



Superior Clamping and Gripping

Product Information

Universal gripper PZB-plus 300

Universal gripper

Robust. Flexible. Precise. Universal gripper PZB-plus

Universal 3-finger centric gripper with large gripping force and high maximum moments per finger, plus center bore

Field of application

For universal use in clean and slightly dirty environments. Suitable for applications that require a center bore, e.g. for workpiece feeding, special sensor systems or optical recognition Systems.

Advantages – Your benefits

Robust multi-tooth guidance for precise handling

High maximum moments possible suitable for using long gripper fingers

High gripping forces achievable for a wide range of applications

Center through-hole available with fitting and female thread, which facilitates assembly of customer attachments. Moreover, the center bore is used for feed-through of supply hoses and others.

Air supply via hose-free direct connection or screw connections for flexible pressure supply in all automated systems

Manifold options optional with mechanic gripping force maintenance









Stroke per jaw 2 ... 35 mm



Functional description

The piston is moved up and down by compressed air. The angled active surfaces of the wedge-hook produce a synchronized, centric jaw movement.



① Base Jaw

for the connection of workpiece-specific gripper fingers

② Center bore

for workpiece feeding, for sensor systems, actuators (ejectors) or optical workpiece recognition

③ Wedge-hook design for high force transmission and centric gripping

(4) Multi-tooth guidance

precise gripping through base jaw guidance with a high load capacity and a minimum Play

5 Housing

is weight-optimized due to the use of high-strength aluminum alloy

General notes about the series

Operating principle: Wedge-hook kinematics

Housing material: Aluminum alloy, anodized

Base jaw material: Steel

Actuation: pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

Warranty: 36 months

Scope of delivery: Brackets for proximity switches, centering sleeves, O-rings for direct connection, assembly instructions (operating manual with declaration of incorporation is available online)

Gripping force maintenance device: possible by using the version with mechanical gripping force maintenance or pressure maintenance valve SDV-P

Gripping force: is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

Finger length: is measured from the reference surface as the distance P in direction to the main axis. The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

Repeat accuracy: is defined as a distribution of the end Position for 100 consecutive strokes.

Workpiece weight: is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.

Application example

Assembly aid for long shafts. Feeding is done space-saving via the center bores of gripper and rotary feed-through.

- **1** 3-finger centric gripper PZB-plus
- Modified Rotary feed-through DDF with center bore



SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.







Compensation unit



Pressure maintenance valve



Flexible position sensor



Universal intermediate jaw



Analog position sensor



Jaw quick-change system



Finger blank



① For more information on these products can be found on the following product pages or at schunk.com.

Options and special information

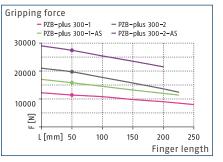
Gripping force maintenance version AS/IS: The mechanical gripping force maintenance version ensures minimum gripping force even in the event of a pressure drop. In the AS/S version this acts as a closing force, in the IS version as an opening force.

Due to the center bore, the PZB-plus series is the optimal standard solution for many fields of application.

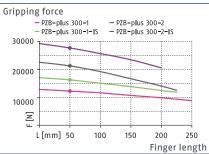
Universal gripper



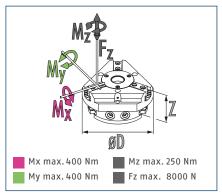
Gripping force 0.D. gripping



Gripping force I.D. gripping



Dimensions and maximum loads



The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

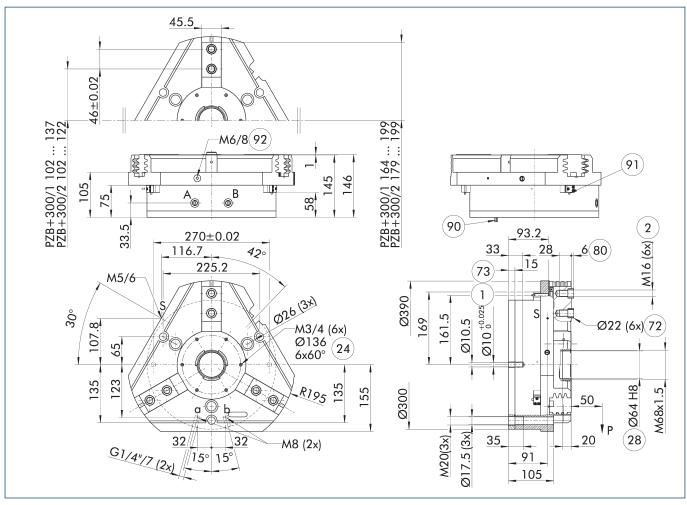
Technical data

Description		PZB-plus 300-1	PZB-plus 300-2	PZB-plus 300-1-AS	PZB-plus 300-2-AS	PZB-plus 300-1-IS	PZB-plus 300-2-IS
ID		0304970	0304971	0304972	0304973	0304974	0304975
Stroke per jaw	[mm]	35	20	35	20	35	20
Closing/opening force	[N]	11400/12200	19700/21200	15800/-	27400/-	-/16200	-/27600
Min. spring force	[N]			4400	7700	3600	6300
Weight	[kg]	38	38	53	53	53	53
Recommended workpiece weight	[kg]	57	100	57	100	57	100
Fluid consumption double stroke	[cm³]	2600	2600	3600	3600	4500	4500
Min./nom./max. operating pressure	[bar]	2/6/8	2/6/8	4/6/6.5	4/6/6.5	4/6/6.5	4/6/6.5
Min./max. air purge pressure	[bar]	0.5/1	0.5/1	0.5/1	0.5/1	0.5/1	0.5/1
Closing/opening time	[s]	1.3/1.3	1.3/1.3	1.2/2.5	1.2/2.5	2.5/1.2	2.5/1.2
Max. permissible finger length	[mm]	250	225	225	200	225	200
Max. permissible mass per finger	[kg]	11.5	11.5	11.5	11.5	11.5	11.5
IP protection class		40	40	40	40	40	40
Min./max. ambient temperature	[°C]	5/90	5/90	5/90	5/90	5/90	5/90
Repeat accuracy	[mm]	0.05	0.05	0.05	0.05	0.05	0.05
Diameter of center bore	[mm]	64	64	64	64	64	64
Dimensions Ø D x Z	[mm]	390 x 146	390 x 146	390 x 196	390 x 196	390 x 196	390 x 196

① It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

Universal gripper

Main view



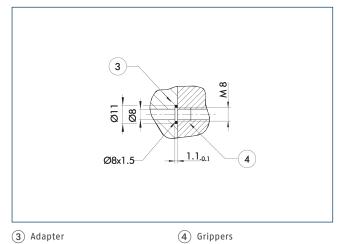
The drawing shows the gripper in the basic version with closed jaws, without dimensional consideration of the options described below.

- The SDV-P pressure maintenance valve can also be used for I.D. or O.D. gripping alternatively or in addition to the spring-loaded, mechanical gripping force maintenance device (see catalog section on accessories).
- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- S Air purge connection
- (1) Gripper connection
- (2) Finger connection
- 24 Bolt circle

- (28) Through-hole
- (72) Fit for centering sleeves
- 73 Fit for centering pins
- 80 Depth of the centering sleeve hole in the counter part
- 90 Sensor MMS 22..
- (91) Sensor IN ...
- (92) Lubricating nipple connection

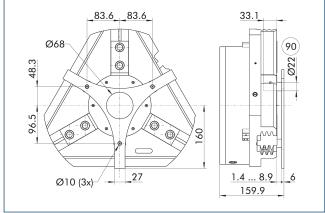
Universal gripper

Hose-free direct connection M8



The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

Spring-loaded pressure piece



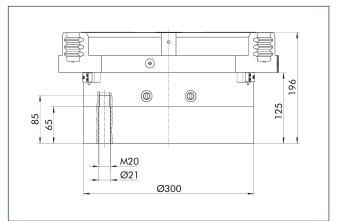
(90) Guide pin

For spring-supported positioning of the workpiece against a stop after the gripper has opened. Especially developed for loading machines.

Description	ID	Stroke	Min. force
		[mm]	[N]
Spring-loaded press	ure piece		
A-PZB-plus 300	0304976	7.5	240

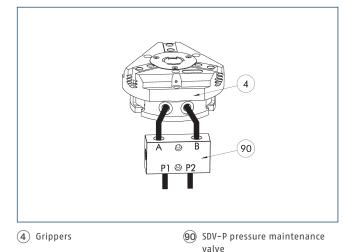
() The optional "spring-loaded pressure piece" can be assembled on a modified PZB-plus 300 if required. Please contact us for further informations.

Gripping force maintenance device AS / IS



The mechanical gripping force maintenance device ensures that a minimum clamping force will be applied even if there is a drop in pressure. This acts as closing force in the AS / S version, and as opening force in the IS version. Besides this, the gripping force maintenance device can be used to increase the gripping force or for single actuated gripping.

SDV-P pressure maintenance valve



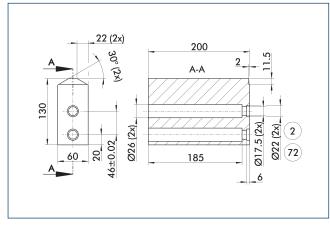
The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter
		[mm]
Pressure maintenance	e valve	
SDV-P 07	0403131	8
Pressure maintenance	e valve with a	ir bleed screw
SDV-P 07-E	0300121	8
SDV-P 10-E	0300109	10

() In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

Universal gripper

Finger blanks ABR- / SBR-PGZN-plus 300



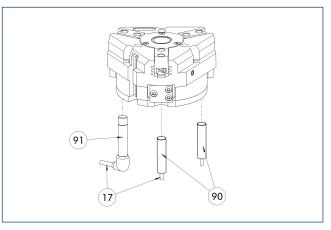
 $(\mathbf{2})$ Finger connection

(72) Fit for centering sleeves

The drawing shows the finger blank which can be reworked by the customer.

Description	ID	Material	Scope of delivery
Finger blank			
ABR-PGZN-plus 300	0300016	Aluminum	1
SBR-PGZN-plus 300	0300026	Steel	1

Inductive Proximity Switches



(17) Cable outlet

(91) Sensor IN..-SA

Sensor IN ...
 Directly mounted end position monitoring.

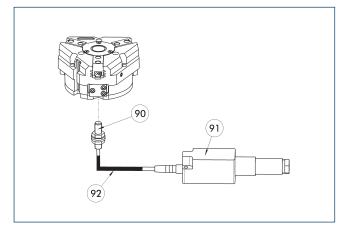
Description ID Often combined Inductive proximity switches IN 80-S-M12 0301578 IN 80-S-M8 0301478 INK 80-S 0301550 Connection cables KA BG08-L 3P-0300-PNP 0301622 KA BG08-L 3P-0500-PNP 0301623 KA BG12-L 3P-0500-PNP 30016369 KA BW08-L 3P-0300-PNP 0301594 KA BW08-L 3P-0500-PNP 0301502 KA BW12-L 3P-0300-PNP 0301503 KA BW12-L 3P-0500-PNP 0301507 clip for plug/socket CLI-M12 0301464 CLI-M8 0301463 Cable extension KV BG12-SG12 3P-0030-PNP 0301999 KV BG12-SG12 3P-0060-PNP 0301998 KV BW08-SG08 3P-0030-PNP 0301495 KV BW08-SG08 3P-0100-PNP 0301496 KV BW08-SG08 3P-0200-PNP 0301497 KV BW12-SG12 3P-0030-PNP 0301595 KV BW12-SG12 3P-0100-PNP 0301596 KV BW12-SG12 3P-0200-PNP 0301597 Sensor distributor V2-M12 0301776 V2-M8 0301775 V4-M8 0301746 0301751 V8-M8

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

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Universal gripper

Flexible position sensor



90 FPS-S sensor

(91) FPS-F5 evaluation electronic

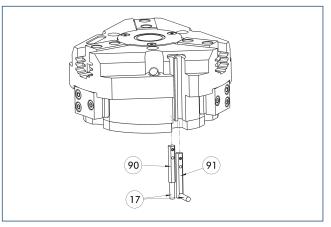
Flexible position monitoring of up to five positions.

Description	ID
Attachment kit for FPS	
AS-FPS-PGZN-plus 300-2	0301642
Sensor	
FPS-S M8	0301704
Evaluation electronics	
FPS-F5	0301805
Cable extension	
KV BG08-SG08 3P-0050	0301598
KV BG08-SG08 3P-0100	0301599

(92) Cable extension

When using an FPS system, an FPS sensor (FPS-S) as well as an electronic processor (FPS-F5 / F5 T) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are optionally available - see catalog chapter "Accessories."

Electronic magnetic switch MMS



17) Cable outlet

(91) Sensor MMS 22...-SA

90 Sensor MMS 22..

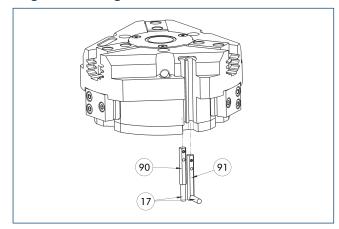
End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	•
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with	lateral cable (outlet
MMS 22-S-M8-PNP-SA	0301042	•
MMSK 22-S-PNP-SA	0301044	
Reed Switches	•	
RMS 22-S-M8	0377720	•
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
clip for plug/socket		
CLI-M8	0301463	
Wireless sensor system		
RSS-T2	0377715	
RSS-T2-US/CA	0377717	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
Sensor distributor		
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

 Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Universal gripper

Programmable magnetic switch MMS 22-PI1



(17) Cable outlet

(91) Sensor MMS 22 ..- PI1-...-SA

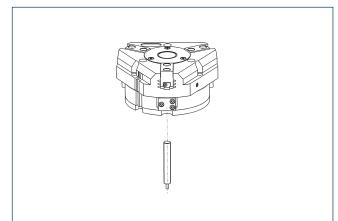
(90) Sensor MMS 22 PI1-...

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI1-S-M8-PNP	0301160	•
MMSK 22-PI1-S-PNP	0301162	
Programmable magnetic switch	with lateral c	able outlet
MMS 22-PI1-S-M8-PNP-SA	0301166	•
MMSK 22-PI1-S-PNP-SA	0301168	
Programmable magnetic switch	with stainles	s steel housing
MMS 22-PI1-S-M8-PNP-HD	0301110	•
MMSK 22-PI1-S-PNP-HD	0301112	

 Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

APS-Z80 analog position sensor



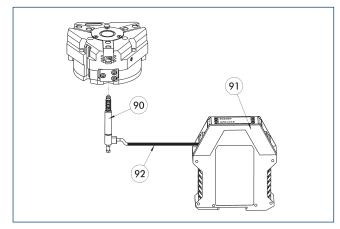
No-contact measuring, analog multi-position monitoring for any number of positions.

Description	ID	Often combined
Mounting kit for APS-Z80		
AS-APS-Z80-PGZN-plus 300-1	0302117	
AS-APS-Z80-PGZN-plus 300-2	0302118	
Analog position sensor		
APS-Z80-K	0302072	
APS-Z80-M8	0302070	•

When using an APS system, one mounting kit (AS-APS-Z80) and one APS-Z80 sensor is required per gripper. The resolution of the sensor can be lower in the peripheral areas of the gripper. You can find further information on the product in the operating manual.

Universal gripper

APS-M1 analog position sensor



 (90)
 APS-M1S sensor
 (92)
 APS-K extension cable

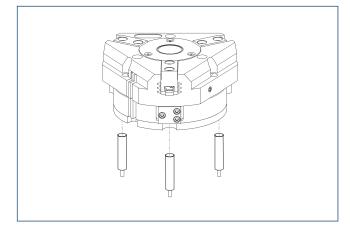
 (91)
 APS-M1E electronic processor
 (92)
 (93)
 (93)
 (94)

Analog multi position monitoring for any desired positions

Description	ID
Mounting kit for APS-M1	
AS-APS-M1-PGZN-plus 300-1	0302088
AS-APS-M1-PGZN-plus 300-2	0302089
Analog position sensor	
APS-M1S	0302062
Connection cables	
APS-K0200	0302066
APS-K0700	0302068
Evaluation electronics	
APS-M1E	0302064

When using an APS system, for each gripper an attachment kit (AS-APS-M1), an APS-M1S sensor (incl. 3 m cable) as well as an electronics (APS-M1e) are required. An extension cable (APS-K) can be connected between the sensor and the electronics as an option. The max. cable length between the sensor and the electronics is 10 m, between the electronics and their control unit (PLC) it is max. 1 m.

Cylindrical reed switches



End position monitoring can be mounted with an attachment kit.

Description	ID
Attachment kit for proximity switch	
AS-RMS 80 PGN/PZN-plus 160-380	0377727
Reed Switches	
RMS 80-S-M8	0377721

Two sensors (closer/S) are required for each unit and extension cables are available as an option. This attachment kit needs to be ordered optionally as an accessory. Two mounting kits are required for each gripper. For sensor cables, note the minimum permissible bending radii. These are generally 35 mm.





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