

Superior Clamping and Gripping



Product Information

4-finger centric gripper PZV 125

Loadable. Precise. Reliable.

Centric gripper PZV

The multi-finger gripper for applications, in which two or three fingers are insufficient

Field of application

4-finger centric grippers have advantages over the usual centric grippers, for example when cylindrical workpieces are being stored in tablets. The PZV handles the workpieces in a controlled, process reliable manner despite the interfering contours.

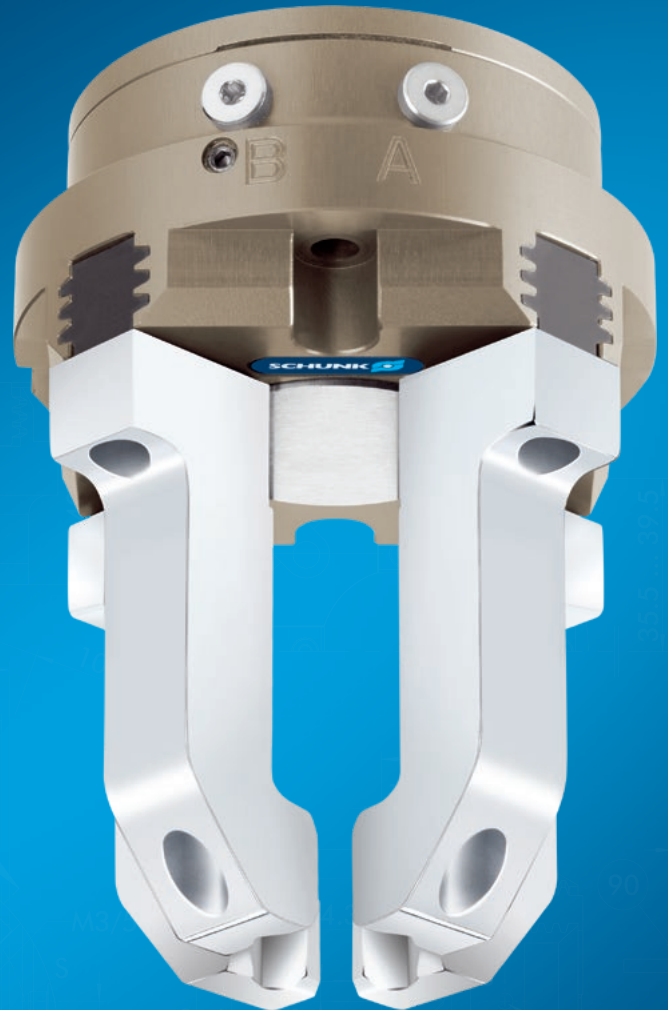
Advantages – Your benefits

Robust multi-tooth guidance for precise handling

Wedge-hook design for high power transmission and synchronized gripping

Air supply via hose-free direct connection or screw connections for flexible pressure supply in all automated systems

Comprehensive sensor accessory program for versatile querying possibilities and stroke position monitoring



Sizes
Quantity: 5



Weight
0.5 .. 10 kg



Gripping force
570 .. 6900 N



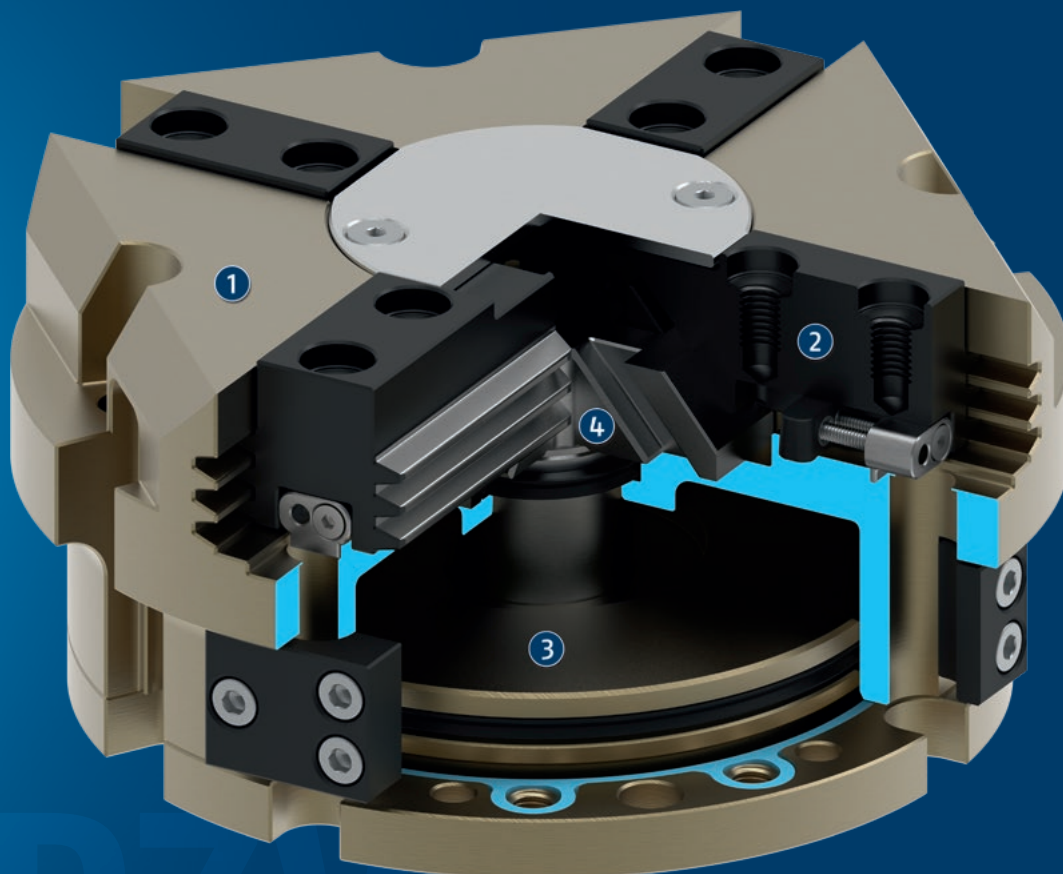
Stroke per jaw
4 .. 16 mm



Workpiece weight
2.8 .. 34.5 kg

Functional description

The piston is moved up and down by compressed air.
The angled active surfaces of the wedge-hook produce a synchronized, centric jaw movement.



- ① **Housing**
is weight-optimized due to the use of high-strength aluminum alloy
- ② **Multi-tooth guidance**
for mounting high loads onto the base jaw
- ③ **Drive**
through pneumatic double piston system
- ④ **Wedge-hook design**
for high force transmission and centric gripping

General notes about the series

Operating principle: Wedge-hook kinematics

Housing material: Aluminum alloy, anodized

Base jaw material: Steel

Actuation: pneumatic, with filtered compressed air as per ISO 8573-1:2010 [7:4:4].

Warranty: 36 months

Scope of delivery: Brackets for proximity switches, centering sleeves, O-rings for direct connection, assembly instructions (operating manual with declaration of incorporation is available online)

Gripping force maintenance device: possible with pressure maintenance valve SDV-P

Gripping force: is the arithmetic sum of the individual force applied to each jaw at distance P (see illustration).

Finger length: is measured from the reference surface as the distance P in direction to the main axis.

The maximum permissible finger length applies until the nominal operating pressure is achieved. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

Repeat accuracy: is defined as a distribution of the end Position for 100 consecutive strokes.

Workpiece weight: is calculated for force-fit gripping with a coefficient of static friction of 0.1 and a safety factor of 2 against workpiece slippage at acceleration due to gravity g. For form-fit or capture gripping, there are significantly higher permissible workpiece weights.

Closing and opening times: are purely the times that the base jaws or fingers are in motion. Valve switching times, hose fill times, or PLC reaction times are not included, and are to be considered when cycle times are calculated.

Application example

Centering and rotation unit for the precise picking up, orientation, and subsequent joining of square materials

- ❶ Multi-finger gripper PZV
- ❷ Collision sensor OPS
- ❸ Rotary actuator SRU-plus
- ❹ Universal linear module Beta

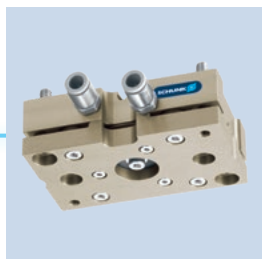


SCHUNK offers more ...

The following components make the product even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.



Rotary feed-through



Tolerance compensation unit



Pressure maintenance valve



Jaw quick-change system



Inductive proximity switches



Magnetic switches



Flexible position sensor



Finger blank

① For more information on these products can be found on the following product pages or at schunk.com.

Options and special information

Intermediate sizes are available on request. Please note that the four-finger grip is an umbrella term, and may lead to a two or three-finger grip in certain cases.

Pressure reduction in case of a two finger application of the PZV 160 and 200: The operating pressure must be reduced to a maximum of 5 bar when using the 4-finger centric gripper PZV 160 and 200 as a (double) 2-finger parallel gripper.

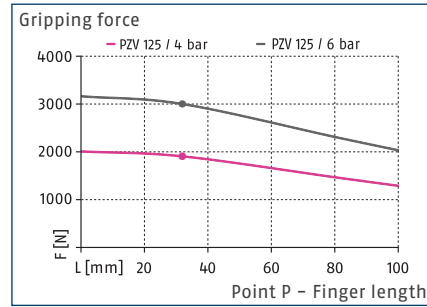
Integrated air purge connection: impedes the ingress of dirt into the inside of the gripper

PZV 125

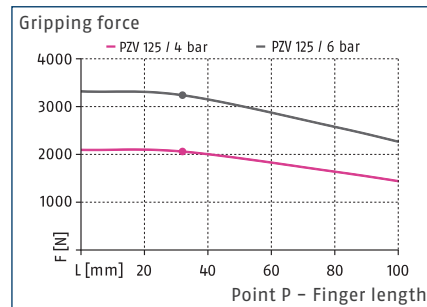
4-finger centric gripper



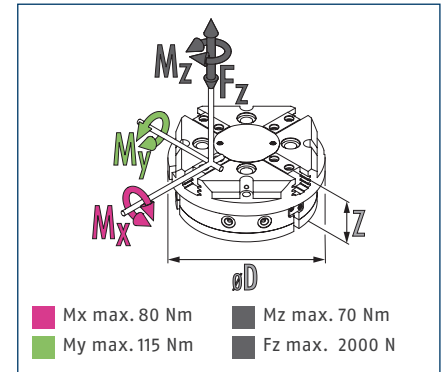
Gripping force O.D. gripping



Gripping force I.D. gripping



Dimensions and maximum loads



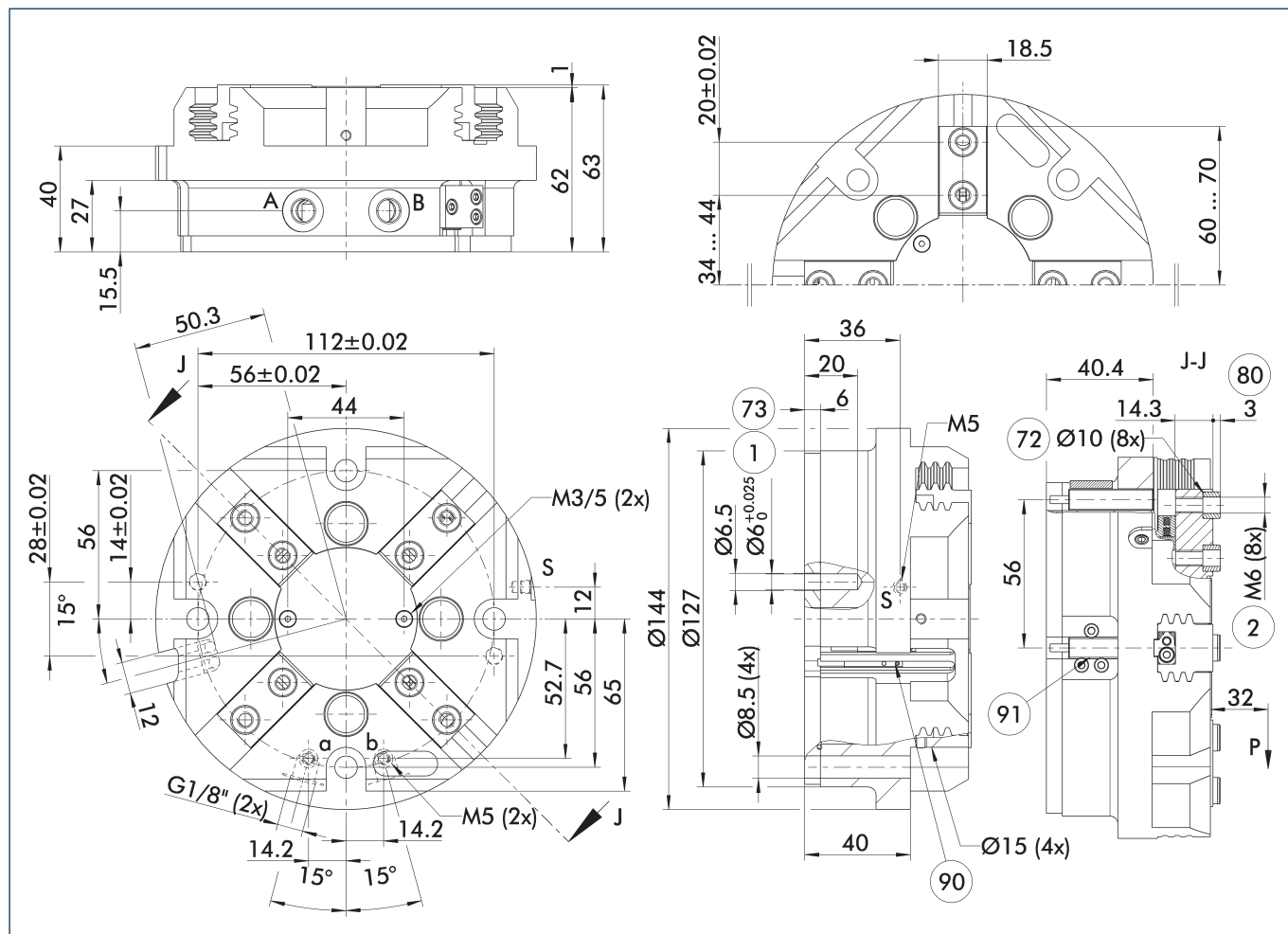
① The indicated moments and forces are static values, apply for each base jaw and may appear simultaneously. Loads may additionally occur to the moment produced by the gripping force itself.

Technical data

Description		PZV 125
ID		0304003
Stroke per jaw	[mm]	10
Closing/opening force	[N]	3000/3230
Weight	[kg]	2.3
Recommended workpiece weight	[kg]	15
Fluid consumption double stroke	[cm³]	230
Min./nom./max. operating pressure	[bar]	2/6/8
Min./max. air purge pressure	[bar]	0.5/1
Closing/opening time	[s]	0.1/0.1
Max. permissible finger length	[mm]	100
Max. permissible mass per finger	[kg]	1.1
IP protection class		40
Min./max. ambient temperature	[°C]	5/90
Repeat accuracy	[mm]	0.01
Dimensions Ø D x Z	[mm]	144 x 63

① It may take a few 100 gripping cycles until the full gripping force (as indicated in the data table) will be available.

Main view



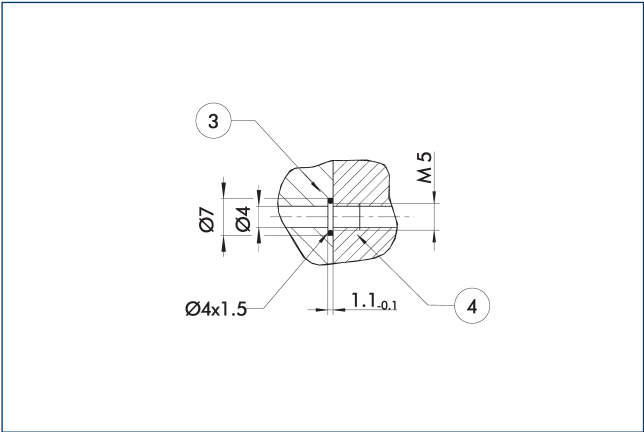
The drawing shows the gripper in the basic version with closed jaws, without dimensional consideration of the options described below.

① The SDV-P pressure maintenance valve can be used as a gripping force maintenance device (see catalog section on accessories).

- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- S Air purge connection
- ① Gripper connection
- ② Finger connection

- ⑦② Fit for centering sleeves
- ⑦③ Fit for centering pins
- ⑧① Depth of the centering sleeve hole in the counter part
- ⑨① Sensor MMS 22..
- ⑨② Sensor IN ...

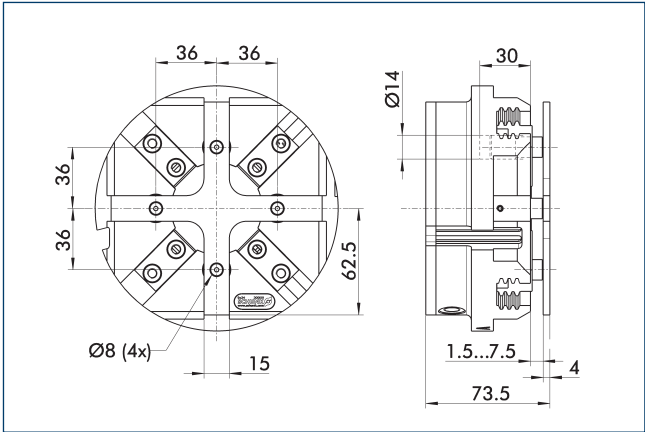
Hose-free direct connection M5



③ Adapter ④ Grippers

The direct connection is used for supplying compressed air without hoses. Instead, the pressure medium is fed through bore-holes in the mounting plate.

Spring-loaded pressure piece

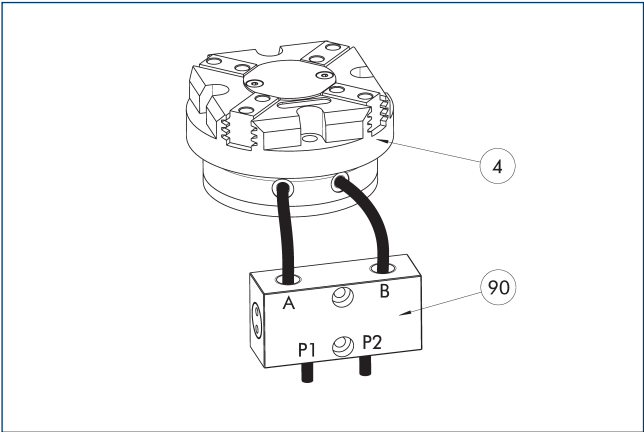


For spring-supported positioning of the workpiece against a stop after the gripper has opened. Especially developed for loading machines.

Description	ID	Stroke [mm]	Min. force [N]
Spring-loaded pressure piece			
A-PZV 125	0304013	6	173

① The pressure piece cannot be combined with the dustproof option. Please contact us if you require a customized pressure piece.

SDV-P pressure maintenance valve



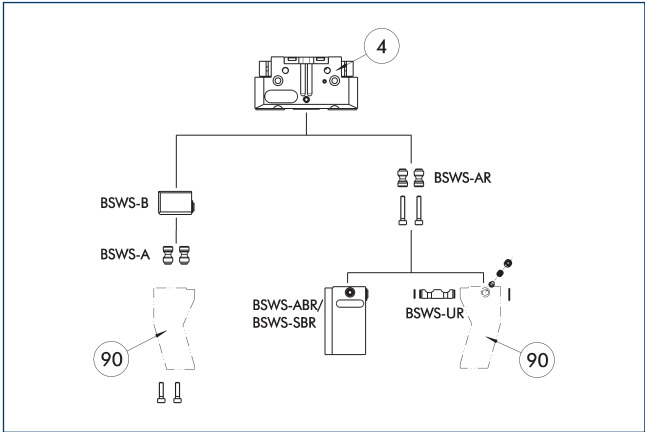
④ Grippers ⑨0 SDV-P pressure maintenance valve

The SDV-P pressure maintenance valve ensures in emergency STOP situations that the pressure in the piston chamber of pneumatic gripper, swivel, linear, and quick-change modules is temporarily maintained.

Description	ID	Recommended hose diameter [mm]
Pressure maintenance valve		
SDV-P 07	0403131	8
Pressure maintenance valve with air bleed screw		
SDV-P 07-E	0300121	8

① In order to achieve the specified closing and opening time for each gripper variant, the recommended hose diameter must be used. The direct allocation of the respective variant of the gripper for the respective SDV-P can be found at schunk.com.

BSWS jaw quick-change jaw systems



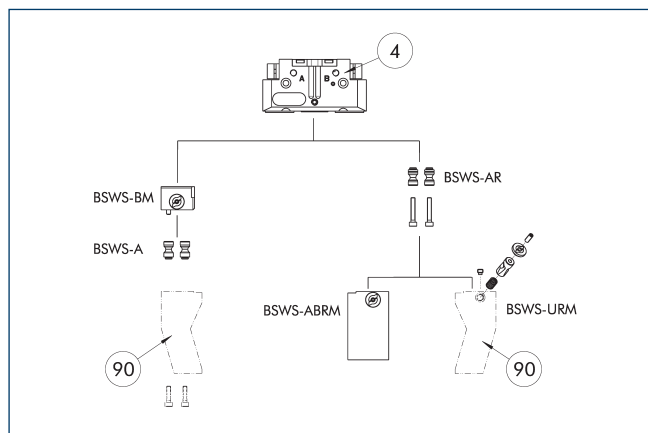
④ Grippers ⑨0 Customized gripper fingers

There are various jaw quick-change systems available for the gripper. For detailed information, please refer to the corresponding product.

Description	ID	Scope of delivery
Jaw quick-change system adapter pin		
BSWS-A 100	0303026	2
BSWS-AR 100	0300094	2
Quick-change jaw system base		
BSWS-B 100	0303027	1
Jaw quick-change system finger blank		
BSWS-ABR-PGZN-plus 100	0300074	1
BSWS-SBR-PGZN-plus 100	0300084	1
Jaw quick-change system locking mechanism		
BSWS-UR 100	0302993	1

① Only systems that are listed in the table, can be used.

Jaw quick-change system BSWs-M



④ Grippers

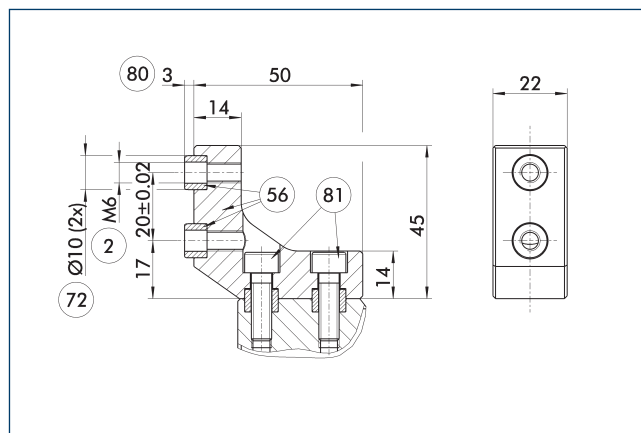
⑨ Customized gripper fingers

There are various jaw quick-change systems available for the gripper. For detailed information, please refer to the corresponding product.

Description	ID	Scope of delivery
Jaw quick-change system adapter pin		
BSWS-A 100	0303026	2
BSWS-AR 100	0300094	2
Quick-change jaw system base		
BSWS-BM 100	1313902	1
Jaw quick-change system finger blank		
BSWS-ABRM-PGZN-plus 100	1420853	1
Jaw quick-change system locking mechanism		
BSWS-URM 100	1398403	1

① Only systems that are listed in the table, can be used.

ZBA-L-plus 100 intermediate jaws



② Finger connection

⑤ Included in the scope of delivery

⑦ Fit for centering sleeves

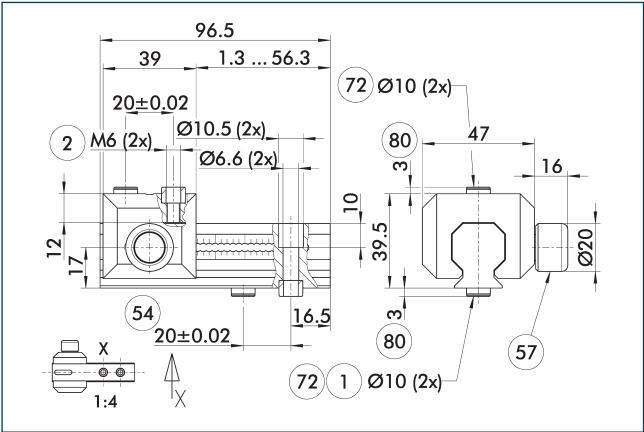
⑧ Depth of the centering sleeve hole in the counter part

⑧ Not included in the scope of delivery

The optional ZBA-L-plus intermediate jaws allow the screw connection diagram of the top jaws to be rotated by 90°. This makes it easier to design and produce top jaws (particularly for long versions) because no deep through-bores are required.

Description	ID	Material	Finger interface	Scope of delivery
Intermediate jaw				
ZBA-L-plus 100	0311742	Aluminum	PGN-plus 100	1

UZB 100 universal intermediate jaw



- ① Gripper connection

② Finger connection

⑤4 Optional right or left connection
- ⑤7 Locking

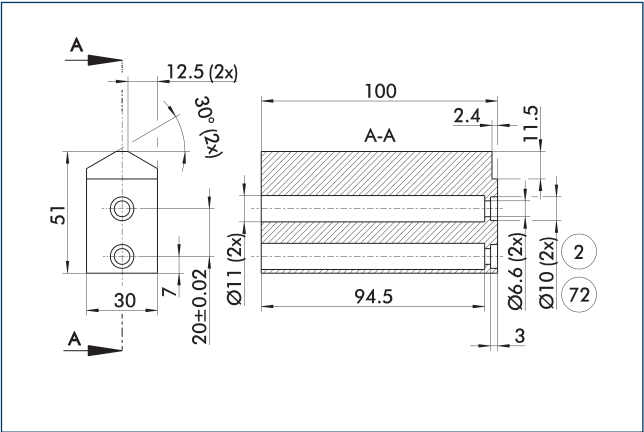
⑦2 Fit for centering sleeves

⑧0 Depth of the centering sleeve hole in the counter part

The drawing shows the UZB universal intermediate jaw. The fully removable UZB-S slide (can also be ordered separately) allows for a quick jaw change.

Description	ID	Grid dimension
		[mm]
Universal intermediate jaw		
UZB 100	0300044	2.5
Finger blank		
ABR-PGZN-plus 100	0300012	
SBR-PGZN-plus 100	0300022	
Slide for universal intermediate jaw		
UZB-S 100	5518272	2.5

Finger blanks ABR- / SBR-PGZN-plus 100

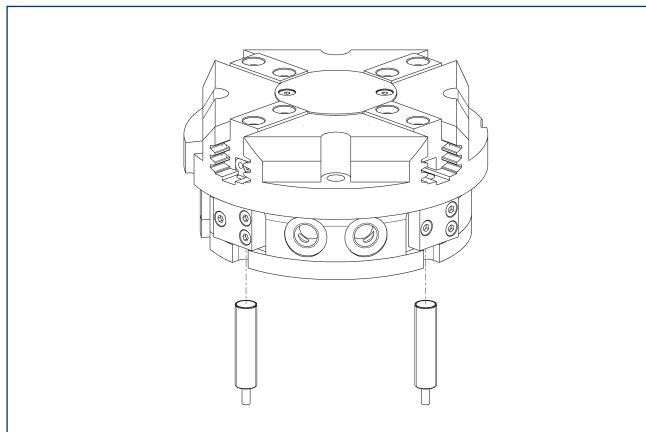


- ② Finger connection
- ⑦2 Fit for centering sleeves

The drawing shows the finger blank which can be reworked by the customer.

Description	ID	Material	Scope of delivery
Finger blank			
ABR-PGZN-plus 100	0300012	Aluminum	1
SBR-PGZN-plus 100	0300022	Steel	1

Inductive Proximity Switches

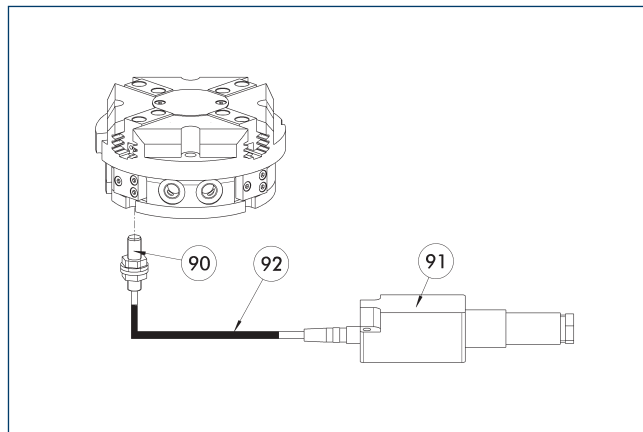


Directly mounted end position monitoring.

Description	ID	Often combined
Inductive proximity switches		
IN 80-S-M12	0301578	
IN 80-S-M8	0301478	●
INK 80-S	0301550	
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	●
KA BG08-L 3P-0500-PNP	0301623	
KA BG12-L 3P-0500-PNP	30016369	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
KA BW12-L 3P-0300-PNP	0301503	
KA BW12-L 3P-0500-PNP	0301507	
clip for plug/socket		
CLI-M12	0301464	
CLI-M8	0301463	
Cable extension		
KV BG12-SG12 3P-0030-PNP	0301999	
KV BG12-SG12 3P-0060-PNP	0301998	
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	●
KV BW12-SG12 3P-0030-PNP	0301595	
KV BW12-SG12 3P-0100-PNP	0301596	
KV BW12-SG12 3P-0200-PNP	0301597	
Sensor distributor		
V2-M12	0301776	●
V2-M8	0301775	●
V4-M8	0301746	
V8-M8	0301751	

- ① Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Flexible position sensor



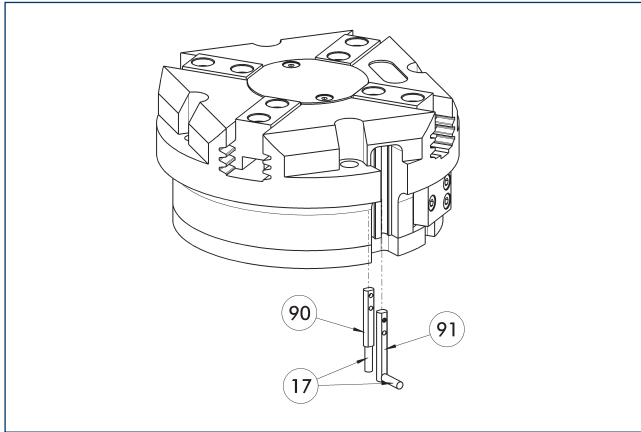
- ⑨⑨ FPS-S sensor ⑨② Cable extension
⑨① FPS-F5 evaluation electronic

Flexible position monitoring of up to five positions.

Description	ID	
Attachment kit for FPS		
AS-FPS-PGZN-plus 100-1	0301634	
Sensor		
FPS-S M8	0301704	
Evaluation electronics		
FPS-F5	0301805	
Cable extension		
KV BG08-SG08 3P-0050	0301598	
KV BG08-SG08 3P-0100	0301599	

- ① When using an FPS system, an FPS sensor (FPS-S) as well as an electronic processor (FPS-F5 / F5 T) are required for each gripper as well as a mounting kit (AS), if listed. Cable extensions (KV) are optionally available – see catalog chapter “Accessories.”

Electronic magnetic switch MMS



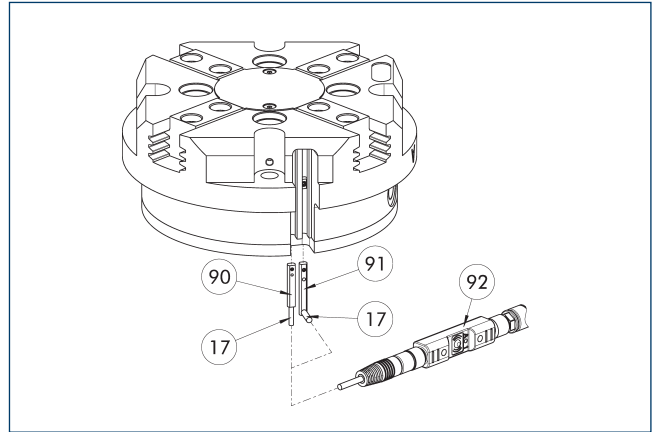
- ①⑦ Cable outlet
①⑨ Sensor MMS 22..
①① Sensor MMS 22...-SA

End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Electronic magnetic switch		
MMS 22-S-M8-PNP	0301032	●
MMSK 22-S-PNP	0301034	
Electronic magnetic switches with lateral cable outlet		
MMS 22-S-M8-PNP-SA	0301042	●
MMSK 22-S-PNP-SA	0301044	
Reed Switches		
RMS 22-S-M8	0377720	●
Connection cables		
KA BG08-L 3P-0300-PNP	0301622	●
KA BG08-L 3P-0500-PNP	0301623	
KA BW08-L 3P-0300-PNP	0301594	
KA BW08-L 3P-0500-PNP	0301502	
clip for plug/socket		
CLI-M8	0301463	
Wireless sensor system		
RSS-T2	0377715	
RSS-T2-US/CA	0377717	
Cable extension		
KV BW08-SG08 3P-0030-PNP	0301495	
KV BW08-SG08 3P-0100-PNP	0301496	
KV BW08-SG08 3P-0200-PNP	0301497	●
Sensor distributor		
V2-M8	0301775	●
V4-M8	0301746	
V8-M8	0301751	

- ① Two sensors are required per unit for monitoring two positions. On option, extension cables and sensor distributors are available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor system.

Programmable magnetic switch MMS 22-PI1



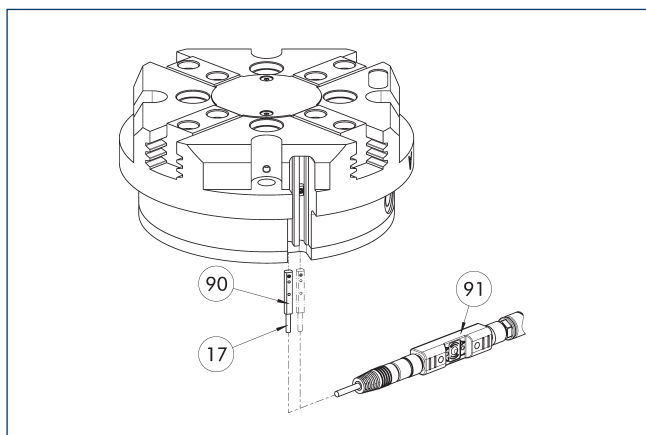
- ①⑦ Cable outlet
①⑨ Sensor MMS 22 ..-PI1-...-SA
①① Sensor MMS 22 PI1-...
①② Connector teaching tool ST

Position monitoring with one programmable switching point per sensor, directly mountable in the C-slot. The electronics are built into the sensor. The cable outlet can be located either axially or laterally (MMS 22...-SA). Programmed using the plug teaching tool ST (to be ordered separately).

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI1-S-M8-PNP	0301160	●
MMSK 22-PI1-S-PNP	0301162	
Programmable magnetic switch with lateral cable outlet		
MMS 22-PI1-S-M8-PNP-SA	0301166	●
MMSK 22-PI1-S-PNP-SA	0301168	
Programmable magnetic switch with stainless steel housing		
MMS 22-PI1-S-M8-PNP-HD	0301110	●
MMSK 22-PI1-S-PNP-HD	0301112	
Plug teaching tool		
ST-MMS 22-PI1-PNP	0301025	

- ① Two sensors (closer/S) are required for each unit and extension cables are available as an option.

Programmable magnetic switch MMS 22-PI2



17 Cable outlet

91 Connector teaching tool ST

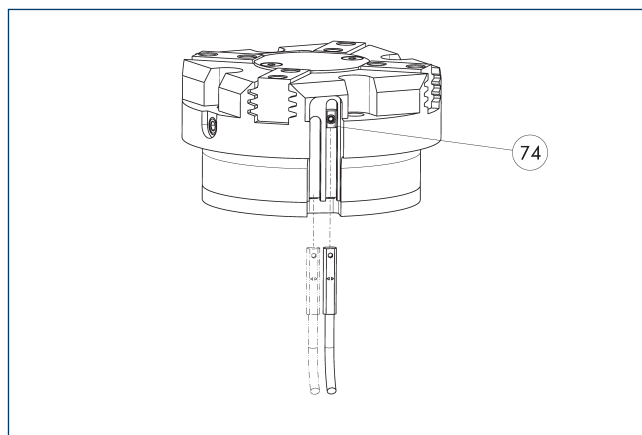
90 MMS 22...-PI2-... sensor

Position monitoring with two programmable switching points per sensor, mountable directly in the C-slot. The electronics are built into the sensor. Programmed using the plug teaching tool ST (to be ordered separately).

Description	ID	Often combined
Programmable magnetic switch		
MMS 22-PI2-S-M8-PNP	0301180	●
MMSK 22-PI2-S-PNP	0301182	
Programmable magnetic switch with lateral cable outlet		
MMS 22-PI2-S-M8-PNP-SA	0301186	●
MMSK 22-PI2-S-PNP-SA	0301188	
Programmable magnetic switch with stainless steel housing		
MMS 22-PI2-S-M8-PNP-HD	0301130	●
MMSK 22-PI2-S-PNP-HD	0301132	
Plug teaching tool		
ST-MMS 22-PI2-PNP	0301026	

- ① Per unit, at least one sensor (closer/S) and an optional cable extension are required. A maximum of one sensor per C-slot or sensor bracket can be mounted.

MMS-P programmable magnetic switch



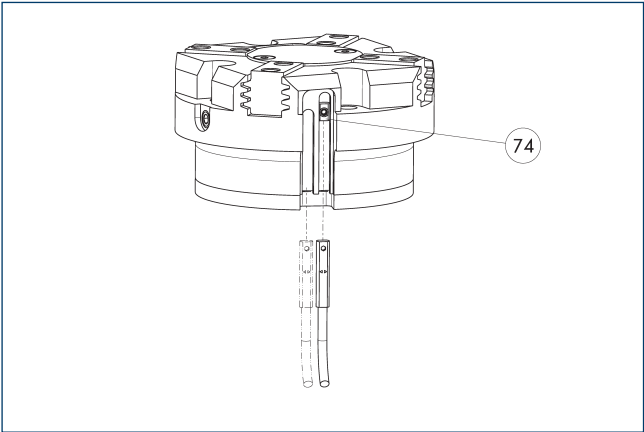
74 Limit stop for sensor

Position monitoring with two programmable positions per sensor. End position monitoring for mounting in the C-slot.

Description	ID	Often combined
Programmable magnetic switch		
MMSK-P 22-S-PNP	0301371	
MMS-P 22-S-M8-PNP	0301370	●
Connection cables		
KA GLN0804-LK-00500-A	0307767	●
KA GLN0804-LK-01000-A	0307768	
KA WLN0804-LK-00500-A	0307765	
KA WLN0804-LK-01000-A	0307766	
clip for plug/socket		
CLI-M8	0301463	
Sensor distributor		
V2-M8-4P-2XM8-3P	0301380	

- ① One sensor is required per unit for monitoring two positions. Extension cables and sensor distributors are optionally available. Additional product variants of the sensor, and further information and technical data can be found in the catalog chapter sensor systems.

Programmable magnetic switch MMS-I0-Link



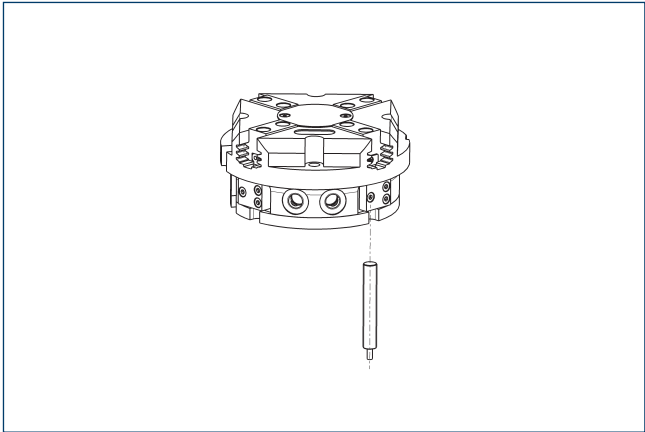
74 Limit stop for sensor

Sensor for multi-position monitoring through detection of the complete gripper stroke. The sensor is mounted directly in the C-slot of the gripper. Sensor programming on the gripper takes place via the IO-Link interface or the MT magnetic teach tool (included in scope of delivery). An IO-Link master is required for operation.

Description	ID	
Programmable magnetic switch		
MMS 22-I0L-M08	0315830	
MMS 22-I0L-M12	0315835	

- ① One sensor is required for each gripper. No additional mounting kit is required – the gripper is equipped for use of the sensor by default. Further information and technical data can be found in the catalog chapter sensor systems.

APS-Z80 analog position sensor

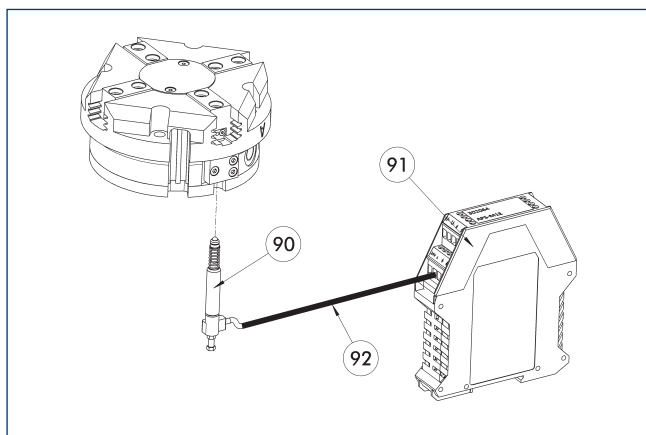


No-contact measuring, analog multi-position monitoring for any number of positions.

Description	ID	Often combined
Mounting kit for APS-Z80		
AS-APS-Z80-PGZN-plus 100-1	0302109	
Analog position sensor		
APS-Z80-K	0302072	
APS-Z80-M8	0302070	●

- ① When using an APS system, one mounting kit (AS-APS-Z80) and one APS-Z80 sensor is required per gripper. The resolution of the sensor can be lower in the peripheral areas of the gripper. You can find further information on the product in the operating manual.

APS-M1 analog position sensor



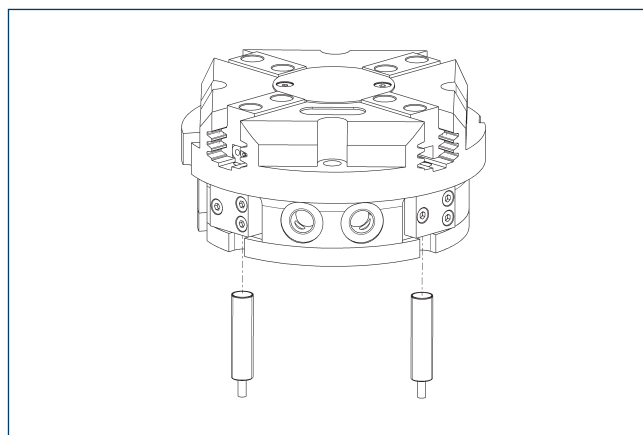
- 90 APS-M1S sensor
 91 APS-M1E electronic processor
 92 APS-K extension cable

Analog multi position monitoring for any desired positions

Description	ID	
Mounting kit for APS-M1		
AS-APS-M1-PGZN-plus 100-1	0302079	
Analog position sensor		
APS-M1S	0302062	
Connection cables		
APS-K0200	0302066	
APS-K0700	0302068	
Evaluation electronics		
APS-M1E	0302064	

- ⓘ When using an APS system, for each gripper an attachment kit (AS-APS-M1), an APS-M1S sensor (incl. 3 m cable) as well as an electronics (APS-M1e) are required. An extension cable (APS-K) can be connected between the sensor and the electronics as an option. The max. cable length between the sensor and the electronics is 10 m, between the electronics and their control unit (PLC) it is max. 1 m.

Cylindrical reed switches



End position monitoring can be mounted with an attachment kit.

Description	ID	
Attachment kit for proximity switch		
AS-RMS 80 PGN/PZN-plus 100/125	0377726	
Reed Switches		
RMS 80-S-M8	0377721	

- ⓘ Two sensors (closer/S) are required for each unit and extension cables are available as an option. This attachment kit needs to be ordered optionally as an accessory. Two mounting kits are required for each gripper. For sensor cables, note the minimum permissible bending radii. These are generally 35 mm.



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