



Superior Clamping and Gripping



## Product Information

Universal gripper PZB-plus 160

# PZB-plus

Universal gripper

## Robust. Flexible. Precise.

### Universal gripper PZB-plus

Universal 3-finger centric gripper with large gripping force and high maximum moments per finger, plus center bore

#### Field of application

For universal use in clean and slightly dirty environments. Suitable for applications that require a center bore, e.g. for workpiece feeding, special sensor systems or optical recognition Systems.

#### Advantages – Your benefits

**Robust multi-tooth guidance** for precise handling

**High maximum moments possible** suitable for using long gripper fingers

**High gripping forces achievable** for a wide range of applications

**Center through-hole** available with fitting and female thread, which facilitates assembly of customer attachments. Moreover, the center bore is used for feed-through of supply hoses and others.

**Air supply via hose-free direct connection or screw connections** for flexible pressure supply in all automated systems

**Manifold options** optional with mechanic gripping force maintenance



Sizes  
Quantity: 9



Weight  
0.26 .. 53 kg



Gripping force  
340 .. 27400 N



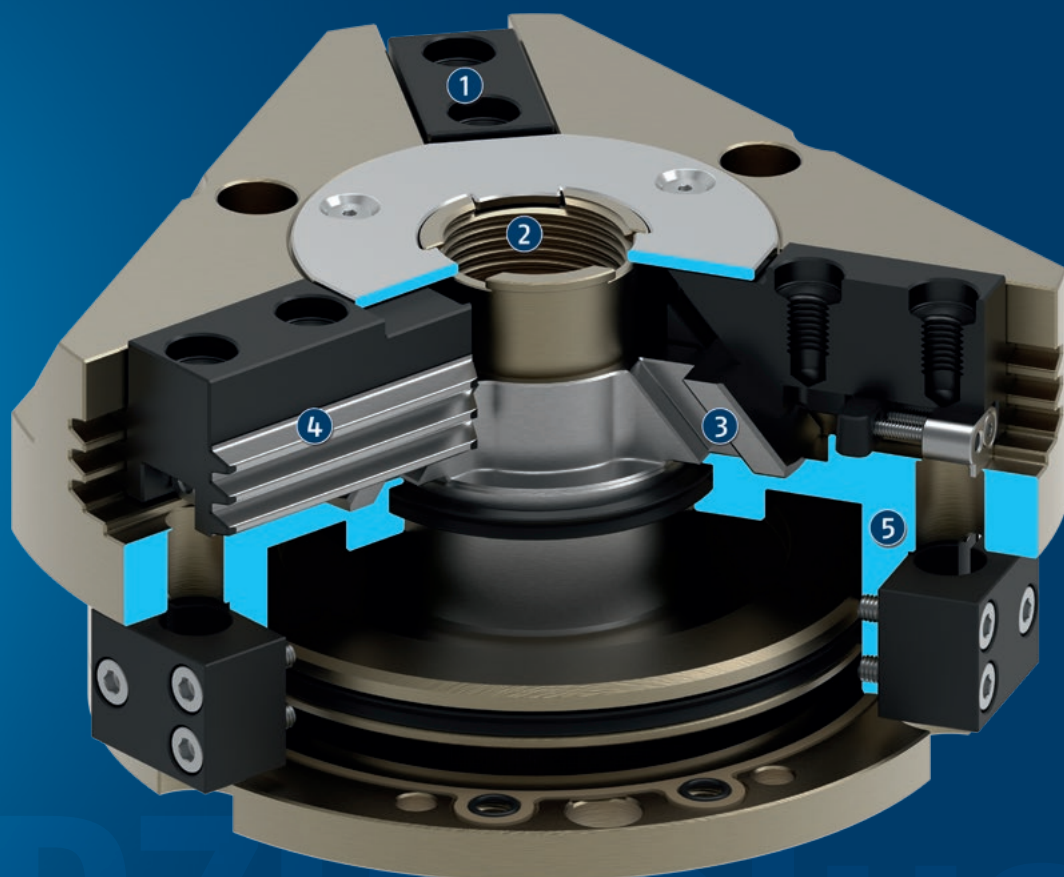
Stroke per jaw  
2 .. 35 mm



Workpiece weight  
1.7 .. 100 kg

## Functional description

The piston is moved up and down by compressed air.  
The angled active surfaces of the wedge-hook produce a synchronized, centric jaw movement.



- ① **Base Jaw**  
for the connection of workpiece-specific gripper fingers
- ② **Center bore**  
for workpiece feeding, for sensor systems, actuators (ejectors) or optical workpiece recognition
- ③ **Wedge-hook design**  
for high force transmission and centric gripping
- ④ **Multi-tooth guidance**  
precise gripping through base jaw guidance with a high load capacity and a minimum Play
- ⑤ **Housing**  
is weight-optimized due to the use of high-strength aluminum alloy

# PZB-plus

Universal gripper

## General notes about the series

**Operating principle:** Wedge-hook kinematics

**Housing material:** Aluminum alloy, anodized

**Base jaw material:** Steel

**Actuation:** pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

**Warranty:** 36 months

**Scope of delivery:** Brackets for proximity switches, centering sleeves, O-rings for direct connection, assembly instructions (operating manual with declaration of incorporation is available online)

**Gripping force maintenance device:** possible by using the version with mechanical gripping force maintenance or pressure maintenance valve SDV-P

**Gripping force:** is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

**Finger length:** is measured from the reference surface as the distance P in direction to the main axis.

The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

**Repeat accuracy:** is defined as a distribution of the end Position for 100 consecutive strokes.

**Workpiece weight:** is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

**Closing and opening times:** are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.

## Application example

Assembly aid for long shafts. Feeding is done space-saving via the center bores of gripper and rotary feed-through.

- 1 3-finger centric gripper PZB-plus
- 2 Modified Rotary feed-through DDF with center bore

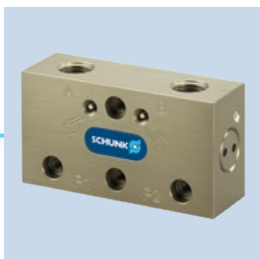


## SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.



Compensation unit



Pressure maintenance valve



Universal intermediate jaw



Jaw quick-change system



Magnetic switches



Flexible position sensor



Analog position sensor



Finger blank



Inductive proximity switches

① For more information on these products can be found on the following product pages or at [schunk.com](http://schunk.com).

## Options and special information

**Gripping force maintenance version AS/IS:** The mechanical gripping force maintenance version ensures minimum gripping force even in the event of a pressure drop. In the AS/S version this acts as a closing force, in the IS version as an opening force.

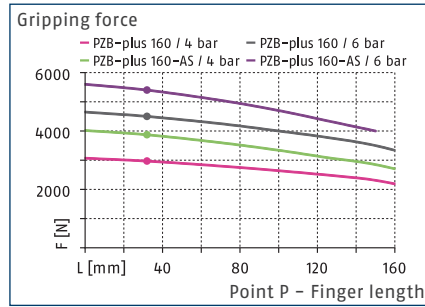
Due to the center bore, the PZB-plus series is the optimal standard solution for many fields of application.

# PZB-plus 160

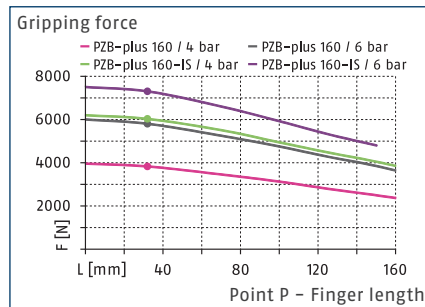
Universal gripper



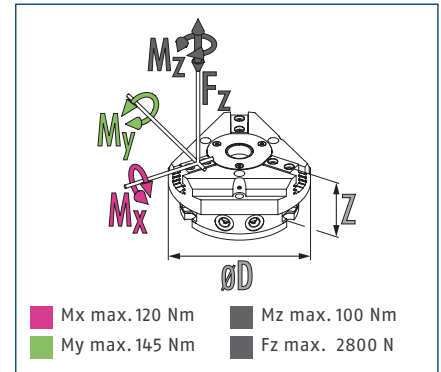
## Gripping force O.D. gripping



## Gripping force I.D. gripping



## Dimensions and maximum loads



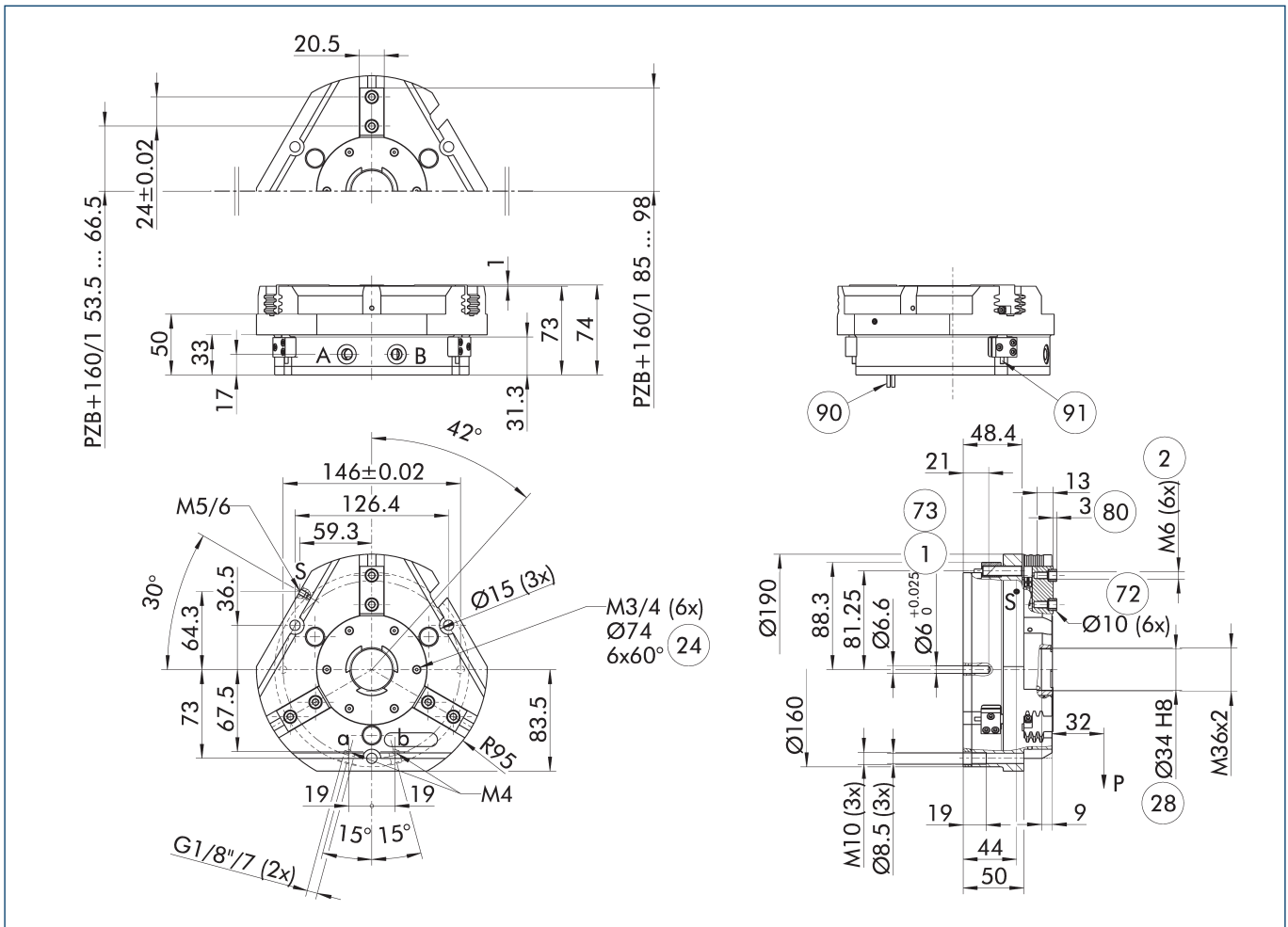
① The indicated moments and forces are static values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

## Technical data

Description		PZB-plus 160-1	PZB-plus 160-1-AS	PZB-plus 160-1-IS
ID		0305190	0305192	0305194
Stroke per jaw	[mm]	13	13	13
Closing/opening force	[N]	4500/5800	5400/-	-/7300
Min. spring force	[N]		900	1500
Weight	[kg]	4.8	7.3	7.3
Recommended workpiece weight	[kg]	22	22	22
Fluid consumption double stroke	[cm <sup>3</sup> ]	360	620	620
Min./nom./max. operating pressure	[bar]	2/6/8	4/6/6.5	4/6/6.5
Min./max. air purge pressure	[bar]	0.5/1	0.5/1	0.5/1
Closing/opening time	[s]	0.5/0.5	0.4/0.8	0.8/0.4
Closing/opening time with spring	[s]		0.80	0.80
Max. permissible finger length	[mm]	160	135	135
Max. permissible mass per finger	[kg]	2.1	2.1	2.1
IP protection class		40	40	40
Min./max. ambient temperature	[°C]	5/90	5/90	5/90
Repeat accuracy	[mm]	0.02	0.02	0.02
Diameter of center bore	[mm]	34	34	34
Dimensions Ø D x Z	[mm]	190 x 74	190 x 101.5	190 x 101.5

① It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

## Main view



The drawing shows the gripper in the basic version with closed jaws, without dimensional consideration of the options described below.

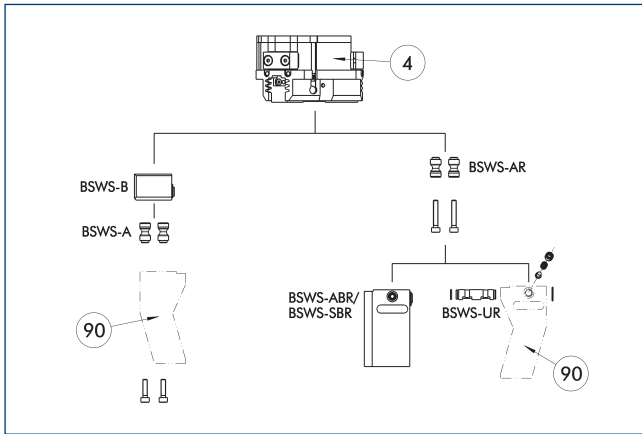
① The SDV-P pressure maintenance valve can also be used for I.D. or O.D. gripping alternatively or in addition to the spring-loaded, mechanical gripping force maintenance device (see catalog section on accessories).

- |  |  |
|--|--|
| A, a Main / direct connection, gripper opening | ②8 Through-hole  |
| B, b Main / direct connection, gripper closing | ②7 Fit for centering sleeves                               |
| S Air purge connection                         | ②73 Fit for centering pins                                 |
| ① Gripper connection                           | ②80 Depth of the centering sleeve hole in the counter part |
| ② Finger connection                            | ②90 Sensor MMS 22..  |
| ②4 Bolt circle                                 | ②91 Sensor IN ...  |





**BSWS jaw quick-change jaw systems**



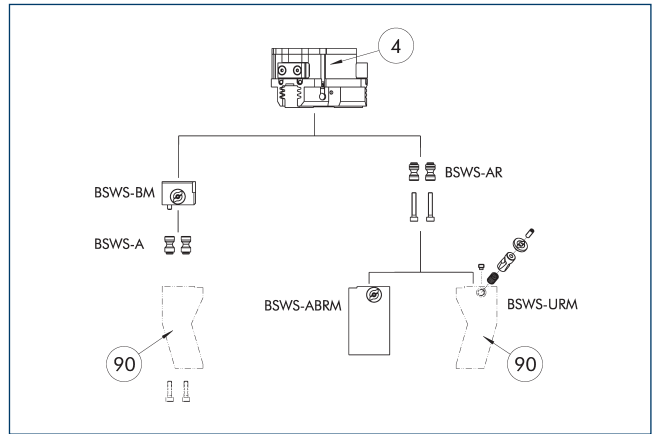
④ Grippers                      ⑨0 Customized gripper fingers

There are various jaw quick-change systems available for the gripper. For detailed information, please refer to the corresponding product.

Description	ID	Scope of delivery
<b>Jaw quick-change system adapter pin</b>		
BSWS-A 125	0303028	2
BSWS-AR 125	0300095	2
<b>Quick-change jaw system base</b>		
BSWS-B 125	0303029	1
<b>Jaw quick-change system finger blank</b>		
BSWS-ABR-PGZN-plus 125	0300075	1
BSWS-SBR-PGZN-plus 125	0300085	1
<b>Jaw quick-change system locking mechanism</b>		
BSWS-UR 125	0302994	1

④ Only systems that are listed in the table, can be used.

**Jaw quick-change system BSWS-M**



④ Grippers                      ⑨0 Customized gripper fingers

There are various jaw quick-change systems available for the gripper. For detailed information, please refer to the corresponding product.

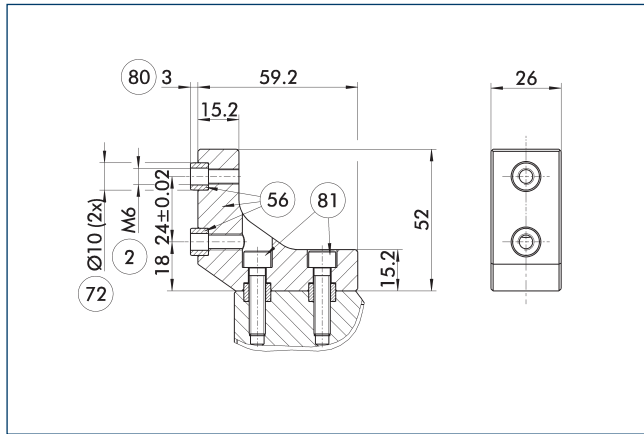
Description	ID	Scope of delivery
<b>Jaw quick-change system adapter pin</b>		
BSWS-A 125	0303028	2
BSWS-AR 125	0300095	2
<b>Quick-change jaw system base</b>		
BSWS-BM 125	1302006	1
<b>Jaw quick-change system finger blank</b>		
BSWS-ABRM-PGZN-plus 125	1420854	1
<b>Jaw quick-change system locking mechanism</b>		
BSWS-URM 125	1398404	1

④ Only systems that are listed in the table, can be used.

# PZB-plus 160

Universal gripper

## ZBA-L-plus 125 intermediate jaws

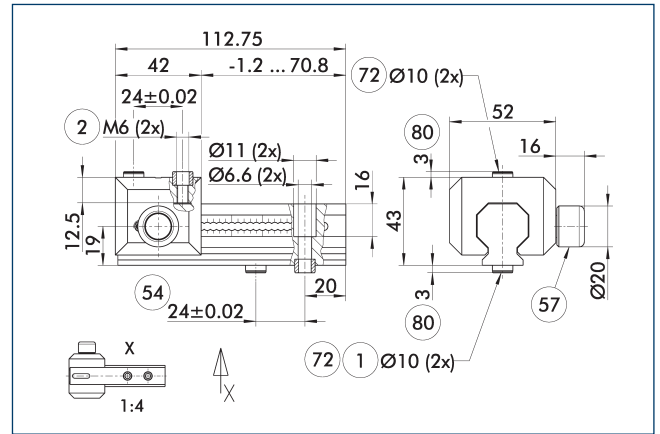


- ② Finger connection
- ⑤⑥ Included in the scope of delivery
- ⑦② Fit for centering sleeves
- ⑧① Depth of the centering sleeve hole in the counter part
- ⑧① Not included in the scope of delivery

The optional ZBA-L-plus intermediate jaws allow the screw connection diagram of the top jaws to be rotated by 90°. This makes it easier to design and produce top jaws (particularly for long versions) because no deep through-bores are required.

Description	ID	Material	Finger interface	Scope of delivery
Intermediate jaw				
ZBA-L-plus 125	0311752	Aluminum	PGN-plus 125	1

## UZB 125 universal intermediate jaw

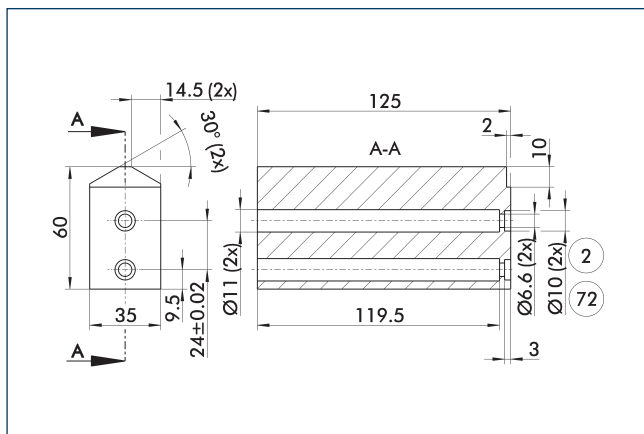


- ① Gripper connection
- ② Finger connection
- ⑤④ Optional right or left connection
- ⑤⑦ Locking
- ⑦② Fit for centering sleeves
- ⑧① Depth of the centering sleeve hole in the counter part

The drawing shows the UZB universal intermediate jaw. The fully removable UZB-S slide (can also be ordered separately) allows for a quick jaw change.

Description	ID	Grid dimension
Universal intermediate jaw		
UZB 125	0300045	3
Finger blank		
ABR-PGZN-plus 125	0300013	
SBR-PGZN-plus 125	0300023	
Slide for universal intermediate jaw		
UZB-S 125	5518273	3

## Finger blanks ABR- / SBR-PGZN-plus 125

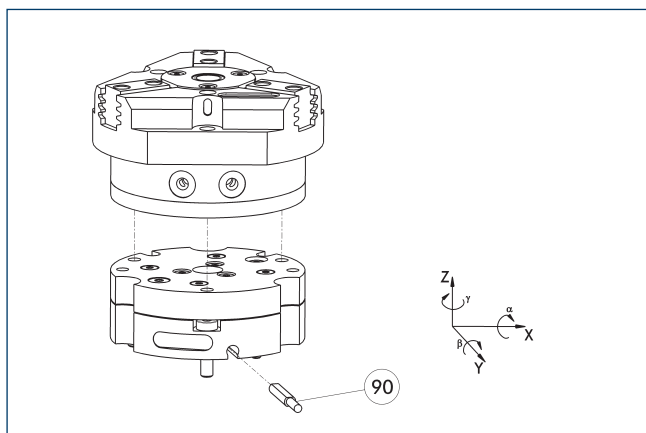


- ② Finger connection
- ⑦② Fit for centering sleeves

The drawing shows the finger blank which can be reworked by the customer.

Description	ID	Material	Scope of delivery
Finger blank			
ABR-PGZN-plus 125	0300013	Aluminum	1
SBR-PGZN-plus 125	0300023	Steel	1

## Tolerance compensation unit TCU



### 90 Monitoring of locking

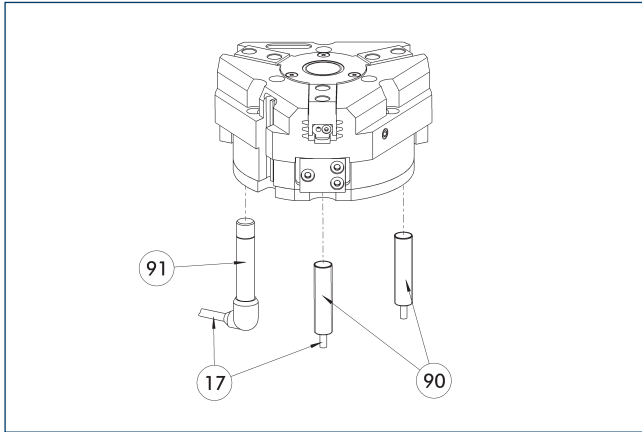
Grippers can be directly mounted without an adapter plate. Tolerance compensation unit and gripper have an identical screw connection diagram. Therefore the tolerance compensation units can be assembled later. Please consider the additional assembly height of the tolerance compensation unit. For details please refer to our catalog robot accessories.

Description	ID	Locking	Deflection	Often combined
Compensation unit				
TCU-Z-160-3-MV	0324838	yes	$\pm 1^\circ / \pm 1^\circ / \pm 1^\circ$	●
TCU-Z-160-3-0V	0324839	no	$\pm 1^\circ / \pm 1^\circ / \pm 1^\circ$	

# PZB-plus 160

Universal gripper

## Inductive Proximity Switches



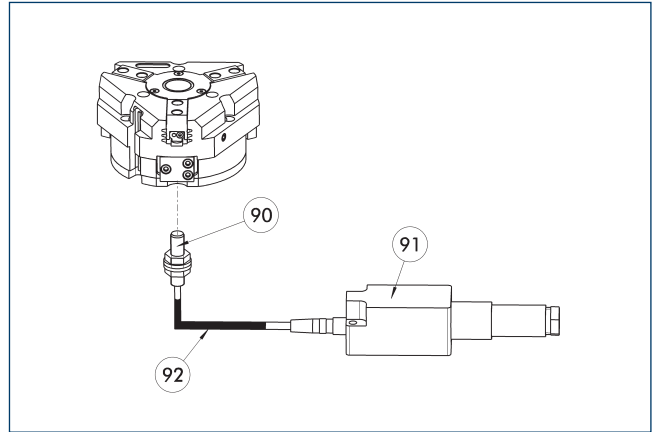
- 17 Cable outlet
- 90 Sensor IN ...
- 91 Sensor IN..-SA

Directly mounted end position monitoring.

Description	ID	Often combined
<b>Inductive proximity switches</b>		
IN 80-S-M12	0301578	
IN 80-S-M8	0301478	●
INK 80-S	0301550	
<b>Inductive proximity switch with lateral cable outlet</b>		
IN 80-S-M12-SA	0301587	
IN 80-S-M8-SA	0301483	●
INK 80-S-SA	0301566	
<b>Connection cables</b>		
KA BG08-L 3P-0300-PNP	0301622	●
KA BG08-L 3P-0500-PNP	0301623	
KA BG12-L 3P-0500-PNP	30016369	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
<b>clip for plug/socket</b>		
CLI-M12	0301464	
CLI-M8	0301463	
<b>Cable extension</b>		
KV BG12-SG12 3P-0030-PNP	0301999	
KV BG12-SG12 3P-0060-PNP	0301998	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	●
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	
<b>Sensor distributor</b>		
V2-M12	0301776	●
V2-M8	0301775	●
V4-M8	0301746	
V8-M8	0301751	

- ① Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

## Flexible position sensor



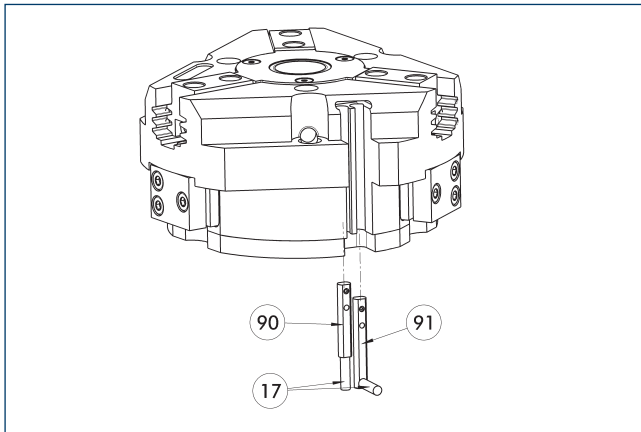
- 90 FPS-S sensor
- 91 FPS-F5 evaluation electronic
- 92 Cable extension

Flexible position monitoring of up to five positions.

Description	ID	
<b>Attachment kit for FPS</b>		
AS-FPS-PGZN-plus 125-1/PZB 160	0301636	
<b>Sensor</b>		
FPS-S M8	0301704	
<b>Evaluation electronics</b>		
FPS-F5	0301805	
<b>Cable extension</b>		
KV BG08-SG08 3P-0050	0301598	
KV BG08-SG08 3P-0100	0301599	

- ① When using an FPS system, an FPS sensor (FPS-S) as well as an electronic processor (FPS-F5 / F5 T) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are optionally available – see catalog chapter “Accessories.”

Electronic magnetic switch MMS



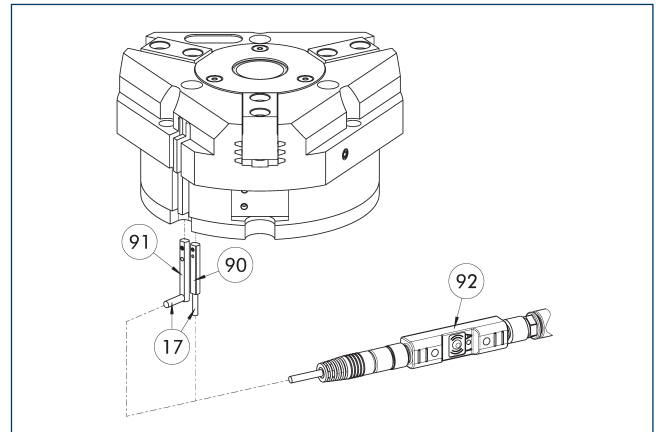
- 17 Cable outlet
- 90 Sensor MMS 22..
- 91 Sensor MMS 22...-SA

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
<b>Electronic magnetic switch</b>		
MMS 22-S-M8-PNP	0301032	●
MMSK 22-S-PNP	0301034	
<b>Electronic magnetic switches with lateral cable outlet</b>		
MMS 22-S-M8-PNP-SA	0301042	●
MMSK 22-S-PNP-SA	0301044	
<b>Reed Switches</b>		
RMS 22-S-M8	0377720	●
<b>Connection cables</b>		
KA BG08-L 3P-0300-PNP	0301622	●
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
<b>clip for plug/socket</b>		
CLI-M8	0301463	
<b>Wireless sensor system</b>		
RSS-T2	0377715	
RSS-T2-US/CA	0377717	
<b>Cable extension</b>		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	●
<b>Sensor distributor</b>		
V2-M8	0301775	●
V4-M8	0301746	
V8-M8	0301751	

① Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Programmable magnetic switch MMS 22-PI1



- 17 Cable outlet
- 90 Sensor MMS 22 PI1-...
- 91 Sensor MMS 22 ...-PI1-...-SA
- 92 Connector teaching tool ST

Position monitoring with one programmable switching point per sensor, directly mountable in the C-slot. The electronics are built into the sensor. The cable outlet can be located either axially or laterally (MMS 22...-SA). Programmed using the plug teaching tool ST (to be ordered separately).

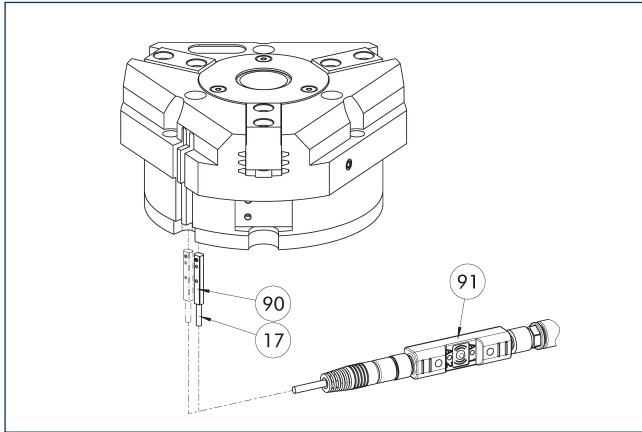
Description	ID	Often combined
<b>Programmable magnetic switch</b>		
MMS 22-PI1-S-M8-PNP	0301160	●
MMSK 22-PI1-S-PNP	0301162	
<b>Programmable magnetic switch with lateral cable outlet</b>		
MMS 22-PI1-S-M8-PNP-SA	0301166	●
MMSK 22-PI1-S-PNP-SA	0301168	
<b>Programmable magnetic switch with stainless steel housing</b>		
MMS 22-PI1-S-M8-PNP-HD	0301110	●
MMSK 22-PI1-S-PNP-HD	0301112	
<b>Plug teaching tool</b>		
ST-MMS 22-PI1-PNP	0301025	

① Two sensors (closer/S) are required for each unit and extension cables are available as an option.

# PZB-plus 160

Universal gripper

## Programmable magnetic switch MMS 22-PI2



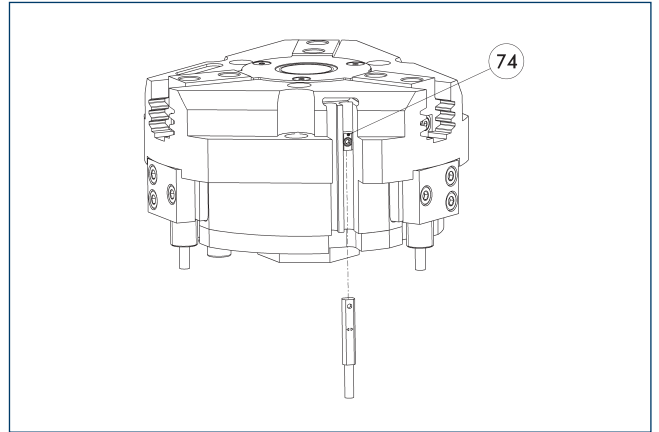
- ①⑦ Cable outlet
- ①⑨ Connector teaching tool ST
- ①⑩ MMS 22...-PI2-... sensor

Position monitoring with two programmable switching points per sensor, mountable directly in the C-slot. The electronics are built into the sensor. Programmed using the plug teaching tool ST (to be ordered separately).

Description	ID	Often combined
<b>Programmable magnetic switch</b>		
MMS 22-PI2-S-M8-PNP	0301180	●
MMSK 22-PI2-S-PNP	0301182	
<b>Programmable magnetic switch with lateral cable outlet</b>		
MMS 22-PI2-S-M8-PNP-SA	0301186	●
MMSK 22-PI2-S-PNP-SA	0301188	
<b>Programmable magnetic switch with stainless steel housing</b>		
MMS 22-PI2-S-M8-PNP-HD	0301130	●
MMSK 22-PI2-S-PNP-HD	0301132	
<b>Plug teaching tool</b>		
ST-MMS 22-PI2-PNP	0301026	

- ① Per unit, at least one sensor (closer/S) and an optional cable extension are required. A maximum of one sensor per C-slot or sensor bracket can be mounted.

## MMS-P programmable magnetic switch



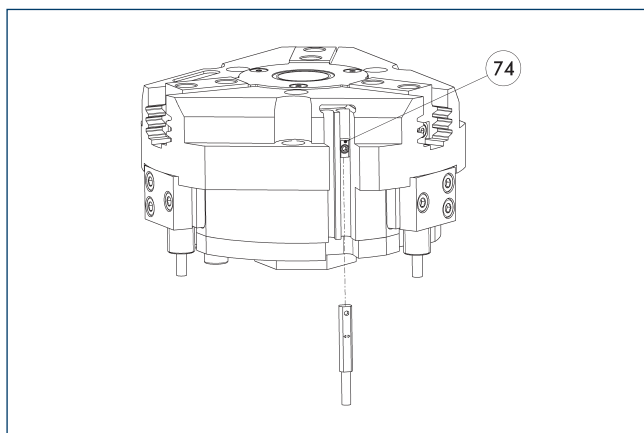
- ①④ Limit stop for sensor

Position monitoring with two programmable positions per sensor. End position monitoring for mounting in the C-slot.

Description	ID	Often combined
<b>Programmable magnetic switch</b>		
MMSK-P 22-S-PNP	0301371	
MMS-P 22-S-M8-PNP	0301370	●
<b>Connection cables</b>		
KA GLN0804-LK-00500-A	0307767	●
KA GLN0804-LK-01000-A	0307768	
KA WLN0804-LK-00500-A	0307765	
KA WLN0804-LK-01000-A	0307766	
<b>clip for plug/socket</b>		
CLI-M8	0301463	
<b>Sensor distributor</b>		
V2-M8-4P-2XM8-3P	0301380	

- ① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

## Programmable magnetic switch MMS-I0-Link



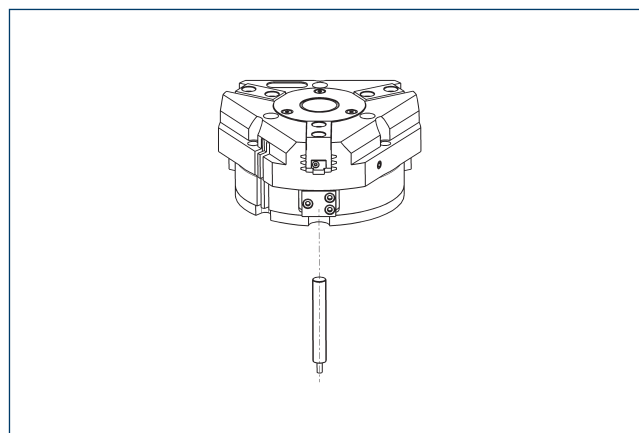
### 74 Limit stop for sensor

Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. Sensor programming on the gripper takes place via the IO-Link interface or the MT magnetic teach tool (included in scope of delivery). An IO-Link master is required for operation.

Description	ID	
Programmable magnetic switch		
MMS 22-I0L-M08	0315830	
MMS 22-I0L-M12	0315835	

- ① One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.

## APS-Z80 analog position sensor



No-contact measuring, analog multi-position monitoring for any number of positions.

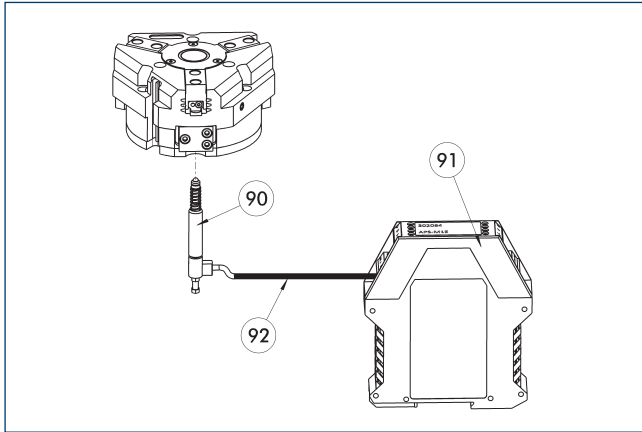
Description	ID	Often combined
Mounting kit for APS-Z80		
AS-APS-Z80-PGZN-plus 125-1	0302111	
Analog position sensor		
APS-Z80-K	0302072	
APS-Z80-M8	0302070	●

- ① When using an APS system, one mounting kit (AS-APS-Z80) and one APS-Z80 sensor is required per gripper. The resolution of the sensor can be lower in the peripheral areas of the gripper. You can find further information on the product in the operating manual.

# PZB-plus 160

Universal gripper

## APS-M1 analog position sensor



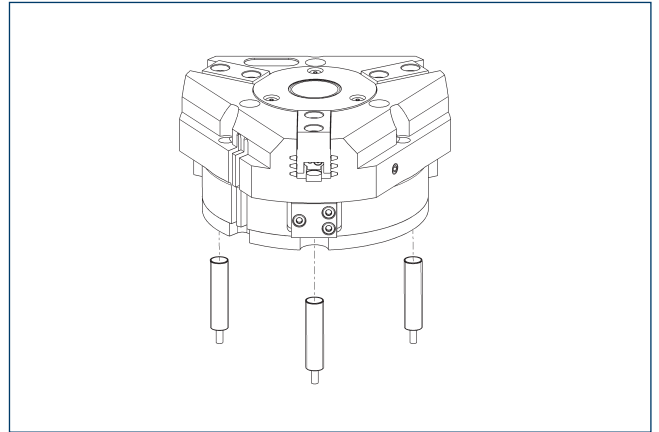
- ⑨⑩ APS-M1S sensor
- ⑨① APS-M1E electronic processor
- ⑨② APS-K extension cable

Analog multi position monitoring for any desired positions

Description	ID
<b>Mounting kit for APS-M1</b>	
AS-APS-M1-PGZN-plus 125-1	0302081
<b>Analog position sensor</b>	
APS-M1S	0302062
<b>Connection cables</b>	
APS-K0200	0302066
APS-K0700	0302068
<b>Evaluation electronics</b>	
APS-M1E	0302064

- ① When using an APS system, for each gripper an attachment kit (AS-APS-M1), an APS-M1S sensor (incl. 3 m cable) as well as an electronics (APS-M1e) are required. An extension cable (APS-K) can be connected between the sensor and the electronics as an option. The max. cable length between the sensor and the electronics is 10 m, between the electronics and their control unit (PLC) it is max. 1 m.

## Cylindrical reed switches



End position monitoring can be mounted with an attachment kit.

Description	ID
<b>Attachment kit for proximity switch</b>	
AS-RMS 80 PGN/PZN-plus 100/125	0377726
<b>Reed Switches</b>	
RMS 80-S-M8	0377721

- ① Two sensors (closer/S) are required for each unit and extension cables are available as an option. This attachment kit needs to be ordered optionally as an accessory. Two mounting kits are required for each gripper. For sensor cables, note the minimum permissible bending radii. These are generally 35 mm.







**SCHUNK GmbH & Co. KG**  
**Spann- und Greiftechnik**

Bahnhofstr. 106 - 134  
D-74348 Lauffen/Neckar  
Tel. +49-7133-103-0  
Fax +49-7133-103-2399  
info@de.schunk.com  
schunk.com

Folgen Sie uns | *Follow us*

