Superior Clamping and Gripping

Product Information

Universal gripper PZB-plus 64

Robust. Flexible. Precise.

Universal gripper PZB-plus

Universal 3-finger centric gripper with large gripping force and high maximum moments per finger, plus center bore

Field of application

For universal use in clean and slightly dirty environments. Suitable for applications that require a center bore, e.g. for workpiece feeding, special sensor systems or optical recognition Systems.

Advantages – Your benefits

Robust multi-tooth guidance for precise handling

High maximum moments possible suitable for using long gripper fingers

High gripping forces achievable for a wide range of applications

Center through-hole available with fitting and female thread, which facilitates assembly of customer attachments. Moreover, the center bore is used for feed-through of supply hoses and others.

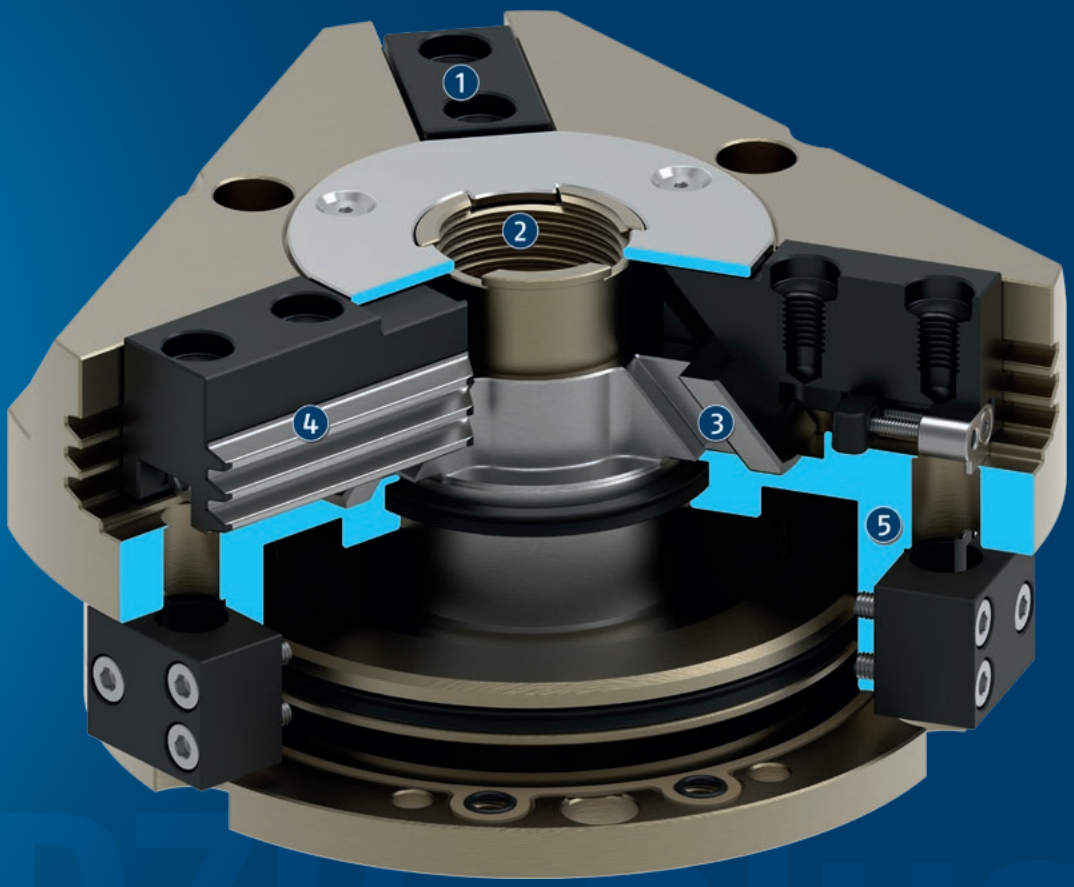
Air supply via hose-free direct connection or screw connections for flexible pressure supply in all automated systems

Manifold options optional with mechanic gripping force maintenance

Sizes	Weight	Gripping force	Stroke per jaw	Workpiece weight
Quantity: 9	0.26 .. 53 kg	340 .. 27400 N	2 .. 35 mm	1.7 .. 100 kg

Functional description

The piston is moved up and down by compressed air.
The angled active surfaces of the wedge-hook produce a synchronized, centric jaw movement.



① **Base Jaw**
for the connection of workpiece-specific gripper fingers

② **Center bore**
for workpiece feeding, for sensor systems, actuators (ejectors) or optical workpiece recognition

③ **Wedge-hook design**
for high force transmission and centric gripping

④ **Multi-tooth guidance**
precise gripping through base jaw guidance with a high load capacity and a minimum Play

⑤ **Housing**
is weight-optimized due to the use of high-strength aluminum alloy

General notes about the series

Operating principle: Wedge-hook kinematics

Housing material: Aluminum alloy, anodized

Base jaw material: Steel

Actuation: pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

Warranty: 36 months

Scope of delivery: Brackets for proximity switches, centering sleeves, O-rings for direct connection, assembly instructions (operating manual with declaration of incorporation is available online)

Gripping force maintenance device: possible by using the version with mechanical gripping force maintenance or pressure maintenance valve SDV-P

Gripping force: is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

Finger length: is measured from the reference surface as the distance P in direction to the main axis.
The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

Repeat accuracy: is defined as a distribution of the end Position for 100 consecutive strokes.

Workpiece weight: is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.

Application example

Assembly aid for long shafts. Feeding is done space-saving via the center bores of gripper and rotary feed-through.

1. 3-finger centric gripper PZB-plus
2. Modified Rotary feed-through DDF with center bore

SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.

Compensation unit

Pressure maintenance valve

Universal intermediate jaw

Jaw quick-change system

Magnetic switches

Flexible position sensor

Analog position sensor

Finger blank

Inductive proximity switches

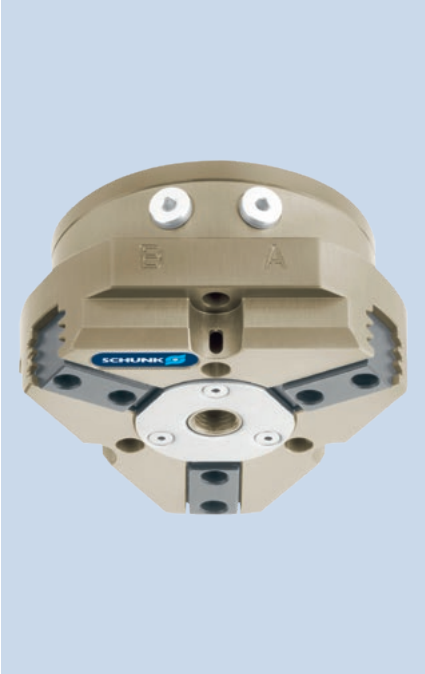
ⓘ For more information on these products can be found on the following product pages or at schunk.com.

Options and special information

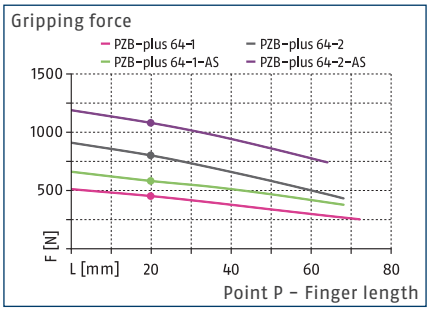
Gripping force maintenance version AS/IS: The mechanical gripping force maintenance version ensures minimum gripping force even in the event of a pressure drop. In the AS/S version this acts as a closing force, in the IS version as an opening force.
Due to the center bore, the PZB-plus series is the optimal standard solution for many fields of application.

PZB-plus 64

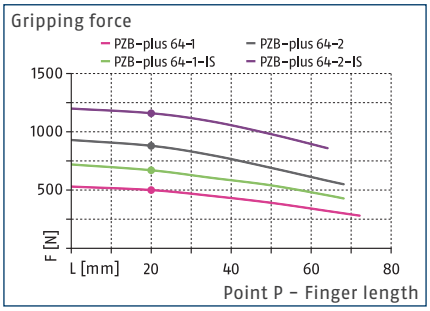
Universal gripper



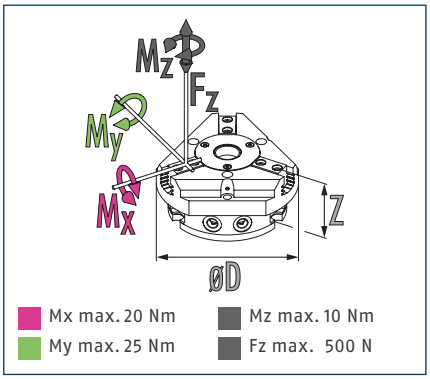
Gripping force O.D. gripping



Gripping force I.D. gripping



Dimensions and maximum loads



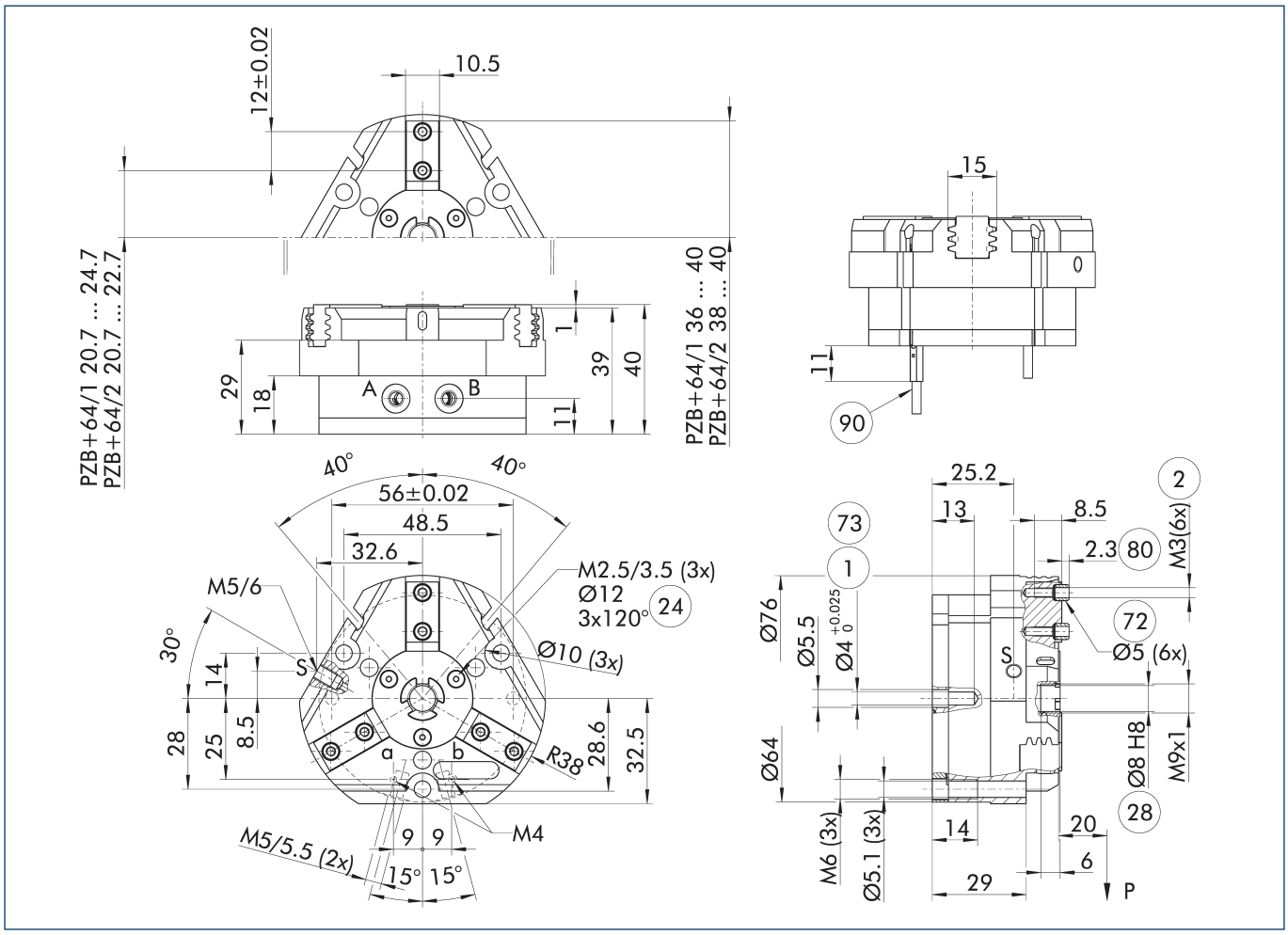
ⓘ The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

Technical data

Description		PZB-plus 64-1	PZB-plus 64-2	PZB-plus 64-1-AS	PZB-plus 64-2-AS	PZB-plus 64-1-IS	PZB-plus 64-2-IS
ID		0305150	0305151	0305152	0305153	0305154	0305155
Stroke per jaw	[mm]	4	2	4	2	4	2
Closing/opening force	[N]	450/500	800/880	580/-	1080/-	-/670	-/1160
Min. spring force	[N]			130	280	170	280
Weight	[kg]	0.51	0.51	0.63	0.63	0.63	0.63
Recommended workpiece weight	[kg]	2.2	5	2.2	5	2.2	5
Fluid consumption double stroke	[cm³]	19.5	19.5	35	35	35	35
Min./nom./max. operating pressure	[bar]	2/6/8	2/6/8	4/6/6.5	4/6/6.5	4/6/6.5	4/6/6.5
Min./max. air purge pressure	[bar]	0.5/1	0.5/1	0.5/1	0.5/1	0.5/1	0.5/1
Closing/opening time	[s]	0.03/0.03	0.03/0.03	0.02/0.04	0.02/0.04	0.04/0.02	0.04/0.02
Closing/opening time with spring	[s]			0.08	0.08	0.08	0.08
Max. permissible finger length	[mm]	72	68	68	64	68	64
Max. permissible mass per finger	[kg]	0.18	0.18	0.18	0.18	0.18	0.18
IP protection class		40	40	40	40	40	40
Min./max. ambient temperature	[°C]	5/90	5/90	5/90	5/90	5/90	5/90
Repeat accuracy	[mm]	0.01	0.01	0.01	0.01	0.01	0.01
Diameter of center bore	[mm]	8	8	8	8	8	8
Dimensions Ø D x Z	[mm]	76 x 40	76 x 40	76 x 52.8	76 x 52.8	76 x 52.8	76 x 52.8

ⓘ It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

Main view



The drawing shows the gripper in the basic version with closed jaws, without dimensional consideration of the options described below.

ⓘ The SDV-P pressure maintenance valve can also be used for I.D. or O.D. gripping alternatively or in addition to the spring-loaded, mechanical gripping force maintenance device (see catalog section on accessories).

A, a Main / direct connection, gripper opening

B, b Main / direct connection, gripper closing

S Air purge connection

(1) Gripper connection

(2) Finger connection

(24) Bolt circle

(28) Through-hole

(72) Fit for centering sleeves

(73) Fit for centering pins

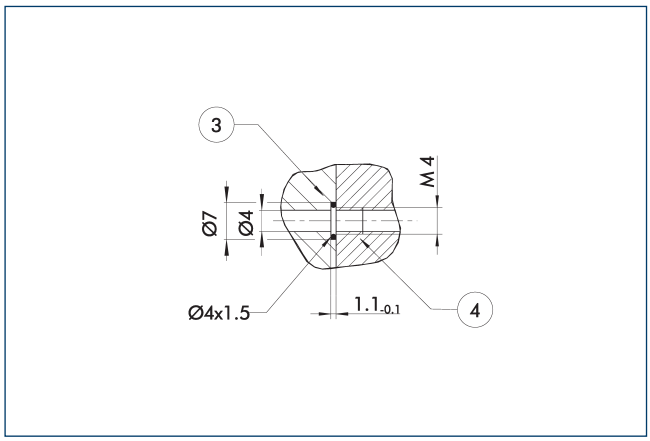
(80) Depth of the centering sleeve hole in the counter part

(90) Sensor MMS 22..

PZB-plus 64

Universal gripper

Hose-free direct connection M4

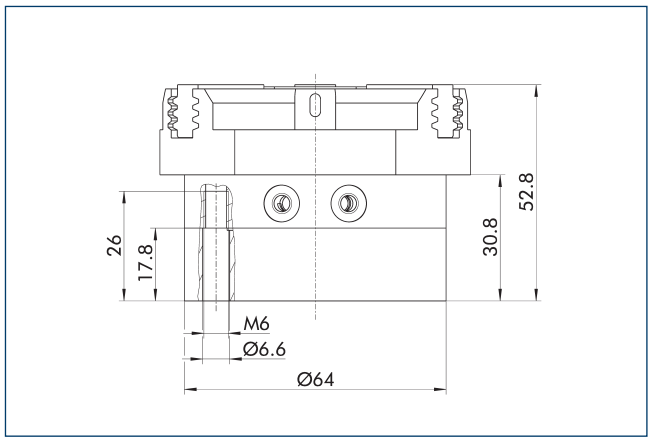


(3) Adapter

(4) Grippers

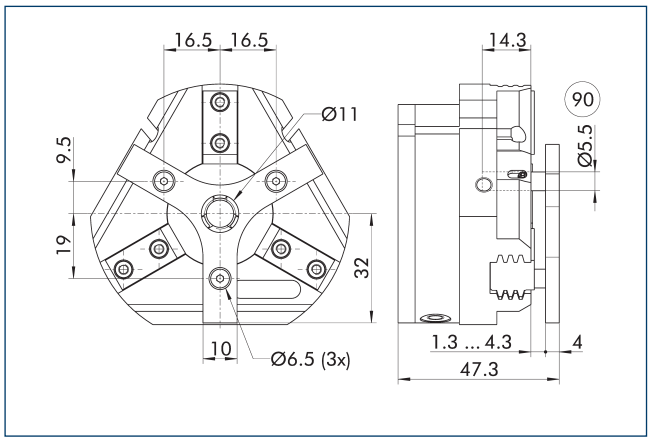
The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

Gripping force maintenance device AS / IS



The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. This acts as closing force in the AS / S version, and as opening force in the IS version. Besides this, the gripping force maintenance device can be used to increase the gripping force or for single actuated gripping.

Spring-loaded pressure piece

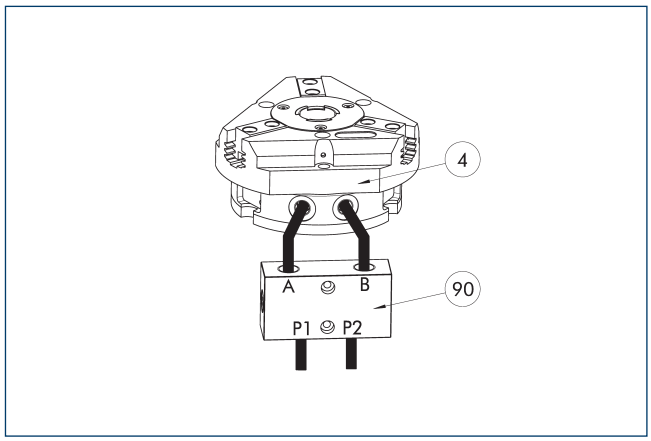


(90) Guide pin

For spring-supported positioning of the workpiece against a stop after the gripper has opened. Especially developed for loading machines.

Description	ID	Stroke	Min. force
		[mm]	[N]
Spring-loaded pressure piece			
A-PZB-plus 64	0305156	3	12

SDV-P pressure maintenance valve



(4) Grippers

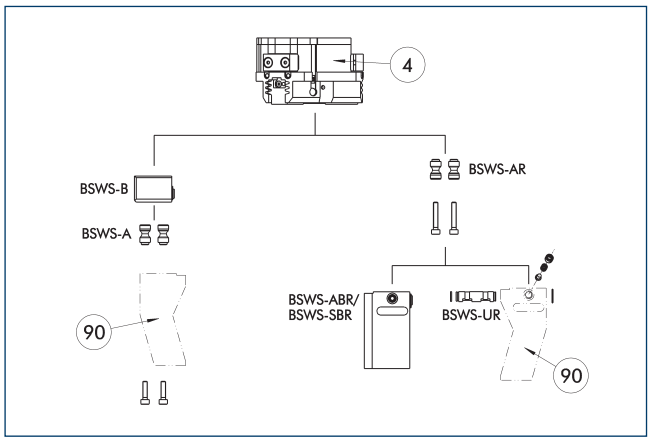
(90) SDV-P pressure maintenance valve

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter
		[mm]
Pressure maintenance valve		
SDV-P 04	0403130	6
SDV-P 07	0403131	8
Pressure maintenance valve with air bleed screw		
SDV-P 04-E	0300120	6
SDV-P 07-E	0300121	8

ⓘ In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

BSWS jaw quick-change jaw systems



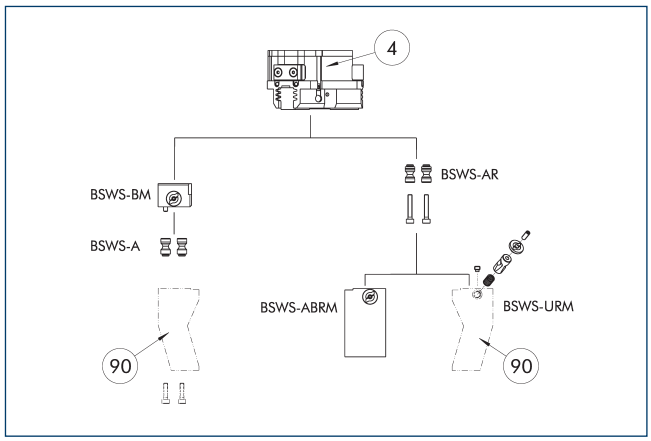
④ Grippers ⑨⓪ Customized gripper fingers

There are various jaw quick-change systems available for the gripper. For detailed information, please refer to the corresponding product.

Description	ID	Scope of delivery
Jaw quick-change system adapter pin		
BSWS-A 50	0303020	2
BSWS-AR 50	0300091	2
Quick-change jaw system base		
BSWS-B 50	0303021	1
Jaw quick-change system finger blank		
BSWS-ABR-PGZN-plus 50	0300071	1
BSWS-SBR-PGZN-plus 50	0300081	1
Jaw quick-change system locking mechanism		
BSWS-UR 50	0302990	1

ⓘ Only systems that are listed in the table, can be used.

Jaw quick-change system BSWS-M



④ Grippers ⑨⓪ Customized gripper fingers

There are various jaw quick-change systems available for the gripper. For detailed information, please refer to the corresponding product.

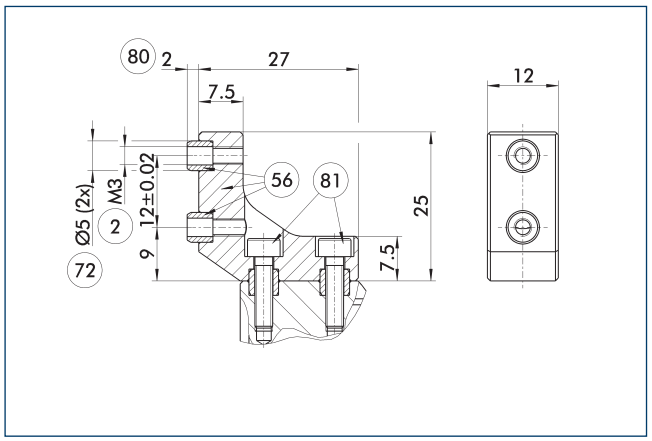
Description	ID	Scope of delivery
Jaw quick-change system adapter pin		
BSWS-A 50	0303020	2
BSWS-AR 50	0300091	2
Quick-change jaw system base		
BSWS-BM 50	1313899	1
Jaw quick-change system finger blank		
BSWS-ABRM-PGZN-plus 50	1420850	1
Jaw quick-change system locking mechanism		
BSWS-URM 50	1380614	1

ⓘ Only systems that are listed in the table, can be used.

PZB-plus 64

Universal gripper

ZBA-L-plus 50 intermediate jaws

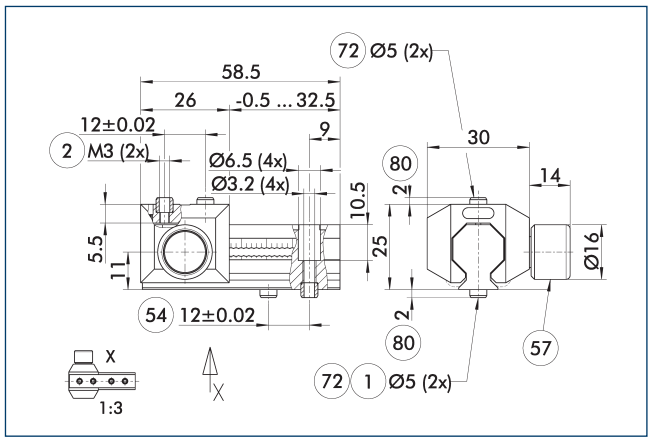


(2) Finger connection
(56) Included in the scope of delivery
(72) Fit for centering sleeves
(80) Depth of the centering sleeve hole in the counter part
(81) Not included in the scope of delivery

The optional ZBA-L-plus intermediate jaws allow the screw connection diagram of the top jaws to be rotated by 90°. This makes it easier to design and produce top jaws (particularly for long versions) because no deep through-bores are required.

Description	ID	Material	Finger interface	Scope of delivery
Intermediate jaw				
ZBA-L-plus 50	0311712	Aluminum	PGN-plus 50	1

UZB 50 universal intermediate jaw

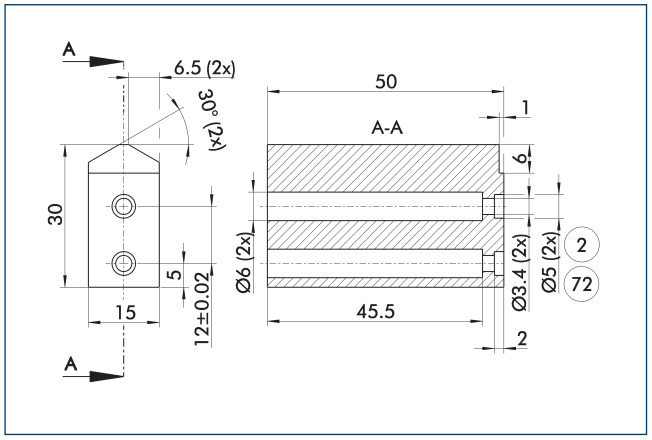


(1) Gripper connection
(2) Finger connection
(54) Optional right or left connection
(57) Locking
(72) Fit for centering sleeves
(80) Depth of the centering sleeve hole in the counter part

The drawing shows the UZB universal intermediate jaw.

Description	ID	Grid dimension
		[mm]
Universal intermediate jaw		
UZB 50	0300041	1.5
Finger blank		
ABR-PGZN-plus 50	0300009	
SBR-PGZN-plus 50	0300019	

Finger blank ABR- / SBR-PGZN-plus 50

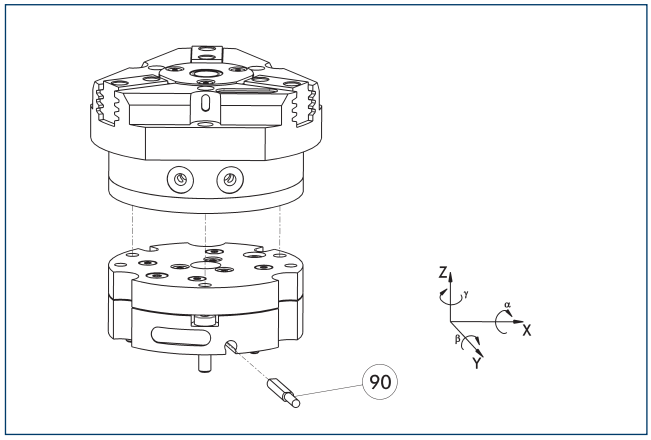


(2) Finger connection
(72) Fit for centering sleeves

The drawing shows the finger blank which can be reworked by the customer.

Description	ID	Material	Scope of delivery
Finger blank			
ABR-PGZN-plus 50	0300009	Aluminum	1
SBR-PGZN-plus 50	0300019	Steel	1

Tolerance compensation unit TCU

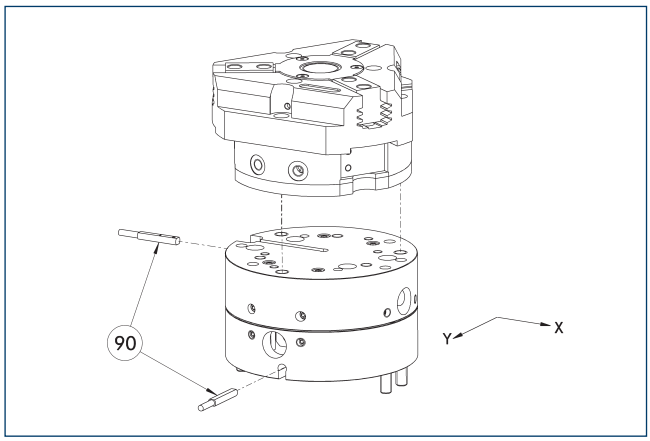


(90) Monitoring of locking

Grippers can be directly mounted without an adapter plate. Tolerance compensation unit and gripper have an identical screw connection diagram. Therefore the tolerance compensation units can be assembled later. Please consider the additional assembly height of the tolerance compensation unit. For details please refer to our catalog robot accessories.

Description	ID	Locking	Deflection	Often combined
Compensation unit				
TCU-Z-064-3-MV	0324766	yes	±1°/±1°/±1°	●
TCU-Z-064-3-OV	0324767	no	±1°/±1°/±1°	

Compensation unit AGE-F

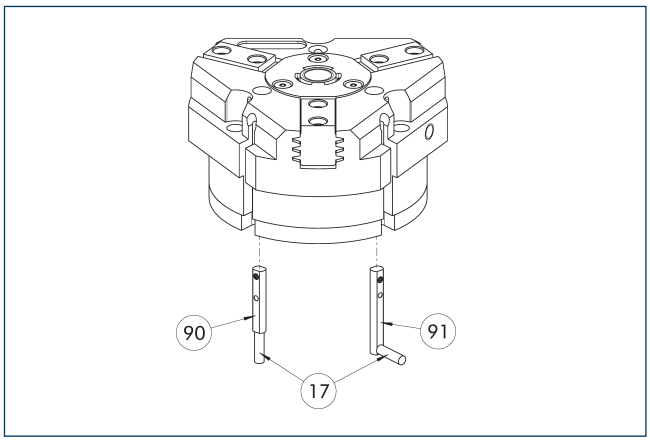


(90) Monitoring

Grippers can be directly mounted without an adapter plate. For details see our catalog Gripping or Robot Accessories.

Description	ID	Compensation XY	Reset force	Often combined
		[mm]	[N]	
Compensation unit				
AGE-F-XY-063-1	0324940	± 4	12	
AGE-F-XY-063-2	0324941	± 4	16	
AGE-F-XY-063-3	0324942	± 4	20	●

Electronic magnetic switch MMS



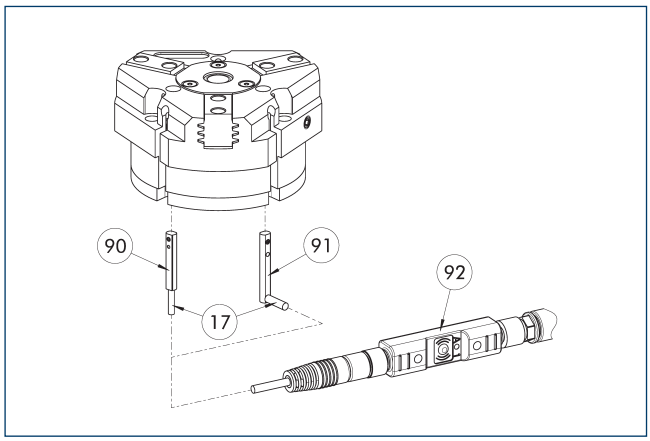
(17) Cable outlet
(90) Sensor MMS 22..
(91) Sensor MMS 22...-SA

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	●
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with lateral cable outlet		
MMS 22-S-M8-PNP-SA	0301042	●
MMSK 22-S-PNP-SA	0301044	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	●
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
clip for plug/socket		
CLI-M8	0301463	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	●
Sensor distributor		
V2-M8	0301775	●
V4-M8	0301746	
V8-M8	0301751	

ⓘ Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Programmable magnetic switch MMS 22-PI1



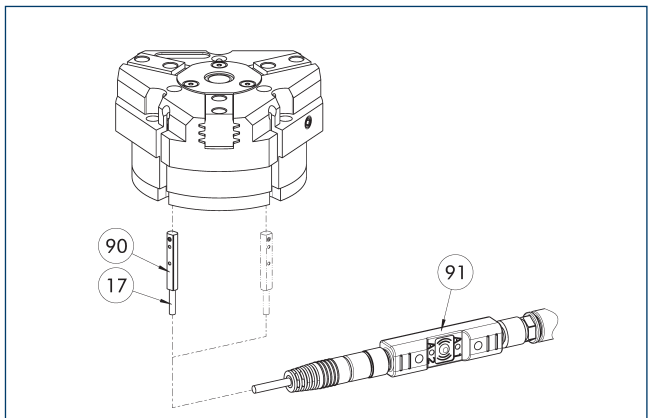
(17) Cable outlet
(90) Sensor MMS 22 PI1-...
(91) Sensor MMS 22 ..-PI1-...-SA
(92) Connector teaching tool ST

Position monitoring with one programmable switching point per sensor, directly mountable in the C-slot. The electronics are built into the sensor. The cable outlet can be located either axially or laterally (MMS 22...-SA). Programmed using the plug teaching tool ST (to be ordered separately).

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI1-S-M8-PNP	0301160	●
MMSK 22-PI1-S-PNP	0301162	
Programmable magnetic switch with lateral cable outlet		
MMS 22-PI1-S-M8-PNP-SA	0301166	●
MMSK 22-PI1-S-PNP-SA	0301168	
Programmable magnetic switch with stainless steel housing		
MMS 22-PI1-S-M8-PNP-HD	0301110	●
MMSK 22-PI1-S-PNP-HD	0301112	
Plug teaching tool		
ST-MMS 22-PI1-PNP	0301025	

ⓘ Two sensors (closer/S) are required for each unit and extension cables are available as an option.

Programmable magnetic switch MMS 22-PI2



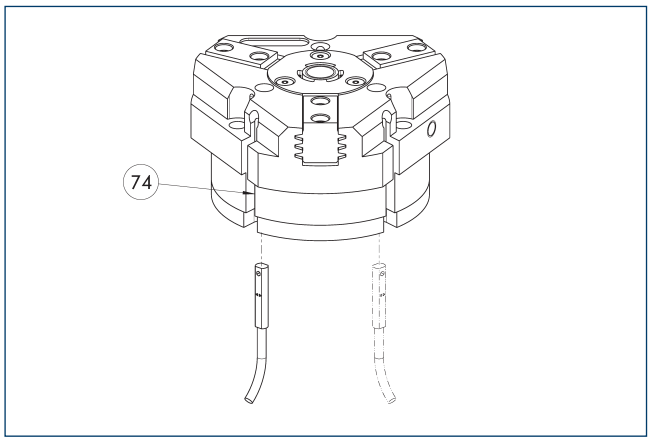
(17) Cable outlet
(90) MMS 22...-PI2-... sensor
(91) Connector teaching tool ST

Position monitoring with two programmable switching points per sensor, mountable directly in the C-slot. The electronics are built into the sensor. Programmed using the plug teaching tool ST (to be ordered separately).

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI2-S-M8-PNP	0301180	●
MMSK 22-PI2-S-PNP	0301182	
Programmable magnetic switch with lateral cable outlet		
MMS 22-PI2-S-M8-PNP-SA	0301186	●
MMSK 22-PI2-S-PNP-SA	0301188	
Programmable magnetic switch with stainless steel housing		
MMS 22-PI2-S-M8-PNP-HD	0301130	●
MMSK 22-PI2-S-PNP-HD	0301132	
Plug teaching tool		
ST-MMS 22-PI2-PNP	0301026	

ⓘ Per unit, at least one sensor (closer/S) and an optional cable extension are required. A maximum of one sensor per C-slot or sensor bracket can be mounted.

MMS-P programmable magnetic switch



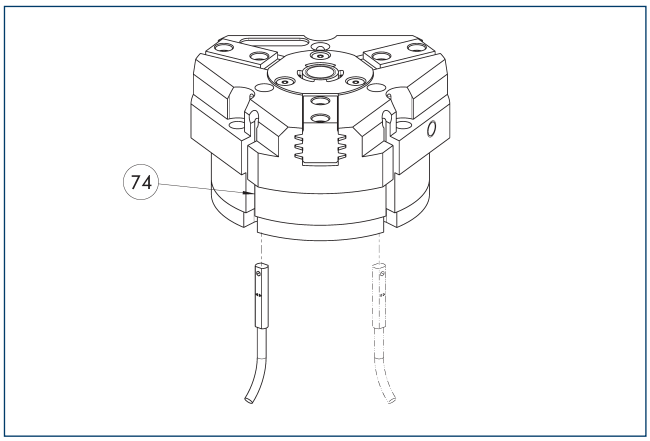
74 Limit stop for sensor

Position monitoring with two programmable positions per sensor. End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Programmable magnetic switch		
MMSK-P 22-S-PNP	0301371	
MMS-P 22-S-M8-PNP	0301370	●
Connection cables		
KA GLN0804-LK-00500-A	0307767	●
KA GLN0804-LK-01000-A	0307768	
KA WLN0804-LK-00500-A	0307765	
KA WLN0804-LK-01000-A	0307766	
clip for plug/socket		
CLI-M8	0301463	
Sensor distributor		
V2-M8-4P-2XM8-3P	0301380	

ⓘ One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

Programmable magnetic switch MMS-IO-Link



74 Limit stop for sensor

Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. Sensor programming on the gripper takes place via the IO-Link interface or the MT magnetic teach tool (included in scope of delivery). An IO-Link master is required for operation.

Description	ID	
Programmable magnetic switch		
MMS 22-IOL-M08	0315830	
MMS 22-IOL-M12	0315835	

ⓘ One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems. The sensor only works on the PZB-plus 64-1 and PZB-plus 64-2 variants. Other variants of the gripper are not compatible with the sensor.

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