

Superior Clamping and Gripping



Product Information

Angular gripper SWG 12

Slim. Reliable. Fast. Gripper for small components SWG

Narrow double-acting 2-finger angular gripper

Field of application

For universal use in clean and slightly dirty environments. Suitable for applications which require a space-optimized gripper Arrangement.

Advantages – Your benefits

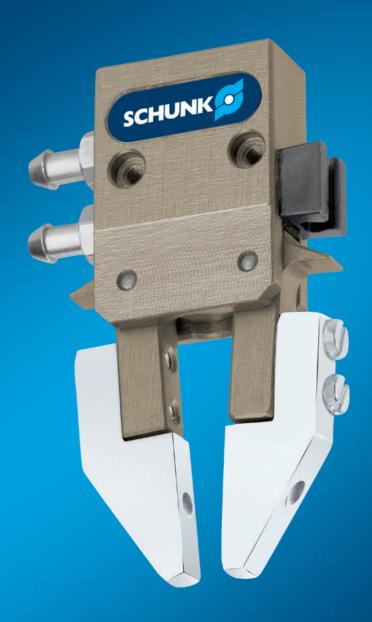
Slim design allowing the grippers to be arranged in a row

Spring-supported gripping force maintenance holds the workpiece even in case of a loss of pressure

Wedge-hook design for high power transmission and synchronized gripping

Light and compact design for space-saving handling without interfering contours

Monitoring via electronic magnetic switches a spacesaving feature in a slot in the housing













Functional description

The piston is moved up and down by compressed air. The kinematics transforms this vertical motion into a synchronous and rotatory gripping motion of the base jaws.



- Housing
 is weight-optimized due to the use of high-strength
 aluminum alloy
- ② Base fingers for the connection of workpiece-specific gripper fingers
- ③ Kinematics precise gear for centric gripping
- Sensor system electronic magnetic switch, space-saving integration in the groove of the housing
- (5) **Gripping force maintenance device** mechanic gripping force maintenance for 0.D. gripping

General notes about the series

Operating principle: double-acting, guided kinematics

Housing material: Aluminum alloy, anodized

Base jaw material: Aluminum alloy, anodized

Actuation: pneumatic, with filtered compressed air as per

ISO 8573-1:2010 [7:4:4].

Warranty: 24 months

Scope of delivery: Centering sleeves, assembly instructions (operating manual with declaration of incorporation is

available online)

Gripping force maintenance device: always integrated by using springs, and also possible via pressure maintenance valve SDV-P

Closing moment: is the arithmetic sum of the individual moment applied to each jaw.

Finger length: is measured from the reference surface as the distance P in direction to the main axis.

Repeat accuracy: is defined as a distribution of the end Position for 100 consecutive strokes.

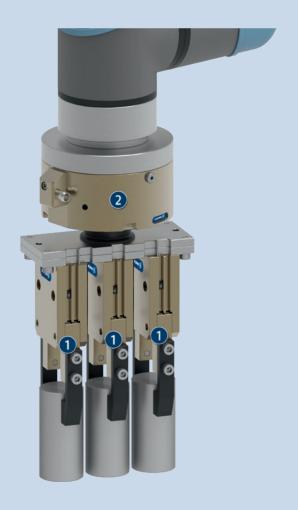
Workpiece weight: is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.

Application example

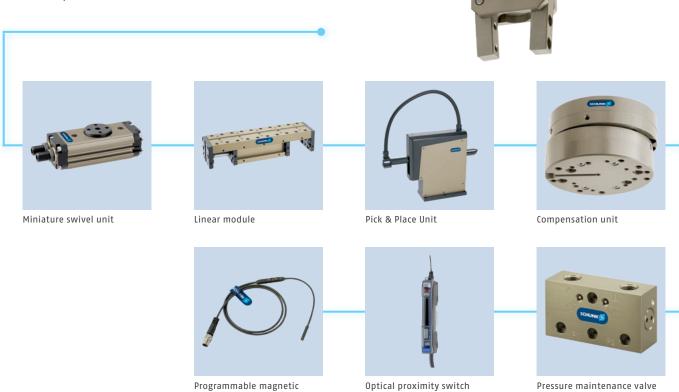
Triple transfer unit for packaging with small boxboards

- 1 2-finger angular gripper SWG
- 2 Collision sensor OPR



SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.



① For more information on these products can be found on the following product pages or at schunk.com.

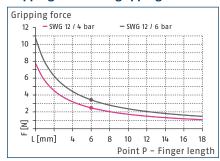
switch

Options and special information

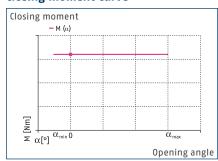
The angular gripper SWG can be directly mounted in a row to reduce interfering contours.



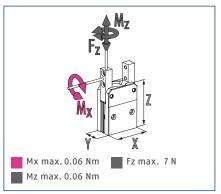
Gripping force O.D. gripping



Closing moment curve



Dimensions and maximum loads

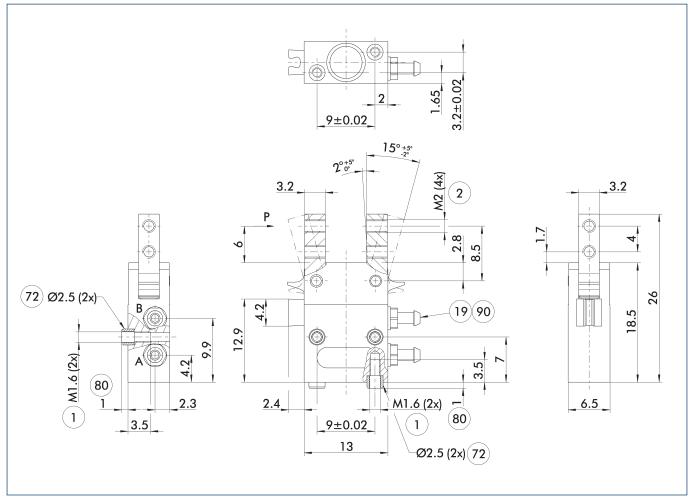


The indicated torques and forces are static values, apply for each base jaw, and may occur simultaneously.

Technical data

Description		SWG 12
ID		0305115
Opening angle per jaw	[°]	15
Closed angle per jaw up to	[°]	7
Closing moment	[Nm]	0.03
Closing moment generated by spring	[Nm]	0.009
Weight	[kg]	0.0048
Recommended workpiece weight	[kg]	0.017
Fluid consumption double stroke	[cm³]	0.07
Min./nom./max. operating pressure	[bar]	4/6/6.5
Closing/opening time	[s]	0.015/0.02
Max. permissible finger length	[mm]	12
Max. permissible mass per finger	[kg]	0.006
IP protection class		30
Min./max. ambient temperature	[°C]	5/90
Repeat accuracy	[mm]	0.05
Dimensions X x Y x Z	[mm]	13 x 6.5 x 18.5

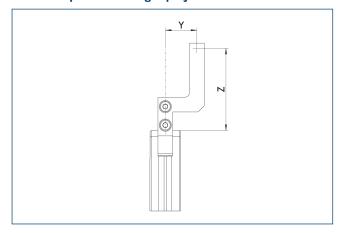
Main view

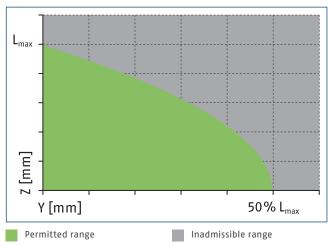


The drawing shows the gripper in the basic version with closed jaws, without dimensional consideration of the options described below.

- ① The SDV-P pressure maintenance valve can be used as a gripping force maintenance device (see catalog section on accessories).
- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- (1) Gripper connection
- (2) Finger connection
- (19) Air connection
- (72) Fit for centering sleeves
- 80 Depth of the centering sleeve hole in the counter part
- Bosch-Rexroth compressed air hose, TU1-S (Ø 3.0-0.6) series, Order no.: 1820712066 (-67/-68/-69)

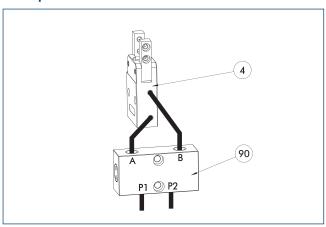
Maximum permitted finger projection





Lmax is equivalent to the maximum permitted finger length, see the technical data table.

SDV-P pressure maintenance valve



4 Grippers

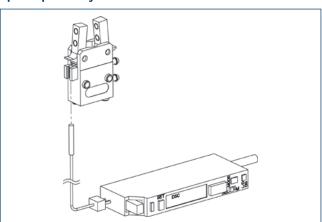
90 SDV-P pressure maintenance

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter
		[mm]
Pressure maintenance	e valve	
SDV-P 04	0403130	6
Pressure maintenance	e valve with a	ir bleed screw
SDV-P 04-E	0300120	6

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

Optical proximity switch



Description	ID		
Optical proximity switch			
ONS 01	0301390		
Optical wave guide			
ONS 01-LWL	0301391		

Per each unit a sensor (ONS 01) as well as an optical wave guide (ONS 01-LWL) are required. Assembly of the optical sensors at the gripper is done with the supplied plastic clip.



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