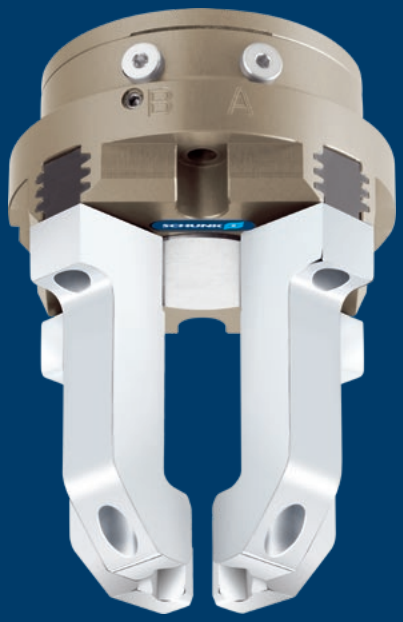


Superior Clamping and Gripping

Product Information

4-finger centric gripper PZV 64

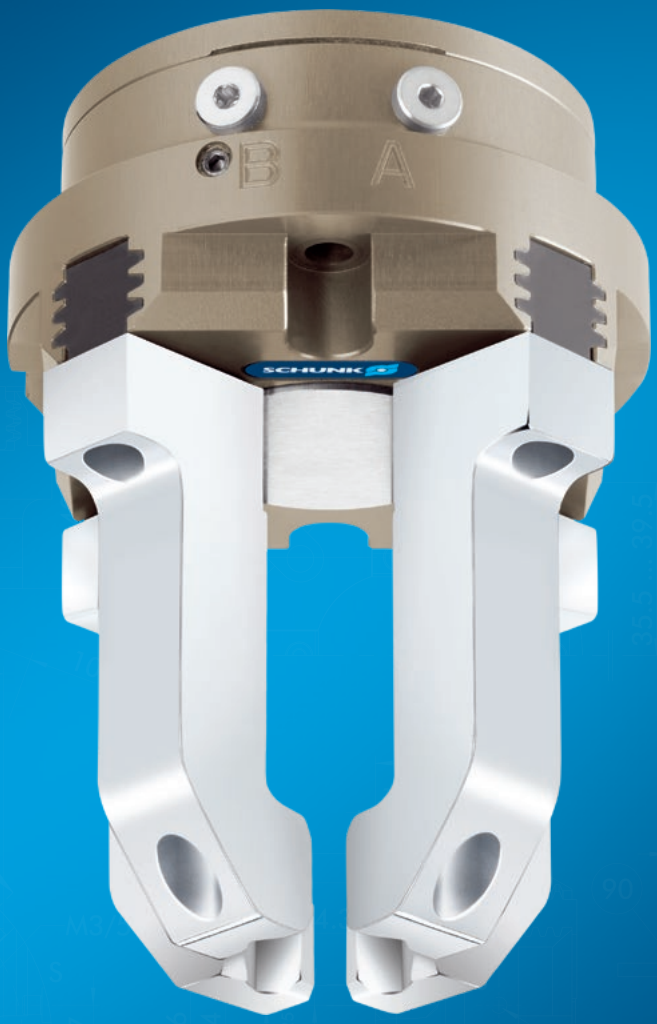
Loadable. Precise. Reliable.

Centric gripper PZV

The multi-finger gripper for applications, in which two or three fingers are insufficient

Field of application

4-finger centric grippers have advantages over the usual centric grippers, for example when cylindrical workpieces are being stored in tablets. The PZV handles the workpieces in a controlled, process reliable manner despite the interfering contours.



Advantages – Your benefits

Robust multi-tooth guidance for precise handling

Wedge-hook design for high power transmission and synchronized gripping

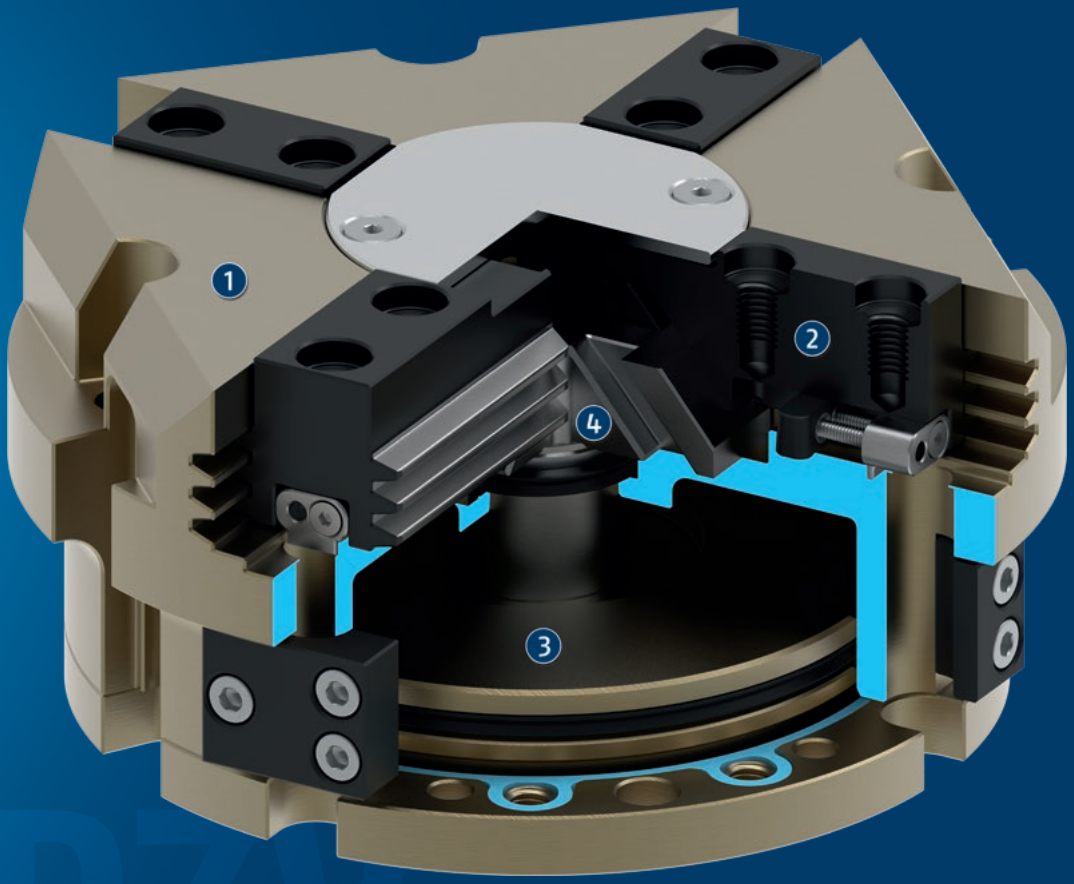
Air supply via hose-free direct connection or screw connections for flexible pressure supply in all automated systems

Comprehensive sensor accessory program for versatile querying possibilities and stroke position monitoring

Sizes	Weight	Gripping force	Stroke per jaw	Workpiece weight
Quantity: 5	0.5 .. 10 kg	570 .. 6900 N	4 .. 16 mm	2.8 .. 34.5 kg

Functional description

The piston is moved up and down by compressed air. The angled active surfaces of the wedge-hook produce a synchronized, centric jaw movement.



① **Housing**
is weight-optimized due to the use of high-strength aluminum alloy

② **Multi-tooth guidance**
for mounting high loads onto the base jaw

③ **Drive**
through pneumatic double piston system

④ **Wedge-hook design**
for high force transmission and centric gripping

General notes about the series

Operating principle: Wedge-hook kinematics

Housing material: Aluminum alloy, anodized

Base jaw material: Steel

Actuation: pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

Warranty: 36 months

Scope of delivery: Brackets for proximity switches, centering sleeves, O-rings for direct connection, assembly instructions (operating manual with declaration of incorporation is available online)

Gripping force maintenance device: possible with pressure maintenance valve SDV-P

Gripping force: is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

Finger length: is measured from the reference surface as the distance P in direction to the main axis.
The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

Repeat accuracy: is defined as a distribution of the end Position for 100 consecutive strokes.

Workpiece weight: is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.

Application example

Centering and rotation unit for the precise picking up, orientation, and subsequent joining of square materials

1. Multi-finger gripper PZV
2. Collision sensor OPS
3. Rotary actuator SRU-plus
4. Universal linear module Beta

SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.

Rotary feed-through

Tolerance compensation unit

Pressure maintenance valve

Jaw quick-change system

Inductive proximity switches

Magnetic switches

Flexible position sensor

Finger blank

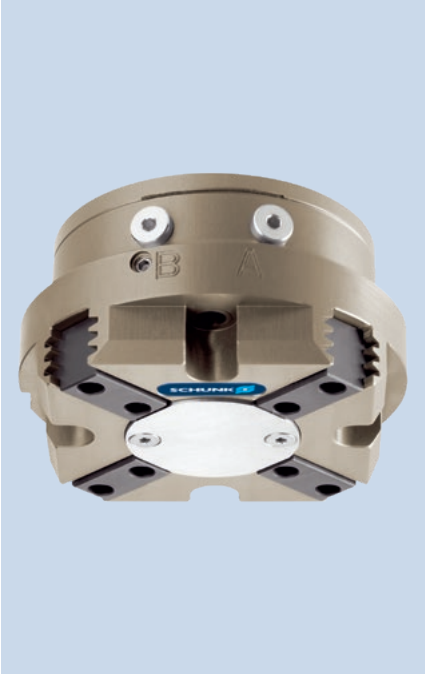
ⓘ For more information on these products can be found on the following product pages or at schunk.com.

Options and special information

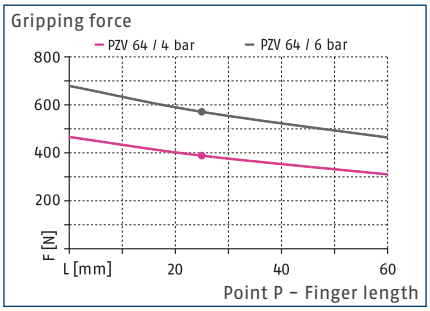
Intermediate sizes are available on request. Please note that the four-finger grip is an umbrella term, and may lead to a two or three-finger grip in certain cases.
Pressure reduction in case of a two finger application of the PZV 160 and 200: The operating pressure must be reduced to a maximum of 5 bar when using the 4-finger centric gripper PZV 160 and 200 as a (double) 2-finger parallel gripper.
Integrated air purge connection: impedes the ingress of dirt into the inside of the gripper

PZV 64

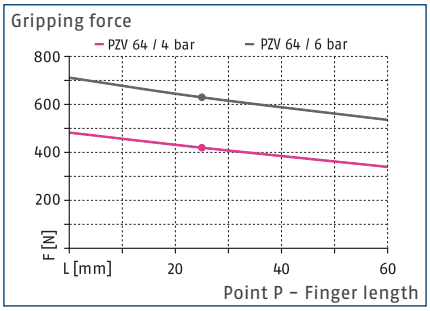
4-finger centric gripper



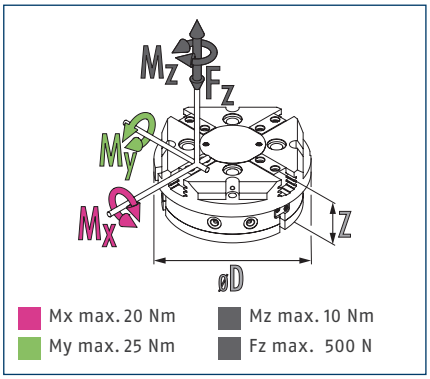
Gripping force O.D. gripping



Gripping force I.D. gripping



Dimensions and maximum loads



Mx max. 20 Nm	Mz max. 10 Nm
My max. 25 Nm	Fz max. 500 N

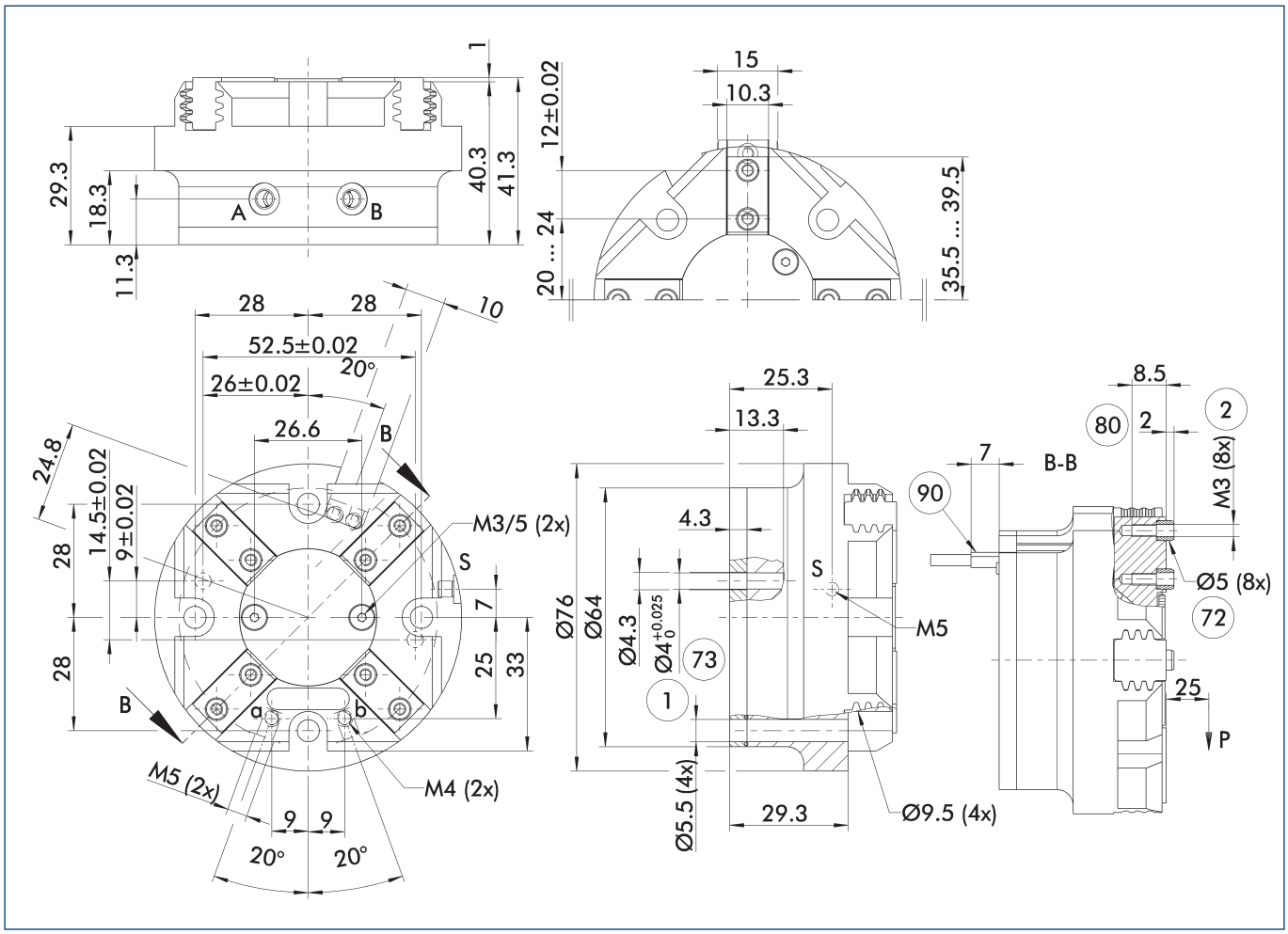
ⓘ The indicated moments and forces are statical values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

Technical data

Description		PZV 64
ID		0304000
Stroke per jaw	[mm]	4
Closing/opening force	[N]	570/630
Weight	[kg]	0.5
Recommended workpiece weight	[kg]	2.8
Fluid consumption double stroke	[cm³]	25
Min./nom./max. operating pressure	[bar]	2/6/8
Min./max. air purge pressure	[bar]	0.5/1
Closing/opening time	[s]	0.02/0.02
Max. permissible finger length	[mm]	64
Max. permissible mass per finger	[kg]	0.18
IP protection class		40
Min./max. ambient temperature	[°C]	5/90
Repeat accuracy	[mm]	0.01
Dimensions Ø D x Z	[mm]	76 x 41.3

ⓘ It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

Main view



The drawing shows the gripper in the basic version with closed jaws, without dimensional consideration of the options described below.

ⓘ The SDV-P pressure maintenance valve can be used as a gripping force maintenance device (see catalog section on accessories).

A, a Main / direct connection, gripper opening

B, b Main / direct connection, gripper closing

S Air purge connection

(1) Gripper connection

(2) Finger connection

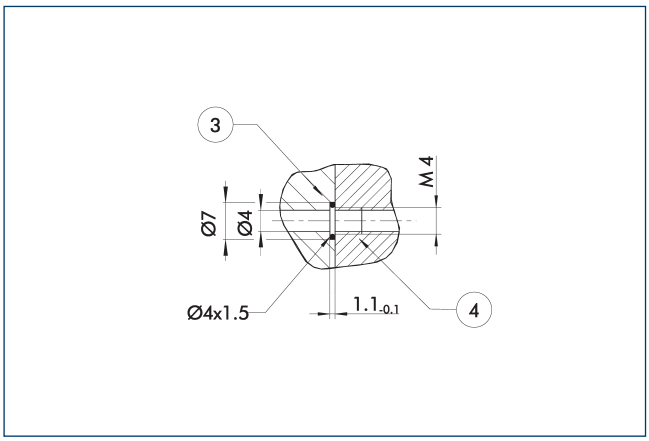
(72) Fit for centering sleeves

(73) Fit for centering pins

(80) Depth of the centering sleeve hole in the counter part

(90) Sensor MMS 22..

Hose-free direct connection M4

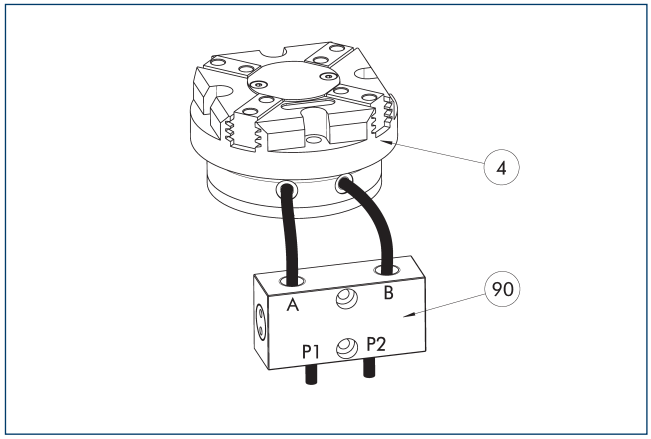


(3) Adapter

(4) Grippers

The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

SDV-P pressure maintenance valve



(4) Grippers

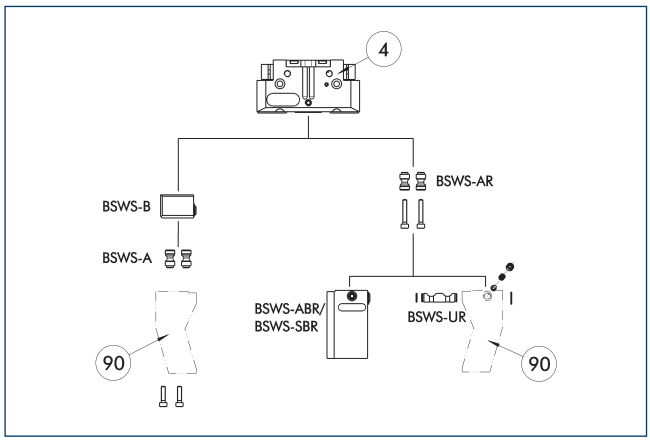
(90) SDV-P pressure maintenance valve

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter
		[mm]
Pressure maintenance valve		
SDV-P 07	0403131	8
Pressure maintenance valve with air bleed screw		
SDV-P 07-E	0300121	8

ⓘ In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

BSWS jaw quick-change jaw systems



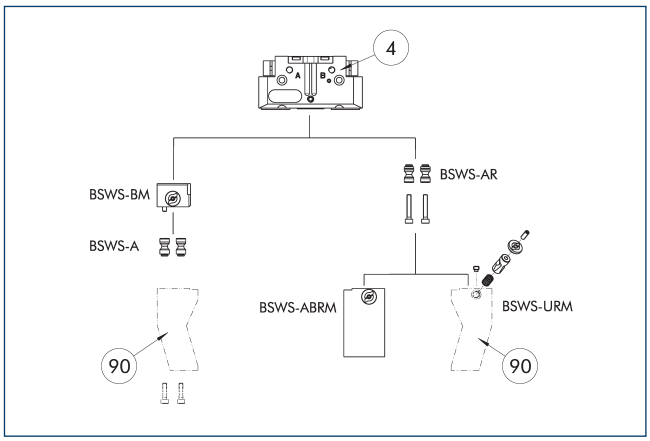
④ Grippers ⑨⓪ Customized gripper fingers

There are various jaw quick-change systems available for the gripper. For detailed information, please refer to the corresponding product.

Description	ID	Scope of delivery
Jaw quick-change system adapter pin		
BSWS-A 50	0303020	2
BSWS-AR 50	0300091	2
Quick-change jaw system base		
BSWS-B 50	0303021	1
Jaw quick-change system finger blank		
BSWS-ABR-PGZN-plus 50	0300071	1
BSWS-SBR-PGZN-plus 50	0300081	1
Jaw quick-change system locking mechanism		
BSWS-UR 50	0302990	1

ⓘ Only systems that are listed in the table, can be used.

Jaw quick-change system BSWS-M



④ Grippers ⑨⓪ Customized gripper fingers

There are various jaw quick-change systems available for the gripper. For detailed information, please refer to the corresponding product.

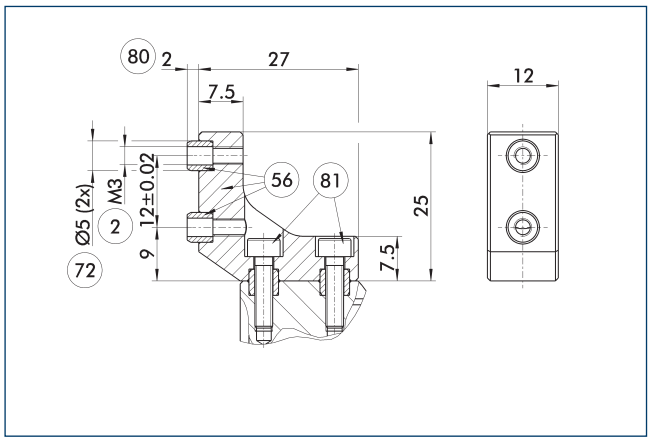
Description	ID	Scope of delivery
Jaw quick-change system adapter pin		
BSWS-A 50	0303020	2
BSWS-AR 50	0300091	2
Quick-change jaw system base		
BSWS-BM 50	1313899	1
Jaw quick-change system finger blank		
BSWS-ABRM-PGZN-plus 50	1420850	1
Jaw quick-change system locking mechanism		
BSWS-URM 50	1380614	1

ⓘ Only systems that are listed in the table, can be used.

PZV 64

4-finger centric gripper

ZBA-L-plus 50 intermediate jaws

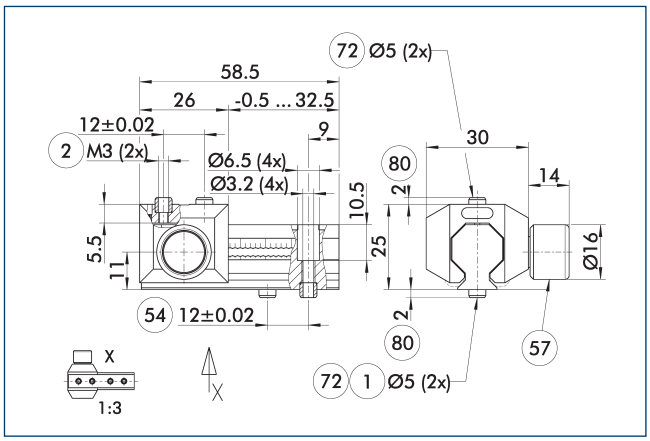


(2) Finger connection
(56) Included in the scope of delivery
(72) Fit for centering sleeves
(80) Depth of the centering sleeve hole in the counter part
(81) Not included in the scope of delivery

The optional ZBA-L-plus intermediate jaws allow the screw connection diagram of the top jaws to be rotated by 90°. This makes it easier to design and produce top jaws (particularly for long versions) because no deep through-bores are required.

Description	ID	Material	Finger interface	Scope of delivery
Intermediate jaw				
ZBA-L-plus 50	0311712	Aluminum	PGN-plus 50	1

UZB 50 universal intermediate jaw

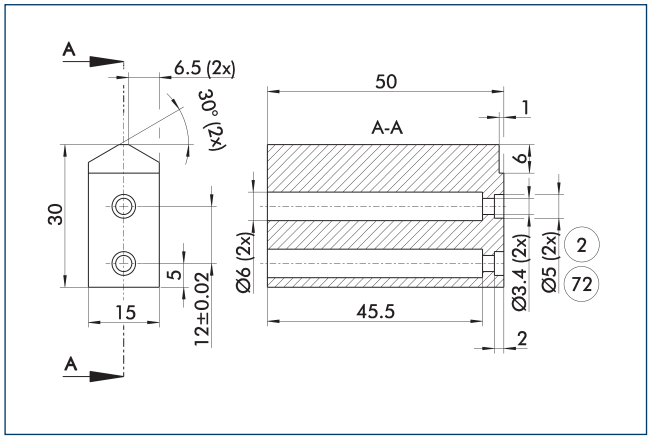


(1) Gripper connection
(2) Finger connection
(54) Optional right or left connection
(57) Locking
(72) Fit for centering sleeves
(80) Depth of the centering sleeve hole in the counter part

The drawing shows the UZB universal intermediate jaw.

Description	ID	Grid dimension
		[mm]
Universal intermediate jaw		
UZB 50	0300041	1.5
Finger blank		
ABR-PGZN-plus 50	0300009	
SBR-PGZN-plus 50	0300019	

Finger blank ABR- / SBR-PGZN-plus 50

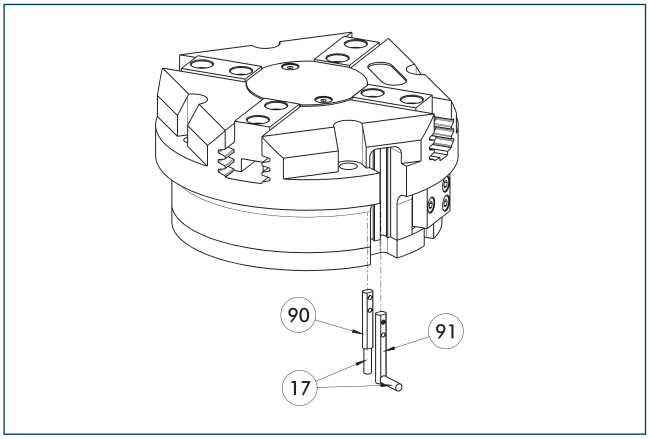


(2) Finger connection
(72) Fit for centering sleeves

The drawing shows the finger blank which can be reworked by the customer.

Description	ID	Material	Scope of delivery
Finger blank			
ABR-PGZN-plus 50	0300009	Aluminum	1
SBR-PGZN-plus 50	0300019	Steel	1

Electronic magnetic switch MMS



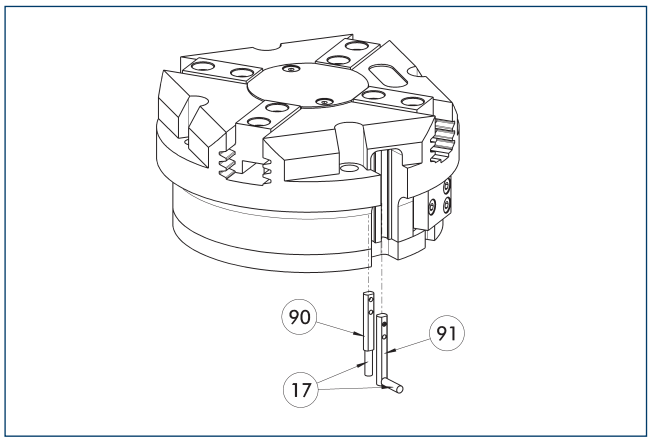
(17) Cable outlet
(91) Sensor MMS 22...-SA
(90) Sensor MMS 22..

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	●
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with lateral cable outlet		
MMS 22-S-M8-PNP-SA	0301042	●
MMSK 22-S-PNP-SA	0301044	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	●
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
clip for plug/socket		
CLI-M8	0301463	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	●
Sensor distributor		
V2-M8	0301775	●
V4-M8	0301746	
V8-M8	0301751	

ⓘ Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Programmable magnetic switch MMS 22-PI1



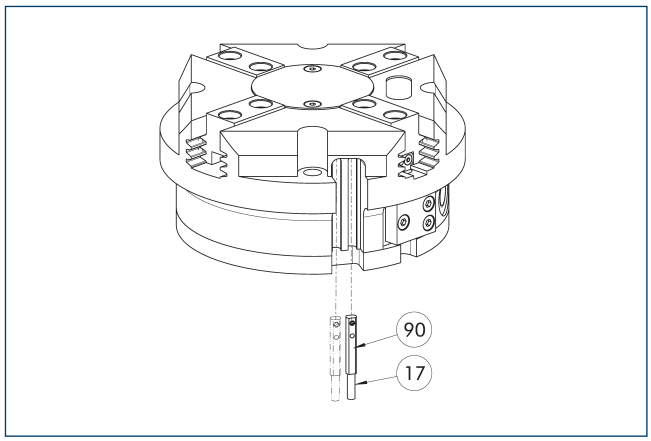
17 Cable outlet
91 Sensor MMS 22 ..-PI1-...-SA
90 Sensor MMS 22 PI1-...

Position monitoring with one programmable position per sensor and integrated electronic system in the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI1-S-M8-PNP	0301160	●
MMSK 22-PI1-S-PNP	0301162	
Programmable magnetic switch with lateral cable outlet		
MMS 22-PI1-S-M8-PNP-SA	0301166	●
MMSK 22-PI1-S-PNP-SA	0301168	
Programmable magnetic switch with stainless steel housing		
MMS 22-PI1-S-M8-PNP-HD	0301110	●
MMSK 22-PI1-S-PNP-HD	0301112	

ⓘ Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Programmable magnetic switch MMS 22-PI2



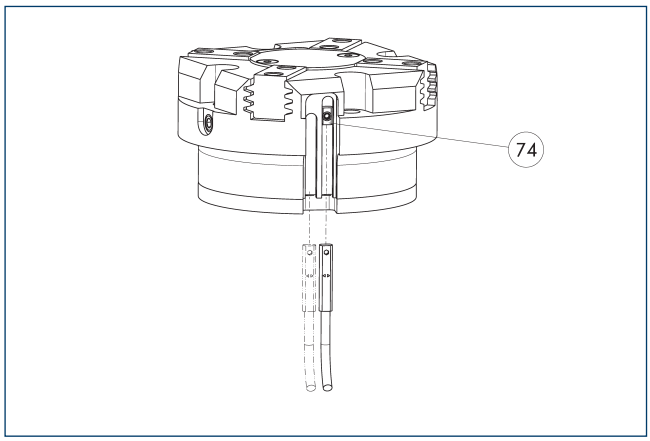
17 Cable outlet
90 MMS 22...-PI2-... sensor

Position monitoring with two programmable positions per sensor and electronics built into the sensor. Can be programmed using MT magnetic teaching tool (included in the scope of delivery) or ST plug teaching tool (optional). End position monitoring for mounting in the C-slot. If the ST plug teaching tools are listed in the table provided, teaching is only possible with the ST teaching tools.

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI2-S-M8-PNP	0301180	●
MMSK 22-PI2-S-PNP	0301182	
Programmable magnetic switch with lateral cable outlet		
MMS 22-PI2-S-M8-PNP-SA	0301186	●
MMSK 22-PI2-S-PNP-SA	0301188	
Programmable magnetic switch with stainless steel housing		
MMS 22-PI2-S-M8-PNP-HD	0301130	●
MMSK 22-PI2-S-PNP-HD	0301132	

ⓘ One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

MMS-P programmable magnetic switch



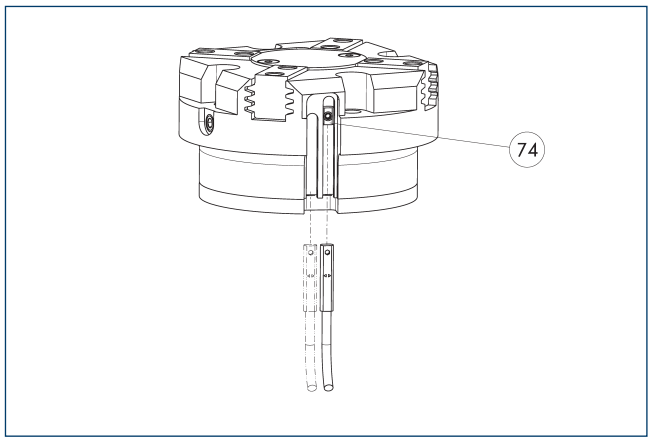
74 Limit stop for sensor

Position monitoring with two programmable positions per sensor. End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Programmable magnetic switch		
MMSK-P 22-S-PNP	0301371	
MMS-P 22-S-M8-PNP	0301370	●
Connection cables		
KA GLN0804-LK-00500-A	0307767	●
KA GLN0804-LK-01000-A	0307768	
KA WLN0804-LK-00500-A	0307765	
KA WLN0804-LK-01000-A	0307766	
clip for plug/socket		
CLI-M8	0301463	
Sensor distributor		
V2-M8-4P-2XM8-3P	0301380	

ⓘ One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

Programmable magnetic switch MMS-IO-Link



74 Limit stop for sensor

Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. Sensor programming on the gripper takes place via the IO-Link interface or the MT magnetic teach tool (included in scope of delivery). An IO-Link master is required for operation.

Description	ID	
Programmable magnetic switch		
MMS 22-IOL-M08	0315830	
MMS 22-IOL-M12	0315835	

ⓘ One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.

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