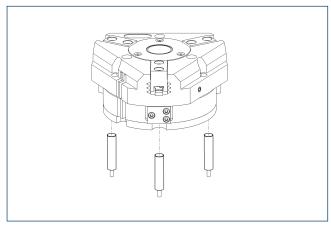
Description	ID
Mounting kit for APS-M1	
AS-APS-M1-PGZN-plus 64-1	0302075
AS-APS-M1-PGZN-plus 64-2	0302076
Analog position sensor	
APS-M1S	0302062
Connection cables	
APS-K0200	0302066
APS-K0700	0302068
Evaluation electronics	
APS-M1E	0302064

When using an APS system, for each gripper an attachment kit (AS-APS-M1), an APS-M1S sensor (incl. 3 m cable) as well as an electronics (APS-M1e) are required. An extension cable (APS-K) can be connected between the sensor and the electronics as an option. The max. cable length between the sensor and the electronics is 10 m, between the electronics and their control unit (PLC) it is max. 1 m.

# PZB-plus 80

Universal gripper

# Cylindrical reed switches



End position monitoring can be mounted with an attachment kit.

Description	ID
Attachment kit for proximity switch	
AS-RMS 80 PGN/PZN-plus 64/80	0377725
Reed Switches	
RMS 80-S-M8	0377721

Two sensors (closer/S) are required for each unit and extension cables are available as an option. This attachment kit needs to be ordered optionally as an accessory. Two mounting kits are required for each gripper. For sensor cables, note the minimum permissible bending radii. These are generally 35 mm.

Universal gripper



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