

Superior Clamping and Gripping



# **Product Information**

Angular gripper PWG-plus 125

# Reliable. Robust. Compact. Universal gripper PWG-plus

Robust 2-finger angular gripper with oval piston and bone drive

## Field of application

For universal use in clean and slightly dirty environments.

## **Advantages - Your benefits**

**Variable top jaw design** since grippers are available in jaw version, but also in finger version via intermediate jaws

**Gripping force maintenance device** for a high process reliability

**Stroke limitation while opening** optional available for confined spaces and short cycle times

Can be used in tough environments due to the gripper's sturdy set-up













# **Functional description**

The kinematics transforms this vertical motion into a synchronous and rotatory gripping motion of the base jaws.



- ① Base Jaw for the connection of workpiece-specific gripper fingers
- ② **Housing**is weight-optimized due to the use of high-strength aluminum alloy
- ③ Drive pneumatic oval piston for maximum driving force
- Lever mechanism for precise and synchronized gripping

#### General notes about the series

Operating principle: force-guided lever gear

Housing material: Aluminum

**Base jaw material:** hard-anodized, high strength aluminum

**Actuation:** pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

Warranty: 24 months

**Scope of delivery:** Centering elements, 0-rings for direct connection, fixed throttle (for sizes 50-200), assembly instructions (operating manual with declaration of incorporation is available online)

**Gripping force maintenance device:** possible by using the version with mechanical gripping force maintenance or pressure maintenance valve SDV-P

**Closing moment:** is the arithmetic sum of the individual moment applied to each jaw.

The indicated closing moment will be reached at an opening angle of 0°. A detailed closing moment course depending on the opening angle can be taken out of the diagram "closing moment course".

**Finger length:** is measured from the reference surface as the distance P in direction to the main axis.

**Repeat accuracy:** is defined as a distribution of the end Position for 100 consecutive strokes.

**Workpiece weight:** is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

**Closing and opening times:** are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.



## **Application example**

Cross gantry for light to mediumweight components.

- 1 Line gantry LPP, pneumatic
- 2 2-finger angular gripper PWG-plus

#### SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.



① For more information on these products can be found on the following product pages or at schunk.com.

## Options and special information

**Gripping force maintenance version AS/IS:** The mechanical gripping force maintenance version ensures minimum gripping force even in the event of a pressure drop. In the AS/S version this acts as a closing force, in the IS version as an opening force

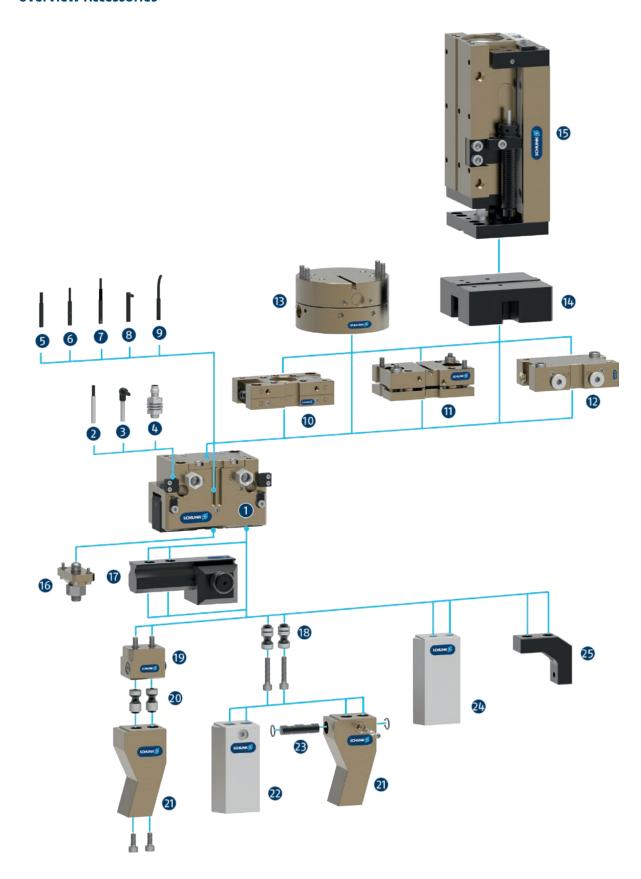
High-temperature version V/HT: for use in hot environments

Power booster version KVZ: if higher gripping forces are required

**Additional versions:** Various options can be combined with each other. Numerous additional options are also available – just tell us what your task is!

# **SCHUNK gripper PWG-plus**

#### **Overview Accessories**



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PWG-plus

Universal 2-finger angular gripper with a high gripping force

#### Sensor system

2 IN ...

Inductive proximity switch with molded cable and straight cable outlet

IN ...-SA

Inductive proximity switch with molded cable and laberal cable outlet

4 IN-C 80

Inductive proximity switch, directly pluggable

MMS 22

Magnetic switch with straight cable outlet for monitoring a position

MMS 22-PI1

Magnetic switch with straight cable outlet for monitoring a freely programmable position

6 MMS 22-PI2

Magnetic switch with straight cable outlet for monitoring two freely programmable position  $% \left\{ 1,2,\ldots,n\right\}$ 

7 MMS 22-PI1-HD

MMS 22-PI1 in robust design

MMS 22-PI2-HD

MMS 22-PI2 in robust design

**8** MMS 22-SA

Magnetic switch with lateral cable outlet for monitoring a position

MMS 22-PI1-SA

Magnetic switch with side cable outlet for monitoring a freely programmable position

MMS-P

Magnetic switch with straight cable outlet for monitoring two freely programmable position

#### **Complementary products**

SDV-P-E-P

Pressure maintenance valve for temporary force and position maintenance

B AGE

Compensation unit for compensation of large tolerances along the X and Y axes

ASG

Adapter plate for combining various automation components in the modular system

CLM

Linear module with pneumatic drive and scope-free pre-loaded junction rollers

16 HVE

Sleeve for protection against dirt

#### **Finger Accessories**

**1** UZB

The universal intermediate jaw allows fast tool-free and reliable plugging and shifting of top jaws at the gripper.

BSWS-AR

Adapter coupling of jaw quick-change system for fast, manual change of top jaws

BSWS-B

Locking mechanism of the jaw quick-change system for fast, manual exchange of top jaws

BSWS-A

Adapter coupling of the jaw quick-change system for adaptation to the customized finger

Customized fingers

BSWS-ABR

Finger blank made of aluminum with interface to the jaw quick-change system

**BSWS-SBR** 

Finger blank made of steel with interface to the jaw quick-change system

BSWS-UR

Locking mechanism for the integration of the jaw quick-change system into customized fingers

ABR/SBR

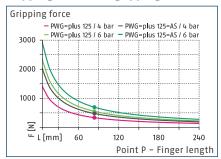
Finger blanks made of steel or aluminum with standardized screw connection diagram

**₯** ZBA

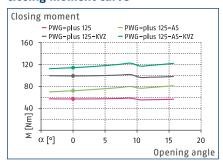
Intermediate jaws for reorientation of the mounting surface



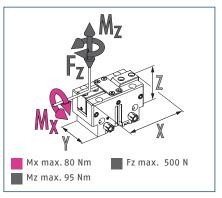
#### Gripping force O.D. gripping



#### **Closing moment curve**



#### **Dimensions and maximum loads**

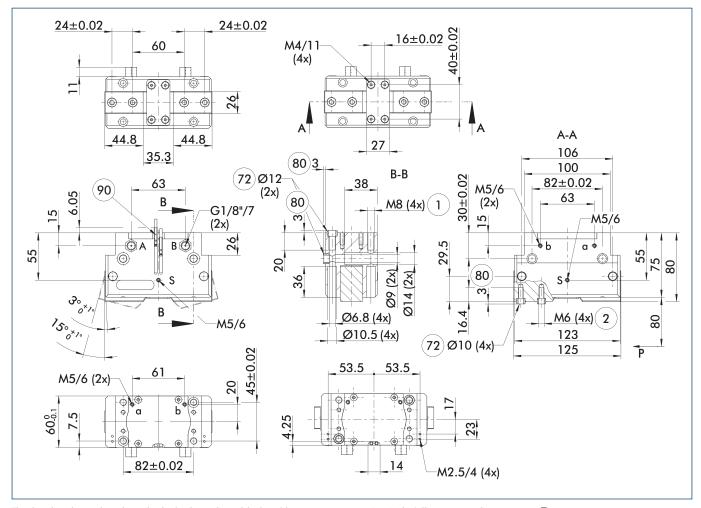


The indicated torques and forces are static values, apply for each base jaw, and may occur simultaneously.

#### Technical data

Description		PWG-plus 125	PWG-plus 125-AS
ID		0311650	0311651
Opening angle per jaw	[°]	15	15
Closed angle per jaw	[°]	3	3
Closing moment	[Nm]	57	72
Closing moment generated by spring	[Nm]		15
Weight	[kg]	1.35	1.85
Recommended workpiece weight	[kg]	2.78	2.78
Fluid consumption double stroke	[cm³]	75.5	107
Min./nom./max. operating pressure	[bar]	2/6/8	4/6/6.5
Min./max. air purge pressure	[bar]	0.5/1	0.5/1
Closing/opening time	[s]	0.14/0.14	0.12/0.2
Max. permissible finger length	[mm]	160	160
Max. permissible mass moment of inertia per chuck jaw	[kgcm²]	203.9	203.9
IP protection class		30	30
Min./max. ambient temperature	[°C]	5/90	5/90
Repeat accuracy	[mm]	0.02	0.02
Dimensions X x Y x Z	[mm]	125 x 60 x 80	125 x 60 x 110
Options and their characteristics			
High-temperature version		39311650	39311651
Min./max. ambient temperature	[°C]	5/130	5/130
Power booster version		0311655	0311656
Closing moment	[Nm]	99	114
Closing moment generated by spring	[Nm]		15
Weight	[kg]	1.85	2.3
Maximum pressure	[bar]	6	6
Max. permissible finger length	[mm]	160	160

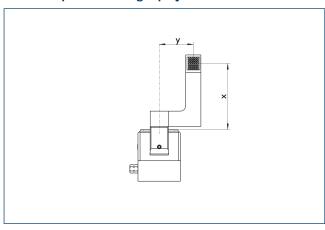
#### Main view

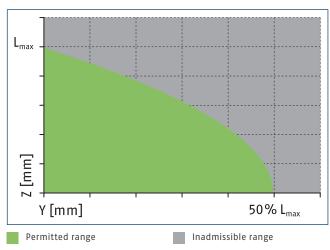


The drawing shows the gripper in the basic version with closed jaws, without dimensional consideration of the options described below.

- ① The SDV-P pressure maintenance valve can also be used for I.D. or 0.D. gripping alternatively or in addition to the spring-loaded, mechanical gripping force maintenance device (see catalog section on accessories).
- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- S Air purge connection
- (1) Gripper connection
- 2 Finger connection
- (72) Fit for centering sleeves
- 80 Depth of the centering sleeve hole in the counter part
- 90 Sensor MMS 22..

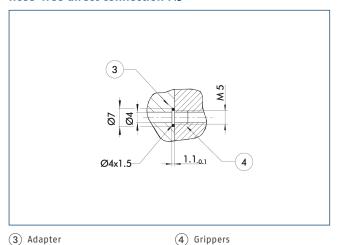
#### Maximum permitted finger projection





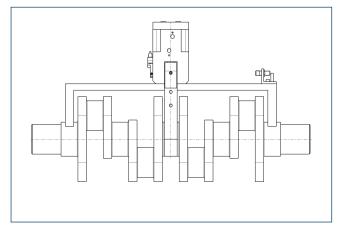
Lmax is equivalent to the maximum permitted finger length, see the technical data table.

#### Hose-free direct connection M5



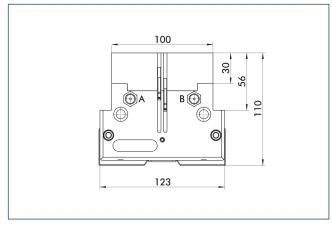
The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting

#### **Shaft support**



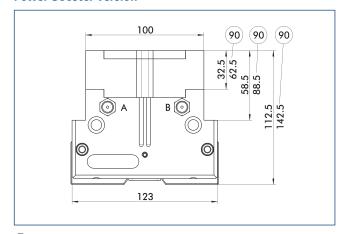
The complete assembly group for handling of cranks and cam shafts can be supplied on request.

#### Gripping force maintenance device



The mechanical gripping force maintenance ensures that a minimum clamping force will be applied even in case of pressure drop. This acts as closing force in the AS version. Besides this, the gripping force maintenance can be used to increase gripping force or for single actuated gripping.

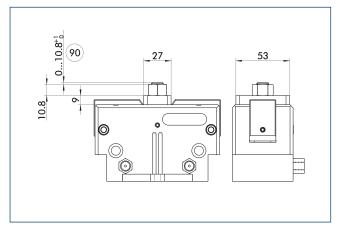
#### **Power booster version**



90 Applies to AS version

The KVZ cylinder increases the gripping forces during opening and closing. A second, in series-connected piston also increases the force on the wedge hook. Please consider that grippers which are equipped with a gripping force maintenance device are higher.

#### Attachment kit for opening angle limitation

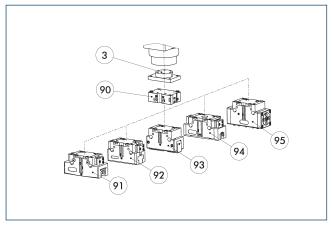


90 Max. adjustment travel

Stepless adjustment of the opening angle is possible with an attachment kit

Description	ID
Stroke adjustment	
HVF-DWG-nlus 125	0311753

#### SDV-P E-P pressure maintenance valve

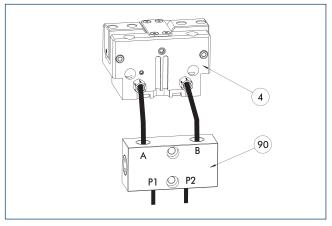


- 3 Adapter
- 90 SDV-P E-P pressure maintenance valve
- (91) PGN-plus / PGN-plus-P 2-finger parallel gripper
- (92) JGP 2-finger parallel grippers
- 2-finger angular gripper PWG-plus
- **94** 2-finger parallel gripper PGB
- 95) Sealed DPG-plus gripper

The SDV-P E-P pressure maintenance valves ensure that the pressure in the piston chamber is maintained temporarily during an emergency stop. SDV-P E-P can be directly connected to the listed grippers without the need for additional pneumatic hoses.

Description	ID	
Pressure maintena	nce valve	
SDV-P 125-E-P	0300127	

#### SDV-P pressure maintenance valve



4 Grippers

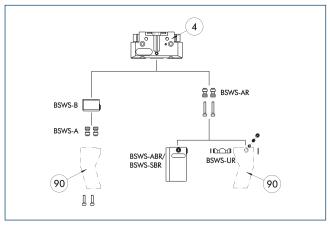
90 SDV-P pressure maintenance

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter	
		[mm]	
Pressure maintenance valve			
SDV-P 04	0403130	6	
Pressure maintenance valve with air bleed screw			
SDV-P 04-E	0300120	6	

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

#### BSWS jaw quick-change jaw systems



4 Grippers

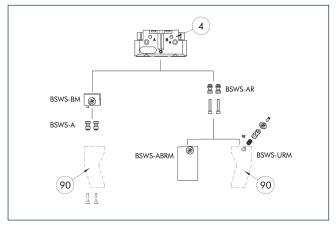
**90** Customized gripper fingers

There are various jaw quick-change systems available for the gripper. For detailed information, please refer to the corresponding product.

Description	ID	Scope of delivery				
Jaw quick-change system adap	ter pin					
BSWS-A 125	0303028	2				
BSWS-AR 125	0300095	2				
Quick-change jaw system base						
BSWS-B 125	0303029	1				
Jaw quick-change system finge	Jaw quick-change system finger blank					
BSWS-ABR-PGZN-plus 125	0300075	1				
BSWS-SBR-PGZN-plus 125	0300085	1				
Jaw quick-change system locking mechanism						
BSWS-UR 125	0302994	1				

① Only systems that are listed in the table, can be used.

#### Jaw quick-change system BSWS-M



(4) Grippers

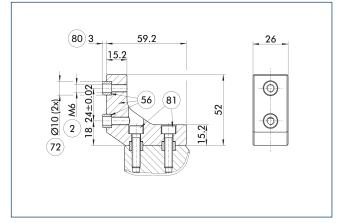
90 Customized gripper fingers

There are various jaw quick-change systems available for the gripper. For detailed information, please refer to the corresponding product.

Description	ID	Scope of delivery				
Jaw quick-change system adapte	Jaw quick-change system adapter pin					
BSWS-A 125	0303028	2				
BSWS-AR 125	0300095	2				
Quick-change jaw system base						
BSWS-BM 125	1302006	1				
Jaw quick-change system finger blank						
BSWS-ABRM-PGZN-plus 125	1420854	1				
Jaw quick-change system locking mechanism						
BSWS-URM 125	1398404	1				

① Only systems that are listed in the table, can be used.

#### ZBA-L-plus 125 intermediate jaws

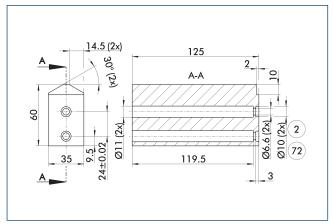


- (2) Finger connection
- (56) Included in the scope of delivery
- 72) Fit for centering sleeves
- 80 Depth of the centering sleeve hole in the counter part
- (81) Not included in the scope of delivery

The optional ZBA-L-plus intermediate jaws allow the screw connection diagram of the top jaws to be rotated by 90°. This makes it easier to design and produce top jaws (particularly for long versions) because no deep through-bores are required.

Description	ID	Material	Finger interface	Scope of delivery
Intermediate jaw				
ZBA-L-plus 125	0311752	Aluminum	PGN-plus	1

#### Finger blanks ABR- / SBR-PGZN-plus 125



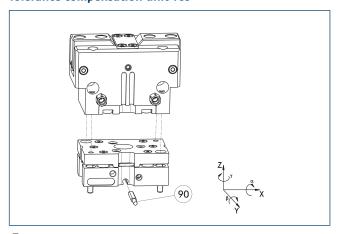
(2) Finger connection

72) Fit for centering sleeves

The drawing shows the finger blank which can be reworked by the customer.

Description	ID	Material	Scope of delivery
Finger blank			
ABR-PGZN-plus 125	0300013	Aluminum	1
SBR-PGZN-plus 125	0300023	Steel	1

#### Tolerance compensation unit TCU

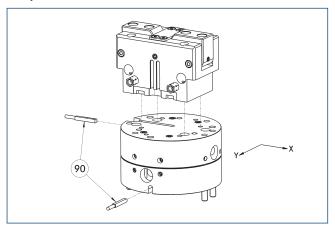


90 Monitoring of locking

Grippers can be directly mounted without an adapter plate. Tolerance compensation unit and gripper have an identical screw connection diagram. Therefore the tolerance compensation units can be assembled later. Please consider the additional assembly height of the tolerance compensation unit. For details please refer to our catalog robot

Description	ID	Locking	Deflection	Often combined
Compensation unit				
TCU-P-125-3-MV	0324828	yes	±1°/±1,5°/±1,5°	•
TCU-P-125-3-0V	0324829	no	±1°/±1,5°/±1,5°	

#### Compensation unit AGE-F

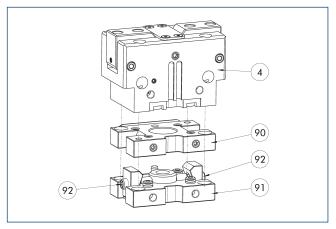


#### 90 Monitoring

Grippers can be directly mounted without an adapter plate. For details see our catalog Gripping or Robot Accessories.

Description	ID	Compensation XY	Reset force	Often combined
		[mm]	[N]	
Compensation unit				
AGE-F-XY-080-1	0324960	± 5	39	
AGE-F-XY-080-2	0324961	± 5	85	
AGE-F-XY-080-3	0324962	± 5	90	•

#### **Compact change system for grippers**

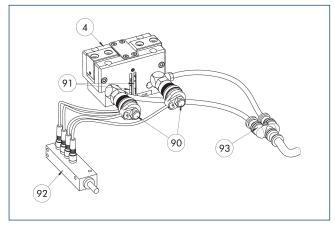


- 4 Grippers
- (91) CWK compact change master
- 90 CWA compact change adapter
- 92 Locking mechanism

Grippers can be directly mounted without an adapter plate. For details see our catalog Gripping or Robot Accessories.

Description	ID
CWA compact change adapter	
CWA-125-P	0305826
CWK compact change master	
CWK-125-P	0305825

#### **Attachment valves**



- 4 Grippers
- 90 Micro valves
- (91) Sensor

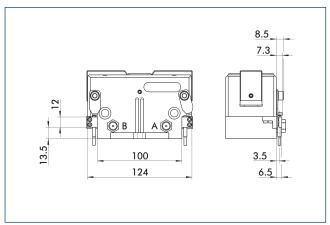
- 92 Sensor distributor
- 93 Y distributor

The set of attachment valves reduces the compressed air consumption as there is no need to ventilate or bleed the supply lines. This can also reduce cycle time. The hose-free direct assembly of the micro valves reduces the hosing effort for the gripper. To further simplify electrical connection of the valves and sensors, their signals can be bundled via an optional distributor.

Description	ID	Often combined
Attachment valve		
ABV-MV30-G1/8	0303328	
ABV-MV30-G1/8-V2-M8	0303396	
ABV-MV30-G1/8-V4-M8	0303366	•
ABV-MV30-G1/8-V8-M8	0303367	

① A set of attachment valves ABV is required per actuator. The ABV set contains two 3/2 micro valves, an Y-distributor for compressed air supply and optionally a sensor distributor with two, four or eight inputs or outputs. Sensors for monitoring the gripper need to be ordered separately. Pneumatic hoses are not included in the scope of delivery.

#### Attachment kit for proximity switch IN 40

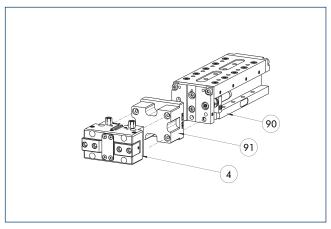


End position monitoring can be mounted with an attachment kit.

Description	ID				
Attachment kit for proximity	switch				
AS-IN40-PWG-plus 125	0311750				

① This attachment kit needs to be ordered optionally as an accessory.

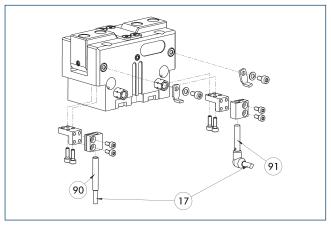
#### **Modular Assembly Automation**



- (4) Grippers
- 91) ASG adapter plate
- 90 CLM/KLM/LM/ELP/ELM/ELS/HLM linear modules

Grippers and linear modules can be combined with standard adapter plates from the modular assembly system. For more information see our main catalog "Modular Assembly Automation".

#### IN 40 inductive proximity switches



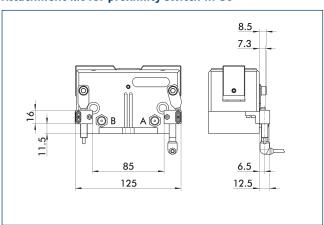
- (17) Cable outlet
- 91) Sensor IN..-SA
- 90 Sensor IN ...

End position monitoring can be mounted with an attachment kit.

Description	ID	Often combined
Attachment kit for proximity	y switch	
AS-IN40-PWG-plus 125	0311750	
Inductive proximity switche	S	
IN 40-S-M12	0301574	
IN 40-S-M8	0301474	•
INK 40-S	0301555	
Inductive proximity switch	with lateral ca	ble outlet
IN 40-S-M12-SA	0301577	
IN 40-S-M8-SA	0301473	•
INK 40-S-SA	0301565	

Two sensors (closer/S) are required for each unit and extension cables are available as an option. This attachment kit needs to be ordered optionally as an accessory. For sensor cables, note the minimum permissible bending radii. These are generally 35 mm.

#### Attachment kit for proximity switch IN 80

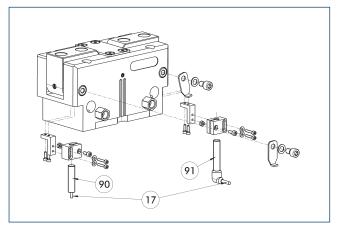


 $\ensuremath{\mathsf{End}}$  position monitoring can be mounted with an attachment kit.

Description	ID
Attachment kit for proximity	switch
AS-IN80-PWG-plus 125	0311751

① This attachment kit needs to be ordered optionally as an accessory.

#### IN 80 inductive proximity switches



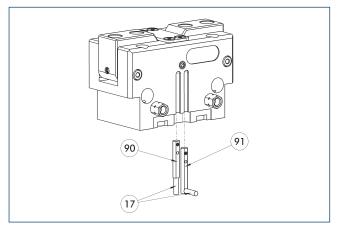
- (17) Cable outlet
- 91) Sensor IN..-SA
- 90 Sensor IN ...

End position monitoring can be mounted with an attachment kit.

Description	ID	Often combined
Attachment kit for proximity	switch	
AS-IN80-PWG-plus 125	0311751	
Inductive proximity switches		
IN 80-S-M12	0301578	
IN 80-S-M8	0301478	•
IN-C 80-S-M8-PNP	0301475	
INK 80-S	0301550	
INK 80-SL	0301579	
Inductive proximity switch w	ith lateral cal	ole outlet
IN 80-S-M12-SA	0301587	
IN 80-S-M8-SA	0301483	•
INK 80-S-SA	0301566	

Two sensors (closer/S) are required for each unit and extension cables are available as an option. This attachment kit needs to be ordered optionally as an accessory. For sensor cables, note the minimum permissible bending radii. These are generally 35 mm.

#### **Electronic magnetic switch MMS**



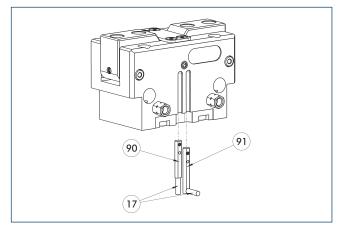
- (17) Cable outlet
- 91) Sensor MMS 22...-SA
- 90 Sensor MMS 22..

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	•
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with	lateral cable (	outlet
MMS 22-S-M8-PNP-SA	0301042	•
MMSK 22-S-PNP-SA	0301044	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
clip for plug/socket		
CLI-M8	0301463	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
Sensor distributor		
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available.
Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

#### Programmable magnetic switch MMS 22-PI1



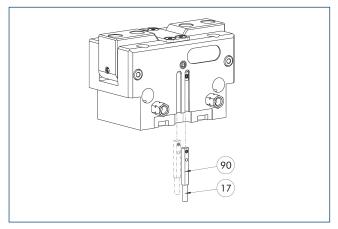
- (17) Cable outlet
- **91** Sensor MMS 22 ..-PI1-...-SA
- 90 Sensor MMS 22 PI1-...

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

		· ·
Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI1-S-M8-PNP	0301160	•
MMSK 22-PI1-S-PNP	0301162	
Programmable magnetic switch	with lateral c	able outlet
MMS 22-PI1-S-M8-PNP-SA	0301166	•
MMSK 22-PI1-S-PNP-SA	0301168	
Programmable magnetic switch	with stainles	s steel housing
MMS 22-PI1-S-M8-PNP-HD	0301110	•
MMSK 22-PI1-S-PNP-HD	0301112	

Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

#### Programmable magnetic switch MMS 22-PI2



(17) Cable outlet

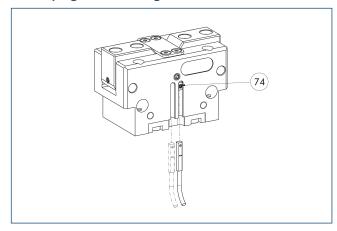
90 MMS 22...-PI2-... sensor

Position monitoring with two programmable positions per sensor and electronics built into the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch	i	
MMS 22-PI2-S-M8-PNP	0301180	•
MMSK 22-PI2-S-PNP	0301182	
Programmable magnetic switch	with lateral c	able outlet
MMS 22-PI2-S-M8-PNP-SA	0301186	•
MMSK 22-PI2-S-PNP-SA	0301188	
Programmable magnetic switch	with stainles	s steel housing
MMS 22-PI2-S-M8-PNP-HD	0301130	•
MMSK 22-PI2-S-PNP-HD	0301132	

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

#### MMS-P programmable magnetic switch



(74) Limit stop for sensor

Position monitoring with two programmable positions per sensor. End position monitoring for mounting in the C-slot.

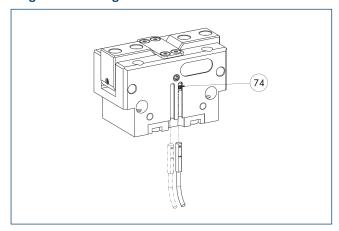
Description	ID	Often combined
Programmable magnetic	switch	
MMSK-P 22-S-PNP	0301371	
MMS-P 22-S-M8-PNP	0301370	•
Connection cables		
KA BG08-L 4P-0500	0307767	•
KA BG08-L 4P-1000	0307768	
KA BW08-L 4P-0500	0307765	
KA BW08-L 4P-1000	0307766	
clip for plug/socket		
CLI-M8	0301463	
Sensor distributor		
V2-M8-4P-2XM8-3P	0301380	

① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

# PWG-plus 125

Angular gripper

#### Programmable magnetic switch MMS-IO-Link



#### 74 Limit stop for sensor

Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. Sensor programming on the gripper takes place via the IO-Link interface or the MT magnetic teach tool (included in scope of delivery). An IO-Link master is required for operation.

Description	ID
Programmable mag	netic switch
MMS 22-I0L-M08	0315830
MMS 22-I0L-M12	0315835

① One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.

Angular gripper



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