# DBS series

## -The situation needs DC power control

- Page

   61
   Specifications and characteristics of Motor/Driver
- 62 Gearhead specifications & allowable speed range/allowable torque/allowable inertia load (GD<sup>2</sup>)

TROY

- 63 Motor allowable radial load/axial load
- 64 Speed Torque characteristic diagrams
- 65 Driver panel functions and wiring instructions
- 66 Motor electromagnetic brake wiring instructions
- 67 Dimensions Motor/Gearhead
- 69 Dimensions Driver
- 69 Dimensions Variable resistor



DC Brushless Motor-DBS series

### Specifications and characteristics of Motor/Driver

Mote	or out	put po	wer	20W	40W	60W	100W	
Rour	nd sha	ft Motor	(M: E/M brake type)	6B020S-D(M)	6B040S-D(M)	9B060S-D(M)	9B100S-D(M)	
Pinic	on shaf	ft Motor	(M: E/M brake type)	6B020P-D(M)	6B040P-D(M)	9B060PD-D(M) 9B060PH-D	9B100PD-D(M) 9B100PH-D	
Motor	r specif	ication ce	ertificate		RoHS	● ※9B060PH-D > 9B100F	PH-D no RoHS certificate	
Drive	r			DBD020-D	DBD040-D	DBD060-D	DBD100-D	
Drive	ver specification certificate				C	E		
nput			Current Min.(A)	2	4	6	10	
ower oltage	DC23	~26V	Rated current(A)	1.48	3.65	4.37	6.73	
Startir	arting Torque (Nm)			0.08	0.16	0.25	0.4	
Rated	l Torque	e (Nm)		0.07	0.14	0.2	0.33	
Allow	able lo	ad inertia	a GD <sup>2</sup> (Kgcm <sup>2</sup> )	4.78	9.55	11.3	20.8	
	× Ir	nput pow	er voltage(V)	DC	24	DC	:24	
orake ⊑/M	Only eries	onsumpt	ion power(W)	6	.5	7.	5	
D L L	E/M			0.3 0.5				
Ð	e EN		. ,		0			
				8				
• • • •			. ,					
					)r / min, no-load ~rated loa			
			Ū.		0			
			to temperature					
Slow start/Slow down time set up Speed control method			n time set up					
			d	•Controlling by internal	al variable resistor (resist variable resistor value tternal variable resistor fo	20KΩ) •Can be used wit	/1mÀ or mo	
Signa	al input	/output n	nethod	<ul><li>Photo coupler(PHOTO</li><li>Open collector transister</li></ul>	COUPLER) or circuit(OPEN COLLEC	6       10         4.37       6.73         0.25       0.4         0.2       0.33         11.3       20.8         DC24         7.5         0.5         33         95         0-3000         load         //± 10%, while in 3000r / min with no load         min, while no load         ~ 3000r / min, while no load         0.2 or r/ min, while no load         0.2 or transistor type, relay-style I / O modules         que output (FLAT TORQUE)         (SLOW START/SLOW DOWN)         s of situation:         t signal output         torque of Motor running more than 7 seconds, er voltage less than about 20%, it operates         isconnected, it operates         isconnected, it operates		
Func	tion			•Within speed control ra	nge, Motor constant torqu op, slow start/slow stop (		)	
Prote	The second se	<ul> <li>Protection function will be the following two kinds of situation:</li> <li>Motor will naturally stop, Driver ALARM contact signal output</li> <li>Overload Protection: Exceeding the rated torque of Motor running more than 7 seconds, it operates</li> <li>Low voltaage Protection: Driver input AC power voltage less than about 20%, it operates</li> <li>Offline Protection: When Motor cable disconnected, it operates</li> <li>disconnect power supply of internal controller, POWER light goes out</li> <li>Over voltage protection: When Driver input DC power voltage exceeds about 25%, it operates</li> </ul>						
				polarity				
nsulation mpedance				above 100MO Between coil and casing	, through to AC 1.8KV / 6	0Hz high pressure, sustai	ned 1sec,	
	1000			no abnormal condition				
			Driver	Between power input te no abnormal condition	rminal and cabinet, throug	gh to AC 0.5KV / 60Hz hig	h pressure, for 1 minute,	

\*1 Nm=10.19716 Kgcm



#### Gearhead specifications & allowable speed range/allowable torque/allowable inertia load (GD<sup>2</sup>)

Gea	r ratio	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30	
peed range	High speed	1000	883	600	500	400	333	300	240	200	166	150	120	100	
(r/min)	Low speed	83.4	69.5	50	41.7	33.4	27.8	25	20	16.7	13.9	12.5	10	8.4	
llowable rque (Nm)	6B020P-D(M) + 6D□	0.18	0.21	0.29	0.35	0.44	0.53	0.59	0.73	0.88	1.1	1.2	1.4	1.7	-
llowable ine	rtia load GD <sup>2</sup> (kgcm <sup>2</sup> )	2.25	3.24	6.25	9.00	14.1	20.3	25.0	39.1	56.3	81.0	100	156	225	
llowable rque (Nm)	6B040P-D(M) + 6D□	0.35	0.42	0.59	0.7	0.88	1.1	1.2	1.5	1.8	2.1	2.3	2.8	3.4	
llowable ine	rtia load GD <sup>2</sup> (kgcm <sup>2</sup> )	4.50	6.48	12.5	18.0	28.1	40.5	50.0	78.1	113	162	200	313	450	
Allowable rque (Nm)	9B060PD-D(M) + 9D□	0.54	0.65	0.9	1.1	1.4	1.6	1.8	2.3	2.7	3.2	3.6	4.3	5.2	
llowable iner	tia load GD <sup>2</sup> (kgcm <sup>2</sup> )	18.0	25.9	50.0	72 <u>.</u> 1	113	162	200	313	450	649	801	1251	1802	
Allowable orque (Nm)	9B060PH-D + 9D⊡H	0.54	0.65	0.9	1.1	1.4	1.6	1.8	2.3	2.7	3.2	3.6	4.3	5.2	
lowable iner	tia load GD <sup>2</sup> (kgcm <sup>2</sup> )	181	260	501	722	1128	1624	2006	3134	4512	6498	8022	12534	18050	
Allowable rque (Nm)	9B100PD-D(M) + 9D□	0.89	1.1	1.5	1.8	2.2	2.7	3.0	3.7	4.5	5.3	5.9	7.1	8.5	
lowable iner	tia load GD <sup>2</sup> (kgcm <sup>2</sup> )	33.3	48.0	92.5	133	208	300	370	578	832	1199	1480	2312	3330	
Allowable rque (Nm)	9B100PH-D + 9D⊡H	2.2	2.6	3.6	4.3	5.4	6.5	7.2	9	10.8	13	14.4	17.2	20.6	
llowable iner	tia load GD <sup>2</sup> (kgcm <sup>2</sup> )	181	260	501	722	1128	1624	2006	3134	4512	6498	8022	12534	18050	
Gear	<sup>-</sup> ratio	36	50	60	75	90	100	120	150	180	200	250	300	360	
	High speed	83	60	50	40	33	30	25	20	16	15	12	10	8	
peed range (r/min)	Low speed	7	5	4.2	3.4	2,8	2.5	2.1	1.7	1.4	1.3	1	0.9	0.7	
Allowable orque (Nm)	6B020P-D(M) + 6D□	2	2.8	3.4	4.2	5	5.6	6.3				.5			
lowable iner	tia load GD <sup>2</sup> (kgcm <sup>2</sup> )	324			625						625				
Allowable orque (Nm)	6B040P-D(M) + 6D□	4	5.6		6	.5					6.5				
llowable iner	tia load GD <sup>2</sup> (kgcm <sup>2</sup> )			62	25						625				
Allowable rque (Nm)	9B060PD-D(M) + 9D□	6.2	8.6	10.3	12.9	15.5	17.2	19.4	24.3	29.2	32.4		40		
llowable iner	tia load GD <sup>2</sup> (kgcm <sup>2</sup> )	2594	5004	7206		11000					11000				
Allowable orque (Nm)	9B060PH-D + 9D⊡H	6.2	8.6	10.3	12.9	15.5	17.2	19.4	24.3	29.2	32.4		40		
llowable ine	rtia load GD <sup>2</sup> (kgcm <sup>2</sup> )	25991			45000						45000				
Allowable rque (Nm)	9B100PD-D(M) + 9D□	10.2	14.2	17	21.3	25.5	28.4	32.1			40				
lowable iner	tia load GD <sup>2</sup> (kgcm <sup>2</sup> )	4795	9249		11(	000					11000				
Allowable orque (Nm)	9B100PH-D + 9D⊡H	24.8	34.4	41.3		50					50				
llowable ine	rtia load GD <sup>2</sup> (kgcm <sup>2</sup> )	25991			45000						45000				

\* Gearhead 6D□/9D□/9D□H, please fill gear ratio in □.

\* In above table stands for after installation of Gearhead, the axis rotation is reversed with Motor axis direction; without marking stands for the same direction as Motor axis rotation.

\*1 Nm=10.19716 Kgcm

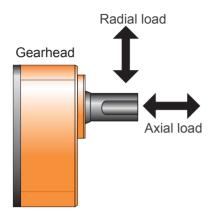
\* In addition to Gearhead 9D H120~360 without Rolls) certificate, other series of Gearhead have Rolls) certificate

\* Also available orthogonal Gearhead: hollow shaft type  $9VD\Box(H)$ , the solid single shaft type  $9VD\Box A(H)$ , the solid biaxial shaft type  $9VD\square B(H)$ , and size please refer to P.10.

Accessories Motor selection



#### Motor allowable radial load/axial load



- 1 Radial load (hanging load): loading is vertical to Gearhead axis power output
- (2) Axial load (thrust load): loading is in the direction of Gearhead axis power output

#### Round shaft type

Model	Permissible overhui	Permissible thrust load			
Model	10mm from output shaft front	20mm from output shaft front	(Unit: Kg f)		
6B020S-D(M)	8	9	Permissible axial loading, not more than 1/2 of Motor weight. But please try to avoid applying		
6B040S-D(M)	8	9	force in the horizontal direction (axial) of motor shaft, when exceeds that will reduce Motor		
9B060S-D(M)	16	17	service life. If axial loading is needed, we recommend applying indirect		
9B100S-D(M)	16	17	transmission, such as: couplings, belts, chains, etc		

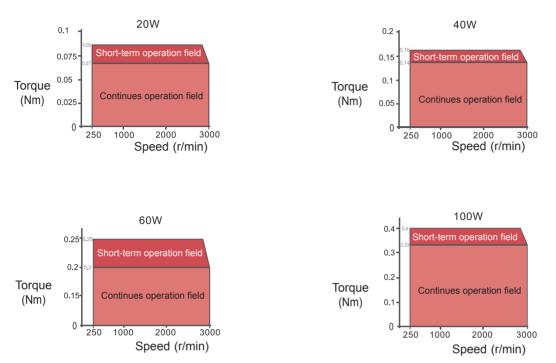
#### Pinion shaft type (Gearhead attached)

Model	Gear ratio	Permissible overhur	Permissible thrust load		
Model		10mm from output shaft front	20mm from output shaft front	(Unit: Kg f)	
6B020P-D(M)	3, 3.6, 5	10	15		
+ 6D□ 6B040P-D(M)	6, 7.5, 9, 10, 12.5, 15,18, 20	15	20	4	
+ 6D	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	20	30		
9B060PD-D(M)+9D□	3, 3.6, 5	30	40		
9B060PH-D+9D⊟H 9B100PD-D(M)+9D⊟	6, 7.5, 9, 10, 12.5, 15,18, 20	40	50	15	
9B100PH-D+9D□H	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	50	65		

\* Gearhead 6D□/9D□/9D□H, please fill gear ratio in□

TRSY- Characteristics Product index Product names Product weight of Motor Gearhead Installation Certificates **Technical Information** Model naming \_ m ≥ ∽ B S S B S U B S 

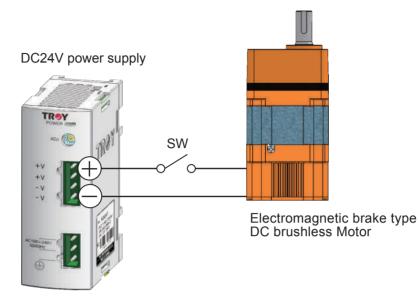
#### Speed - Torque characteristic diagrams



Brushless Motor **DBS** series Driver panel functions and DC24V wiring instructions +24V 1 GND ALARM POWER 3 2 SPEED 4 SS 5 SD Œ 6 7 ON : Internal speed setting /OFF : External speed setting EXT/INT-SP ٦O STOP/RUN ON : Start /OFF : Stop Ċ ON : Instantaneous brake stop/OFF : Brake release 8 9 10 BRAKE 6 CW/CCW ON : Counterclockwise operation/OFF : Clockwise operation 6 Trigger ON: Relieve abnormal warning signal A.R. MOTOR  $\overline{}$ 0 SPEED OUT(+) S.O. 0 0 ALARM OUT(+) 12 17 A.O. 13 VR-H **\_\_**\_ 0 14 15 VR-M **∍**-0  $\odot$ ⊳-0 VR-L 16 -COM External variable resistor H.M.L signal isolation line metal mesh, please contact FG -COM -(More detail seeing instructions)

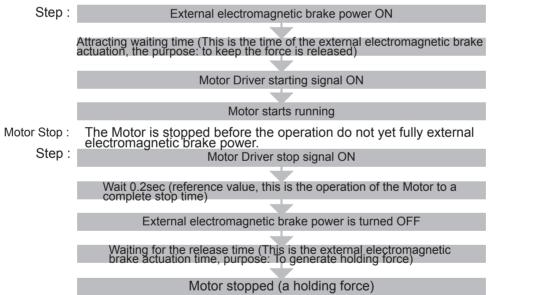
Number	Panel marked	Function	Explanation
1	+24V \ GND	DC power voltage input terminal	DC power voltage input connection
2	POWER	Power indicator	LED (green) lights when input power
3	ALARM	Unusual indicator	Overload, low voltage, disconnection any protective function is activated LED (red) lights
4	SPEED	Internal speed setting button	20 ~ 100W speed control range: 250 ~ 3000r/min
5	SS/SD	Slow start, stop time setting button	Slow start 0.5 ~ 10 sec; slow stop 0.5 ~ 5 sec
6	EXT/INT-SP	Speed setting switch to select the input mode	External/internal speed setting mode switch selection
7	STOP/RUN	Stop/start signal input	Stop/start signal switch input
8	BRAKE	Instantaneous brake stop signal input	Executive instantaneous brake stop / brake release signal switch input
9	CW/CCW	The direction of rotation switch to select input	CW/CCW operation switch selection
10	A.R.	Abnormal warning signal release input	A.R. trigger input contacts (Length "L" state 10ms) to release the error of warning signal
11	S.O.	Speed signal output	Using while monitoring Motor speed, digital signal output 12Pulse/rev
12	A.O.	Abnormal warning signal output	Overload, low voltage, disconnection any protective function is activated, Motor stops naturally, and outputs an abnormality warning signal.
13	VR-H		
14	VR-M	Motor wiring connector	An external connection terminal variable resistor or external DC voltage (0 ~ 5V) control of speed control range: 250 ~ 3000r / min
15	VR-L		
16	-COM	Control signal grounding	GND contact inputs and outputs a control signal common ground wire, and the external DC power contact
17	MOTOR	Motor wiring connector	Motor and Driver connection

#### Electromagnetic brake wiring instructions



♦ Operation instruction

Motor start/Motor stop with external electromagnetic brake operating procedures: Motor start: Must energize external electromagnetic brake before the Motor starts



#### Precautions

1. This series of external electromagnetic brake using the brake power is part of the hold-type. 2. External electromagnetic brake is designed to allow the Motor stops when the holding force has to be used as a safety brake, electromagnetic brake, do not use this as a Motor positioning or emergency brake applications.

3. Always to pull the Motor before starting the external electromagnetic brake energized (means no brakes); Motor stopped before the operation do not yet fully external electromagnetic brake power (expressed brakes).

4.External electromagnetic brake suction time and release time value refer to the product specification. 5.Motor brakes to stop for about 0.2sec (test conditions in the Motor no-load speed 3000r / min, the electromagnetic brake is energized, the brake actuator signal ON time of the Driver, this time as a reference base, but the actual length of time will stop according to the inertia load or frictional load ... different load patterns and has fluctuated.

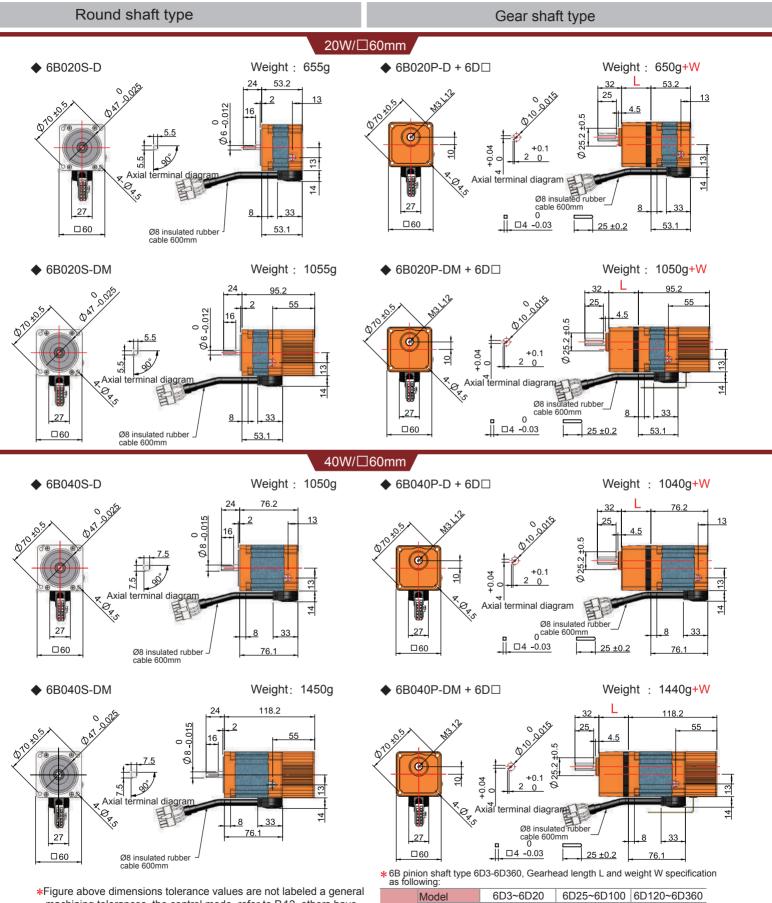
6.We recommend to do the actual measuring device operating time at the time of commissioning.

Brushless

**DBS** series

#### Dimensions - Motor/Gearhead

Unit : mm



39.5

300

ad Length L (mm

Weight W (g)

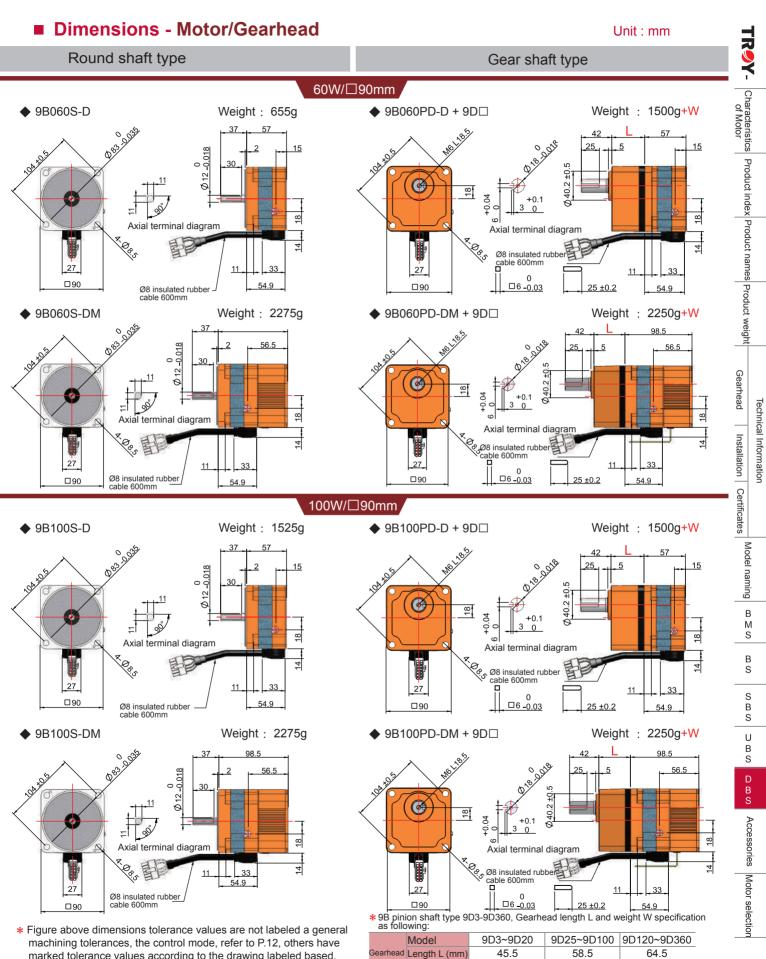
39.5

325

43.5

365

Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.



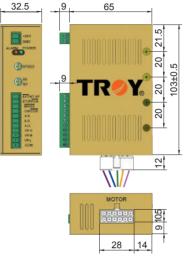
Weight W (g)

marked tolerance values according to the drawing labeled based.

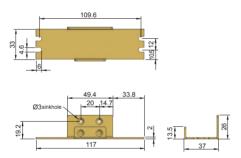


#### Dimensions - Driver

Model : DBD020-D / DBD040-D Dimensions Weight : 210g are common

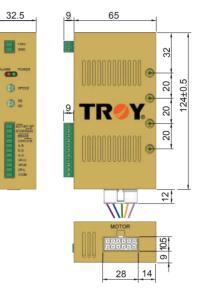


#### Mounting sheet

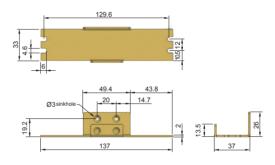


Model : DBD060-D / DBD100-D Dimensions Weight : 290g

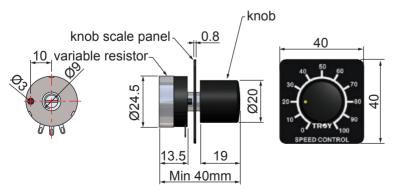
Unit : mm



Mounting sheet



#### Dimensions - Variable resistor



\* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

Weight: 30g

Machanism:	[Operating of I	arge ind	ex table					Date dd/mr	n / yy	
Company name:		Contact	person:			Departr	artment/Title:			
TEL:	FAX:		1	Application:			Use a	rea:		
Power input: □S	ingle -phase AC:	V 🗆	Three -p	hase AC: _	V	DC:	V	Frequency:	Hz	
Activated mode:	□Single direction □Regulated special □Single direction stop time:S □Clockwise/courses Stop:Secons Stop:Secons	eed (Ran n run s Second/S inter cloc nd/Seque	ge: rp top 、run Sequence kwise rej ence 、C(	$\sim \_ rpm$ $\sim stop \rightarrow (A)$ $\Rightarrow; Run, stop$ peated $\rightarrow (a)$	1) Activa total CW:	ated time Sequ Seco	e: S ience / ond/Se	/Minutes)	ence,	
Required motor:	AC induction mot Torque DC brushless mo DBS Series Stepping motor:	otor: 🗆 BN	AS Series	s ⊡BS Seri	ies [			-		
[Mechanism re	ference ]		-	sketch you mechanism		ual trans	smissio	on		
	DT Object W									
		1								
L'Drive mechani	sm and operating	uala			_	1				
	Object mass Index table diam	eter				kg cm				
	Width			Lt :	=	cm				
	Material			ρ =	=					
	Positioning angle	e *(no	te)	$\theta$ =	=	deg				
	Positioning time	*(no	te)	To =	=	sec				
	Stopping accura	су		:	±	mm				
	*(note)Please en	ter the m	ax speed	t						
		- <b>t</b>	> ·							
Recommendation	n products (Sele	cted spe	cs ) :							

After complete above information, please fax it to nearby regional business office, we will select applicable product for you as soon as possible

Technical Information

Motor selection

				L	Date dd / mm	/ уу
Company name:	Contact person:		Departi	ment/Tit	tle:	
TEL: FAX:		Application:		Use a	rea:	
Power input: Single -phase AC:	V □Three	-phase AC: V	□DC	: <u>V</u>	Frequency:	Hz
stop time: □Clockwise/cou Stop: Secc	eed (Range: on run stop sru Second/Sequen unter clockwise		vated tin al Sec : Sec	me: quence cond/Se	/Minutes)	ence,
□DBS Series	otor: □BMS Ser	□Reversible □S ies □BS Series phase □5 phase	□SBS		-	
[Mechanism reference]		【Please sketch part of mecha		ctual tra	ansmission	
[Drive mechanism and operating	g data ]					
Work+Table mass Screw angle Screw shaft diameter Screw Length Screw pitch Material Screw efficiency	$W = \underline{kg}$ $\alpha = \underline{deg}$ $D_B = \underline{cm}$ $L_B = \underline{cm}$ $P_B = \underline{cm}$ $\rho = \underline{cm}$ $\eta = \underline{cm}$	sliding surfaces Positioning dist Positioning time Push / Pull forc	s tance e ce	*(note)	L =0 To =s	cm sec kg
Internal frictional coefficient of pilot pressure nut	μυ=	*(note)Please	enter th	e max s	speed	

\* After complete above information, please fax it to nearby regional business office, we will select applicable product for you as soon as possible

TROY- Characteristics Product index Product names Product weight of Motor

Gearhead

Installation Certificates

Model naming

B M S

> B S

> S B S

> U B S

> D B S

> Motor selection

Technical Information

Machanism:	Belt and pulle	y]					D	ate dd / mn	n / yy
Company name:		Contact p	erson:			Departr	nent/Tit	ile:	
TEL:	FAX:			Application:			Use ar	rea:	
Power input: DSing	gle -phase AC:	V 🛛	Three	-phase AC:	V		V	Frequency:	Hz
Γ	Regulated special Single direction stop time: Clockwise/con Stop: Seco	eed (Rang on run st Second/So unter clock	ge: op 、 ru equent kwise r ence 、	rpm ~ rpi In 、 stop $\rightarrow$ ( ce; Run, stop repeated $\rightarrow$ (	m) (Activ o tota (CW	vated tir al Sec : Sec	ne: S quence cond/Se	/Minutes)	uence,
	C induction mo ITorque C brushless m IDBS Series tepping motor:	otor: □BN	1S Ser	ies	ries	-		-	
(Mechanism refer	Dbject Belt LP1	Motor	_	ase sketch y : of mechanis		ictual tra	ansmiss	sion	
[Drive mechanisn	n and operating	g data ]							
Work + Table + I	Pulley W =	kg	Belt 、	pulley efficie	ncy			η =	
Screw angle	α =	deg	frictior	al coefficien	t of s	liding su	urfaces	μ =	
Pulley diameter	D <sub>P</sub> 1 =	cm	Positio	oning distand	e *(r	ote)		L =	cm
Width	Lp1 =	cm	Positio	oning time *(	note)	1		To=	sec
Material	ρ1 =			Pull force				F <sub>A</sub> =	kg
Pulley diameter	Dp2 =	cm	Stoppi	ng accuracy				±	mm
Width	Lp2 =								
Material	ρ2 =		*(note)	Please ente	r the	max sp	eed		
Recommendation p	products (Sele	cted spec	s) :						

\* After complete above information, please fax it to nearby regional business office, we will select applicable product for you as soon as possible

TROY- Characteristics Product index Product names Product weight of Motor

Gearhead

Installation Certificates

Model naming

B M S

B S

SBS UBS DBS Accessories

Motor selectior

Technical Information

■Machanism:	[Others]	_			D	ate dd/mm	/ yy
Company name:		Contact person		Departme	ent/Tit	ile:	
	FAX:		Application:	L	Jse ar	rea:	
Power input: □Si	ngle -phase AC	C:V □Three	-phase AC:V		V	Frequency:	Hz
Activated mode:	□Regulated sp □Single direct stop time: □Clockwise/co Stop: Sec	ion operating con peed (Range: ion run 、stop 、ru Second/Sequen ounter clockwise cond/Sequence、 quence/Minute)	rpm ~ rpm ) un 、 stop $\rightarrow$ (Acti ce; Run, stop tota repeated $\rightarrow$ (CW	vated time alSeque ':Secor	e: S ence / nd/Se	/Minutes)	ence,
	□Torque DC brushless n □DBS Series	otor: □Induction notor: □BMS Ser r: □2 phase □3	ies □BS Series	⊡SBS Se		C C	
-	•	ng data ] : Use t ating conditions r	•				
Recommendation	n products(Se	lected specs):					
* After complete applicable proc		tion, please fax it soon as possible	to nearby regiona	al busines:	s offic	e, we will sel	ect

**TR/Y**- Characteristics Product index Product names Product weight of Motor

Gearhead

Installation Certificates

Model naming

B M S

> B S

S B S U B S D B S

Motor selection

Technical Information