



Superior Clamping and Gripping

Product Information

4-finger centric gripper PZV 100

Loadable. Precise. Reliable. Centric gripper PZV

The multi-finger gripper for applications, in which two or three fingers are insufficient

Field of application

4-finger centric grippers have advantages over the usual centric grippers, for example when cylindrical workpieces are being stored in tablets. The PZV handles the workpieces in a controlled, process reliable manner despite the interfering contours.

Advantages – Your benefits

Robust multi-tooth guidance for precise handling

Wedge-hook design for high power transmission and synchronized gripping

Air supply via hose-free direct connection or screw connections for flexible pressure supply in all automated systems

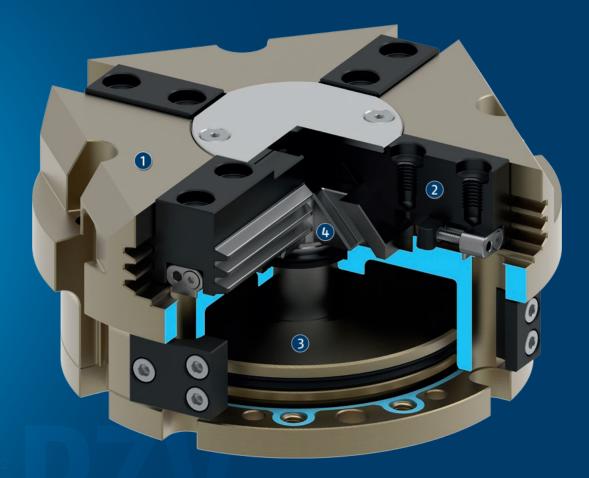
Comprehensive sensor accessory program for versatile querying possibilities and stroke position monitoring





Functional description

The piston is moved up and down by compressed air. The angled active surfaces of the wedge-hook produce a synchronized, centric jaw movement.



1 Housing

is weight-optimized due to the use of high-strength aluminum alloy

- ② Multi-tooth guidance for mounting high loads onto the base jaw
- ③ Drive through pneumatic double piston system
- Wedge-hook design for high force transmission and centric gripping

General notes about the series

Operating principle: Wedge-hook kinematics

Housing material: Aluminum alloy, anodized

Base jaw material: Steel

Actuation: pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

Warranty: 36 months

Scope of delivery: Brackets for proximity switches, centering sleeves, O-rings for direct connection, assembly instructions (operating manual with declaration of incorporation is available online)

Gripping force maintenance device: possible with pressure maintenance valve SDV-P

Gripping force: is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

Finger length: is measured from the reference surface as the distance P in direction to the main axis. The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

Repeat accuracy: is defined as a distribution of the end Position for 100 consecutive strokes.

Workpiece weight: is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.

Application example

Centering and rotation unit for the precise picking up, orientation, and subsequent joining of square materials

- Multi-finger gripper PZV
- 2 Collision sensor OPS
- **3** Rotary actuator SRU-plus
- O Universal linear module Beta



SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.





Inductive proximity switches



Finger blank

① For more information on these products can be found on the following product pages or at schunk.com.

Magnetic switches

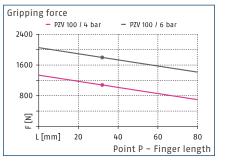
Options and special information

Intermediate sizes are available on request. Please note that the four-finger grip is an umbrella term, and may lead to a two or three-finger grip in certain cases.

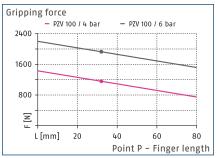
Pressure reduction in case of a two finger application of the PZV 160 and 200: The operating pressure must be reduced to a maximum of 5 bar when using the 4-finger centric gripper PZV 160 and 200 as a (double) 2-finger parallel gripper. Integrated air purge connection: impedes the ingress of dirt into the inside of the gripper



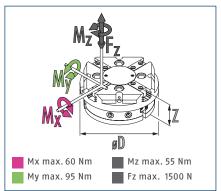
Gripping force O.D. gripping



Gripping force I.D. gripping



Dimensions and maximum loads



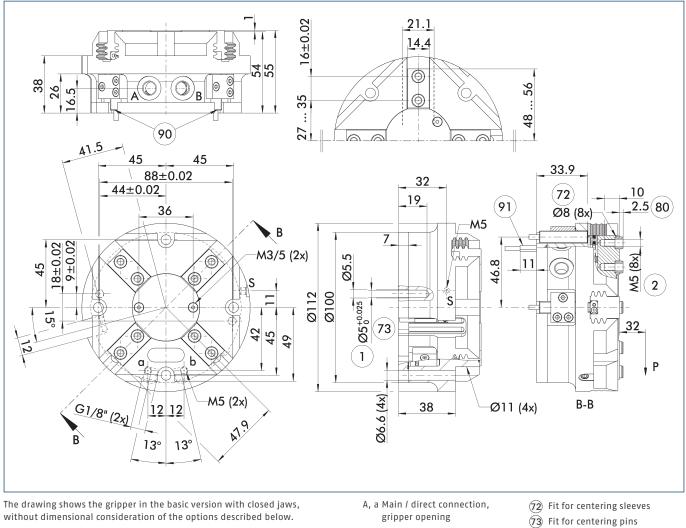
The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

Technical data

Description		PZV 100
ID		0304002
Stroke per jaw	[mm]	8
Closing/opening force	[N]	1800/1900
Weight	[kg]	1.6
Recommended workpiece weight	[kg]	9
Fluid consumption double stroke	[cm³]	120
Min./nom./max. operating pressure	[bar]	2/6/8
Min./max. air purge pressure	[bar]	0.5/1
Closing/opening time	[s]	0.04/0.04
Max. permissible finger length	[mm]	80
Max. permissible mass per finger	[kg]	0.6
IP protection class		40
Min./max. ambient temperature	[°C]	5/90
Repeat accuracy	[mm]	0.01
Dimensions Ø D x Z	[mm]	112 x 55

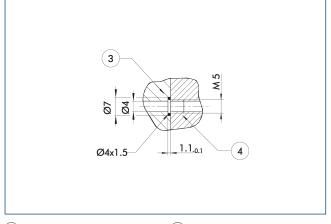
① It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

Main view



- () The SDV-P pressure maintenance valve can be used as a gripping force maintenance device (see catalog section on accessories).
- B, b Main / direct connection, gripper closing
- Air purge connection S
- (1) Gripper connection
- $(\mathbf{2})$ Finger connection
- (80) Depth of the centering sleeve hole in the counter part
- (90) Sensor IN ...
- (91) Sensor MMS 22..

Hose-free direct connection M5

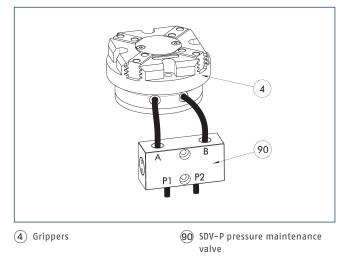


3 Adapter

(4) Grippers

The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

SDV-P pressure maintenance valve

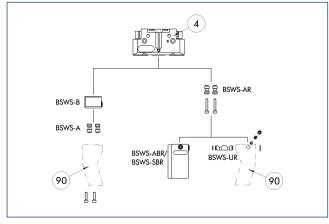


The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter		
		[mm]		
Pressure maintenance valve with air bleed screw				
SDV-P 10-E	0300109	10		

In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

BSWS jaw quick-change jaw systems



(4) Grippers

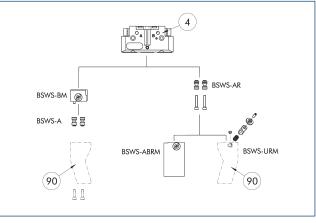
90 Customized gripper fingers

There are various jaw quick-change systems available for the gripper. For detailed information, please refer to the corresponding product.

Description	ID	Scope of delivery			
Jaw quick-change system ada	Jaw quick-change system adapter pin				
BSWS-A 80	0303024	2			
BSWS-AR 80	0300093	2			
Quick-change jaw system base					
BSWS-B 80	0303025	1			
Jaw quick-change system finger blank					
BSWS-ABR-PGZN-plus 80	0300073	1			
BSWS-SBR-PGZN-plus 80	0300083	1			
Jaw quick-change system locking mechanism					
BSWS-UR 80	0302992	1			

Only systems that are listed in the table, can be used.

Jaw quick-change system BSWS-M



(4) Grippers

90 Customized gripper fingers

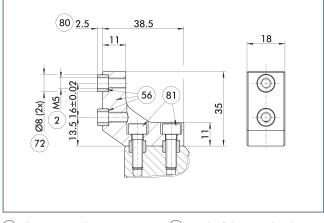
There are various jaw quick-change systems available for the gripper. For detailed information, please refer to the corresponding product.

ID	Scope of delivery				
Jaw quick-change system adapter pin					
0303024	2				
0300093	2				
Quick-change jaw system base					
1313901	1				
Jaw quick-change system finger blank					
1420852	1				
Jaw quick-change system locking mechanism					
1398402	1				
	ter pin 0303024 0300093 1313901 r blank 1420852 ng mechanism				

Only systems that are listed in the table, can be used.

4-finger centric gripper

ZBA-L-plus 80 intermediate jaws

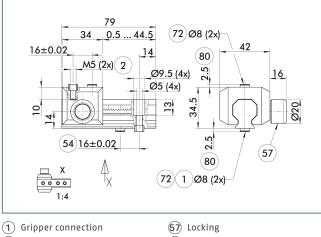


- $(\mathbf{2})$ Finger connection
- (80) Depth of the centering sleeve hole in the counter part
- (56) Included in the scope of delivery (72) Fit for centering sleeves
- (81) Not included in the scope of delivery

The optional ZBA-L-plus intermediate jaws allow the screw connection diagram of the top jaws to be rotated by 90°. This makes it easier to design and produce top jaws (particularly for long versions) because no deep through-bores are required.

Description	ID	Material	Finger interface	Scope of delivery
Intermediate jaw				
ZBA-L-plus 80	0311732	Aluminum	PGN-plus 80	1

UZB 80 universal intermediate jaw



- 2 Finger connection
- (54) Optional right or left

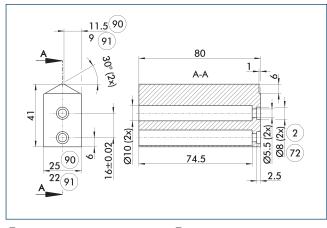
connection

- (72) Fit for centering sleeves
- (80) Depth of the centering sleeve hole in the counter part

The drawing shows the UZB universal intermediate jaw. The fully removable UZB-S slide (can also be ordered separately) allows for a quick jaw change.

Description	ID	Grid dimension	
		[mm]	
Universal intermediate	jaw		
UZB 80	0300043	2	
Finger blank			
ABR-PGZN-plus 80	0300011		
SBR-PGZN-plus 80	0300021		
Slide for universal intermediate jaw			
UZB-S 80	5518271	2	

Finger blanks ABR- / SBR-PGZN-plus 80



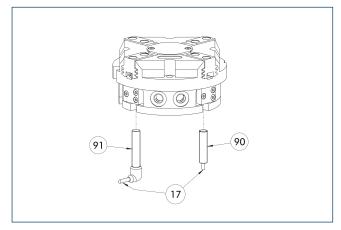
(2) Finger connection (72) Fit for centering sleeves

(90) ABR-PGZN-plus (91) SBR-PGZN-plus

The drawing shows the finger blank which can be reworked by the customer.

Description	ID	Material	Scope of delivery
Finger blank			
ABR-PGZN-plus 80	0300011	Aluminum	1
SBR-PGZN-plus 80	0300021	Steel	1

Inductive Proximity Switches



17 Cable outlet

91) Sensor IN..-SA

90 Sensor IN ...

Directly mounted end position monitoring.

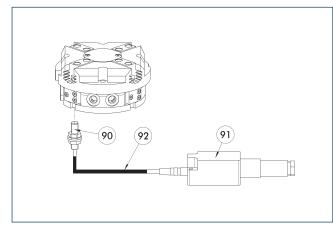
Description	ID	Often combined
Inductive proximity switches		
IN 80-S-M12	0301578	
IN 80-S-M8	0301478	•
INK 80-S	0301550	
Inductive proximity switch with la	teral cable ou	tlet
IN 80-S-M12-SA	0301587	
IN 80-S-M8-SA	0301483	•
INK 80-S-SA	0301566	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BG12-L 3P-0500-PNP	30016369	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
clip for plug/socket		
CLI-M12	0301464	
CLI-M8	0301463	
Cable extension		
KV BG12-SG12 3P-0030-PNP	0301999	
KV BG12-SG12 3P-0060-PNP	0301998	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	
Sensor distributor		
V2-M12	0301776	•
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

 Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

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4-finger centric gripper

Flexible position sensor



90 FPS-S sensor

(91) FPS-F5 evaluation electronic

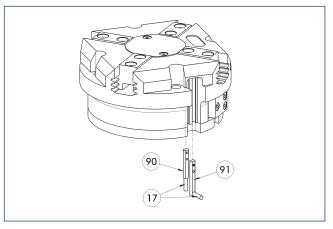
Flexible position monitoring of up to five positions.

Description	ID
Attachment kit for FPS	
AS-FPS-PGZN-plus 80-1/PZB 80/PZB 100	0301632
Sensor	
FPS-S M8	0301704
Evaluation electronics	
FPS-F5	0301805
Cable extension	
KV BG08-SG08 3P-0050	0301598
KV BG08-SG08 3P-0100	0301599

(92) Cable extension

When using an FPS system, an FPS sensor (FPS-S) as well as an electronic processor (FPS-F5 / F5 T) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are optionally available - see catalog chapter "Accessories."

Electronic magnetic switch MMS



17) Cable outlet

(91) Sensor MMS 22...-SA

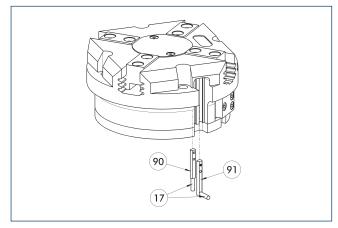
90 Sensor MMS 22..

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	•
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with	lateral cable of	outlet
MMS 22-S-M8-PNP-SA	0301042	•
MMSK 22-S-PNP-SA	0301044	
Reed Switches		
RMS 22-S-M8	0377720	•
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	•
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
clip for plug/socket		
CLI-M8	0301463	
Wireless sensor system		
RSS-T2	0377715	
RSS-T2-US/CA	0377717	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	•
Sensor distributor		
V2-M8	0301775	•
V4-M8	0301746	
V8-M8	0301751	

 Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Programmable magnetic switch MMS 22-PI1



17) Cable outlet

(91) Sensor MMS 22 ..- PI1-...-SA

90 Sensor MMS 22 PI1-...

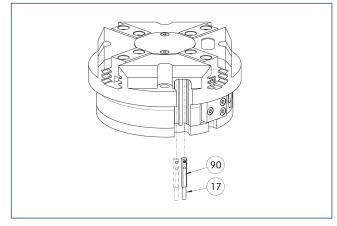
Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided,

teaching is only possible with the ST teaching tools.

0 91		8			
Description	ID	Often combined			
Programmable magnetic switch					
MMS 22-PI1-S-M8-PNP	0301160	•			
MMSK 22-PI1-S-PNP	0301162				
Programmable magnetic switch with lateral cable outlet					
MMS 22-PI1-S-M8-PNP-SA	0301166	•			
MMSK 22-PI1-S-PNP-SA	0301168				
Programmable magnetic switch with stainless steel housing					
MMS 22-PI1-S-M8-PNP-HD	0301110	•			
MMSK 22-PI1-S-PNP-HD	0301112				

 Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Programmable magnetic switch MMS 22-PI2



(17) Cable outlet

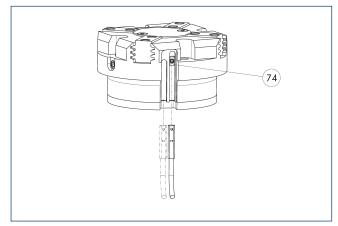
90 MMS 22...-PI2-... sensor

Position monitoring with two programmable positions per sensor and electronics built into the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined			
Programmable magnetic switch					
MMS 22-PI2-S-M8-PNP	0301180	•			
MMSK 22-PI2-S-PNP	0301182				
Programmable magnetic switch with lateral cable outlet					
MMS 22-PI2-S-M8-PNP-SA	0301186	•			
MMSK 22-PI2-S-PNP-SA	0301188				
Programmable magnetic switch with stainless steel housing					
MMS 22-PI2-S-M8-PNP-HD	0301130	•			
MMSK 22-PI2-S-PNP-HD	0301132				

One sensor is required per unit for monitoring two positions.
Extension cables and sensor distributors are optionally available.
Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

MMS-P programmable magnetic switch



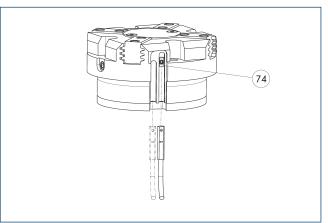
(74) Limit stop for sensor

Position monitoring with two programmable positions per sensor. End position monitoring for mounting in the C-slot.

Description	ID	Often combined				
Programmable magnetic switch						
MMSK-P 22-S-PNP	0301371					
MMS-P 22-S-M8-PNP	0301370	•				
Connection cables						
KA GLN0804-LK-00500-A	0307767	•				
KA GLN0804-LK-01000-A	0307768					
KA WLN0804-LK-00500-A	0307765					
KA WLN0804-LK-01000-A	0307766					
clip for plug/socket						
CLI-M8	0301463					
Sensor distributor						
V2-M8-4P-2XM8-3P	0301380					

One sensor is required per unit for monitoring two positions.
Extension cables and sensor distributors are optionally available.
Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

Programmable magnetic switch MMS-IO-Link



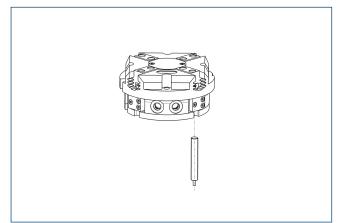
(74) Limit stop for sensor

Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. Sensor programming on the gripper takes place via the IO-Link interface or the MT magnetic teach tool (included in scope of delivery). An IO-Link master is required for operation.

Description	ID	
Programmable magnetic switch		
MMS 22-10L-M08	0315830	
MMS 22-I0L-M12	0315835	

① One sensor is required for each gripper. No additional mounting kit is required - the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.

APS-Z80 analog position sensor

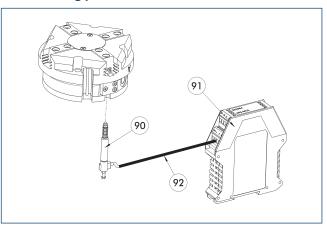


No-contact measuring, analog multi-position monitoring for any number of positions.

Description	ID	Often combined
Mounting kit for APS-Z80		
AS-APS-Z80-PGZN-plus 80-1	0302107	
Analog position sensor		
APS-Z80-K	0302072	
APS-Z80-M8	0302070	•

When using an APS system, one mounting kit (AS-APS-Z80) and one APS-Z80 sensor is required per gripper. The resolution of the sensor can be lower in the peripheral areas of the gripper. You can find further information on the product in the operating manual.

APS-M1 analog position sensor



90 APS-M1S sensor

(92) APS-K extension cable

(91) APS-M1E electronic processor

Analog multi position monitoring for any desired positions

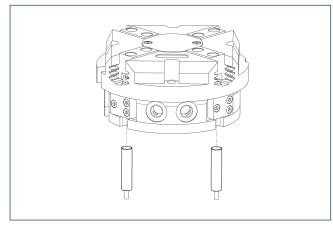
Description	ID
Mounting kit for APS-M1	
AS-APS-M1-PGZN-plus 80-1	0302077
Analog position sensor	
APS-M1S	0302062
Connection cables	
APS-K0200	0302066
APS-K0700	0302068
Evaluation electronics	
APS-M1E	0302064

When using an APS system, for each gripper an attachment kit (AS-APS-M1), an APS-M1S sensor (incl. 3 m cable) as well as an electronics (APS-M1e) are required. An extension cable (APS-K) can be connected between the sensor and the electronics as an option. The max. cable length between the sensor and the electronics is 10 m, between the electronics and their control unit (PLC) it is max. 1 m.

PZV 100

4-finger centric gripper

Cylindrical reed switches



End position monitoring can be mounted with an attachment kit.

Description	ID				
Attachment kit for proximity switch					
AS-RMS 80 PGN/PZN-plus 64/80	0377725				
Reed Switches					
RMS 80-S-M8	0377721				

Two sensors (closer/S) are required for each unit and extension cables are available as an option. This attachment kit needs to be ordered optionally as an accessory. Two mounting kits are required for each gripper. For sensor cables, note the minimum permissible bending radii. These are generally 35 mm.

17





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