AC Servomotors [1S-series with Safety Functionality]

R88M-1AL /-1AM

Contents

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- Specifications
- Names and Functions
- External Dimensions



Ordering Information

Refer to the Ordering Information.

Specifications

General Specifications

	Item		Specifications		
Operating am humidity	bient temperature	and	0 to 40°C 20% to 90% (with no condensation)		
Storage ambie	ent temperature an	d humidity	-20 to 65°C 20% to 90% (with no condensation)		
Operating and	l storage atmosphe	ere	No corrosive gases		
Vibration resi	stance *		Acceleration of 49 m/s ² 24.5 m/s ² max. in X, Y, and Z directions when the motor is stopped		
Impact resista	ince		Acceleration of 98 m/s ² max. 3 times each in X, Y, and Z directions		
Insulation res	istance		Between power terminals and FG terminals: 10 MΩ min. (at 500 VDC Megger)		
Dielectric stre	ngth		Between power terminals and FG terminals: 1,500 VAC for 1 min (voltage 200 V) Between power terminals and FG terminals: 1,800 VAC for 1 min (voltage 400 V) Between brake terminal and FG terminals: 1,000 VAC for 1 min		
Insulation class	ss		Class F		
Protective str	ucture		IP67 (except for the through-shaft part and connector pins)		
International	EU Directives and UK legislation	Low Voltage	EN 60034-1/-5		
standard	UL standards		UL 1004-1/-6		
	CSA standards		CSA C22.2 No.100 (with cUR mark)		

^{*}The amplitude may be increased by machine resonance. As a guideline, 80% of the specified value must not be exceeded.

Note: 1. Do not use the cable when it is laying in oil or water.

Encoder Specifications

Item	Specifications			
Encoder system	Optical batteryless absolute encoder			
Resolution per rotation	20 bits			
Multi-rotation data hold	12 bits			
Output signal	Serial communications			
Output interface	RS485 compliant			

Note: It is possible to use an absolute encoder as an incremental encoder.

Refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and Safety Functionality User's Manual (Cat.No.I621) for details.

^{2.} Do not expose the cable outlet or connections to stress due to bending or its own weight.

Characteristics

3,000-r/min Servomotors

			Model (R88M-)	200 VAC			
	Item		Unit	1AM20030T	1AM40030T	1AM75030T	
Rated output *	1*2		W	200	400	750	
Rated torque *	1*2		N·m	0.637	1.27	2.39	
Rated rotation	speed *1*2		r/min		3000		
Maximum rotat	ion speed		r/min		6000		
Momentary max	ximum torq	ue *1*3	N·m	2.2 *4	4.5 *4	8.4 *4	
Rated current *	*1 *2		A(rms)	1.5	2.5	4.6	
Momentary max	ximum curre	ent *1	A(rms)	5.6	9.1	16.9	
D - 4 ! 4! -		Without brake	×10 ⁻⁴ kg·m ²	0.224	0.446	1.825	
Rotor inertia		With brake	×10 ⁻⁴ kg·m ²	0.284	0.506	2.075	
Applicable load	l inertia		×10 ⁻⁴ kg·m ²	4.80	8.40	19.4	
Torque constar	nt *1		N·m/A(rms)	0.48	0.56	0.59	
Power rate *1*	:5		kW/s	18.1	36.2	31.3	
Mechanical tim	e constant :	* 5	ms	0.79	0.58	0.66	
Electrical time	constant		ms	2.4	2.6	3.3	
Allowable radia	I load *6		N	245	245	490	
Allowable thrus	st load *6		N	88	88	196	
Without brake		out brake	kg	1.3	1.8	3.2	
Weight	With	brake	kg	1.7	2.2	4.1	
Radiator plate o	dimensions	(material)	mm		250 × 250 × t6 (aluminum)		
	Excitation	voltage *8	V	24 DC ±10%			
	Current consumption (at 20°C)		Α	0.32	0.32	0.37	
	Static friction torque		N·m	1.37 min.	1.37 min.	2.55 min.	
	Attraction	time	ms	30 max.	30 max.	40 max.	
	Release tii	me * 9	ms	20 max.	20 max.	35 max.	
Dunka	Backlash		۰	1.2 max.	1.2 max.	1.0 max.	
Brake specifications	Allowable	braking work	J	60	60	250	
*7	Allowable	total work	J	60,000	60,000	250,000	
	Allowable acceleration		rad/s²		10,000 max.		
	Brake lifetime (acceleration/ deceleration)			10 million times min.			
	Brake lifet (ON/OFF),				1 million times min.		
	Insulation	class			Class F		

For models with an oil seal the following derating is used due to increase in friction torque.

Model (R88M-)		1AM20030T-O/	1AM40030T-O/	1AM75030T-O/
Item	Unit	-OS2/-BO/-BOS2	-OS2/-BO/-BOS2	-OS2/-BO/-BOS2
Derating rate	%	95	80	90
Rated output	W	190	320	675
Rated current	A (rms)	1.5	2.1	4.2

` '			Model (R88M-)	200 VAC				
	Item		Unit	1AL1K030T	1AL1K530T	1AL2K030T	1AL2K6307	
Rated output *	1*2		w	1,000	1,500	2,000	2,600	
Rated torque *	1*2		N·m	3.18	4.77	6.37	8.28	
Rated rotation	speed *1*2		r/min		3,0	000		
Maximum rotat	ion speed		r/min		5,0	000		
Momentary max	ximum torque	*1*3	N·m	9.55	14.3	19.1	24.8	
Rated current *	*1 *2		A(rms)	5.2	8.8	12.5	14.8	
Momentary max	ximum current	: *1	A(rms)	16.9	28.4	41.0	47.3	
Rotor inertia	W	/ithout brake	×10 ⁻⁴ kg·m ²	2.105	2.105	2.405	6.813	
Rotor mertia	W	/ith brake	×10 ⁻⁴ kg·m ²	2.555	2.555	2.855	7.313	
Applicable load	l inertia		×10 ⁻⁴ kg·m ²	35.3	47.6 60.2		118	
Torque constar	nt *1		N·m/A(rms)	0.67	0.58	0.56	0.62	
Power rate *1*	:5		kW/s	48	108	169	101	
Mechanical tim	e constant *5		ms	0.58	0.58	0.50	0.47	
Electrical time	constant		ms	5.9	6.1	6.4	11	
Allowable radia	l load *6		N	490				
Allowable thrus	st load *6		N	196				
Majaht	Withou	t brake	kg	5.8	5.8	6.5	11.5	
weight	Weight With brake		kg	7.5	7.5	8.2	13.5	
Radiator plate of	dimensions (m	aterial)	mm	400 × 400 × t	20 (aluminum)	470 × 470 × t	20 (aluminum)	
	Excitation vo	ltage *8	V		24 VD	C±10%		
	Current cons (at 20°C)	sumption	Α	0.70	0.70	0.70	0.66	
	Static friction	n torque	N·m	9.3 min.	9.3 min.	9.3 min.	12 min.	
	Attraction tin	ne	ms	100 max.	100 max.	100 max.	100 max.	
	Release time	*9	ms	30 max.	30 max.	30 max.	30 max.	
Brake	Backlash		۰	1.0 max.	1.0 max.	1.0 max.	0.8 max.	
specifications	Allowable bra	aking work	J	500	500	500	1000	
*7	Allowable to	tal work	J	900,000	900,000	900,000	3000,000	
	Allowable an acceleration	gular	rad/s²		10,000	0 max.		
	Brake lifetime (acceleration	e / deceleration)			10 million	times min.		
	Brake lifetime (ON/OFF), B1	~			1 million t	times min.		
	Insulation cla	ass			Cla	ss F		

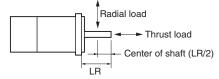
Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

Model (R88M			Model (R88M-)	AC400V				
	Item		Unit	1AL75030C	1AL1K030C	1AL1K530C		
Rated output *	1*2		w	750	1,000	1,500		
Rated torque *	1*2		N·m	2.39	3.18	4.77		
Rated rotation	speed *1*2		r/min	<u> </u>	3,000			
Maximum rotat	ion speed		r/min		5,000			
Momentary max	ximum torq	ue *1*3	N·m	7.16	9.55	14.3		
Rated current 3	×1 * 2		A(rms)	3.0	3.0	4.5		
Momentary max	ximum curr	ent *1	A(rms)	9.6	9.6	14.1		
Doton in outin		Without brake	×10 ⁻⁴ kg·m ²	1.305	2.105	2.105		
Rotor inertia		With brake	×10 ⁻⁴ kg·m ²	1.755	2.555	2.555		
Applicable load	l inertia		×10 ⁻⁴ kg·m ²	38.6	35.3	47.6		
Torque constar	nt *1		N·m/A(rms)	0.91	1.17	1.17		
Power rate *1*	:5		kW/s	44	48	108		
Mechanical tim	e constant :	*5	ms	1.1	0.58	0.58		
Electrical time	constant		ms	4.3	5.9	5.9		
Allowable radia	I load *6		N		490			
Allowable thrus	st load *6		N	196				
Weight	With	out brake	kg	4.2	5.8	5.8		
weight	With	brake	kg	5.9	7.5	7.5		
Radiator plate	dimensions	(material)	mm	305 × 305 × t20 (aluminum)	400 × 400 × t2	0 (aluminum)		
	Excitation	voltage *8	V	24 VDC±10%				
	Current consumption (at 20°C)		Α	0.70	0.70	0.70		
	Static frict	ion torque	N·m	9.3 min.	9.3 min.	9.3 min.		
	Attraction	time	ms	100 max.	100 max.	100 max.		
	Release ti	me * 9	ms	30 max.	30 max.	30 max.		
Brake	Backlash		o	1.0 max.	1.0 max.	1.0 max.		
specifications	Allowable	braking work	J	500	500	500		
*7	Allowable	total work	J	900,000	900,000	900,000		
	Allowable acceleration		rad/s²		10,000 max.			
	Brake lifet (accelerati	ime ion/ deceleration)			10 million times min.			
	Brake lifet (ON/OFF),				1 million times min.			
	Insulation	class			Class F			

Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

			Model (R88M-)	AC	400V	
	Item		Unit	1AL2K030C	1AL3K030C	
Rated output *1*2		W	2,000	3,000		
Rated torque *	1*2		N·m	6.37	9.55	
Rated rotation s	speed *1*2		r/min	3.	,000	
Maximum rotati	on speed		r/min	5	,000	
Momentary max	cimum torq	ue *1*3	N·m	19.1	28.7	
Rated current *	1*2		A(rms)	6.3	8.7	
Momentary max	cimum curre	ent *1	A(rms)	19.8	27.7	
D - 4 141 -		Without brake	×10 ⁻⁴ kg·m ²	2.405	6.813	
Rotor inertia		With brake	×10 ⁻⁴ kg·m ²	2.855	7.313	
Applicable load	inertia		×10 ⁻⁴ kg·m ²	60.2	118	
Torque constan	ıt *1		N·m/A(rms)	1.15	1.23	
Power rate *1*	5		kW/s	169	134	
Mechanical time	e constant :	* 5	ms	0.52	0.49	
Electrical time of	constant		ms	6.3	11	
Allowable radia	l load *6		N	490		
Allowable thrus	t load *6		N	196		
A/ - ! - ! - 4	With	out brake	kg	6.5	11.5	
Neight	With	brake	kg	8.2	13.5	
Radiator plate d	limensions	(material)	mm	470 × 470 × t20 (aluminum)		
	Excitation	voltage *8	V	24 VDC±10%		
	Current consumption (at 20°C)		Α	0.70	0.66	
	Static frict	ion torque	N·m	9.3 min.	12 min.	
	Attraction	time	ms	100 max.	100 max.	
	Release tii	me * 9	ms	30 max.	30 max.	
Dunka.	Backlash		۰	1.0 max.	0.8 max.	
Brake specifications	Allowable	braking work	J	500	1,000	
* 7	Allowable	total work	J	900,000	3,000,000	
	Allowable acceleration		rad/s²	10,00	00 max.	
	Brake lifet (accelerati	ime on/ deceleration)		10 millior	n times min.	
	Brake lifet (ON/OFF),			1 million	times min.	
	Insulation	class		Cla	ass F	

- *1. This is a typical value for when the Servomotor is used at a normal temperature (20°C, 65%) in combination with a Servo Drive.
- *2. The rated values are the values with which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
- *3. The momentary maximum torque is approximately 300% of the rated torque, except for some models.
- *4. The momentary maximum torque is approximately 350% of the rated torque. Output at the momentary maximum torque shortens detection time of the overload protection function. Refer to Electronic Thermal Function in the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and Safety Functionality User's Manual (Cat. No. I621) for details.
- ***5.** This value is for models without options.
- ***6.** The allowable radial and thrust loads are the values determined for a limit of 20,000 hours at normal operating temperatures. The allowable radial loads are applied as shown in the following diagram.

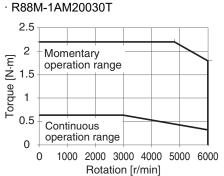


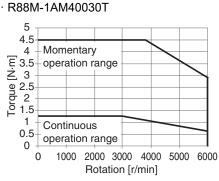
- *7. When the brake is released for a vertical axis, refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and Safety Functionality User's Manual (Cat. No. 1621) to set an appropriate value for Brake Interlock Output (4610 hex).
- *8. This is a non-excitation brake. It is released when excitation voltage is applied.
- *9. This value is a reference value.

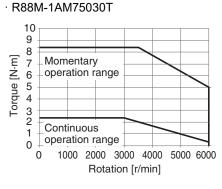
Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

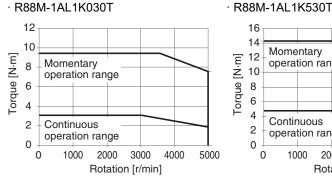
Torque-Rotation Speed Characteristics for 3,000-r/min Servomotors (200 VAC)

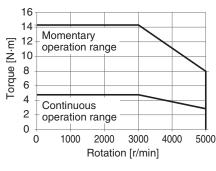
The following graphs show the characteristics with a 3-m standard cable and a 3-phase 200-VAC or single-phase 220-VAC input.

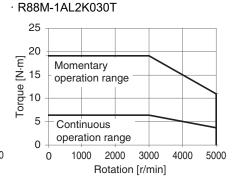




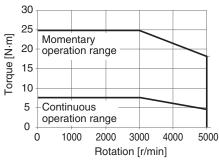








· R88M-1AL2K630T

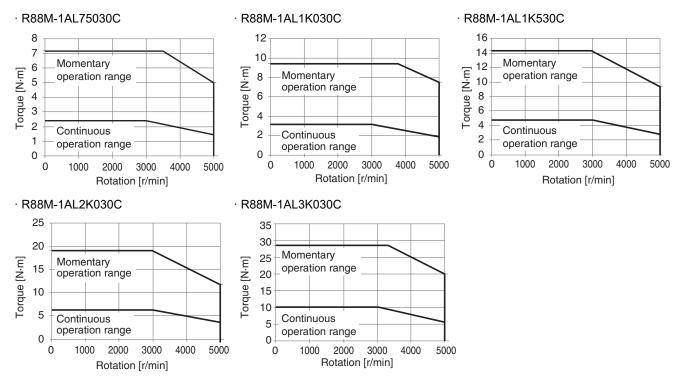


Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

Torque-Rotation Speed Characteristics for 3,000-r/min Servomotors (400 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 3-phase 400-VAC input.



Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

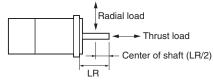
1,500-r/min Servomotors

			Model (R88M-)	AC	200V	
	Item		Unit	1AM1K515T	1AM2K715T	
Rated output *	ated output *1*2		W	1,500	2,700	
Rated torque *	1*2		N·m	9.55	17.2	
Rated rotation s	speed *1*2	2	r/min	1,	500	
Maximum rotati	ion speed		r/min	3,1	000	
Momentary max	kimum torq	ue *1	N·m	28.7	51.6	
Rated current *	:1*2		A(rms)	8.6	14.6	
Momentary max	ximum curr	ent *1	A(rms)	28.4	49.3	
3-4		Without brake	×10 ⁻⁴ kg·m ²	12.413	40.013	
Rotor inertia		With brake	×10 ⁻⁴ kg·m ²	13.013	45.113	
Applicable load	l inertia		×10 ⁻⁴ kg·m²	127.05	270.63	
Torque constar	nt *1		N·m/A(rms)	1.11	1.29	
Power rate *1*	3		kW/s	73	74	
lechanical time	e constant	*3	ms	0.75	1.0	
Electrical time	constant		ms	17	19	
Allowable radia	I load *4		N	490	1176	
Allowable thrus	st load *4		N	196	490	
Voimbt	With	out brake	kg	11	18	
Veight	With	brake	kg	13	22	
Radiator plate o	dimensions	(material)	mm	470 × 470 × t20 (aluminum)		
	Excitation	voltage *6	V	24 VD	C±10%	
	Current co (at 20°C)	onsumption	Α	0.66	1.20	
	Static frict	tion torque	N·m	12 min.	22 min.	
	Attraction	time	ms	100 max.	120 max.	
	Release ti	me * 7	ms	30 max.	50 max.	
Brake	Backlash		0	0.6 max.	0.8 max.	
specifications	Allowable	braking work	J	1,000	1,400	
* 5	Allowable	total work	J	3,000,000	4,600,000	
	Allowable accelerati		rad/s²	10,00	0 max.	
	Brake lifet	time ion/ deceleration)		10 million	times min.	
	Brake lifet (ON/OFF),			1 million	times min.	
	Insulation	class		Cla	iss F	

Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

		Model (R88M-)	AC400V		
	Item	Unit	1AM1K515C	1AM3K015C	
Rated output *1*2		W	1,500	3,000	
Rated torque *1*2		N·m	9.55	19.1	
Rated rotation	speed *1*2	r/min	1,	500	
Maximum rotat	ion speed	r/min	3,	000	
Momentary max	ximum torque *1	N·m	28.7	57.3	
Rated current %	k1 * 2	A(rms)	4.4	8.5	
Momentary max	ximum current *1	A(rms)	14.1	28.3	
Rotor inertia	Without brake	×10 ⁻⁴ kg·m ²	12.413	40.013	
Rotor mertia	With brake	×10 ⁻⁴ kg·m ²	13.013	45.113	
Applicable load	d inertia	×10 ⁻⁴ kg·m ²	127.05	270.63	
Torque constar	nt *1	N·m/A(rms)	2.21	2.46	
Power rate *1*	:3	kW/s	73	91	
Mechanical tim	e constant *3	ms	0.75	1.2	
Electrical time	constant	ms	17	16	
Allowable radia	al load *4	N	490	1176	
Allowable thrust load *4		N	196	490	
Neight	Without brake	kg	11	18	
weight	With brake	kg	13	22	
Radiator plate o	dimensions (material)	mm	470 × 470 × t20 (aluminum)		
	Excitation voltage *6	V	24 VDC±10%		
	Current consumption (at 20°C)	A	0.66	1.20	
	Static friction torque	N·m	12 min.	22 min.	
	Attraction time	ms	100 max.	120 max.	
	Release time *7	ms	30 max.	50 max.	
Brake	Backlash	0	0.6 max.	0.8 max.	
specifications	Allowable braking work	J	1,000	1,400	
*5	Allowable total work	J	3,000,000	4,600,000	
	Allowable angular acceleration	rad/s²	10,00	00 max.	
	Brake lifetime (acceleration/ deceleration)		10 million	times min.	
			1 million times min.		
	Brake lifetime (ON/OFF), B10d		1 million	times min.	

- *1. This is a typical value for when the Servomotor is used at a normal temperature (20°C, 65%) in combination with a Servo Drive.
- *2. The rated values are the values with which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
- *3. This value is for models without options.
- ***4.** The allowable radial and thrust loads are the values determined for a limit of 20,000 hours at normal operating temperatures. The allowable radial loads are applied as shown in the following diagram.

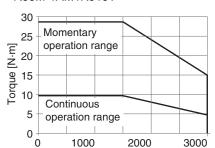


- *5. When the brake is released for a vertical axis, refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and Safety Functionality User's Manual (Cat. No. I621) to set an appropriate value for Brake Interlock Output (4610 hex).
- ***6.** This is a non-excitation brake. It is released when excitation voltage is applied.
- *7. This value is a reference value.
- Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

Torque-Rotation Speed Characteristics for 1,500-r/min Servomotors (200 VAC)

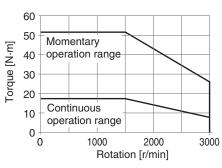
The following graphs show the characteristics with a 3-m standard cable and a 3-phase 200-VAC or single-phase 220-VAC input.

· R88M-1AM1K515T



Rotation [r/min]

· R88M-1AM2K715T



Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

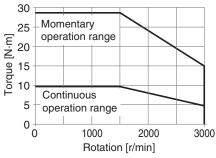
Torque-Rotation Speed Characteristics for 1,500-r/min Servomotors (400 VAC)

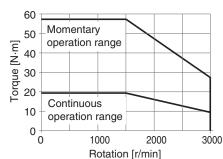
The following graphs show the characteristics with a 3-m standard cable and a 3-phase 400-VAC input.

· R88M-1AM1K515C









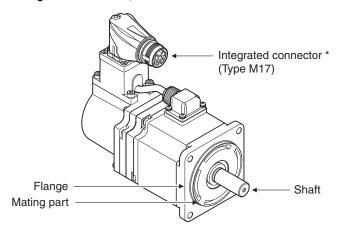
Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.

Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

Part Names

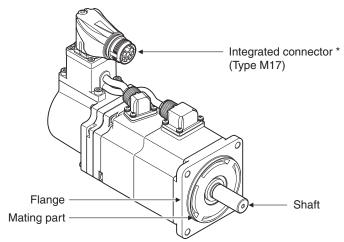
Servomotor Part Names

Flange Size of 60×60, 80×80



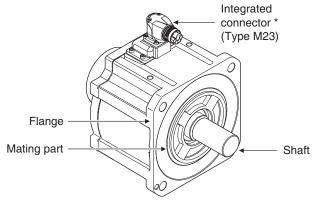
* For servomotors without Brake, brake wire signals are not use (terminal open).

200 VAC 200 W Servomotors (without Brake)



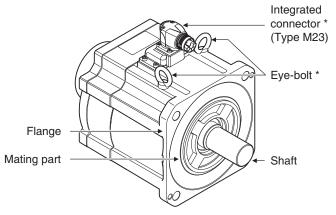
200 VAC 200 W Servomotors (with Brake)

Flange Size of 100×100, 130×130, 180×180



* For servomotors without Brake, brake wire signals are not use (terminal open).

400 VAC 3 kW Servomotors (without Brake)



* In some cases, eye bolts are not equipped, depending on the Servomotor's mass.

400 VAC 3 kW Servomotors (with Brake)

Servomotor Functions

Shaft

The load is mounted on this shaft.

The direction which is in parallel with the shaft is called the thrust direction, and the direction which is perpendicular to the shaft is called the radial direction.

Flange

Used for mounting the Servomotor on the equipment.

Fit the mating part into the equipment and use the mounting holes to screw the Servomotor.

Integrated Connector

This is an integrated connector that can connect each cable for power, encoder and brake all at once.

The power cable supplies power to the phases U, V, and W of the Servomotor.

The encoder cable supplies power to the encoder of the Servomotor and communicates with the Servo Drive.

The brake cable supplies power to the brake coil.

The cable outlet direction can be selected. The change of the cable outlet direction shall be up to five times.

Eye-bolt

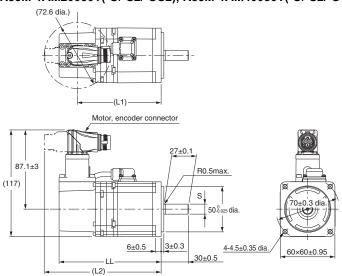
Used for lifting and moving the motor by putting a wire rope, for example, through the shaft.

(Unit: mm)

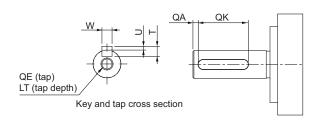
3,000-r/min Servomotors (200 V)

200 W/400 W (without Brake)

R88M-1AM20030T(-O/-S2/-OS2), R88M-1AM40030T(-O/-S2/-OS2)



Shaft-end with key and tap



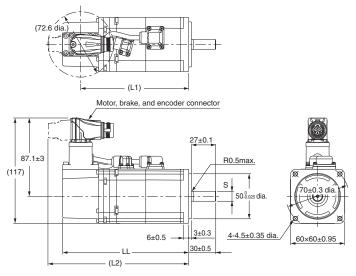
Model	Dimensions [mm]					
Model	S	LL	L1	L2		
R88M-1AM20030T(-S2)	11 dia0.011	112±1	92	128		
R88M-1AM40030T(-S2)	14 dia. 0	138±1	118	154		
R88M-1AM20030T-O(S2)	11 dia. 0	119±1	99	135		
R88M-1AM40030T-O(S2)	14 dia0.011	145±1	125	161		

Model	Dimensions [mm]						
Wiodei	QA	QK	W	Т	U	QE	LT
R88M- 1AM20030T(-S2/-OS2)	2	20	4-0.03	4	1.5.0.2	M4	10
R88M- 1AM40030T(-S2/-OS2)	2	20	5-0.03	5	2-0.2	M5	12

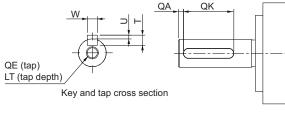
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

200 W/400 W (with Brake)

R88M-1AM20030T-B(O/S2/OS2), R88M-1AM40030T-B(O/S2/OS2)



Snant-end	with key	anu tap	

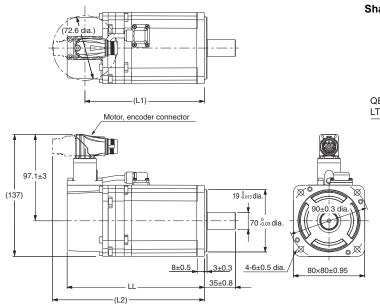


Model	Dimensions [mm]						
Woder	S	LL	L1	L2			
R88M-1AM20030T-B(S2)	11 dia0.011	140±1	120	156			
R88M-1AM40030T-B(S2)	14 dia0.011	166±1	146	182			
R88M-1AM20030T-BO(S2)	11 dia0.011	147±1	127	163			
R88M-1AM40030T-BO(S2)	14 dia. 0	173±1	153	189			

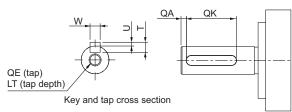
Model	Dimensions [mm]							
	QA	QK	W	Т	U	QE	LT	
R88M- 1AM20030T-B(S2/OS2)	2	20	4-0.03	4	1.5-0.2	M4	10	
R88M- 1AM40030T-B(S2/OS2)	2	20	5-0.03	5	2-0.2	M5	12	

750 W (without Brake)

R88M-1AM75030T(-O/-S2/-OS2)



Shaft-end with key and tap



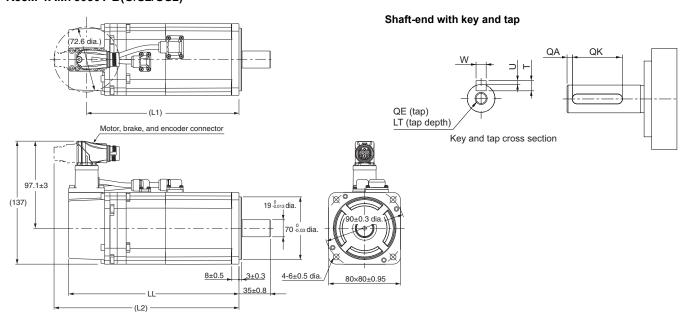
Model	Dimensions [mm]					
Model	LL	L1	L2			
R88M-1AM75030T(-S2)	154±1	134	170			
R88M-1AM75030T-O(S2)	161±1	141	177			

Model	Dimensions [mm]						
Wiodei	QA	QK	W	Т	U	QE	LT
R88M- 1AM75030T(-S2/-OS2)	3	24	6-0.03	6	2.5-0.2	M5	12

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

750 W (with Brake)

R88M-1AM75030T-B(O/S2/OS2)

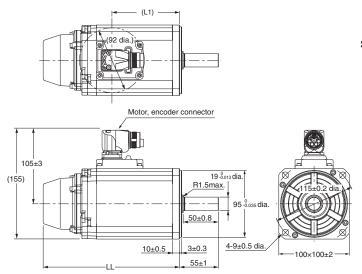


Model	Dimensions [mm]					
Model	LL	L1	L2			
R88M-1AM75030T-B(S2)	189.8±2	170	206			
R88M-1AM75030T-BO(S2)	196.8±2	177	213			

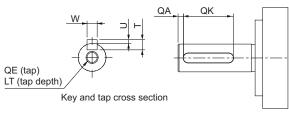
Model		Dimensions [mm]						
Model	QA	QK	W	Т	U	QE	LT	
R88M-1AM75030T- B(S2/OS2)	3	24	6-0.03	6	2.5-0.2	M5	12	

1 kW/1.5 kW/2 kW (without Brake)

R88M-1AL1K030T(-O/-S2/-OS2), R88M-1AL1K530T(-O/-S2/-OS2), R88M-1AL2K030T(-O/-S2/-OS2)



Shaft-end with key and tap



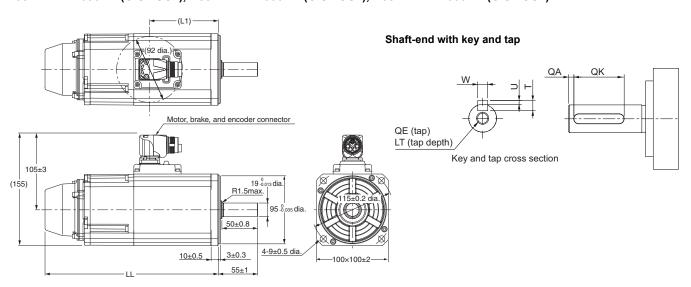
Model	Dimensions [mm]					
Model	LL	L1				
R88M- 1AL1K030T(-O/-S2/-OS2)	193.5±2	96				
R88M- 1AL1K530T(-O/-S2/-OS2)	193.5±2	96				
R88M- 1AL2K030T(-O/-S2/-OS2)	204.5±3	107				

Model	Dimensions [mm]						
Wodel	QA	QK	W	Т	U	QE	LT
R88M- 1AL1K030T(-S2/-OS2)	3	42	6-0.03	6	2.5-0.2	M5	12
R88M- 1AL1K530T(-S2/-OS2)	3	42	6-0.03	6	2.5-0.2	M5	12
R88M- 1AL2K030T(-S2/-OS2)	3	42	6-0.03	6	2.5-0.2	M5	12

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

1 kW/1.5 kW/2 kW (with Brake)

R88M-1AL1K030T-B(O/S2/OS2), R88M-1AL1K530T-B(O/S2/OS2), R88M-1AL2K030T-B(O/S2/OS2)

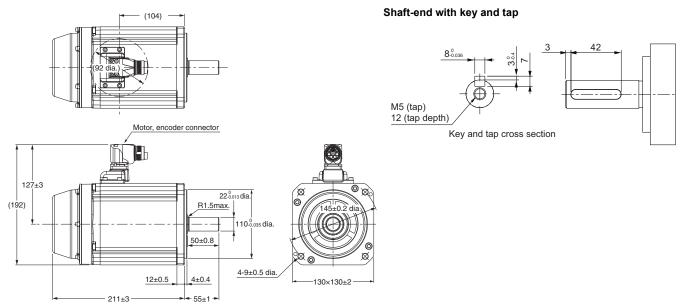


Model	Dimensions [mm]					
Woder	LL	L1				
R88M- 1AL1K030T-B(O/S2/OS2)	242±3	96				
R88M- 1AL1K530T-B(O/S2/OS2)	242±3	96				
R88M- 1AL2K030T-B(O/S2/OS2)	253±3	107				

Model	Dimensions [mm]							
Wodel	QA	QK	W	Т	U	QE	LT	
R88M-1AL1K030T- B(S2/OS2)	3	42	6-0.03	6	2.5-0.2	M5	12	
R88M-1AL1K530T- B(S2/OS2)	3	42	6-0.03	6	2.5-0.2	M5	12	
R88M-1AL2K030T- B(S2/OS2)	3	42	6-0.03	6	2.5-0.2	M5	12	

2.6 kW (without Brake)

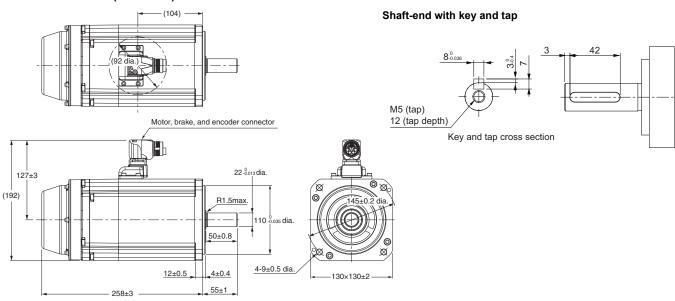
R88M-1AL2K630T(-O/-S2/-OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

2.6 kW (with Brake)

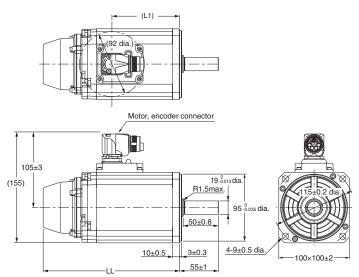
R88M-1AL2K630T-B(O/S2/OS2)



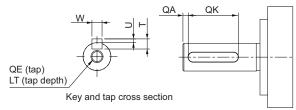
3,000-r/min Servomotors (400 V)

750 W/1 kW/1.5 kW/2 kW (without Brake)

R88M-1AL75030C(-O/ -S2/ -OS2), R88M-1AL1K030C(-O/ -S2/ -OS2) R88M-1AL1K530C(-O/ -S2/ -OS2), R88M-1AL2K030C(-O/ -S2/ -OS2)



Shaft-end with key and tap



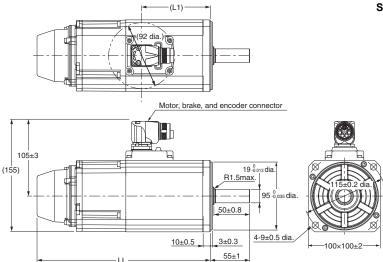
Model	Dimensions [mm]				
Model	LL	L1			
R88M-1AL75030C(-O/-S2/-OS2)	164.5±2	67			
R88M-1AL1K030C(-O/-S2/-OS2)	193.5±2	96			
R88M-1AL1K530C(-O/-S2/-OS2)	193.5±2	96			
R88M-1AL2K030C(-O/-S2/-OS2)	204.5±3	107			

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

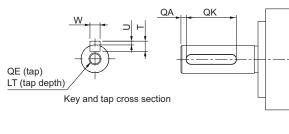
Model	Dimensions [mm]							
Wodel	QA	QK	W	Т	U	QE	LT	
R88M- 1AL75030C(-S2/-OS2)	3	42	6-0.03	6	2.5-0.2	M5	12	
R88M- 1AL1K030C(-S2/-OS2)	3	42	6-0.03	6	2.5-0.2	M5	12	
R88M- 1AL1K530C(-S2/-OS2)	3	42	6-0.03	6	2.5-0.2	M5	12	
R88M- 1AL2K030C(-S2/-OS2)	3	42	6-0.03	6	2.5-0.2	M5	12	

750 W/1 kW/1.5 kW/2 kW (with Brake)

R88M-1AL75030C-B(O/S2/OS2), R88M-1AL1K030C-B(O/S2/OS2) R88M-1AL1K530C-B(O/S2/OS2), R88M-1AL2K030C-B(O/S2/OS2)



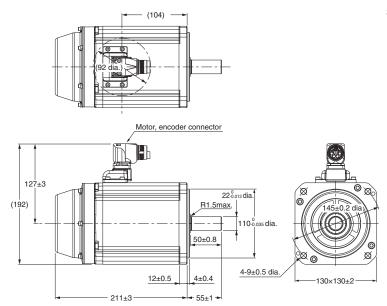
Snart-end	with	ĸey	and	tap



Model	Dimensions [mm]			
Model	LL	L1		
R88M-1AL75030C-B(O/S2/OS2)	213±3	67		
R88M-1AL1K030C-B(O/S2/OS2)	242±3	96		
R88M-1AL1K530C-B(O/S2/OS2)	242±3	96		
R88M-1AL2K030C-B(O/S2/OS2)	253±3	107		

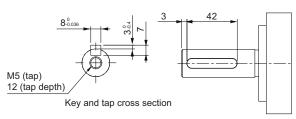
Model	Dimensions [mm]						
Wodel	QA	QK	W	Т	U	QE	LT
R88M-1AL75030C- B(S2/OS2)	3	42	6-0.03	6	2.5-0.2	M5	12
R88M-1AL1K030C- B(S2/OS2)	3	42	6-0.03	6	2.5-0.2	M5	12
R88M-1AL1K530C- B(S2/OS2)	3	42	6-0.03	6	2.5-0.2	M5	12
R88M-1AL2K030C- B(S2/OS2)	3	42	6-0.03	6	2.5-0.2	M5	12

3 kW (without Brake) R88M-1AL3K030C(-O/-S2/-OS2)



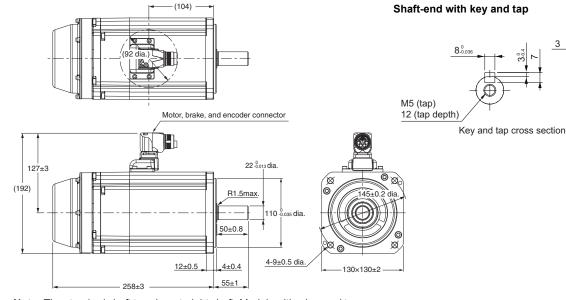
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap



3 kW (with Brake)

R88M-1AL3K030C-B(O/S2/OS2)

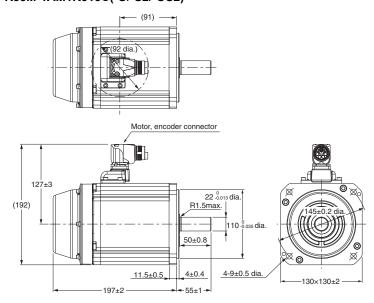


1,500-r/min Servomotors (200 V/400 V)

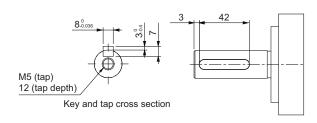
1.5 kW (without Brake)

R88M-1AM1K515T(-O/-S2/-OS2)

R88M-1AM1K515C(-O/-S2/-OS2)



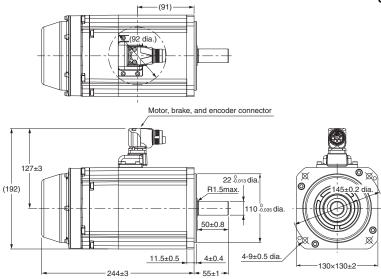
Shaft-end with key and tap



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

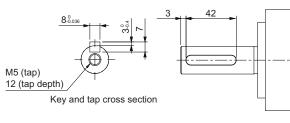
1.5 kW (with Brake)

R88M-1AM1K515T-B(O/S2/OS2) R88M-1AM1K515C-B(O/S2/OS2)

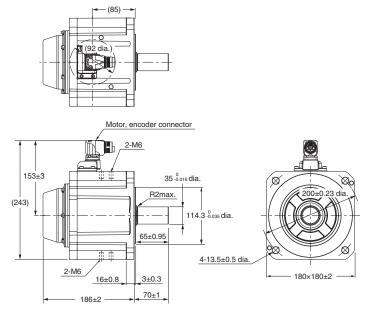


Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap

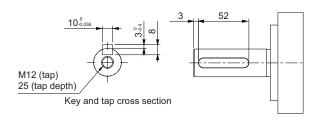


2.7 kW (without Brake) R88M-1AM2K715T(-O/-S2/-OS2) 3 kW (without Brake) R88M-1AM3K015C(-O/-S2/-OS2)

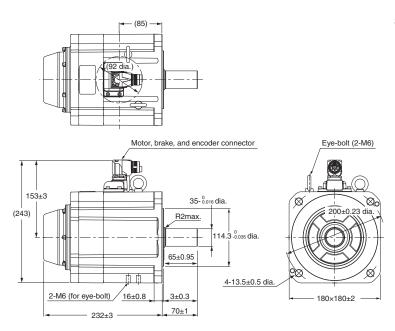


Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap

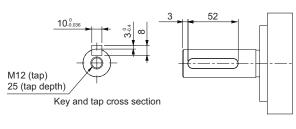


2.7 kW (with Brake) R88M-1AM2K715T-B(O/S2/OS2) 3 kW (with Brake) R88M-1AM3K015C-B(O/S2/OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number. Models with an oil seal are indicated with "O" at the end of the model number.

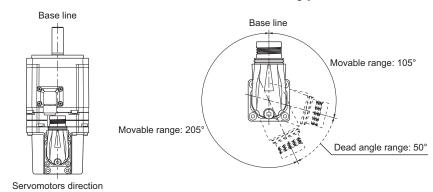
Shaft-end with key and tap



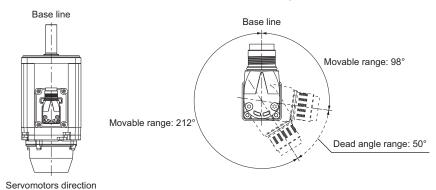
Cable Outlet Direction of Integrated Connector

The cable outlet direction of the servomotor for connector type M17 or M23 can be selected. The below shows the selectable range. The change of the cable outlet direction shall be up to five times. For a procedure of the change of the cable outlet direction, refer to the AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications and Safety Functionality User's Manual (I621).

Cable Outlet Direction of Connector Type M17



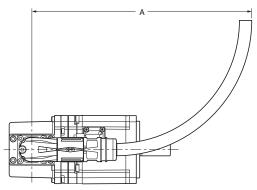
Cable Outlet Direction of Connector Type M23



AC Servo System 1S-series with Safety Functionality Cable Wiring Dimension for a Case of Servo Motor Installing

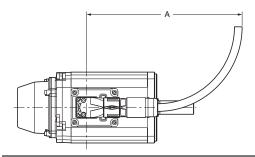
The Integrated cable wiring dimensions are shown below the table according to connector type for Servomotors. The dimensions from the rotation center of the Integrated connector to the Integrated cable surrounding are indicated as A.

Servo Motor for Connector Type M17



Model	Dimensions [mm]
Wodel	Α
R88M-1AM20030T(-O/-S2/-OS2)	
R88M-1AM40030T(-O/-S2/-OS2)	
R88M-1AM75030T(-O/-S2/-OS2)	210
R88M-1AM20030T-B(O/S2/OS2)	210
R88M-1AM40030T-B(O/S2/OS2)	
R88M-1AM75030T-B(O/S2/OS2)	

Servo Motor for Connector Type M23



Model	Dimensions [mm]
wodei	Α
R88M-1AL75030C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1AL1K030T(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1AL1K030C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1AL1K530T(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1AL1K530C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1AL2K030T(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1AL2K030C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	270
R88M-1AL2K630T(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1AL3K030C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1AM1K515T(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1AM1K515C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1AM2K715T(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1AM3K015C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	