



Superior Clamping and Gripping

Product Information

Angular gripper SGW 50

Light. Fast. Flexible.

Gripper for small components SGW

Small, simple pressurized plastic angular gripper with spring return

Field of application

Universal application in clean and slightly dirty environments, with special requirements on corrosion resistance and anti-static properties of the gripping unit

Advantages – Your benefits

Housing made of plastic Making the gripper extremely light and free from corrosion

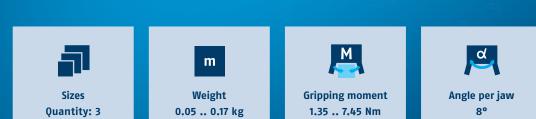
One-way acting 3-fold piston with lever gear for high power transmission and synchronized gripping

Spring-loaded pressure piece for optional pressing and separating of workpieces

favorable in price especially suitable for low-budget applications



2)Ø3.4 (6x)─∕ |





Functional description

The horizontally arranged pistons are pressed away from each other by compressed air.

The base jaws are opened at an angle and in a synchronized fashion by the bearing-mounted lever mechanism. Reset is done by compression spring.



① Base Jaw

for the connection of workpiece-specific gripper fingers

② Lever mechanism

for precise and synchronized gripping

③ Drive

single-acting double piston system with spring return

(4) Housing

weight-optimized due to the use of plastics

General notes about the series

Operating principle: one-way acting 3-fold piston with lever gear and spring reset

Housing material: Plastic with metal functional components

Base jaw material: Plastic

Actuation: pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

Warranty: 24 months

Scope of delivery: Centering pins, 0-rings for direct connection, assembly instructions (operating manual with declaration of incorporation is available online)

Gripping force maintenance device: not possible

Closing moment: is the arithmetic sum of the individual moment applied to each jaw.

Finger length: is measured from the reference surface as the distance P in direction to the main axis.

Repeat accuracy: is defined as a distribution of the end Position for 100 consecutive strokes.

Workpiece weight: is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.

Application example

Robot handling with gripper unit for loading and unloading of round plastic sleeves, are weight-optimized due to the use of plastic components.

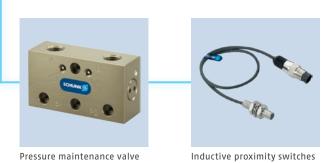
1 3-finger angular gripper SGW



SCHUNK offers more ...

The following components make the product even more productive - the suitable addition for the highest functionality, flexibility, reliability, and controlled production.





① For more information on these products can be found on the following product pages or at schunk.com.

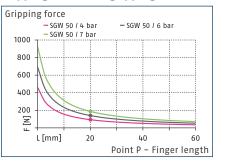
Options and special information

Due to the use of plastics, this gripper is characterized by a low weight.

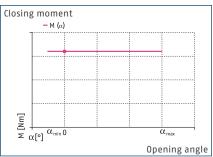




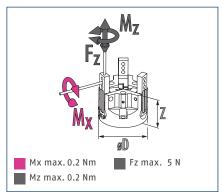
Gripping force O.D. gripping



Closing moment curve



Dimensions and maximum loads



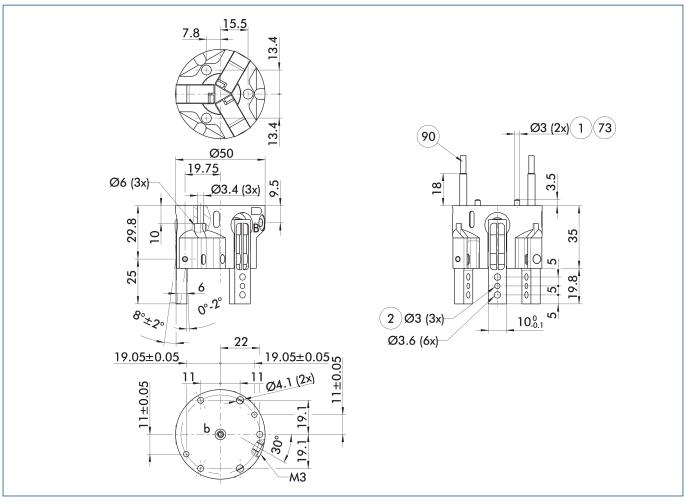
The indicated torques and forces are static values, apply for each base jaw, and may occur simultaneously.

Technical data

Description		SGW 50
ID		0305205
Opening angle per jaw	[°]	8
Closed angle per jaw up to	[°]	2
Closing moment	[Nm]	3.55
Weight	[kg]	0.09
Recommended workpiece weight	[kg]	0.6
Fluid consumption double stroke	[cm ³]	1
Min./nom./max. operating pressure	[bar]	4/6/7
Closing/opening time	[s]	0.02/0.03
Max. permissible finger length	[mm]	40
Max. permissible mass per finger	[kg]	0.05
IP protection class		20
Min./max. ambient temperature	[°C]	5/90
Repeat accuracy	[mm]	0.1
Dimensions Ø D x Z	[mm]	50 x 35

SGW 50 Angular gripper

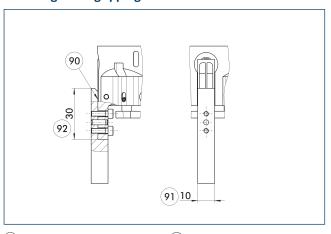
Main view



The drawing shows the gripper in the basic version with closed jaws, without dimensional consideration of the options described below.

- The SDV-P pressure maintenance valve can be used as a gripping force maintenance device (see catalog section on accessories).
- B, b Main / direct connection, gripper closing
- \bigcirc 1 Gripper connection
- Finger connection
 Fit for centering pins
 Sensor IN ...

Jaw design 0.D. gripping

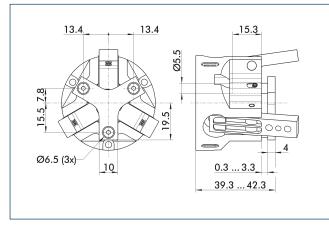


90 Support of the top jaws at the base jaw

(91) Maximum finger width(92) Maximum supporting length

Angular gripper

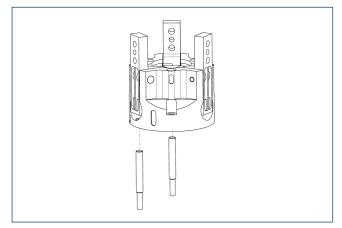
Spring-loaded pressure piece



For spring-supported positioning of the workpiece against a stop after the gripper has opened. Especially developed for loading machines.

Description	ID	Stroke	Min. force	
		[mm]	[N]	
Spring-loaded pressure piece				
A-SGW 50	0305208	3	12	

Inductive Proximity Switches



(17) Cable outlet

(91) Sensor IN..-SA

\sim				
90	Sensor	IN	•••	

Directly mounted end position monitoring.

Description	ID	Often combined					
Inductive proximity switches							
IN 40-S-M12	0301574						
IN 40-S-M8	0301474	•					
INK 40-S	0301555						
Inductive proximity switch with lateral cable outlet							
IN 40-S-M12-SA	0301577						
IN 40-S-M8-SA	0301473	•					
INK 40-S-SA	0301565						
Connection cables							
KA BG08-L 3P-0300-PNP	0301622	•					
KA BG08-L 3P-0500-PNP	0301623						
KA BG12-L 3P-0500-PNP	30016369						
KA BW08-L 3P-0300-PNP	0301594						
KA BW08-L 3P-0500-PNP	0301502						
KA BW12-L 3P-0300-PNP	0301503						
KA BW12-L 3P-0500-PNP	0301507						
clip for plug/socket							
CLI-M12	0301464						
CLI-M8	0301463						
Cable extension							
KV BG12-SG12 3P-0030-PNP	0301999						
KV BG12-SG12 3P-0060-PNP	0301998						
KV BW08-SG08 3P-0030-PNP	0301495						
KV BW08-SG08 3P-0100-PNP	0301496						
KV BW08-SG08 3P-0200-PNP	0301497	•					
KV BW12-SG12 3P-0030-PNP	0301595						
KV BW12-SG12 3P-0100-PNP	0301596						
KV BW12-SG12 3P-0200-PNP	0301597						
Sensor distributor							
V2-M12	0301776	•					
V2-M8	0301775	•					
V4-M8	0301746						
V8-M8	0301751						

 Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.



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